

# Module Handbook M.Sc. Mechatronics and Information Technology 2025 (Master of Science)

SPO 2025

Summer term 2025

Date: 11/04/2025

KIT DEPARTMENTS OF MECHANICAL ENGINEERING / ELECTRICAL ENGINEERING AND INFORMATION TECHNOLOGY



## Table Of Contents

|  |           |
|--|-----------|
| <b>1. Description of the degree program</b> .....  | <b>14</b> |
| 1.1. List of abbreviations .....   | 14        |
| 1.2. Subjects .....  | 14        |
| 1.2.1. Field of Specialization .....   | 14        |
| 1.3. Curriculum .....  | 15        |
| 1.4. Additional Examinations .....   | 15        |
| 1.5. Recognition of external study achievements .....  | 15        |
| 1.6. Semester abroad and student mobility .....  | 16        |
| 1.7. Calculation of grades .....   | 16        |
| 1.8. Master's Thesis .....   | 16        |
| <b>2. Goals, structure and acquisition of competences</b> .....                                    | <b>17</b> |
| 2.1. Conformity of module structure with competence goals .....                                    | 17        |
| 2.2. Acquisition of competences .....  | 17        |
| <b>3. General Information</b> .....  | <b>18</b> |
| 3.1. Study program details .....   | 18        |
| 3.2. Content .....   | 18        |
| 3.3. Qualification Goals .....   | 19        |
| 3.4. Studies and Examination Regulations .....   | 20        |
| <b>4. Field of study structure</b> .....   | <b>21</b> |
| 4.1. Master's Thesis .....   | 21        |
| 4.2. Field of Specialization in Mechatronics and Information Technology .....                      | 21        |
| 4.2.1. Energy Technology .....   | 21        |
| 4.2.2. Industrial Informatics and Systems Engineering .....  | 27        |
| 4.2.3. Vehicle Systems Engineering .....   | 30        |
| 4.2.4. Micro System Technology .....   | 33        |
| 4.2.5. Automation, Control, and Robotics .....   | 36        |
| 4.2.6. Autonomous Systems and AI .....   | 39        |
| 4.2.7. Design of Mechatronic Systems .....   | 42        |
| 4.3. Elective Area in Mechatronics and Information Technology .....                                | 45        |
| 4.4. Interdisciplinary Qualifications .....  | 52        |
| <b>5. Notes on modules and courses</b> .....   | <b>51</b> |
| <b>6. Publisher</b> .....  | <b>52</b> |
| <b>7. Modules</b> .....  | <b>53</b> |
| 7.1. Actuators and Sensors in Nanotechnology - M-MACH-102698 .....                                 | 55        |
| 7.2. Adaptive Optics - M-ETIT-103802 .....   | 57        |
| 7.3. Advanced Artificial Intelligence - M-INFO-107198 .....  | 59        |
| 7.4. Advanced Communications Engineering - M-ETIT-106815 .....                                     | 60        |
| 7.5. Analog Circuit Design - M-ETIT-100466 .....   | 61        |
| 7.6. Analysis Tools for Combustion Diagnostics - M-MACH-107031 .....                               | 62        |
| 7.7. Antennas and Beamforming - M-ETIT-106956 .....  | 63        |
| 7.8. Applied Information Theory - M-ETIT-100444 .....  | 64        |
| 7.9. Artificial Intelligence in Production - M-MACH-105968 .....                                   | 65        |
| 7.10. Automated Visual Inspection and Image Processing [24169] - M-INFO-100826 .....               | 67        |
| 7.11. Automotive Engineering I - M-MACH-100501 .....   | 68        |
| 7.12. Automotive Engineering II - M-MACH-100502 .....  | 69        |
| 7.13. Automotive Vision - M-MACH-107148 .....  | 70        |
| 7.14. Automotive Vision - M-MACH-102693 .....  | 72        |
| 7.15. Basics of Converter Control - M-ETIT-100400 .....  | 73        |
| 7.16. Basics of Technical Logistics II - M-MACH-105302 .....                                       | 74        |
| 7.17. Batteries and Fuel Cells - M-ETIT-100532 .....   | 75        |
| 7.18. Batteries and Fuel Cells Laboratory - M-ETIT-100381 .....                                    | 76        |
| 7.19. Battery and Fuel Cells Systems - M-ETIT-100377 .....   | 77        |
| 7.20. Bioelectric Signals - M-ETIT-100549 .....  | 78        |
| 7.21. Biologically Inspired Robots - M-MACH-106903 .....   | 79        |
| 7.22. BioMEMS - Microfluidic Chipsystems V - M-MACH-105484 .....                                   | 81        |
| 7.23. BioMEMS - Microsystems Technologies for Life Sciences and Medicine I - M-MACH-100489 .....   | 82        |
| 7.24. BioMEMS - Microsystems Technologies for Life Sciences and Medicine II - M-MACH-100490 .....  | 83        |
| 7.25. BioMEMS - Microsystems Technologies for Life Sciences and Medicine III - M-MACH-100491 ..... | 84        |
| 7.26. BioMEMS - Microsystemtechnology for Life-Science and Medicine IV - M-MACH-105483 .....       | 85        |

|  |     |
|--|-----|
| 7.27. CAD Engineering Project for Intelligent Systems - M-MACH-106905 .....                                  | 86  |
| 7.28. CAE-Workshop - M-MACH-102684 .....   | 87  |
| 7.29. Channel Coding: Algebraic Methods for Communications and Storage - M-ETIT-105616 .....                 | 88  |
| 7.30. CO <sub>2</sub> -Neutral Combustion Engines and their Fuels I - M-MACH-107060 .....                    | 89  |
| 7.31. CO <sub>2</sub> -Neutral Combustion Engines and their Fuels II - M-MACH-107180 .....                   | 90  |
| 7.32. Cognitive Automobiles - Laboratory - M-MACH-106744 .....   | 91  |
| 7.33. Combined Cycle Power Plants - M-MACH-107062 .....  | 93  |
| 7.34. Communication Systems and Protocols - M-ETIT-100539 .....  | 94  |
| 7.35. Communications Engineering Laboratory - M-ETIT-107136 .....  | 96  |
| 7.36. Components of Power Systems - M-ETIT-106689 .....  | 97  |
| 7.37. Computational Fluid Dynamics (CFD) for Energy Technologies - M-MACH-107157 .....                       | 99  |
| 7.38. Computational Intelligence - M-MACH-105296 .....   | 100 |
| 7.39. Continuum Mechanics - M-MACH-105180 .....  | 101 |
| 7.40. Control of Linear Multivariable Systems - M-ETIT-100374 .....  | 102 |
| 7.41. Control of Mobile Machines - M-MACH-106468 .....   | 104 |
| 7.42. Control of Power-Electronic Systems - M-ETIT-105915 .....  | 105 |
| 7.43. Control Technology - M-MACH-105348 .....   | 106 |
| 7.44. Control Theory Laboratory - M-ETIT-105467 .....  | 107 |
| 7.45. Current Topics on BioMEMS - M-MACH-105485 .....  | 108 |
| 7.46. Cyber-Physical Modeling - M-ETIT-106953 .....  | 109 |
| 7.47. Data Analytics for Engineers - M-MACH-105307 .....   | 111 |
| 7.48. Data-Driven Algorithms in Vehicle Technology - M-MACH-107151 .....                                     | 112 |
| 7.49. Decision-Making and Motion Planning for Automated Driving - M-MACH-106926 .....                        | 113 |
| 7.50. Deep Learning and Neural Networks - M-INFO-107197 .....  | 114 |
| 7.51. Deep Learning for Computer Vision I: Basics - M-INFO-105753 .....                                      | 115 |
| 7.52. Deep Learning for Computer Vision II: Advanced Topics - M-INFO-105755 .....                            | 116 |
| 7.53. Deep Learning for Engineers - M-MACH-107088 .....  | 117 |
| 7.54. Design and Development of Mobile Machines - M-MACH-107055 .....  | 118 |
| 7.55. Design and Optimization of Conventional and Electrified Automotive Transmissions - M-MACH-107082 ..... | 119 |
| 7.56. Design of Electrical Machines - M-ETIT-100515 .....  | 121 |
| 7.57. Design with Plastics - M-MACH-102712 .....   | 122 |
| 7.58. Development of Automated Production Systems - M-MACH-107020 .....                                      | 123 |
| 7.59. Development of Hybrid Powertrains - M-MACH-107078 .....  | 124 |
| 7.60. Development of Oil-Hydraulic Powertrain Systems - M-MACH-107059 .....                                  | 125 |
| 7.61. Digital Beam-Forming for Imaging Radar - M-ETIT-105415 .....   | 126 |
| 7.62. Digital Circuit Design - M-ETIT-100473 .....   | 127 |
| 7.63. Digital Control - M-MACH-107045 .....  | 128 |
| 7.64. Digital Hardware Design Laboratory - M-ETIT-102266 .....   | 129 |
| 7.65. Digital Hardware Design Laboratory - M-ETIT-102264 .....   | 130 |
| 7.66. Digital Twin Engineering - M-ETIT-106040 .....   | 131 |
| 7.67. Digitalization of Products, Services & Production - M-MACH-105476 .....                                | 133 |
| 7.68. Distributed Discrete Event Systems - M-ETIT-100361 .....   | 134 |
| 7.69. Drive System Engineering B: Stationary Machinery - M-MACH-107190 .....                                 | 135 |
| 7.70. Drive Train of Mobile Machines - M-MACH-105800 .....   | 136 |
| 7.71. Dynamics of Electro-Mechanical Systems - M-MACH-105612 .....   | 137 |
| 7.72. Dynamics of the Automotive Drive Train - M-MACH-102700 .....   | 138 |
| 7.73. Electric Drives and Power Electronics Lab - M-ETIT-107138 .....  | 139 |
| 7.74. Electric Drives for E-Mobility - M-ETIT-106971 .....   | 141 |
| 7.75. Electric Power Transmission & Grid Control - M-ETIT-105394 .....                                       | 142 |
| 7.76. Electrical Energy Systems Lab - M-ETIT-107137 .....  | 143 |
| 7.77. Electrocatalysis - M-ETIT-105883 .....   | 144 |
| 7.78. Elements of Technical Logistics - M-MACH-102688 .....  | 145 |
| 7.79. Elements of Technical Logistics incl. Project - M-MACH-105015 .....                                    | 146 |
| 7.80. Energy Storage and Network Integration - M-ETIT-101969 .....   | 147 |
| 7.81. Energy Systems I - Renewable Energy - M-MACH-107139 .....  | 149 |
| 7.82. Energy Topology and Resilience - M-MACH-107061 .....   | 150 |
| 7.83. Engine Measurement Techniques - M-MACH-107160 .....  | 151 |
| 7.84. Engineering Materials for the Energy Transition - M-MACH-107066 .....                                  | 152 |
| 7.85. Fabrication Processes in Microsystem Technology - M-MACH-105478 .....                                  | 153 |
| 7.86. Field Propagation and Coherence - M-ETIT-100566 .....  | 154 |
| 7.87. Flows and Heat Transfer in Energy Technology - M-MACH-107120 .....                                     | 156 |
| 7.88. Fundamentals in the Development of Commercial Vehicles - M-MACH-105824 .....                           | 157 |

|  |     |
|--|-----|
| 7.89. Fundamentals of Combustion I - M-MACH-102707 .....   | 159 |
| 7.90. Fundamentals of Combustion II - M-MACH-107117 .....  | 160 |
| 7.91. Fundamentals of Energy Technology - M-MACH-102690 .....  | 161 |
| 7.92. Fundamentals of Reactor Safety for the Operation and Dismantling of Nuclear Power Plants - M-MACH-107150 .....   | 162 |
| 7.93. Fusion Technology A - M-MACH-107124 .....  | 163 |
| 7.94. Fusion Technology B - M-MACH-107154 .....  | 164 |
| 7.95. Handling Characteristics of Motor Vehicles I - M-MACH-105288 .....   | 165 |
| 7.96. Handling Characteristics of Motor Vehicles II - M-MACH-107073 .....  | 166 |
| 7.97. Hardware Modeling and Simulation - M-ETIT-100449 .....   | 167 |
| 7.98. Hardware Synthesis and Optimization - M-ETIT-106963 .....  | 169 |
| 7.99. Hardware/Software Co-Design - M-ETIT-100453 .....  | 170 |
| 7.100. Heat and Mass Transfer - M-MACH-102717 .....  | 172 |
| 7.101. Heat Pumps - M-MACH-107075 .....  | 173 |
| 7.102. High-Voltage Technology - M-ETIT-105060 .....   | 174 |
| 7.103. High-Voltage Test Technique - M-ETIT-100417 .....   | 175 |
| 7.104. Holistic Approach of Managing Power Plant Operation under Uncertainty and Volatility - M-MACH-107097 .....  | 176 |
| 7.105. Hot Research Topics in AI for Engineering Applications - M-MACH-107089 .....  | 177 |
| 7.106. Human Brain and Central Nervous System: Anatomy, Information Transfer, Signal Processing, Neurophysiology and Therapy [24139 / 24678] - M-INFO-100725 ..... | 178 |
| 7.107. Human-Machine-Interaction in Anthropomatics: Basics [24100] - M-INFO-100824 .....   | 179 |
| 7.108. Humanoid Robots - Seminar - M-INFO-107152 .....   | 180 |
| 7.109. Hydrogen and reFuels - Energy Conversion in Combustion Engines - M-MACH-107158 .....  | 181 |
| 7.110. Industrial Circuitry - M-ETIT-100399 .....  | 182 |
| 7.111. Industrial Mobile Robotics Lab - M-MACH-106830 .....  | 183 |
| 7.112. Information Fusion - M-ETIT-103264 .....  | 185 |
| 7.113. Information Processing in Sensor Networks - M-INFO-100895 .....   | 186 |
| 7.114. Information Systems and Supply Chain Management - M-MACH-105281 .....   | 187 |
| 7.115. Information Technology in Industrial Automation Systems - M-ETIT-100367 .....   | 188 |
| 7.116. Innovation and Project Management in Rail Vehicle Engineering - M-MACH-106514 .....   | 189 |
| 7.117. Innovation2Business – Innovation Strategy in the Industrial Corporate Practice - M-MACH-107188 .....  | 190 |
| 7.118. Innovative Concepts for Programming Industrial Robots [24179] - M-INFO-100791 .....   | 191 |
| 7.119. Innovative Nuclear Systems - M-MACH-107119 .....  | 192 |
| 7.120. Integrated Intelligent Sensors - M-ETIT-100457 .....  | 193 |
| 7.121. Integrated Product Development - M-MACH-107141 .....  | 194 |
| 7.122. Integrated Systems and Circuits - M-ETIT-100474 .....   | 196 |
| 7.123. Interdisciplinary Qualifications - M-ETIT-107193 .....  | 197 |
| 7.124. International Production Engineering - M-MACH-105109 .....  | 199 |
| 7.125. Introduction into Energy Economics - M-WIWI-100498 .....  | 201 |
| 7.126. Introduction to Automotive and Industrial Lidar Technology - M-ETIT-105461 .....  | 202 |
| 7.127. Introduction to Bionics - M-MACH-106525 .....   | 203 |
| 7.128. Introduction to Microsystem Technology I - M-MACH-102691 .....  | 204 |
| 7.129. Introduction to Microsystem Technology II - M-MACH-102706 .....   | 205 |
| 7.130. Introduction to Nanotechnology - M-MACH-107207 .....  | 206 |
| 7.131. Introduction to Nuclear Energy - M-MACH-107122 .....  | 207 |
| 7.132. IT/OT-Security Seminar - M-ETIT-106789 .....  | 208 |
| 7.133. IT-Fundamentals of Logistics: Opportunities for Digital Transformation - M-MACH-105282 .....  | 210 |
| 7.134. Lab Computer-Aided Methods for Measurement and Control - M-MACH-105291 .....  | 212 |
| 7.135. Lab Course on Nanoelectronics - M-ETIT-100468 .....   | 213 |
| 7.136. Laboratory Exercise in Energy Technology - M-MACH-107206 .....  | 214 |
| 7.137. Laboratory FPGA Based Circuit Design - M-ETIT-100470 .....  | 215 |
| 7.138. Laboratory in Software Engineering - M-ETIT-100460 .....  | 216 |
| 7.139. Laboratory Information Systems in Power Engineering - M-ETIT-107159 .....   | 217 |
| 7.140. Laboratory Mechatronic Measurement Systems - M-ETIT-103448 .....  | 218 |
| 7.141. Laboratory Mechatronics - M-MACH-102699 .....   | 219 |
| 7.142. Laboratory Nanotechnology - M-ETIT-100478 .....   | 220 |
| 7.143. Laboratory Optoelectronics - M-ETIT-100477 .....  | 222 |
| 7.144. Laboratory Solar Energy - M-ETIT-102350 .....   | 223 |
| 7.145. Leadership in Interdisciplinary Teams - M-MACH-107142 .....   | 225 |
| 7.146. Liberalised Power Markets - M-WIWI-105403 .....   | 226 |
| 7.147. Lighting Engineering - M-ETIT-100485 .....  | 228 |
| 7.148. Lightweight Engineering Design - M-MACH-102696 .....  | 229 |
| 7.149. Localization of Mobile Agents [24613] - M-INFO-100840 .....   | 230 |

|  |     |
|--|-----|
| 7.150. Logistics and Supply Chain Management - M-MACH-105298 .....                   | 231 |
| 7.151. Machine Dynamics - M-MACH-102694 .....  | 232 |
| 7.152. Machine Learning - Basic Methods - M-INFO-105252 .....                        | 233 |
| 7.153. Machine Learning - Foundations and Algorithms - M-INFO-107169 .....           | 234 |
| 7.154. Machine Learning 1 - M-WIWI-105003 .....                                      | 235 |
| 7.155. Machine Learning 2 - M-WIWI-105006 .....                                      | 236 |
| 7.156. Machine Learning and Optimization in Energy Systems - M-WIWI-106604 .....     | 237 |
| 7.157. Machine Learning for Robotic Systems 1 - M-MACH-106457 .....                  | 238 |
| 7.158. Machine Learning for Robotic Systems 2 - M-MACH-106652 .....                  | 240 |
| 7.159. Machine Tools and Industrial Handling - M-MACH-105107 .....                   | 241 |
| 7.160. Machine Vision [Sp-MV] - M-MACH-101923 .....                                  | 242 |
| 7.161. Magnet Technology of Fusion Reactors - M-MACH-107223 .....                    | 245 |
| 7.162. Master's Thesis - M-ETIT-107192 .....   | 246 |
| 7.163. Material Flow in Logistic Systems - M-MACH-104984 .....                       | 247 |
| 7.164. Materials for Lightweight Construction - M-MACH-102727 .....                  | 248 |
| 7.165. Materials Recycling and Sustainability - M-MACH-107043 .....                  | 249 |
| 7.166. Mathematical Methods in Continuum Mechanics - M-MACH-106210 .....             | 250 |
| 7.167. Mathematical Methods in Fluid Mechanics - M-MACH-107032 .....                 | 251 |
| 7.168. Mathematical Methods in Hydraulics - M-MACH-107210 .....                      | 252 |
| 7.169. Mechanical Properties of Nanomaterials and Microsystems - M-MACH-107185 ..... | 253 |
| 7.170. Medical Image Processing for Guidance and Navigation - M-ETIT-106672 .....    | 254 |
| 7.171. Micro System Simulation - M-MACH-105486 .....                                 | 257 |
| 7.172. Microactuators - M-MACH-100487 .....  | 259 |
| 7.173. Microenergy Technologies - M-MACH-102714 .....                                | 261 |
| 7.174. Microsystem Product Design for Young Entrepreneurs - M-MACH-107195 .....      | 262 |
| 7.175. Microsystem Technology - M-ETIT-100454 .....                                  | 263 |
| 7.176. Microwave Engineering - M-ETIT-100535 .....                                   | 264 |
| 7.177. Microwave Engineering Lab - M-ETIT-106973 .....                               | 265 |
| 7.178. Microwaves Measurement Techniques - M-ETIT-100424 .....                       | 266 |
| 7.179. Microwaves Measurement Techniques - M-ETIT-107007 .....                       | 267 |
| 7.180. Miniaturized Heat Transfer - M-MACH-107063 .....                              | 268 |
| 7.181. MMIC Design Laboratory - M-ETIT-105464 .....                                  | 269 |
| 7.182. Mobile Machines - M-MACH-107041 .....   | 270 |
| 7.183. Modern Control Concepts I - M-MACH-105308 .....                               | 271 |
| 7.184. Modern Control Concepts II - M-MACH-105313 .....                              | 272 |
| 7.185. Modern Control Concepts III - M-MACH-105314 .....                             | 274 |
| 7.186. Modern Radio Systems Engineering - M-ETIT-100427 .....                        | 276 |
| 7.187. Modern VLSI Technologies - M-ETIT-106921 .....                                | 277 |
| 7.188. Modules in English Language: - M-ETIT-107301 .....                            | 278 |
| 7.189. Modules in German Language: - M-ETIT-107300 .....                             | 279 |
| 7.190. Motion in Human and Machine - Seminar - M-INFO-102555 .....                   | 281 |
| 7.191. Motor Vehicle Laboratory - M-MACH-102695 .....                                | 282 |
| 7.192. Nano- and Quantum Electronics - M-ETIT-105604 .....                           | 283 |
| 7.193. NMR Micro Probe Hardware Conception and Construction - M-MACH-107196 .....    | 285 |
| 7.194. Nonlinear Control Systems - M-ETIT-100371 .....                               | 286 |
| 7.195. Nonlinear Optics - M-ETIT-100430 .....  | 287 |
| 7.196. Novel Actuators and Sensors - M-MACH-105292 .....                             | 288 |
| 7.197. Nuclear Power and Reactor Technology - M-MACH-107042 .....                    | 289 |
| 7.198. Nuclear Power Plant Technology - M-MACH-107121 .....                          | 290 |
| 7.199. Numerical Fluid Mechanics - M-MACH-107036 .....                               | 292 |
| 7.200. Numerical Methods - M-MATH-105831 .....                                       | 293 |
| 7.201. Numerical Methods with Programming Practice - M-MATH-106972 .....             | 295 |
| 7.202. Optical Design Lab - M-ETIT-100464 .....                                      | 297 |
| 7.203. Optical Engineering and Machine Vision - M-ETIT-106974 .....                  | 298 |
| 7.204. Optical Transmitters and Receivers - M-ETIT-100436 .....                      | 300 |
| 7.205. Optical Waveguides and Fibers - M-ETIT-100506 .....                           | 301 |
| 7.206. Optimal Control and Estimation - M-ETIT-102310 .....                          | 303 |
| 7.207. Optimization of Dynamic Systems - M-ETIT-100531 .....                         | 304 |
| 7.208. Optoelectronic Measurement Engineering - M-ETIT-100484 .....                  | 306 |
| 7.209. Organ Support Systems - M-MACH-102702 .....                                   | 307 |
| 7.210. Pattern Recognition [24675] - M-INFO-100825 .....                             | 308 |
| 7.211. Photonics and Communications Lab - M-ETIT-104485 .....                        | 309 |

|  |     |
|--|-----|
| 7.212. Photovoltaics - M-ETIT-100513 .....   | 310 |
| 7.213. Physical Basics of Laser Technology - M-MACH-107064 .....   | 311 |
| 7.214. Plasma Sources - M-ETIT-100481 .....  | 313 |
| 7.215. Polymers in MEMS A: Chemistry, Synthesis and Applications - M-MACH-107183 .....                             | 314 |
| 7.216. Polymers in MEMS B: Physics, Microstructuring and Applications [MIT-Export] - M-MACH-107035 .....           | 316 |
| 7.217. Polymers in MEMS C: Biopolymers and Bioplastics - M-MACH-107085 .....                                       | 318 |
| 7.218. Power Electronic Systems in Energy Technology - M-ETIT-106067 .....   | 320 |
| 7.219. Power Electronics - M-ETIT-104567 .....   | 321 |
| 7.220. Power Electronics for Photovoltaics and Wind Energy - M-ETIT-102261 .....                                   | 323 |
| 7.221. Power System Protection and Automation - M-ETIT-106506 .....  | 325 |
| 7.222. Power Systems and Economy - M-ETIT-100413 .....   | 326 |
| 7.223. Power Tool Design - M-MACH-107144 .....   | 327 |
| 7.224. Power Tool Design Project Work - M-MACH-107145 .....  | 329 |
| 7.225. Practical Aspects of Electrical Drives - M-ETIT-100394 .....  | 330 |
| 7.226. Practical Course Polymers in MEMS - M-MACH-107034 .....   | 332 |
| 7.227. Practical Course: Autonomous Driving - M-MACH-107052 .....  | 333 |
| 7.228. Practical Course: Machine Learning and Intelligent Systems - M-INFO-105958 .....                            | 334 |
| 7.229. Practical Course: Smart Energy System - M-INFO-105955 .....   | 335 |
| 7.230. Practical Course: Software Development and Application of Mobile, Bio-Inspired Robots - M-MACH-106904 ..... | 336 |
| 7.231. Practical Machine Learning - M-ETIT-106673 .....  | 337 |
| 7.232. Practical Project Robotics and Automation I (Software) - M-INFO-102224 .....                                | 339 |
| 7.233. Practical Project Robotics and Automation II (Hardware) - M-INFO-102230 .....                               | 340 |
| 7.234. Practical Tools for Control Engineers - M-ETIT-106780 .....   | 341 |
| 7.235. Practical Training in Basics of Microsystem Technology - M-MACH-105479 .....                                | 342 |
| 7.236. Principles of Whole Vehicle Engineering I - M-MACH-105289 .....   | 343 |
| 7.237. Principles of Whole Vehicle Engineering II - M-MACH-105290 .....  | 344 |
| 7.238. Probabilistic Measurement and Estimation - M-MACH-107087 .....  | 345 |
| 7.239. Product- and Production-Concepts for modern Automobiles - M-MACH-105346 .....                               | 346 |
| 7.240. Product Development – Methods of Product Engineering - M-MACH-102718 .....                                  | 347 |
| 7.241. Production Techniques Laboratory - M-MACH-102711 .....  | 349 |
| 7.242. Project Management in the Development of Products for Safety-Critical Applications - M-ETIT-104475 .....    | 351 |
| 7.243. Project Workshop: Automotive Engineering - M-MACH-107074 .....  | 352 |
| 7.244. ProVIL - Product Development in a Virtual Idea Laboratory - M-MACH-105418 .....                             | 353 |
| 7.245. Python Algorithms for Automotive Engineering - M-MACH-107072 .....  | 355 |
| 7.246. Quality Management - M-MACH-105332 .....  | 357 |
| 7.247. Quantum Detectors and Sensors - M-ETIT-105606 .....   | 358 |
| 7.248. Quantum Machines I - M-MACH-107164 .....  | 359 |
| 7.249. Quantum Machines II - M-MACH-107165 .....   | 360 |
| 7.250. Radio-Frequency Electronics - M-ETIT-106955 .....   | 361 |
| 7.251. Rail System Technology - M-MACH-103232 .....  | 362 |
| 7.252. Rail Vehicle Technology - M-MACH-102683 .....   | 363 |
| 7.253. Railway System Digitalisation - M-MACH-106513 .....   | 365 |
| 7.254. Railways in the Transportation Market - M-MACH-107044 .....   | 367 |
| 7.255. Re:Invent - Revolutionary Business Models as the Basis for Product Innovations - M-MACH-106662 .....        | 368 |
| 7.256. Reactor Physics - M-MACH-107071 .....   | 370 |
| 7.257. Reactor Safety 1: Fundamentals - M-MACH-107116 .....  | 371 |
| 7.258. Real Time Control of Electrical Drives - M-ETIT-105916 .....  | 372 |
| 7.259. Real-Time Systems [24576] - M-INFO-100803 .....   | 373 |
| 7.260. Reinforcement Learning - M-INFO-105623 .....  | 374 |
| 7.261. Reliability and Test Engineering - M-MACH-106050 .....  | 376 |
| 7.262. Renewable Energy-Resources, Technologies and Economics - M-WIWI-100500 .....                                | 378 |
| 7.263. Robotics - Practical Course - M-INFO-107155 .....   | 379 |
| 7.264. Robotics II - Humanoid Robotics - M-INFO-107123 .....   | 380 |
| 7.265. Robotics III - Sensors and Perception in Robotics [24635] - M-INFO-107130 .....                             | 381 |
| 7.266. Seamless Engineering - M-MACH-105725 .....  | 382 |
| 7.267. Seminar Data-Mining in Production - M-MACH-105477 .....   | 384 |
| 7.268. Seminar Electrocatalysis - M-ETIT-105629 .....  | 385 |
| 7.269. Seminar Embedded Systems - M-ETIT-100455 .....  | 386 |
| 7.270. Seminar for Rail System Technology - M-MACH-104197 .....  | 387 |
| 7.271. Seminar Industrial Process and Plant Engineering - M-ETIT-106970 .....                                      | 388 |
| 7.272. Seminar Intelligent Industrial Robots - M-INFO-102212 .....   | 390 |
| 7.273. Seminar New Components and Systems of Power Electronics - M-ETIT-100396 .....                               | 391 |

|  |            |
|--|------------|
| 7.274. Seminar Novel Concepts for Solar Energy Harvesting - M-ETIT-103447 .....  | 392        |
| 7.275. Seminar: Bionic Algorithms and Robot Technologies - M-MACH-106902 .....   | 393        |
| 7.276. Sensors - M-ETIT-100378 .....   | 394        |
| 7.277. Signal Processing Lab - M-ETIT-106633 .....   | 395        |
| 7.278. Signal Processing Methods - M-ETIT-106899 .....   | 396        |
| 7.279. Signal Processing with Nonlinear Fourier Transforms and Koopman Operators - M-ETIT-106675 .....   | 398        |
| 7.280. Simulation and Optimization in Robotics and Biomechanics - M-INFO-106504 .....  | 400        |
| 7.281. Simulation with Lumped Parameters - M-MACH-107053 .....   | 401        |
| 7.282. Software Engineering - M-ETIT-100450 .....  | 402        |
| 7.283. Solar Energy - M-ETIT-100524 .....  | 403        |
| 7.284. Solar Thermal Energy Systems [Sp-STES] - M-MACH-101924 .....  | 405        |
| 7.285. Spaceborne Radar Remote Sensing - M-ETIT-103042 .....   | 407        |
| 7.286. Stochastic Information Processing [24113] - M-INFO-100829 .....   | 408        |
| 7.287. Strategic Product Development - Identification of Potentials of Innovative Products - M-MACH-107140 .....   | 409        |
| 7.288. Structural Materials - M-MACH-100291 .....  | 410        |
| 7.289. Student Innovation Lab - M-ETIT-105073 .....  | 411        |
| 7.290. Superconducting Magnet Technology - M-ETIT-106684 .....   | 414        |
| 7.291. Superconducting Power Systems - M-ETIT-106683 .....   | 416        |
| 7.292. Sustainable Product Engineering: Sustainable Product Design - Long-term Business Success with Sustainably<br>Developed Products - M-MACH-107189 ..... | 417        |
| 7.293. System Integration and Communication Structures in Industry 4.0 and IoT - M-ETIT-106026 .....   | 419        |
| 7.294. System Integration in Micro- and Nanotechnology - M-MACH-105315 .....   | 420        |
| 7.295. System Integration in Micro- and Nanotechnology 2 - M-MACH-105316 .....   | 421        |
| 7.296. System-on-Chip Laboratory - M-ETIT-100451 .....   | 422        |
| 7.297. Systems and Software Engineering - M-ETIT-100537 .....  | 423        |
| 7.298. Technical Design in Product Development - M-MACH-105318 .....   | 425        |
| 7.299. Technical Optics - M-ETIT-100538 .....  | 427        |
| 7.300. Thermal Solar Energy - M-MACH-102388 .....  | 428        |
| 7.301. Thermal Turbomachines I - M-MACH-107219 .....   | 430        |
| 7.302. Thermal-Fluid-Dynamics - M-MACH-107112 .....  | 431        |
| 7.303. Tires and Wheel Development for Passenger Cars - M-MACH-107070 .....  | 432        |
| 7.304. Tractors - M-MACH-107058 .....  | 433        |
| 7.305. Ubiquitous Computing [24146] - M-INFO-107161 .....  | 434        |
| 7.306. Validation of Technical Systems - M-MACH-107143 .....   | 436        |
| 7.307. Vehicle Drive Technology - M-MACH-107056 .....  | 438        |
| 7.308. Vehicle Lightweight Design - Strategies, Concepts, Materials - M-MACH-102703 .....  | 439        |
| 7.309. Vehicle Systems for Urban Mobility - M-MACH-106515 .....  | 440        |
| 7.310. Virtual Engineering 1 - M-MACH-105293 .....   | 441        |
| 7.311. Virtual Engineering A [WW4INGMB29] - M-MACH-101283 .....  | 442        |
| 7.312. Virtual Engineering Lab - M-MACH-105475 .....   | 443        |
| 7.313. Wearable Robotic Technologies - M-INFO-107113 .....   | 444        |
| 7.314. Windpower - M-MACH-105732 .....   | 445        |
| 7.315. Workshop Finite Element Method in Electromagnetics - M-ETIT-107147 .....  | 446        |
| <b>8. Courses .....</b>  | <b>445</b> |
| 8.1. Actuators and Sensors in Nanotechnology - T-MACH-105238 .....   | 447        |
| 8.2. Adaptive Optics - T-ETIT-107644 .....   | 448        |
| 8.3. Advanced Artificial Intelligence - T-INFO-114220 .....  | 449        |
| 8.4. Advanced Communications Engineering - T-ETIT-113676 .....   | 450        |
| 8.5. Analog Circuit Design - T-ETIT-100973 .....   | 451        |
| 8.6. Analysis Tools for Combustion Diagnostics - T-MACH-105167 .....   | 452        |
| 8.7. Antennas and Beamforming - T-ETIT-113920 .....  | 453        |
| 8.8. Appliance and Power Tool Design - T-MACH-105229 .....   | 454        |
| 8.9. Appliance and Power Tool Design Project Work - T-MACH-110767 .....  | 455        |
| 8.10. Applied Information Theory - T-ETIT-100748 .....   | 456        |
| 8.11. Artificial Intelligence in Production - T-MACH-112115 .....  | 457        |
| 8.12. Automated Visual Inspection and Image Processing - T-INFO-101363 .....   | 458        |
| 8.13. Automotive Engineering I - T-MACH-100092 .....   | 459        |
| 8.14. Automotive Engineering II - T-MACH-102117 .....  | 460        |
| 8.15. Automotive Vision - T-MACH-105218 .....  | 461        |
| 8.16. Automotive Vision - T-MACH-114149 .....  | 462        |
| 8.17. Basics of Converter Control - T-ETIT-100717 .....  | 463        |
| 8.18. Basics of Technical Logistics II - T-MACH-109920 .....   | 464        |

|  |     |
|--|-----|
| 8.19. Batteries and Fuel Cells - T-ETIT-100983 .....   | 465 |
| 8.20. Batteries and Fuel Cells Laboratory - T-ETIT-100708 .....  | 466 |
| 8.21. Battery and Fuel Cells Systems - T-ETIT-100704 .....   | 467 |
| 8.22. Bioelectric Signals - T-ETIT-101956 .....  | 468 |
| 8.23. Biologically Inspired Robots - T-MACH-113856 .....   | 469 |
| 8.24. BioMEMS - Microfluidic Chipsystems V - T-MACH-111069 .....   | 470 |
| 8.25. BioMEMS - Microsystems Technologies for Life-Sciences and Medicine I - T-MACH-100966 .....             | 471 |
| 8.26. BioMEMS - Microsystems Technologies for Life-Sciences and Medicine II - T-MACH-100967 .....            | 472 |
| 8.27. BioMEMS - Microsystems Technologies for Life-Sciences and Medicine III - T-MACH-100968 .....           | 473 |
| 8.28. BioMEMS - Microsystems Technologies for Life-Sciences and Medicine IV - T-MACH-106877 .....            | 474 |
| 8.29. CAD Engineering Project for Intelligent Systems - T-MACH-113857 .....                                  | 475 |
| 8.30. CAE-Workshop - T-MACH-105212 .....   | 476 |
| 8.31. CATIA Advanced - T-MACH-105312 .....   | 477 |
| 8.32. CATIA CAD Training Course - T-MACH-102185 .....  | 478 |
| 8.33. CFD for Power Engineering - T-MACH-114187 .....  | 479 |
| 8.34. Channel Coding: Algebraic Methods for Communications and Storage - T-ETIT-111244 .....                 | 480 |
| 8.35. CO <sub>2</sub> -Neutral Combustion Engines and their Fuels I - T-MACH-111550 .....                    | 481 |
| 8.36. CO <sub>2</sub> -Neutral Combustion Engines and their Fuels II - T-MACH-111560 .....                   | 482 |
| 8.37. Cognitive Automobiles - Laboratory - T-MACH-105378 .....   | 483 |
| 8.38. Combined Cycle Power Plants - T-MACH-105444 .....  | 484 |
| 8.39. Communication Systems and Protocols - T-ETIT-101938 .....  | 485 |
| 8.40. Communications Engineering Laboratory - T-ETIT-114159 .....  | 486 |
| 8.41. Components of Power Systems - T-ETIT-113445 .....  | 487 |
| 8.42. Computational Intelligence - T-MACH-105314 .....   | 488 |
| 8.43. Continuum Mechanics of Solids and Fluids - T-MACH-110377 .....   | 489 |
| 8.44. Control of Linear Multivariable Systems - T-ETIT-100666 .....  | 490 |
| 8.45. Control of Mobile Machines - T-MACH-111821 .....   | 491 |
| 8.46. Control of Mobile Machines – Prerequisites - T-MACH-111820 .....                                       | 492 |
| 8.47. Control of Power-Electronic Systems - T-ETIT-111897 .....  | 493 |
| 8.48. Control Technology - T-MACH-105185 .....   | 494 |
| 8.49. Control Theory Laboratory - T-ETIT-111009 .....  | 495 |
| 8.50. Current Topics on BioMEMS - T-MACH-102176 .....  | 496 |
| 8.51. Cyber-Physical Modeling - T-ETIT-113908 .....  | 497 |
| 8.52. Data Analytics for Engineers - T-MACH-105694 .....   | 498 |
| 8.53. Data-Driven Algorithms in Vehicle Technology - T-MACH-112126 .....                                     | 499 |
| 8.54. Decision-Making and Motion Planning for Automated Driving - T-MACH-113597 .....                        | 500 |
| 8.55. Deep Learning and Neural Networks - T-INFO-114219 .....  | 501 |
| 8.56. Deep Learning for Computer Vision I: Basics - T-INFO-111491 .....                                      | 502 |
| 8.57. Deep Learning for Computer Vision II: Advanced Topics - T-INFO-111494 .....                            | 503 |
| 8.58. Deep Learning for Engineers - T-MACH-113882 .....  | 504 |
| 8.59. Design and Development of Mobile Machines - T-MACH-105311 .....  | 505 |
| 8.60. Design and Development of Mobile Machines - Advance - T-MACH-108887 .....                              | 506 |
| 8.61. Design and Optimization of Conventional and Electrified Automotive Transmissions - T-MACH-110958 ..... | 507 |
| 8.62. Design of Electrical Machines - T-ETIT-100785 .....  | 508 |
| 8.63. Design with Plastics - T-MACH-105330 .....   | 509 |
| 8.64. Development of Hybrid Drivetrains - T-MACH-110817 .....  | 510 |
| 8.65. Development of Oil-Hydraulic Powertrain Systems - T-MACH-105441 .....                                  | 511 |
| 8.66. Digital Beam-Forming for Imaging Radar - T-ETIT-110940 .....   | 512 |
| 8.67. Digital Circuit Design - T-ETIT-100974 .....   | 513 |
| 8.68. Digital Control - T-MACH-105317 .....  | 514 |
| 8.69. Digital Hardware Design Laboratory - T-ETIT-104571 .....   | 515 |
| 8.70. Digital Hardware Design Laboratory - T-ETIT-104570 .....   | 516 |
| 8.71. Digital Twin Engineering - T-ETIT-112224 .....   | 517 |
| 8.72. Digitalization of Products, Services & Production - T-MACH-108491 .....                                | 518 |
| 8.73. Digitization in the Railway System - T-MACH-113016 .....   | 519 |
| 8.74. Distributed Discrete Event Systems - T-ETIT-100960 .....   | 520 |
| 8.75. Drive System Engineering B: Stationary Machinery - T-MACH-114000 .....                                 | 521 |
| 8.76. Drive Train of Mobile Machines - T-MACH-105307 .....   | 522 |
| 8.77. Dynamics of Electro-Mechanical Systems - T-MACH-111260 .....   | 523 |
| 8.78. Dynamics of the Automotive Drive Train - T-MACH-105226 .....   | 524 |
| 8.79. Educational Development for Student Teachers - Basic Level - T-ETIT-100797 .....                       | 525 |
| 8.80. Electric Drives and Power Electronics Lab - T-ETIT-114162 .....  | 526 |



|  |     |
|--|-----|
| 8.81. Electric Drives for E-Mobility - T-ETIT-113936 .....   | 527 |
| 8.82. Electric Power Transmission & Grid Control - T-ETIT-110883 .....   | 528 |
| 8.83. Electrical Energy Systems Lab - T-ETIT-114160 .....  | 529 |
| 8.84. Electrocatalysis - T-ETIT-111831 .....   | 530 |
| 8.85. Elements and Systems of Technical Logistics - T-MACH-102159 .....  | 531 |
| 8.86. Elements and Systems of Technical Logistics - Project - T-MACH-108946 .....  | 532 |
| 8.87. Energy Storage and Network Integration - T-ETIT-104644 .....   | 533 |
| 8.88. Energy Systems I: Renewable Energy - T-MACH-105408 .....   | 534 |
| 8.89. Energy Systems II: Reactor Physics - T-MACH-105550 .....   | 535 |
| 8.90. Energy Topology and Resilience - T-MACH-112755 .....   | 536 |
| 8.91. Engine Measurement Techniques - T-MACH-105169 .....  | 537 |
| 8.92. Engineering Materials for the Energy Transition - T-MACH-112691 .....  | 538 |
| 8.93. Engineer's Field of Work - T-MACH-105721 .....   | 539 |
| 8.94. Entrepreneurship - T-WIWI-102864 .....   | 540 |
| 8.95. Ethics of Technology - T-MACH-113903 .....   | 541 |
| 8.96. Fabrication Processes in Microsystem Technology - T-MACH-102166 .....  | 542 |
| 8.97. Field Propagation and Coherence - T-ETIT-100976 .....  | 543 |
| 8.98. Flows and Heat Transfer in Energy Technology - T-MACH-105403 .....   | 544 |
| 8.99. Fundamentals in the Development of Commercial Vehicles - T-MACH-111389 .....   | 545 |
| 8.100. Fundamentals of Automobile Development I - T-MACH-105162 .....  | 546 |
| 8.101. Fundamentals of Automobile Development II - T-MACH-105163 .....   | 547 |
| 8.102. Fundamentals of Combustion I - T-MACH-105213 .....  | 548 |
| 8.103. Fundamentals of Combustion II - T-MACH-114044 .....   | 549 |
| 8.104. Fundamentals of Energy Technology - T-MACH-105220 .....   | 550 |
| 8.105. Fundamentals of Reactor Safety for the Operation and Dismantling of Nuclear Power Plants - T-MACH-105530 .....                              | 551 |
| 8.106. Fusion Technology A - T-MACH-105411 .....   | 552 |
| 8.107. Fusion Technology B - T-MACH-105433 .....   | 553 |
| 8.108. Handling Characteristics of Motor Vehicles I - T-MACH-105152 .....  | 554 |
| 8.109. Handling Characteristics of Motor Vehicles II - T-MACH-105153 .....   | 555 |
| 8.110. Hardware Modeling and Simulation - T-ETIT-100672 .....  | 556 |
| 8.111. Hardware Synthesis and Optimization - T-ETIT-113922 .....   | 557 |
| 8.112. Hardware/Software Co-Design - T-ETIT-100671 .....   | 558 |
| 8.113. Heat and Mass Transfer - T-MACH-105292 .....  | 559 |
| 8.114. Heatpumps - T-MACH-105430 .....   | 560 |
| 8.115. High-Voltage Technology - T-ETIT-110266 .....   | 561 |
| 8.116. High-Voltage Test Technique - T-ETIT-101915 .....   | 562 |
| 8.117. Holistic Approach of Managing Power Plant Operation under Uncertainty and Volatility - T-MACH-112238 .....                                  | 563 |
| 8.118. Hot Research Topics in AI for Engineering Applications - T-MACH-113669 .....  | 564 |
| 8.119. Human Brain and Central Nervous System: Anatomy, Information Transfer, Signal Processing, Neurophysiology and Therapy - T-INFO-101262 ..... | 565 |
| 8.120. Human-Machine-Interaction in Anthropomatics: Basics - T-INFO-101361 .....   | 566 |
| 8.121. Humanoid Robots - Seminar - T-INFO-114170 .....   | 567 |
| 8.122. Hydrogen and reFuels - Energy Conversion in Combustion Engines - T-MACH-111585 .....  | 568 |
| 8.123. Industrial Business Administration - T-WIWI-100796 .....  | 569 |
| 8.124. Industrial Circuitry - T-ETIT-100716 .....  | 570 |
| 8.125. Industrial Mobile Robotics Lab - T-MACH-113701 .....  | 571 |
| 8.126. Information Engineering - T-MACH-102209 .....   | 572 |
| 8.127. Information Fusion - T-ETIT-106499 .....  | 573 |
| 8.128. Information Processing in Sensor Networks - T-INFO-101466 .....   | 574 |
| 8.129. Information Systems and Supply Chain Management - T-MACH-102128 .....   | 575 |
| 8.130. Information Technology in Industrial Automation Systems - T-ETIT-100698 .....   | 576 |
| 8.131. Innovation and Project Management in Rail Vehicle Engineering - T-MACH-113068 .....   | 577 |
| 8.132. Innovation Lab - T-ETIT-110291 .....  | 578 |
| 8.133. Innovation2Business – Innovation Strategy in the Industrial Corporate Practice - T-MACH-112882 .....  | 579 |
| 8.134. Innovative Concepts for Programming Industrial Robots - T-INFO-101328 .....   | 580 |
| 8.135. Innovative Nuclear Systems - T-MACH-105404 .....  | 581 |
| 8.136. Integrated Intelligent Sensors - T-ETIT-100961 .....  | 582 |
| 8.137. Integrated Product Development - T-MACH-105401 .....  | 583 |
| 8.138. Integrated Systems and Circuits - T-ETIT-100972 .....   | 584 |
| 8.139. Intellectual Property Rights and Strategies in Industrial Companies - T-MACH-105442 .....   | 585 |
| 8.140. International Production Engineering A - T-MACH-110334 .....  | 586 |
| 8.141. International Production Engineering B - T-MACH-110335 .....  | 587 |

|  |     |
|--|-----|
| 8.142. Introduction to Automotive and Industrial Lidar Technology - T-ETIT-111011 .....    | 588 |
| 8.143. Introduction to Bionics - T-MACH-111807 .....                                       | 589 |
| 8.144. Introduction to Energy Economics - T-WIWI-102746 .....                              | 590 |
| 8.145. Introduction to Microsystem Technology I - T-MACH-114100 .....                      | 591 |
| 8.146. Introduction to Microsystem Technology II - T-MACH-105183 .....                     | 592 |
| 8.147. Introduction to Nanotechnology - T-MACH-111814 .....                                | 593 |
| 8.148. Introduction to Nuclear Energy - T-MACH-105525 .....                                | 594 |
| 8.149. Introduction to Philosophy of Technology - T-MACH-113883 .....                      | 595 |
| 8.150. Introduction to the Scientific Method (Seminar, Englisch) - T-ETIT-111317 .....     | 596 |
| 8.151. Introduction to the Scientific Method (Seminar, German) - T-ETIT-111316 .....       | 597 |
| 8.152. IoT Platform for Engineering - T-MACH-106743 .....                                  | 598 |
| 8.153. IT/OT-Security Seminar - T-ETIT-113648 .....  | 599 |
| 8.154. IT-Fundamentals of Logistics - T-MACH-105187 .....                                  | 600 |
| 8.155. Lab Computer-Aided Methods for Measurement and Control - T-MACH-105341 .....        | 601 |
| 8.156. Lab Course on Nanoelectronics - T-ETIT-100757 .....                                 | 602 |
| 8.157. Laboratory Exercise in Energy Technology - T-MACH-105331 .....                      | 603 |
| 8.158. Laboratory FPGA Based Circuit Design - T-ETIT-100759 .....                          | 604 |
| 8.159. Laboratory in Software Engineering - T-ETIT-100681 .....                            | 605 |
| 8.160. Laboratory Information Systems in Power Engineering - T-ETIT-114183 .....           | 606 |
| 8.161. Laboratory Mechatronic Measurement Systems - T-ETIT-106854 .....                    | 607 |
| 8.162. Laboratory Mechatronics - T-MACH-105370 .....                                       | 608 |
| 8.163. Laboratory Nanotechnology - T-ETIT-100765 .....                                     | 609 |
| 8.164. Laboratory Optoelectronics - T-ETIT-100764 .....                                    | 610 |
| 8.165. Laboratory Solar Energy - T-ETIT-104686 .....                                       | 611 |
| 8.166. Leadership in Interdisciplinary Teams - T-MACH-106460 .....                         | 612 |
| 8.167. Liberalised Power Markets - T-WIWI-107043 .....                                     | 613 |
| 8.168. Lighting Engineering - T-ETIT-100772 .....  | 614 |
| 8.169. Lightweight Engineering Design - T-MACH-105221 .....                                | 615 |
| 8.170. Localization of Mobile Agents - T-INFO-101377 .....                                 | 616 |
| 8.171. Localization of Mobile Agents Pass - T-INFO-114169 .....                            | 617 |
| 8.172. Logistics and Supply Chain Management - T-MACH-110771 .....                         | 618 |
| 8.173. Machine Dynamics - T-MACH-105210 .....  | 619 |
| 8.174. Machine Learning - Basic Methods - T-INFO-110630 .....                              | 620 |
| 8.175. Machine Learning - Foundations and Algorithms - T-INFO-111558 .....                 | 621 |
| 8.176. Machine Learning 1 - Basic Methods - T-WIWI-106340 .....                            | 622 |
| 8.177. Machine Learning 2 – Advanced Methods - T-WIWI-106341 .....                         | 623 |
| 8.178. Machine Learning and Optimization in Energy Systems - T-WIWI-113073 .....           | 624 |
| 8.179. Machine Learning for Robotic Systems 1 - T-MACH-113064 .....                        | 625 |
| 8.180. Machine Learning for Robotic Systems 2 - T-MACH-113403 .....                        | 626 |
| 8.181. Machine Tools and High-Precision Manufacturing Systems - T-MACH-110962 .....        | 627 |
| 8.182. Machine Vision - T-MACH-105223 .....  | 628 |
| 8.183. Magnet Technology of Fusion Reactors - T-MACH-105434 .....                          | 629 |
| 8.184. Master's Thesis - T-ETIT-114214 .....   | 630 |
| 8.185. Material Flow in Logistic Systems - T-MACH-102151 .....                             | 631 |
| 8.186. Materials of Lightweight Construction - T-MACH-105211 .....                         | 632 |
| 8.187. Materials Recycling and Sustainability - T-MACH-110937 .....                        | 633 |
| 8.188. Mathematical Methods in Continuum Mechanics - T-MACH-110375 .....                   | 634 |
| 8.189. Mathematical Methods in Fluid Mechanics - T-MACH-113955 .....                       | 635 |
| 8.190. Mathematical Methods in Fluid Mechanics - T-MACH-113956 .....                       | 636 |
| 8.191. Mathematical Methods in Hydraulics - T-MACH-113912 .....                            | 637 |
| 8.192. Mechanical Properties of Nanomaterials and Microsystems - T-MACH-114018 .....       | 638 |
| 8.193. Medical Image Processing for Guidance and Navigation - T-ETIT-113425 .....          | 639 |
| 8.194. Methods and Processes of PGE - Product Generation Engineering - T-MACH-109192 ..... | 640 |
| 8.195. Microactuators - T-MACH-101910 .....  | 641 |
| 8.196. Microenergy Technologies - T-MACH-105557 .....                                      | 642 |
| 8.197. Microsystem Product Design for Young Entrepreneurs - T-MACH-105814 .....            | 643 |
| 8.198. Microsystem Simulation - T-MACH-108383 .....  | 644 |
| 8.199. Microsystem Technology - T-ETIT-100752 .....  | 645 |
| 8.200. Microwave Engineering - T-ETIT-100802 .....   | 646 |
| 8.201. Microwave Engineering Lab - T-ETIT-113938 .....                                     | 647 |
| 8.202. Microwaves Measurement Techniques - T-ETIT-100733 .....                             | 648 |
| 8.203. Microwaves Measurement Techniques - T-ETIT-114046 .....                             | 649 |

|  |     |
|--|-----|
| 8.204. Miniaturized Heat Exchangers - T-MACH-108613 .....  | 650 |
| 8.205. MMIC Design Laboratory - T-ETIT-111006 .....  | 651 |
| 8.206. Mobile Machines - T-MACH-105168 .....   | 652 |
| 8.207. Modern Control Concepts I - T-MACH-105539 .....   | 653 |
| 8.208. Modern Control Concepts II - T-MACH-106691 .....  | 654 |
| 8.209. Modern Control Concepts III - T-MACH-106692 .....   | 655 |
| 8.210. Modern Radio Systems Engineering - T-ETIT-100735 .....  | 656 |
| 8.211. Modern VLSI Technologies - T-ETIT-113864 .....  | 657 |
| 8.212. Motion in Human and Machine - Seminar - T-INFO-105140 .....   | 658 |
| 8.213. Motor Vehicle Labor (graded) - T-ETIT-114320 .....  | 659 |
| 8.214. Nano- and Quantum Electronics - T-ETIT-111232 .....   | 660 |
| 8.215. NMR Micro Probe Hardware Conception and Construction - T-MACH-108407 .....                                  | 661 |
| 8.216. Nonlinear Control Systems - T-ETIT-100980 .....   | 662 |
| 8.217. Nonlinear Optics - T-ETIT-101906 .....  | 663 |
| 8.218. Novel Actuators and Sensors - T-MACH-102152 .....   | 664 |
| 8.219. Nuclear Power and Reactor Technology - T-MACH-110332 .....  | 665 |
| 8.220. Nuclear Power Plant Technology - T-MACH-105402 .....  | 666 |
| 8.221. Numerical Fluid Mechanics - T-MACH-105338 .....   | 667 |
| 8.222. Numerical Methods - Exam - T-MATH-111700 .....  | 668 |
| 8.223. Numerical Methods - Workshop - T-MATH-113937 .....  | 669 |
| 8.224. Optical Design Lab - T-ETIT-100756 .....  | 670 |
| 8.225. Optical Engineering and Machine Vision - T-ETIT-113941 .....  | 671 |
| 8.226. Optical Transmitters and Receivers - T-ETIT-100639 .....  | 672 |
| 8.227. Optical Waveguides and Fibers - T-ETIT-101945 .....   | 673 |
| 8.228. Optimal Control and Estimation - T-ETIT-104594 .....  | 674 |
| 8.229. Optimization of Dynamic Systems - T-ETIT-100685 .....   | 675 |
| 8.230. Optoelectronic Measurement Engineering - T-ETIT-100771 .....  | 676 |
| 8.231. Organ Support Systems - T-MACH-105228 .....   | 677 |
| 8.232. Pattern Recognition - T-INFO-101362 .....   | 678 |
| 8.233. Photonics and Communications Lab - T-ETIT-109173 .....  | 679 |
| 8.234. Photovoltaics - T-ETIT-101939 .....   | 680 |
| 8.235. Physical Basics of Laser Technology - T-MACH-102102 .....   | 681 |
| 8.236. Plasma Sources - T-ETIT-100768 .....  | 682 |
| 8.237. PLM for Product Development in Mechatronics - T-MACH-102181 .....   | 683 |
| 8.238. Polymers in MEMS A: Chemistry, Synthesis and Applications - T-MACH-102192 .....                             | 684 |
| 8.239. Polymers in MEMS B: Physics, Microstructuring and Applications - T-MACH-102191 .....                        | 685 |
| 8.240. Polymers in MEMS C: Biopolymers and Bioplastics - T-MACH-102200 .....                                       | 686 |
| 8.241. Power Electronic Systems in Energy Technology - T-ETIT-112286 .....   | 687 |
| 8.242. Power Electronics - T-ETIT-109360 .....   | 688 |
| 8.243. Power Electronics for Photovoltaics and Wind Energy - T-ETIT-104569 .....                                   | 689 |
| 8.244. Power System Protection and Automation - T-ETIT-113164 .....  | 690 |
| 8.245. Power Systems and Economy - T-ETIT-100725 .....   | 691 |
| 8.246. Practical Aspects of Electrical Drives - T-ETIT-100711 .....  | 692 |
| 8.247. Practical Course Polymers in MEMS - T-MACH-105556 .....   | 693 |
| 8.248. Practical Course: Autonomous Driving - T-MACH-113713 .....  | 694 |
| 8.249. Practical Course: Machine Learning and Intelligent Systems - T-INFO-112104 .....                            | 695 |
| 8.250. Practical Course: Robotics - T-INFO-114172 .....  | 696 |
| 8.251. Practical Course: Smart Energy System - T-INFO-112030 .....   | 697 |
| 8.252. Practical Course: Software Development and Application of Mobile, Bio-Inspired Robots - T-MACH-113854 ..... | 698 |
| 8.253. Practical Machine Learning - T-ETIT-113426 .....  | 699 |
| 8.254. Practical Project Robotics and Automation I (Software) - T-INFO-104545 .....                                | 700 |
| 8.255. Practical Project Robotics and Automation II (Hardware) - T-INFO-104552 .....                               | 701 |
| 8.256. Practical Tools for Control Engineers - T-ETIT-113628 .....   | 702 |
| 8.257. Practical Training in Basics of Microsystem Technology - T-MACH-102164 .....                                | 703 |
| 8.258. Probabilistic Measurement and Estimation - T-MACH-113873 .....  | 704 |
| 8.259. Product- and Production-Concepts for Modern Automobiles - T-MACH-110318 .....                               | 705 |
| 8.260. Production Techniques Laboratory - T-MACH-105346 .....  | 706 |
| 8.261. Project Management in the Development of Products for Safety-Critical Applications - T-ETIT-109148 .....    | 707 |
| 8.262. Project Workshop: Automotive Engineering - T-MACH-102156 .....  | 708 |
| 8.263. ProVIL - Product Development in a Virtual Idea Laboratory - T-MACH-106738 .....                             | 709 |
| 8.264. Python Algorithms for Vehicle Technology - T-MACH-110796 .....  | 710 |
| 8.265. Quality Management - T-MACH-102107 .....  | 711 |

|   |     |
|---|-----|
| 8.266. Quantum Detectors and Sensors - T-ETIT-111234 .....  | 712 |
| 8.267. Quantum Machines I - T-MACH-113827 .....   | 713 |
| 8.268. Quantum Machines II - T-MACH-113826 .....  | 714 |
| 8.269. Radio-Frequency Electronics - T-ETIT-113910 .....  | 715 |
| 8.270. Rail System Technology - T-MACH-106424 .....   | 716 |
| 8.271. Rail Vehicle Technology - T-MACH-105353 .....  | 717 |
| 8.272. Railways in the Transportation Market - T-MACH-105540 .....  | 718 |
| 8.273. Re:Invent - Revolutionary Business Models as the Basis for Product Innovations - T-MACH-111888 .....                   | 719 |
| 8.274. Reactor Safety I: Fundamentals - T-MACH-105405 .....   | 720 |
| 8.275. Real Time Control of Electrical Drives - T-ETIT-111898 .....   | 721 |
| 8.276. Real-Time Systems - T-INFO-101340 .....  | 722 |
| 8.277. Reinforcement Learning - T-INFO-111255 .....   | 723 |
| 8.278. Reliability and Test Engineering - T-MACH-111840 .....   | 724 |
| 8.279. Renewable Energy-Resources, Technologies and Economics - T-WIWI-100806 .....   | 725 |
| 8.280. Robotics II - Humanoid Robotics - T-INFO-114152 .....  | 726 |
| 8.281. Robotics III - Sensors and Perception in Robotics - T-INFO-114155 .....  | 727 |
| 8.282. Seamless Engineering - T-MACH-111401 .....   | 728 |
| 8.283. Self Assignment-HOC-SPZ-FORUM-graded - T-ETIT-111688 .....   | 729 |
| 8.284. Self Assignment-HOC-SPZ-FORUM-graded - T-ETIT-111689 .....   | 730 |
| 8.285. Self Assignment-HOC-SPZ-FORUM-ungraded - T-ETIT-112899 .....   | 731 |
| 8.286. Self Assignment-HOC-SPZ-FORUM-ungraded - T-ETIT-112898 .....   | 732 |
| 8.287. Seminar Application of Artificial Intelligence in Production - T-MACH-112121 .....                                     | 733 |
| 8.288. Seminar Creating a Patent Specification - T-ETIT-100754 .....  | 734 |
| 8.289. Seminar Data-Mining in Production - T-MACH-108737 .....  | 735 |
| 8.290. Seminar Development of Automated Production Systems - T-MACH-113999 .....  | 736 |
| 8.291. Seminar Electrocatalysis - T-ETIT-111256 .....   | 737 |
| 8.292. Seminar Embedded Systems - T-ETIT-100753 .....   | 738 |
| 8.293. Seminar for Rail System Technology - T-MACH-108692 .....   | 739 |
| 8.294. Seminar Industrial Process and Plant Engineering - T-ETIT-113932 .....   | 740 |
| 8.295. Seminar Intelligent Industrial Robots - T-INFO-104526 .....  | 741 |
| 8.296. Seminar New Components and Systems of Power Electronics - T-ETIT-100713 .....  | 742 |
| 8.297. Seminar Novel Concepts for Solar Energy Harvesting - T-ETIT-108344 .....   | 743 |
| 8.298. Seminar Project Management for Engineers - T-ETIT-100814 .....   | 744 |
| 8.299. Seminar Project Management for Engineers - T-ETIT-108820 .....   | 745 |
| 8.300. Seminar: Bionic Algorithms and Robot Technologies - T-MACH-113842 .....  | 746 |
| 8.301. Sensors - T-ETIT-101911 .....  | 747 |
| 8.302. Signal Processing Lab - T-ETIT-113369 .....  | 748 |
| 8.303. Signal Processing Methods - T-ETIT-113837 .....  | 749 |
| 8.304. Signal Processing with Nonlinear Fourier Transforms and Koopman Operators - T-ETIT-113428 .....                        | 750 |
| 8.305. SIL Entrepreneurship Project - T-WIWI-110166 .....   | 751 |
| 8.306. Simulation and Optimization in Robotics and Biomechanics - T-INFO-113123 .....   | 752 |
| 8.307. Simulation with Lumped Parameters - T-MACH-113862 .....  | 753 |
| 8.308. Simulator Exercises Combined Cycle Power Plants - T-MACH-105445 .....  | 754 |
| 8.309. Software Engineering - T-ETIT-108347 .....   | 755 |
| 8.310. Solar Energy - T-ETIT-100774 .....   | 756 |
| 8.311. Solar Thermal Energy Systems - T-MACH-106493 .....   | 757 |
| 8.312. Spaceborne Radar Remote Sensing - Exam - T-ETIT-112857 .....   | 758 |
| 8.313. Spaceborne Radar Remote Sensing - Workshop - T-ETIT-112858 .....   | 759 |
| 8.314. Stochastic Information Processing - T-INFO-101366 .....  | 760 |
| 8.315. Strategic Product Development - Identification of Potentials of Innovative Products - T-MACH-105696 .....              | 761 |
| 8.316. Strategic Product Development - Identification of Potentials of Innovative Products - Case Study - T-MACH-110396 ..... | 762 |
| 8.317. Strategy Derivation for Engineers - T-ETIT-111369 .....  | 763 |
| 8.318. Structural Materials - T-MACH-100293 .....   | 764 |
| 8.319. Superconducting Magnet Technology - T-ETIT-113440 .....  | 765 |
| 8.320. Superconducting Power Systems - T-ETIT-113439 .....  | 766 |
| 8.321. Sustainable Product Engineering - T-MACH-114033 .....  | 767 |
| 8.322. System Integration and Communication Structures in Industry 4.0 and IoT - T-ETIT-112212 .....                          | 768 |
| 8.323. System Integration in Micro- and Nanotechnology - T-MACH-105555 .....  | 769 |
| 8.324. System Integration in Micro- and Nanotechnology 2 - T-MACH-110272 .....  | 770 |
| 8.325. System-on-Chip Laboratory - T-ETIT-100798 .....  | 771 |
| 8.326. Systems and Software Engineering - T-ETIT-100675 .....   | 772 |

|   |            |
|---|------------|
| 8.327. Technical Design in Product Development - T-MACH-105361 .....                      | 773        |
| 8.328. Technical Optics - T-ETIT-100804 .....   | 774        |
| 8.329. Technology Assessment and its Normative Basis - T-MACH-113884 .....                | 775        |
| 8.330. Thermal Solar Energy - T-MACH-105225 .....   | 776        |
| 8.331. Thermal Turbomachines I - T-MACH-114052 .....                                      | 777        |
| 8.332. Thermal-Fluid-Dynamics - T-MACH-106372 .....                                       | 778        |
| 8.333. Tires and Wheel Development for Passenger Cars - T-MACH-102207 .....               | 779        |
| 8.334. Tractors - T-MACH-105423 .....   | 780        |
| 8.335. Tutorial Continuum Mechanics of Solids and Fluids - T-MACH-110333 .....            | 782        |
| 8.336. Tutorial Mathematical Methods in Continuum Mechanics - T-MACH-110376 .....         | 783        |
| 8.337. Tutorial Mathematical Methods in Hydraulics - T-MACH-113913 .....                  | 784        |
| 8.338. Tutorial Simulation with Lumped Parameters - T-MACH-113863 .....                   | 785        |
| 8.339. Ubiquitous Computing - T-INFO-114188 .....   | 786        |
| 8.340. Validation of Technical Systems - T-MACH-113982 .....                              | 787        |
| 8.341. Vehicle Drive Technology - T-MACH-113997 .....                                     | 788        |
| 8.342. Vehicle Lightweight Design - Strategies, Concepts, Materials - T-MACH-105237 ..... | 789        |
| 8.343. Vehicle Systems for Urban Mobility - T-MACH-113069 .....                           | 790        |
| 8.344. Virtual Engineering I - T-MACH-102123 .....  | 791        |
| 8.345. Virtual Engineering Lab - T-MACH-106740 .....                                      | 792        |
| 8.346. Wearable Robotic Technologies - T-INFO-114145 .....                                | 793        |
| 8.347. Windpower - T-MACH-105234 .....  | 794        |
| 8.348. Workshop Finite Element Method in Electromagnetics - T-ETIT-114166 .....           | 795        |
| <b>9. Appendix .....</b>  | <b>794</b> |
| 9.1. Definition - About this MHB .....  | 796        |

## 1 Description of the degree program

### 1.1 List of abbreviations

Departments: ETIT KIT Department of Electrical Engineering and Information Technology

*KIT-Fakultät für Elektrotechnik und Informationstechnik*

MACH KIT Department of Mechanical Engineering

*KIT-Fakultät für Maschinenbau*

INFO KIT Department of Informatics

*KIT-Fakultät für Informatik*

CIW KIT Department of Chemical and Process Engineering

*KIT-Fakultät für Chemieingenieurwesen und Verfahrenstechnik*

PHYS KIT Department of Physics

*KIT-Fakultät für Physik*

WIWI Department of Economics and Management

*KIT-Fakultät für Wirtschaftswissenschaften*

Semester: WS winter term (*Wintersemester*)

SS summer term (*Sommersemester*)

Achievements: V Lecture (*Vorlesung*)

Ü Exercise (*Übung*)

P Laboratory (*Praktikum*)

CR Credit Points (*Leistungspunkte*)

Pr Examination (*Prüfung*)

Miscellaneous: B.Sc. Degree program (*Studiengang*) Bachelor of Science

M.Sc. Degree program (*Studiengang*) Master of Science

SPO Study and examination regulations

(*Studien- und Prüfungsordnung*)

SWS contact hours per week (*Semesterwochenstunden*)

### 1.2 Subjects

The legal basis for the degree program and the conduct of examinations are the currently valid Study and Examination Regulations (Studien- und Prüfungsordnung, SPO)

(<https://www.mach.kit.edu/Master-MIT.php>).

The program degree M.Sc. Mechatronics and Information Technology consists of the following subjects, which are explained in more detail in this and the following chapter. A detailed list of the corresponding modules can be found in the chapter "Field of study structure".

- Field of Specialization: 60 CR
  - Methodical (min. 8 CR)
  - General (min. 16 CR)
  - Internship/Lab Course (exactly 1)
  - Additive Electives
- Elective Area: 22 CR
  - Internship/Lab Course (max. 1)
- Interdisciplinary Qualifications: 8 CR
- Master's Thesis: 30 CR

In total: 120 CR

#### 1.2.1 Field of Specialization

Students choose a **Field of Specialization (FoS)** from the following list. Each field includes 60 CR:

- **Energy Technology** (*Energietechnik*)
- **Industrial Informatics and Systems Engineering** (*Industrieinformatik und Systems Engineering*)
- **Vehicle Systems Engineering** (*Fahrzeugtechnik*)
- **Micro System Technology** (*Mikrosystemtechnik*)
- **Automation, Control, and Robotics** (*Automation, Steuerung und Robotik*)
- **Autonomous Systems and AI** (*Autonome Systeme und KI*)
- **Design of Mechatronic Systems** (*Konstruktion Mechatronischer Systeme*)

The list of modules may be subject to adjustments resulting from the departure of teaching staff, the reorganization of courses and other circumstances. Therefore, the module list in the module handbook is adjusted to current conditions before each semester. In principle, students can choose all modules for their study plan that are included in the according areas of the recent module handbook. Omitted modules cannot be started any more. If they have already been taken, they will of course remain valid. Exams will be offered two additional terms after the course was given at last.

### 1.3 Curriculum

The general study plan shows the structure of the study program:

| Master MIT SS25 - Version: 24.06.2024   |  |   |                            |
|---|--|---|----------------------------|
| 1. - 3. Sem   |  |   | 4. Sem                     |
| Field of Specialization in Mechatronics and Information Technology ( $\Sigma$ 60 CP): |  |   |                            |
| Mandatory Electives –<br>Methodical<br>(at least 8 CP)                                | Mandatory Electives –<br>General<br>(at least 16 CP) | Internship / Lab<br>Course<br>(exactly one) | Additive Electives         |
| Elective Area in Mechatronics and Information Technology (22 CP)                      |  |   | Master's Thesis<br>(30 CP) |
| Interdisciplinary Qualifications (8 CP)   |  |   |                            |

### 1.4 Additional Examinations

According to SPO Article 15, additional examinations can be acquired, that may result in up to 30 credit points more than required for passing the Master's examination. When registering for an examination in a module, this must already be declared as an additional examination. The assignment of a module can be changed again later on request.

Additional examinations are not included in the overall grade, but are listed in the Transcript of Records.

### 1.5 Recognition of external study achievements

The basic rules for the recognition of external achievements (credits and grades) can be found in the study and examination regulations:

- Master SPO 2025 of 2025-01-17, Article 18

According to these regulations, the achievements required in the curriculum can also be achieved through recognition of external credits and grades.

External achievements may be acquired as follows:

1. within the higher education system (worldwide)
2. outside the higher education system (at institutions with standardized quality assurance systems; recognition may be denied if more than 50 percent of the curriculum are to be substituted)

Recognition is granted upon application by the student. With regard to the acquired competencies, it must be ensured that there is no significant difference to the achievements or degrees that are to be replaced. The application must be submitted within the first semester after enrollment at KIT.

The examination board is responsible for recognition and crediting and involves the responsible program consultant in the decision. Recognized credits and grades that were not achieved at KIT are shown as "recognized" in the transcript of records.

There are two options for recognition:

- **Recognition instead of a KIT event**  
An event taught at KIT is replaced by the recognized event. The examination whether the acquired competences are equivalent to the KIT event is carried out by the subject examiner who conducts the event to be replaced at KIT.
- **Recognition of the original event**  
The event will be recognized with the original title. The course can be taken in the Interdisciplinary Subject, in the Interdisciplinary Qualifications, or in the Additional Examinations. The examination whether the acquired competences justify a recognition is carried out by the program consultant.

Experience has shown that recognition "instead of" is difficult, because the competencies taught in courses are usually determined by the lecturer and are rarely the same at other universities. Recognition of "the original", on the other hand, only checks whether the competencies acquired are appropriate to a university course.

If a comparable grading system is used, the grade of the performance to be recognized is taken over. If the grading system is not comparable, the grade will be converted.

The exact procedure is described at "Recognition of external examinations" (<https://www.mach.kit.edu/english/4522.php>).

## 1.6 Semester abroad and student mobility

The KIT departments support and promote stays abroad. For this purpose, there are a number of partnerships with foreign universities. Please contact the departments for up-to-date information. However, students are also encouraged to contact foreign universities on their own.

It is advisable to complete most of the **Methodical** and **General** modules in the Field of Specialization before the stay abroad. The work done at the foreign institution can then be recognized in the **Additive Electives**, the **Elective Area** and in the **Interdisciplinary Qualifications**. Therefore, the third semester is well suited for a stay abroad.

Prior to the stay abroad, the achievements to be made at the foreign university are fixed in a written Learning Agreement. The current form and detailed information can be found on the websites of the KIT Department of Electrical Engineering and Information Technology (<https://www.etit.kit.edu/english/internationales.php>) and the KIT Department of Mechanical Engineering (<https://www.mach.kit.edu/english/4201.php>). Under the title "Recognition at the Sending Institution" it is stated in which subject the modules in the degree program Mechatronics and Information Technology are recognized at KIT. Please contact a program consultant with the completed form.

After the stay abroad, the examination results obtained abroad will be recognized in accordance with the procedure in section 1.5.

## 1.7 Calculation of grades

The module grades in the **Field of Specialization** and the **Elective Area** are weighted with the corresponding credit points to form the overall grade.

The calculation of grades is based on the regulations of the study and examination regulations SPO, Article §7 as well as Article §20, paragraph 2.

## 1.8 Master's Thesis

The **Master's Thesis** should demonstrate that the student is able to work on a problem from the field of mechatronics and information technology independently and within a limited time, using scientific methods that correspond to the state of the art in research. The module **Master's Thesis** is assigned to 30 credit points. It consists of the **Master's Thesis** and a final presentation of the results. The presentation has to take place within the preparation of the **Master's Thesis**.

The prerequisite for admission to the module **Master's Thesis** is that the student is usually in the 2<sup>nd</sup> year of study and has successfully completed module examinations in the sum of 75 CR.

The recommended preparation time is four months in full-time. The maximum preparation time is six months.

The **Master's Thesis** may be completed at all institutes at the KIT Department of Electrical Engineering and Information Technology and the KIT Department of Mechanical Engineering.

Due to the interdisciplinary orientation, the participation of institutes of other faculties is desired. With the approval of the examination board, external **Master's Theses** can also be approved, provided that supervision by a university lecturer is guaranteed. The registration of the **Master's Thesis** has to be done electronically in the Campus Management by the students themselves (<https://campus.studium.kit.edu/english/index.php>), but only after consultation and approval by the supervising professor.



## 2 Goals, structure and acquisition of competences

### 2.1 Conformity of module structure with competence goals

The Master's degree program is structured according to the following concept (see general study plan in the previous chapter):

- Intensive specialization in an area of choice. For this purpose, seven **Fields of Specialization (FoS)** with a total of 60 credit points are offered. Each **FoS** consists of **Methodical** modules (at least 8 CR) and **General**, mainly applied, modules (at least 16 CR), which are specified according to the chosen Field of Specialization. All of the **Methodical** modules may be chosen in the **General** elective block also. Within each **FoS** exactly one **Internship/Lab Course** must be selected. In addition, further courses (**Additive Electives**) of the areas electrical and mechanical engineering as well as information and computer technology are offered, which the students can compile themselves. Within this area a second **Internship/Lab Course** may be chosen.
- During the preparation of their **Master's Thesis**, students are guided to conduct independent scientific research.

An essential fundamental component of the Master's degree program is the great freedom that students are given in the selection of elective modules, the Interdisciplinary Qualifications, and the entire scheduling of studies. This way the students' self and social competence can be optimally promoted.

The structure of the Master's degree program and its modules thus support the qualification goals, formulated above:

The fundamentally oriented courses of the **Methodical** and **General** modules of each **FoS** may be primarily completed in the first two terms. Based on this the students can specialize in choosing further modules of the **Additive Electives**. At the same time, starting in the first term, the Interdisciplinary Qualifications can be chosen freely.

Finally, the fourth term is reserved for the Master's Thesis.

### 2.2 Acquisition of competences

In the Master's degree program, the acquisition of interdisciplinary competencies is promoted through seminars, university internships, **Interdisciplinary Qualifications**, and the **Master's Thesis**, as well as through the general organization of the studies.

Most students complete a seminar as part of the **Additive Electives** (seminars are offered by many institutes and are basically structured in the same way). There they specifically learn to conduct independent literature research, have to apply oral and technical presentation skills and prepare documentations. They learn to work in a self-organized and reflexive manner and improve their communicative, organizational, and didactical skills. They have to analyze a topic independently and present it to an expert audience.

In the **Internships** and **Lab Courses** (in each **FoS** exactly one can be chosen), the focus is on imparting expert knowledge and the practical handling of laboratory equipment or software tools. Here, students will sharpen their analytical skills through playful handling of technology and, at the same time, learn how to work together in teams and develop their own ideas and solutions. Within the **Additive Electives** a second **Internship/Lab Course** may be chosen.

The **Interdisciplinary Qualifications** with an amount of 8 CR are scheduled within the first to third term. 4 CR have to be chosen from the elective block **Engineering Ethics** and another 4 CR may be chosen freely from the **Further Interdisciplinary Qualifications**.

In addition, courses from the Language Center (Sprachzentrum, SPZ), the House of Competence (HoC), or the FORUM can be chosen. The **Interdisciplinary Qualifications** are intended to build up competencies in interdisciplinary thinking, in conveying expert knowledge from non-electrical or non-mechanical engineering disciplines, as well as in writing and speaking a foreign language.

Achievements can be booked in the module "**Interdisciplinary Qualifications** (Überfachliche Qualifikationen)" by the students themselves. Students can access the module via the menu item "Examinations – Exam Registration and Unregistration" at the Campus Management Portal, which is also used to access the study schedule. Here you will find a tab "ÜQ/SQ-Leistungen", which displays the list of unassigned own achievements.

In the following, the taken Interdisciplinary Qualifications have to be assigned to the courses (Teilleistungen) of SPZ, HoC, or FORUM with the title "Self Assignment-HOC-SPZ-FORUM..." according to the grading scale, graded or ungraded. Title and credits of the achievement are adopted automatically.

Further interdisciplinary qualifications or other modules can be acquired within the subject **Additional Examinations**.

The **Master's Thesis**, which must be completed in the fourth term, corresponds to 30 CR. Students learn how to apply scientific methods in the development of new ideas and solutions. They train their analytical thinking as well as working efficiently towards a goal under a given timeline. In addition, students learn to organize themselves and their work process effectively. Knowledge gaps are identified and closed. The Master's Thesis ends with a final presentation of about 20 minutes followed by a discussion (defense). During the preparation of the presentation, the students are guided and supported by their supervisors. The students learn to communicate own and collaboratively developed results in written and oral form. While working on the **Master's Thesis**, it is expected to attend the presentations and defenses of fellow students. This trains to communicate and collaborate with specialists in related disciplines.

The ability to work independently, to organize oneself optimally, and to clearly structure even large long-term tasks can hardly be conveyed in a course by simple explanation. In order to enable students to train themselves optimally in this respect, a large degree of freedom in the selection of courses, in the **Additive Electives**, the **Interdisciplinary Qualifications**, and the entire scheduling of studies is an essential part of the Master's degree program. Only in this way students can optimally attain self- and social competence.

## 3 General Information

### 3.1 Study program details

|  |   |
|--|---|
| <b>KIT-Department</b>                  | KIT Departments of Mechanical Engineering / Electrical Engineering and Information Technology   |
| <b>Academic Degree</b>                 | Master of Science (M.Sc.)   |
| <b>Examination Regulations Version</b> | 2025  |
| <b>Regular terms</b>                   | 4 terms   |
| <b>Maximum terms</b>                   | 8 terms   |
| <b>Credits</b>                         | 120   |
| <b>Language</b>                        | English   |
| <b>Grade calculation</b>               | Weighted by (Weight * CP)   |
| <b>Additional Information</b>          | <p>Link to study program<br/> <a href="http://www.stg-mit.kit.edu">www.stg-mit.kit.edu</a></p> <p>Department<br/> <a href="https://www.mach.kit.edu/Master-MIT.php">https://www.mach.kit.edu/Master-MIT.php</a></p> <p>Business unit Studium und Lehre<br/> <a href="https://www.sle.kit.edu/vorstudium/master-mechatronik-informationstechnik.php">https://www.sle.kit.edu/vorstudium/master-mechatronik-informationstechnik.php</a></p> |

### 3.2 Content

The academic qualifications obtained in the Bachelor's degree are further deepened and supplemented in the Master's degree. The graduates are able to apply the scientific knowledge and methods independently and to evaluate their significance and reach for the solution of complex scientific and social problems.

The field of study is chosen by the students through the selection of the Field of Specialization and the modules in the Elective Area.

### 3.3 Qualification Goals

The competence goals of the Master's degree program Mechatronics and Information Technology are divided into the following four main competence profiles:

1. **Expertise:** Students get to know the fundamentals of the discipline, as well as current research topics, processes, and results.
2. **Research and problem-solving skills:** Students learn the skills and techniques to meet challenges in research and industry.
3. **Assessment and planning skills:** Students participate in professional and research discourse and apply acquired knowledge, as well as learned techniques.
4. **Personal and social skills:** Students work on (their own) research projects, are integrated into a scientific team, are capable of independent and sustained professional and scientific development, and assess the social and societal impact of their activities.

For points 1 and 2 the focus is on lecturer activity, for points 3 and 4 correspondingly on student activity.

For the Master's degree program, these competence requirements can be further described in the following objectives:

#### Expert knowledge

The graduates of the Master's degree program Mechatronics and Information Technology

1. have an in-depth knowledge of mathematics and physics and an advanced expert knowledge of electrical and mechanical engineering as well as information technology. They are able to recognize and evaluate demanding technical and scientific tasks and problems in mechatronics and information technology and to formulate approaches to solve them.
2. master demanding scientific methods of their discipline and have learned to use them to analyze identified problems or subject-related issues according to the state of their knowledge.
3. possess in-depth knowledge in a combination of the core competences of mechatronics and information technology (e.g. automation and control technology, electrical energy systems, high-voltage technology, electrical drives, power electronics, digital technology, information technology, digital signal processing, communications engineering, high-frequency technology, measurement technology, imaging techniques, lighting technology, optoelectronics, circuitry, microelectronics, optical communication systems, materials science, construction and product development, engineering mechanics, robotics, modern software techniques).

#### Research and problem-solving skills

The graduates of the Master's degree program Mechatronics and Information Technology

1. are qualified to work as engineers and scientists in one of the main application fields of mechatronics and information technology (e.g. Automotive Engineering, Power Engineering, Automation Technology, Industrial Handling, Microsystems Technology, Medical Technology).
2. are familiar with the procedures for the analysis and design of components, circuits, systems, and equipment in mechatronics.
3. are familiar with advanced methods of presenting and processing information, programming, algorithmic formulation of processes, and the use of programming tools.
4. possess an in-depth understanding of the methods of mechatronics and information technology.
5. are capable of further qualification through a doctorate program (PhD).

#### Assessment and planning skills

The graduates of the Master's degree program Mechatronics and Information Technology

1. can evaluate mechatronic designs based on elements of electrical and mechanical engineering as well as information technology, using various solution alternatives.
2. recognize limits of the validity of theories and solutions in a wide variety of applications and new developments.
3. can critically question results and transfer solutions to other areas of application.

#### Personal and social skills

The graduates of the Master's degree program Mechatronics and Information Technology

1. are familiar with independent project work as well as interdisciplinary teamwork, are able to grasp the results of others, and are able to communicate their own and team results in writing and orally.
2. are able to familiarize themselves independently with new and complex subject areas in technical sciences and their methods.
3. are able to work scientifically on research-related problems and develop complex assemblies or systems.

4. possess a deeper understanding of applications of mechatronics and information technology in various fields of work, know the limits and dangers involved, and apply their knowledge responsibly and for the benefit of society, taking safety and ecological requirements into account. They actively contribute to the opinion-forming process in society with regard to scientific and technical issues.
5. are able to communicate and cooperate with specialists in an interdisciplinary manner.

### 3.4 Studies and Examination Regulations

<https://www.sle.kit.edu/english/vorstudium/master-mechatronics-information-technology.php>

## 4 Field of study structure

| Mandatory  |       |
|--|-------|
| Master's Thesis  | 30 CR |
| Field of Specialization in Mechatronics and Information Technology   | 60 CR |
| Elective Area in Mechatronics and Information Technology   | 22 CR |
| Interdisciplinary Qualifications<br><i>This field will not influence the calculated grade of its parent.</i> | 8 CR  |

### 4.1 Master's Thesis

**Credits**  
30

| Mandatory     |                 |
|---------------|-----------------|
| M-ETIT-107192 | Master's Thesis |
|               | 30 CR           |

### 4.2 Field of Specialization in Mechatronics and Information Technology

**Credits**  
60

| Field of Specialization in Mechatronics and Information Technology (Election: at most 1 item) |       |
|---|-------|
| Energy Technology   | 60 CR |
| Industrial Informatics and Systems Engineering  | 60 CR |
| Vehicle Systems Engineering   | 60 CR |
| Micro System Technology   | 60 CR |
| Automation, Control, and Robotics   | 60 CR |
| Autonomous Systems and AI   | 60 CR |
| Design of Mechatronic Systems   | 60 CR |

#### 4.2.1 Energy Technology

Part of: Field of Specialization in Mechatronics and Information Technology

**Credits**  
60

#### Election notes

All modules are listed with English titles, regardless of the course language.

To see English modules with English titles and German modules with German titles visit the [German website](#).

The primarily mentioned modules (alphabetically ordered) are given in English, the further below mentioned ones in German (alphabetically ordered).

| <b>Mandatory Electives – Methodical (Election: at least 8 credits)</b> |  |      |
|--|--|------|
|  | <b>- Modules in English Language -</b>                     |      |
| M-ETIT-100539  | Communication Systems and Protocols                        | 5 CR |
| M-MACH-107032  | Mathematical Methods in Fluid Mechanics                    | 6 CR |
| M-MATH-105831  | Numerical Methods  | 5 CR |
| M-MATH-106972  | Numerical Methods with Programming Practice                | 6 CR |
| M-ETIT-100531  | Optimization of Dynamic Systems                            | 5 CR |
|  | <b>- Modules in German Language -</b>                      |      |
| M-ETIT-100374  | Control of Linear Multivariable Systems                    | 6 CR |
| M-MACH-107036  | Numerical Fluid Mechanics                                  | 4 CR |
| <b>Mandatory Electives – General (Election: at least 16 credits)</b>   |  |      |
|  | <b>- Modules in English Language -</b>                     |      |
| M-ETIT-100539  | Communication Systems and Protocols                        | 5 CR |
| M-ETIT-105394  | Electric Power Transmission & Grid Control                 | 6 CR |
| M-MACH-107032  | Mathematical Methods in Fluid Mechanics                    | 6 CR |
| M-MATH-105831  | Numerical Methods  | 5 CR |
| M-MATH-106972  | Numerical Methods with Programming Practice                | 6 CR |
| M-ETIT-100531  | Optimization of Dynamic Systems                            | 5 CR |
| M-ETIT-104567  | Power Electronics  | 6 CR |
|  | <b>- Modules in German Language -</b>                      |      |
| M-MACH-107031  | Analysis Tools for Combustion Diagnostics                  | 4 CR |
| M-ETIT-100532  | Batteries and Fuel Cells                                   | 5 CR |
| M-ETIT-100374  | Control of Linear Multivariable Systems                    | 6 CR |
| M-ETIT-105915  | Control of Power-Electronic Systems                        | 6 CR |
| M-ETIT-100515  | Design of Electrical Machines                              | 5 CR |
| M-MACH-102707  | Fundamentals of Combustion I                               | 4 CR |
| M-MACH-102690  | Fundamentals of Energy Technology                          | 8 CR |
| M-MACH-107122  | Introduction to Nuclear Energy                             | 4 CR |
| M-MACH-107036  | Numerical Fluid Mechanics                                  | 4 CR |
| <b>Internship/Lab Course (Election: 1 item)</b>                        |  |      |
|  | <b>- Modules in English Language -</b>                     |      |
| M-ETIT-107138  | Electric Drives and Power Electronics Lab                  | 6 CR |
| M-MACH-107206  | Laboratory Exercise in Energy Technology                   | 4 CR |
| M-ETIT-107159  | Laboratory Information Systems in Power Engineering        | 6 CR |
| M-INFO-105955  | Practical Course: Smart Energy System                      | 6 CR |
|  | <b>- Modules in German Language -</b>                      |      |
| M-ETIT-100381  | Batteries and Fuel Cells Laboratory                        | 6 CR |
| M-ETIT-102350  | Laboratory Solar Energy                                    | 6 CR |
| <b>Additive Electives (Election: )</b>                                 |  |      |
|  | <b>- Modules in English Language -</b>                     |      |
| M-MACH-107062  | Combined Cycle Power Plants                                | 6 CR |
| M-ETIT-100539  | Communication Systems and Protocols                        | 5 CR |
| M-ETIT-106689  | Components of Power Systems                                | 3 CR |
| M-MACH-107157  | Computational Fluid Dynamics (CFD) for Energy Technologies | 4 CR |
| M-ETIT-106971  | Electric Drives for E-Mobility                             | 4 CR |
| M-ETIT-105394  | Electric Power Transmission & Grid Control                 | 6 CR |
| M-ETIT-105883  | Electrocatalysis   | 5 CR |
| M-ETIT-101969  | Energy Storage and Network Integration                     | 4 CR |
| M-MACH-107066  | Engineering Materials for the Energy Transition            | 4 CR |
| M-MACH-107117  | Fundamentals of Combustion II                              | 4 CR |
| M-WIWI-105403  | Liberalised Power Markets                                  | 6 CR |
| M-MACH-107032  | Mathematical Methods in Fluid Mechanics                    | 6 CR |

|               |  |      |
|---------------|--|------|
| M-MATH-105831 | Numerical Methods  | 5 CR |
| M-MATH-106972 | Numerical Methods with Programming Practice  | 6 CR |
| M-WIWI-100500 | Renewable Energy-Resources, Technologies and Economics   | 4 CR |
| M-ETIT-100531 | Optimization of Dynamic Systems  | 5 CR |
| M-ETIT-104567 | Power Electronics  | 6 CR |
| M-ETIT-100524 | Solar Energy   | 6 CR |
| M-MACH-101924 | Solar Thermal Energy Systems   | 4 CR |
| M-MACH-107219 | Thermal Turbomachines I  | 8 CR |
| M-ETIT-107147 | Workshop Finite Element Method in Electromagnetics   | 3 CR |
|               | <b>- Modules in German Language -</b>  |      |
| M-MACH-107031 | Analysis Tools for Combustion Diagnostics  | 4 CR |
| M-ETIT-100400 | Basics of Converter Control  | 3 CR |
| M-ETIT-100532 | Batteries and Fuel Cells   | 5 CR |
| M-ETIT-100377 | Battery and Fuel Cells Systems   | 3 CR |
| M-MACH-107060 | CO <sub>2</sub> -Neutral Combustion Engines and their Fuels I  | 4 CR |
| M-ETIT-100374 | Control of Linear Multivariable Systems  | 6 CR |
| M-ETIT-105915 | Control of Power-Electronic Systems  | 6 CR |
| M-ETIT-100515 | Design of Electrical Machines  | 5 CR |
| M-MACH-107139 | Energy Systems I - Renewable Energy  | 4 CR |
| M-MACH-107120 | Flows and Heat Transfer in Energy Technology   | 4 CR |
| M-MACH-107124 | Fusion Technology A  | 4 CR |
| M-MACH-107154 | Fusion Technology B  | 4 CR |
| M-MACH-102707 | Fundamentals of Combustion I   | 4 CR |
| M-MACH-102690 | Fundamentals of Energy Technology  | 8 CR |
| M-MACH-107150 | Fundamentals of Reactor Safety for the Operation and Dismantling of Nuclear Power Plants               | 4 CR |
| M-WIWI-100498 | Introduction into Energy Economics   | 5 CR |
| M-MACH-102717 | Heat and Mass Transfer   | 4 CR |
| M-MACH-107075 | Heat Pumps   | 4 CR |
| M-ETIT-105060 | High-Voltage Technology  | 6 CR |
| M-MACH-107097 | Holistic Approach of Managing Power Plant Operation under Uncertainty and Volatility                   | 4 CR |
| M-ETIT-100399 | Industrial Circuitry   | 3 CR |
| M-MACH-107119 | Innovative Nuclear Systems   | 4 CR |
| M-MACH-107122 | Introduction to Nuclear Energy   | 4 CR |
| M-MACH-107223 | Magnet Technology of Fusion Reactors   | 4 CR |
| M-MACH-107043 | Materials Recycling and Sustainability   | 4 CR |
| M-MACH-107042 | Nuclear Power and Reactor Technology   | 4 CR |
| M-MACH-107121 | Nuclear Power Plant Technology   | 4 CR |
| M-MACH-107036 | Numerical Fluid Mechanics  | 4 CR |
| M-ETIT-100513 | Photovoltaics  | 6 CR |
| M-ETIT-102261 | Power Electronics for Photovoltaics and Wind Energy<br><i>First usage possible until Sep 30, 2025.</i> | 3 CR |
| M-ETIT-106067 | Power Electronic Systems in Energy Technology  | 6 CR |
| M-MACH-107061 | Energy Topology and Resilience   | 4 CR |
| M-ETIT-100413 | Power Systems and Economy  | 3 CR |
| M-ETIT-100394 | Practical Aspects of Electrical Drives   | 4 CR |
| M-ETIT-106506 | Power System Protection and Automation   | 3 CR |
| M-MACH-107071 | Reactor Physics  | 4 CR |
| M-MACH-107116 | Reactor Safety 1: Fundamentals   | 4 CR |
| M-ETIT-105916 | Real Time Control of Electrical Drives   | 6 CR |
| M-ETIT-105629 | Seminar Electrocatalysis   | 3 CR |
| M-ETIT-100396 | Seminar New Components and Systems of Power Electronics  | 4 CR |

|               |                                  |      |
|---------------|----------------------------------|------|
| M-ETIT-100537 | Systems and Software Engineering | 5 CR |
| M-MACH-107112 | Thermal-Fluid-Dynamics           | 4 CR |
| M-MACH-102388 | Thermal Solar Energy             | 4 CR |
| M-MACH-105732 | Windpower                        | 4 CR |



**4.2.2 Industrial Informatics and Systems Engineering****Credits****Part of: Field of Specialization in Mechatronics and Information Technology**

60

**Election notes**

All modules are listed with English titles, regardless of the course language.

**To see English modules with English titles and German modules with German titles visit the [German website](#).**

The primarily mentioned modules (alphabetically ordered) are given in English, the further below mentioned ones in German (alphabetically ordered).

| <b>Mandatory Electives – Methodical (Election: at least 8 credits)</b> |  |       |
|--|--|-------|
|  | <b>- Modules in English Language -</b>   |       |
| M-MACH-105296  | Computational Intelligence   | 4 CR  |
| M-ETIT-106953  | Cyber-Physical Modeling  | 6 CR  |
| M-MATH-105831  | Numerical Methods  | 5 CR  |
| M-MATH-106972  | Numerical Methods with Programming Practice                                    | 6 CR  |
| M-ETIT-100531  | Optimization of Dynamic Systems  | 5 CR  |
| M-ETIT-106899  | Signal Processing Methods  | 6 CR  |
|  | <b>- Modules in German Language -</b>  |       |
| M-ETIT-103264  | Information Fusion   | 4 CR  |
| M-INFO-100825  | Pattern Recognition  | 6 CR  |
| <b>Mandatory Electives – General (Election: at least 16 credits)</b>   |  |       |
|  | <b>- Modules in English Language -</b>   |       |
| M-MACH-105296  | Computational Intelligence   | 4 CR  |
| M-ETIT-106953  | Cyber-Physical Modeling  | 6 CR  |
| M-ETIT-106040  | Digital Twin Engineering   | 4 CR  |
| M-ETIT-100449  | Hardware Modeling and Simulation   | 4 CR  |
| M-ETIT-106789  | IT/OT-Security Seminar   | 4 CR  |
| M-MATH-105831  | Numerical Methods  | 5 CR  |
| M-MATH-106972  | Numerical Methods with Programming Practice                                    | 6 CR  |
| M-ETIT-100531  | Optimization of Dynamic Systems  | 5 CR  |
| M-ETIT-106899  | Signal Processing Methods  | 6 CR  |
| M-ETIT-100537  | Systems and Software Engineering   | 5 CR  |
|  | <b>- Modules in German Language -</b>  |       |
| M-ETIT-103264  | Information Fusion   | 4 CR  |
| M-INFO-100825  | Pattern Recognition  | 6 CR  |
| M-ETIT-106673  | Practical Machine Learning   | 6 CR  |
| M-MACH-106662  | Re:Invent - Revolutionary Business Models as the Basis for Product Innovations | 4 CR  |
| <b>Internship/Lab Course (Election: 1 item)</b>                        |  |       |
|  | <b>- Modules in English Language -</b>   |       |
| M-MACH-105725  | Seamless Engineering   | 9 CR  |
| M-ETIT-106633  | Signal Processing Lab  | 6 CR  |
| M-ETIT-105073  | Student Innovation Lab   | 15 CR |
|  | <b>- Modules in German Language -</b>  |       |
| M-MACH-102699  | Laboratory Mechatronics  | 4 CR  |
| M-INFO-105958  | Practical Course: Machine Learning and Intelligent Systems                     | 8 CR  |
| M-MACH-106050  | Reliability and Test Engineering   | 5 CR  |
| <b>Additive Electives (Election: )</b>                                 |  |       |
|  | <b>- Modules in English Language -</b>   |       |
| M-INFO-107198  | Advanced Artificial Intelligence   | 6 CR  |
| M-ETIT-100539  | Communication Systems and Protocols  | 5 CR  |
| M-MACH-105296  | Computational Intelligence   | 4 CR  |
| M-ETIT-106953  | Cyber-Physical Modeling  | 6 CR  |
| M-ETIT-106040  | Digital Twin Engineering   | 4 CR  |
| M-INFO-107169  | Machine Learning - Foundations and Algorithms                                  | 6 CR  |
| M-MATH-105831  | Numerical Methods  | 5 CR  |
| M-MATH-106972  | Numerical Methods with Programming Practice                                    | 6 CR  |
| M-ETIT-100531  | Optimization of Dynamic Systems  | 5 CR  |
| M-ETIT-106780  | Practical Tools for Control Engineers  | 4 CR  |
| M-WIWI-100500  | Renewable Energy-Resources, Technologies and Economics                         | 4 CR  |
| M-INFO-106504  | Simulation and Optimization in Robotics and Biomechanics                       | 6 CR  |
|  | <b>- Modules in German Language -</b>  |       |

|               |  |      |
|---------------|--|------|
| M-MACH-105968 | Artificial Intelligence in Production  | 8 CR |
| M-MACH-106468 | Control of Mobile Machines   | 4 CR |
| M-ETIT-100449 | Hardware Modeling and Simulation   | 4 CR |
| M-ETIT-103264 | Information Fusion   | 4 CR |
| M-INFO-100895 | Information Processing in Sensor Networks  | 6 CR |
| M-ETIT-100367 | Information Technology in Industrial Automation Systems                            | 3 CR |
| M-WIWI-100498 | Introduction into Energy Economics   | 5 CR |
| M-MACH-106525 | Introduction to Bionics  | 4 CR |
| M-MACH-105282 | IT-Fundamentals of Logistics: Opportunities for Digital Transformation             | 4 CR |
| M-ETIT-106789 | IT/OT-Security Seminar   | 4 CR |
| M-MACH-105298 | Logistics and Supply Chain Management  | 9 CR |
| M-INFO-100825 | Pattern Recognition  | 6 CR |
| M-ETIT-106673 | Practical Machine Learning   | 6 CR |
| M-ETIT-104475 | Project Management in the Development of Products for Safety-Critical Applications | 4 CR |
| M-MACH-106662 | Re:Invent - Revolutionary Business Models as the Basis for Product Innovations     | 4 CR |
| M-ETIT-106970 | Seminar Industrial Process and Plant Engineering                                   | 4 CR |
| M-ETIT-106899 | Signal Processing Methods  | 6 CR |
| M-ETIT-100450 | Software Engineering   | 3 CR |
| M-INFO-100829 | Stochastic Information Processing  | 6 CR |
| M-ETIT-106026 | System Integration and Communication Structures in Industry 4.0 and IoT            | 3 CR |
| M-ETIT-100537 | Systems and Software Engineering   | 5 CR |

**4.2.3 Vehicle Systems Engineering****Credits****Part of: Field of Specialization in Mechatronics and Information Technology****60****Election notes**

All modules are listed with English titles, regardless of the course language.

**To see English modules with English titles and German modules with German titles visit the [German website](#).**

The primarily mentioned modules (alphabetically ordered) are given in English, the further below mentioned ones in German (alphabetically ordered).

| <b>Mandatory Electives – Methodical (Election: at least 8 credits)</b> |   |      |
|--|---|------|
|  | <b>- Modules in English Language -</b>                        |      |
| M-MATH-105831  | Numerical Methods   | 5 CR |
| M-MATH-106972  | Numerical Methods with Programming Practice                   | 6 CR |
| M-ETIT-100537  | Systems and Software Engineering                              | 5 CR |
|  | <b>- Modules in German Language -</b>                         |      |
| M-MACH-106468  | Control of Mobile Machines                                    | 4 CR |
| M-MACH-102718  | Product Development – Methods of Product Engineering          | 6 CR |
| M-MACH-107053  | Simulation with Lumped Parameters                             | 4 CR |
| <b>Mandatory Electives – General (Election: at least 16 credits)</b>   |   |      |
|  | <b>- Modules in English Language -</b>                        |      |
| M-MACH-107148  | Automotive Vision   | 6 CR |
| M-MACH-107151  | Data-Driven Algorithms in Vehicle Technology                  | 4 CR |
| M-MACH-106926  | Decision-Making and Motion Planning for Automated Driving     | 6 CR |
| M-MATH-105831  | Numerical Methods   | 5 CR |
| M-MATH-106972  | Numerical Methods with Programming Practice                   | 6 CR |
| M-ETIT-100537  | Systems and Software Engineering                              | 5 CR |
|  | <b>- Modules in German Language -</b>                         |      |
| M-MACH-100501  | Automotive Engineering I                                      | 8 CR |
| M-ETIT-100532  | Batteries and Fuel Cells                                      | 5 CR |
| M-MACH-107060  | CO <sub>2</sub> -Neutral Combustion Engines and their Fuels I | 4 CR |
| M-MACH-106468  | Control of Mobile Machines                                    | 4 CR |
| M-MACH-107041  | Mobile Machines   | 8 CR |
| M-MACH-102718  | Product Development – Methods of Product Engineering          | 6 CR |
| M-MACH-102683  | Rail Vehicle Technology                                       | 4 CR |
| M-MACH-107053  | Simulation with Lumped Parameters                             | 4 CR |
| <b>Internship/Lab Course (Election: 1 item)</b>                        |   |      |
|  | <b>- Modules in English Language -</b>                        |      |
| M-ETIT-107138  | Electric Drives and Power Electronics Lab                     | 6 CR |
| M-MACH-105725  | Seamless Engineering  | 9 CR |
|  | <b>- Modules in German Language -</b>                         |      |
| M-ETIT-100381  | Batteries and Fuel Cells Laboratory                           | 6 CR |
| M-MACH-106744  | Cognitive Automobiles - Laboratory                            | 6 CR |
| M-MACH-102695  | Motor Vehicle Laboratory                                      | 4 CR |
| M-MACH-107052  | Practical Course: Autonomous Driving                          | 6 CR |
| M-MACH-106050  | Reliability and Test Engineering                              | 5 CR |
| <b>Additive Electives (Election: )</b>                                 |   |      |
|  | <b>- Modules in English Language -</b>                        |      |
| M-MACH-107148  | Automotive Vision   | 6 CR |
| M-MACH-107151  | Data-Driven Algorithms in Vehicle Technology                  | 4 CR |
| M-MACH-106926  | Decision-Making and Motion Planning for Automated Driving     | 6 CR |
| M-ETIT-106971  | Electric Drives for E-Mobility                                | 4 CR |
| M-MATH-105831  | Numerical Methods   | 5 CR |
| M-MATH-106972  | Numerical Methods with Programming Practice                   | 6 CR |
| M-MACH-107074  | Project Workshop: Automotive Engineering                      | 6 CR |
| M-ETIT-100537  | Systems and Software Engineering                              | 5 CR |
| M-MACH-107143  | Validation of Technical Systems                               | 4 CR |
|  | <b>- Modules in German Language -</b>                         |      |
| M-MACH-100501  | Automotive Engineering I                                      | 8 CR |
| M-MACH-100502  | Automotive Engineering II                                     | 4 CR |
| M-ETIT-100532  | Batteries and Fuel Cells                                      | 5 CR |
| M-MACH-107060  | CO <sub>2</sub> -Neutral Combustion Engines and their Fuels I | 4 CR |

|               |  |      |
|---------------|--|------|
| M-MACH-107180 | CO <sub>2</sub> -Neutral Combustion Engines and their Fuels II                   | 5 CR |
| M-MACH-106468 | Control of Mobile Machines   | 4 CR |
| M-MACH-107055 | Design and Development of Mobile Machines  | 4 CR |
| M-MACH-107082 | Design and Optimization of Conventional and Electrified Automotive Transmissions | 4 CR |
| M-ETIT-100515 | Design of Electrical Machines  | 5 CR |
| M-MACH-107078 | Development of Hybrid Powertrains  | 4 CR |
| M-MACH-107059 | Development of Oil-Hydraulic Powertrain Systems                                  | 4 CR |
| M-MACH-102700 | Dynamics of the Automotive Drive Train   | 4 CR |
| M-MACH-107160 | Engine Measurement Techniques  | 4 CR |
| M-MACH-105824 | Fundamentals in the Development of Commercial Vehicles                           | 4 CR |
| M-MACH-105288 | Handling Characteristics of Motor Vehicles I                                     | 4 CR |
| M-MACH-107073 | Handling Characteristics of Motor Vehicles II                                    | 4 CR |
| M-MACH-107158 | Hydrogen and reFuels - Energy Conversion in Combustion Engines                   | 4 CR |
| M-MACH-106514 | Innovation and Project Management in Rail Vehicle Engineering                    | 4 CR |
| M-MACH-107210 | Mathematical Methods in Hydraulics   | 6 CR |
| M-MACH-107041 | Mobile Machines  | 8 CR |
| M-ETIT-100394 | Practical Aspects of Electrical Drives   | 4 CR |
| M-MACH-105346 | Product- and Production-Concepts for modern Automobiles                          | 4 CR |
| M-MACH-102718 | Product Development – Methods of Product Engineering                             | 6 CR |
| M-MACH-107072 | Python Algorithms for Automotive Engineering                                     | 4 CR |
| M-MACH-102683 | Rail Vehicle Technology  | 4 CR |
| M-MACH-106513 | Railway System Digitalisation  | 4 CR |
| M-MACH-107044 | Railways in the Transportation Market  | 4 CR |
| M-ETIT-100378 | Sensors  | 3 CR |
| M-MACH-107053 | Simulation with Lumped Parameters  | 4 CR |
| M-MACH-107070 | Tires and Wheel Development for Passenger Cars                                   | 4 CR |
| M-MACH-107058 | Tractors   | 4 CR |
| M-MACH-107056 | Vehicle Drive Technology   | 4 CR |
| M-MACH-102703 | Vehicle Lightweight Design - Strategies, Concepts, Materials                     | 4 CR |
| M-MACH-106515 | Vehicle Systems for Urban Mobility   | 4 CR |

**4.2.4 Micro System Technology****Credits****Part of: Field of Specialization in Mechatronics and Information Technology**

60

**Election notes**

All modules are listed with English titles, regardless of the course language.

**To see English modules with English titles and German modules with German titles visit the [German website](#).**

The primarily mentioned modules (alphabetically ordered) are given in English, the further below mentioned ones in German (alphabetically ordered).

| <b>Mandatory Electives – Methodical (Election: at least 8 credits)</b> |  |      |
|--|--|------|
|  | <b>- Modules in English Language -</b>                               |      |
| M-MACH-105296  | Computational Intelligence   | 4 CR |
| M-MATH-105831  | Numerical Methods  | 5 CR |
| M-MATH-106972  | Numerical Methods with Programming Practice                          | 6 CR |
|  | <b>- Modules in German Language -</b>                                |      |
| M-ETIT-100374  | Control of Linear Multivariable Systems                              | 6 CR |
| M-ETIT-100361  | Distributed Discrete Event Systems                                   | 4 CR |
| M-MACH-102718  | Product Development – Methods of Product Engineering                 | 6 CR |
| <b>Mandatory Electives – General (Election: at least 16 credits)</b>   |  |      |
|  | <b>- Modules in English Language -</b>                               |      |
| M-MACH-105296  | Computational Intelligence   | 4 CR |
| M-MATH-105831  | Numerical Methods  | 5 CR |
| M-MATH-106972  | Numerical Methods with Programming Practice                          | 6 CR |
| M-MACH-107183  | Polymers in MEMS A: Chemistry, Synthesis and Applications            | 4 CR |
| M-MACH-107035  | Polymers in MEMS B: Physics, Microstructuring and Applications       | 4 CR |
| M-MACH-107164  | Quantum Machines I   | 4 CR |
| M-MACH-107165  | Quantum Machines II  | 4 CR |
|  | <b>- Modules in German Language -</b>                                |      |
| M-MACH-100489  | BioMEMS - Microsystems Technologies for Life Sciences and Medicine I | 4 CR |
| M-ETIT-100374  | Control of Linear Multivariable Systems                              | 6 CR |
| M-ETIT-100361  | Distributed Discrete Event Systems                                   | 4 CR |
| M-MACH-102691  | Introduction to Microsystem Technology I                             | 4 CR |
| M-MACH-102706  | Introduction to Microsystem Technology II                            | 4 CR |
| M-MACH-106210  | Mathematical Methods in Continuum Mechanics                          | 6 CR |
| M-MACH-100487  | Microactuators   | 4 CR |
| M-MACH-102718  | Product Development – Methods of Product Engineering                 | 6 CR |
| M-ETIT-100378  | Sensors  | 3 CR |
| <b>Internship/Lab Course (Election: 1 item)</b>                        |  |      |
|  | <b>- Modules in English Language -</b>                               |      |
| M-MACH-107195  | Microsystem Product Design for Young Entrepreneurs                   | 4 CR |
| M-ETIT-105464  | MMIC Design Laboratory   | 6 CR |
| M-MACH-107196  | NMR Micro Probe Hardware Conception and Construction                 | 4 CR |
| M-MACH-107034  | Practical Course Polymers in MEMS                                    | 2 CR |
| M-MACH-105725  | Seamless Engineering   | 9 CR |
|  | <b>- Modules in German Language -</b>                                |      |
| M-ETIT-100478  | Laboratory Nanotechnology  | 6 CR |
| M-MACH-105479  | Practical Training in Basics of Microsystem Technology               | 4 CR |
| M-ETIT-100451  | System-on-Chip Laboratory  | 6 CR |
| <b>Additive Electives (Election: )</b>                                 |  |      |
|  | <b>- Modules in English Language -</b>                               |      |
| M-ETIT-103802  | Adaptive Optics  | 3 CR |
| M-MACH-105296  | Computational Intelligence   | 4 CR |
| M-MATH-105831  | Numerical Methods  | 5 CR |
| M-MATH-106972  | Numerical Methods with Programming Practice                          | 6 CR |
| M-MACH-107185  | Mechanical Properties of Nanomaterials and Microsystems              | 4 CR |
| M-MACH-102714  | Microenergy Technologies   | 4 CR |
| M-MACH-105486  | Micro System Simulation  | 4 CR |
| M-ETIT-100535  | Microwave Engineering  | 5 CR |
| M-ETIT-106921  | Modern VLSI Technologies   | 6 CR |
| M-ETIT-105604  | Nano- and Quantum Electronics  | 6 CR |
| M-MACH-107183  | Polymers in MEMS A: Chemistry, Synthesis and Applications            | 4 CR |



|               |  |      |
|---------------|--|------|
| M-MACH-107035 | Polymers in MEMS B: Physics, Microstructuring and Applications         | 4 CR |
| M-MACH-107085 | Polymers in MEMS C: Biopolymers and Bioplastics                        | 4 CR |
| M-ETIT-105606 | Quantum Detectors and Sensors  | 6 CR |
| M-MACH-107164 | Quantum Machines I   | 4 CR |
| M-MACH-107165 | Quantum Machines II  | 4 CR |
| M-ETIT-106955 | Radio-Frequency Electronics  | 6 CR |
|               | <b>- Modules in German Language -</b>                                  |      |
| M-MACH-102698 | Actuators and Sensors in Nanotechnology                                | 4 CR |
| M-MACH-100489 | BioMEMS - Microsystems Technologies for Life Sciences and Medicine I   | 4 CR |
| M-MACH-100490 | BioMEMS - Microsystems Technologies for Life Sciences and Medicine II  | 4 CR |
| M-MACH-100491 | BioMEMS - Microsystems Technologies for Life Sciences and Medicine III | 4 CR |
| M-MACH-105483 | BioMEMS - Microsystemtechnology for Life-Science and Medicine IV       | 4 CR |
| M-MACH-105484 | BioMEMS - Microfluidic Chipsystems V                                   | 4 CR |
| M-ETIT-100374 | Control of Linear Multivariable Systems                                | 6 CR |
| M-MACH-105485 | Current Topics on BioMEMS  | 4 CR |
| M-ETIT-100361 | Distributed Discrete Event Systems                                     | 4 CR |
| M-MACH-107207 | Introduction to Nanotechnology   | 4 CR |
| M-MACH-105478 | Fabrication Processes in Microsystem Technology                        | 4 CR |
| M-INFO-100895 | Information Processing in Sensor Networks                              | 6 CR |
| M-ETIT-100474 | Integrated Systems and Circuits  | 4 CR |
| M-MACH-102691 | Introduction to Microsystem Technology I                               | 4 CR |
| M-MACH-102706 | Introduction to Microsystem Technology II                              | 4 CR |
| M-MACH-106210 | Mathematical Methods in Continuum Mechanics                            | 6 CR |
| M-MACH-100487 | Microactuators   | 4 CR |
| M-ETIT-100454 | Microsystem Technology   | 3 CR |
| M-MACH-107063 | Miniaturized Heat Transfer   | 4 CR |
| M-MACH-105292 | Novel Actuators and Sensors  | 4 CR |
| M-ETIT-100484 | Optoelectronic Measurement Engineering                                 | 3 CR |
| M-MACH-107064 | Physical Basics of Laser Technology                                    | 5 CR |
| M-MACH-102718 | Product Development – Methods of Product Engineering                   | 6 CR |
| M-ETIT-100455 | Seminar Embedded Systems   | 4 CR |
| M-ETIT-100378 | Sensors  | 3 CR |
| M-MACH-105315 | System Integration in Micro- and Nanotechnology                        | 4 CR |
| M-MACH-105316 | System Integration in Micro- and Nanotechnology 2                      | 4 CR |

**4.2.5 Automation, Control, and Robotics****Credits****Part of: Field of Specialization in Mechatronics and Information Technology**

60

**Election notes**

All modules are listed with English titles, regardless of the course language.

**To see English modules with English titles and German modules with German titles visit the [German website](#).**

The primarily mentioned modules (alphabetically ordered) are given in English, the further below mentioned ones in German (alphabetically ordered).

| <b>Mandatory Electives – Methodical (Election: at least 8 credits)</b> |   |       |
|--|---|-------|
|  | <b>- Modules in English Language -</b>  |       |
| M-ETIT-106953  | Cyber-Physical Modeling   | 6 CR  |
| M-ETIT-100531  | Optimization of Dynamic Systems   | 5 CR  |
| M-INFO-107130  | Robotics III - Sensors and Perception in Robotics                                     | 3 CR  |
|  | <b>- Modules in German Language -</b>   |       |
| M-ETIT-100374  | Control of Linear Multivariable Systems   | 6 CR  |
| M-MACH-107087  | Probabilistic Measurement and Estimation  | 4 CR  |
| <b>Mandatory Electives – General (Election: at least 16 credits)</b>   |   |       |
|  | <b>- Modules in English Language -</b>  |       |
| M-INFO-107198  | Advanced Artificial Intelligence  | 6 CR  |
| M-MACH-106903  | Biologically Inspired Robots  | 3 CR  |
| M-ETIT-106953  | Cyber-Physical Modeling   | 6 CR  |
| M-MACH-107088  | Deep Learning for Engineers   | 6 CR  |
| M-MACH-106457  | Machine Learning for Robotic Systems 1  | 5 CR  |
| M-MACH-101923  | Machine Vision  | 8 CR  |
| M-ETIT-100531  | Optimization of Dynamic Systems   | 5 CR  |
| M-INFO-105623  | Reinforcement Learning  | 6 CR  |
| M-INFO-107130  | Robotics III - Sensors and Perception in Robotics                                     | 3 CR  |
|  | <b>- Modules in German Language -</b>   |       |
| M-ETIT-100374  | Control of Linear Multivariable Systems   | 6 CR  |
| M-MACH-107087  | Probabilistic Measurement and Estimation  | 4 CR  |
| <b>Internship/Lab Course (Election: 1 item)</b>                        |   |       |
|  | <b>- Modules in English Language -</b>  |       |
| M-MACH-106905  | CAD Engineering Project for Intelligent Systems                                       | 3 CR  |
| M-MACH-106904  | Practical Course: Software Development and Application of Mobile, Bio-Inspired Robots | 6 CR  |
| M-INFO-107155  | Robotics - Practical Course   | 6 CR  |
| M-MACH-105725  | Seamless Engineering  | 9 CR  |
| M-ETIT-105073  | Student Innovation Lab  | 15 CR |
|  | <b>- Modules in German Language -</b>   |       |
| M-MACH-105475  | Virtual Engineering Lab   | 4 CR  |
| M-ETIT-105467  | Control Theory Laboratory   | 6 CR  |
| M-INFO-105252  | Machine Learning - Basic Methods  | 5 CR  |
| M-ETIT-106673  | Practical Machine Learning  | 6 CR  |
| M-MACH-106050  | Reliability and Test Engineering  | 5 CR  |
| <b>Additive Electives (Election: )</b>                                 |   |       |
|  | <b>- Modules in English Language -</b>  |       |
| M-INFO-107198  | Advanced Artificial Intelligence  | 6 CR  |
| M-MACH-107148  | Automotive Vision   | 6 CR  |
| M-MACH-106903  | Biologically Inspired Robots  | 3 CR  |
| M-MACH-105296  | Computational Intelligence  | 4 CR  |
| M-ETIT-106953  | Cyber-Physical Modeling   | 6 CR  |
| M-MACH-107088  | Deep Learning for Engineers   | 6 CR  |
| M-MACH-107089  | Hot Research Topics in AI for Engineering Applications                                | 4 CR  |
| M-INFO-107152  | Humanoid Robots - Seminar   | 3 CR  |
| M-MACH-106457  | Machine Learning for Robotic Systems 1  | 5 CR  |
| M-MACH-106652  | Machine Learning for Robotic Systems 2  | 5 CR  |
| M-MACH-101923  | Machine Vision  | 8 CR  |
| M-INFO-102555  | Motion in Human and Machine - Seminar   | 3 CR  |
| M-ETIT-100531  | Optimization of Dynamic Systems   | 5 CR  |
| M-INFO-105623  | Reinforcement Learning  | 6 CR  |

|               |   |      |
|---------------|---|------|
| M-INFO-107123 | Robotics II - Humanoid Robotics                       | 3 CR |
| M-INFO-107130 | Robotics III - Sensors and Perception in Robotics     | 3 CR |
| M-MACH-106902 | Seminar: Bionic Algorithms and Robot Technologies     | 3 CR |
| M-ETIT-106899 | Signal Processing Methods                             | 6 CR |
|               | <b>- Modules in German Language -</b>                 |      |
| M-MACH-102698 | Actuators and Sensors in Nanotechnology               | 4 CR |
| M-INFO-100826 | Automated Visual Inspection and Image Processing      | 6 CR |
| M-ETIT-100374 | Control of Linear Multivariable Systems               | 6 CR |
| M-MACH-106468 | Control of Mobile Machines                            | 4 CR |
| M-MACH-105348 | Control Technology                                    | 4 CR |
| M-INFO-105753 | Deep Learning for Computer Vision I: Basics           | 3 CR |
| M-MACH-107045 | Digital Control                                       | 4 CR |
| M-ETIT-100361 | Distributed Discrete Event Systems                    | 4 CR |
| M-ETIT-100453 | Hardware/Software Co-Design                           | 4 CR |
| M-INFO-100824 | Human-Machine-Interaction in Anthropomatics: Basics   | 3 CR |
| M-ETIT-103264 | Information Fusion                                    | 4 CR |
| M-INFO-100791 | Innovative Concepts for Programming Industrial Robots | 4 CR |
| M-INFO-100840 | Localization of Mobile Agents                         | 6 CR |
| M-MACH-100487 | Microactuators  | 4 CR |
| M-MACH-105314 | Modern Control Concepts III                           | 4 CR |
| M-ETIT-100371 | Nonlinear Control Systems                             | 3 CR |
| M-ETIT-102310 | Optimal Control and Estimation                        | 3 CR |
| M-MACH-102702 | Organ Support Systems                                 | 4 CR |
| M-MACH-107087 | Probabilistic Measurement and Estimation              | 4 CR |
| M-INFO-100803 | Real-Time Systems                                     | 6 CR |
| M-INFO-102212 | Seminar Intelligent Industrial Robots                 | 3 CR |
| M-ETIT-100378 | Sensors   | 3 CR |
| M-INFO-100829 | Stochastic Information Processing                     | 6 CR |

**4.2.6 Autonomous Systems and AI****Credits****Part of: Field of Specialization in Mechatronics and Information Technology**

60

**Election notes**

All modules are listed with English titles, regardless of the course language.

**To see English modules with English titles and German modules with German titles visit the [German website](#).**

The primarily mentioned modules (alphabetically ordered) are given in English, the further below mentioned ones in German (alphabetically ordered).

-----

Presumably, in the area "**Mandatory Electives – General**" the following courses are selectable:

- Machine Learning with Python (WiSe), T-MACH-113927
- Robotic Intelligence for mobile Systems (SoSe), T-MACH-114034

Booking can be done via Study Program Service ETIT/MIT.

| <b>Mandatory Electives – Methodical (Election: at least 8 credits)</b> |   |       |
|--|---|-------|
|  | <b>- Modules in English Language -</b>  |       |
| M-INFO-107198  | Advanced Artificial Intelligence  | 6 CR  |
| M-MACH-107088  | Deep Learning for Engineers   | 6 CR  |
| M-MACH-106457  | Machine Learning for Robotic Systems 1  | 5 CR  |
| M-MACH-101923  | Machine Vision  | 8 CR  |
| M-ETIT-100531  | Optimization of Dynamic Systems   | 5 CR  |
|  | <b>- Modules in German Language -</b>   |       |
| M-MACH-107087  | Probabilistic Measurement and Estimation  | 4 CR  |
| <b>Mandatory Electives – General (Election: at least 16 credits)</b>   |   |       |
|  | <b>- Modules in English Language -</b>  |       |
| M-INFO-107198  | Advanced Artificial Intelligence  | 6 CR  |
| M-MACH-107148  | Automotive Vision   | 6 CR  |
| M-MACH-106903  | Biologically Inspired Robots  | 3 CR  |
| M-MACH-107088  | Deep Learning for Engineers   | 6 CR  |
| M-MACH-106457  | Machine Learning for Robotic Systems 1  | 5 CR  |
| M-MACH-106652  | Machine Learning for Robotic Systems 2  | 5 CR  |
| M-MACH-101923  | Machine Vision  | 8 CR  |
| M-ETIT-100531  | Optimization of Dynamic Systems   | 5 CR  |
| M-INFO-107130  | Robotics III - Sensors and Perception in Robotics                                     | 3 CR  |
|  | <b>- Modules in German Language -</b>   |       |
| M-MACH-105968  | Artificial Intelligence in Production   | 8 CR  |
| M-MACH-107087  | Probabilistic Measurement and Estimation  | 4 CR  |
| M-MACH-107072  | Python Algorithms for Automotive Engineering  | 4 CR  |
| <b>Internship/Lab Course (Election: 1 item)</b>                        |   |       |
|  | <b>- Modules in English Language -</b>  |       |
| M-MACH-106905  | CAD Engineering Project for Intelligent Systems                                       | 3 CR  |
| M-MACH-106830  | Industrial Mobile Robotics Lab  | 4 CR  |
| M-MACH-106904  | Practical Course: Software Development and Application of Mobile, Bio-Inspired Robots | 6 CR  |
| M-MACH-105725  | Seamless Engineering  | 9 CR  |
| M-ETIT-105073  | Student Innovation Lab  | 15 CR |
|  | <b>- Modules in German Language -</b>   |       |
| M-MACH-106744  | Cognitive Automobiles - Laboratory  | 6 CR  |
| M-ETIT-105467  | Control Theory Laboratory   | 6 CR  |
| M-INFO-105958  | Practical Course: Machine Learning and Intelligent Systems                            | 8 CR  |
| M-ETIT-106673  | Practical Machine Learning  | 6 CR  |
| M-MACH-106050  | Reliability and Test Engineering  | 5 CR  |
| <b>Additive Electives (Election: )</b>                                 |   |       |
|  | <b>- Modules in English Language -</b>  |       |
| M-INFO-107198  | Advanced Artificial Intelligence  | 6 CR  |
| M-MACH-107148  | Automotive Vision   | 6 CR  |
| M-MACH-106903  | Biologically Inspired Robots  | 3 CR  |
| M-MACH-105296  | Computational Intelligence  | 4 CR  |
| M-ETIT-106953  | Cyber-Physical Modeling   | 6 CR  |
| M-MACH-107151  | Data-Driven Algorithms in Vehicle Technology  | 4 CR  |
| M-INFO-107197  | Deep Learning and Neural Networks   | 6 CR  |
| M-MACH-107088  | Deep Learning for Engineers   | 6 CR  |
| M-MACH-107089  | Hot Research Topics in AI for Engineering Applications                                | 4 CR  |
| M-ETIT-105461  | Introduction to Automotive and Industrial Lidar Technology                            | 3 CR  |
| M-MACH-106457  | Machine Learning for Robotic Systems 1  | 5 CR  |
| M-MACH-106652  | Machine Learning for Robotic Systems 2  | 5 CR  |

|               |   |      |
|---------------|---|------|
| M-MACH-101923 | Machine Vision                                    | 8 CR |
| M-ETIT-100531 | Optimization of Dynamic Systems                   | 5 CR |
| M-INFO-105623 | Reinforcement Learning                            | 6 CR |
| M-INFO-107130 | Robotics III - Sensors and Perception in Robotics | 3 CR |
|               | <b>- Modules in German Language -</b>             |      |
| M-MACH-105968 | Artificial Intelligence in Production             | 8 CR |
| M-ETIT-100374 | Control of Linear Multivariable Systems           | 6 CR |
| M-MACH-107045 | Digital Control                                   | 4 CR |
| M-ETIT-100361 | Distributed Discrete Event Systems                | 4 CR |
| M-ETIT-103264 | Information Fusion                                | 4 CR |
| M-MACH-105313 | Modern Control Concepts II                        | 4 CR |
| M-MACH-105314 | Modern Control Concepts III                       | 4 CR |
| M-ETIT-100371 | Nonlinear Control Systems                         | 3 CR |
| M-ETIT-102310 | Optimal Control and Estimation                    | 3 CR |
| M-MACH-107087 | Probabilistic Measurement and Estimation          | 4 CR |
| M-MACH-107072 | Python Algorithms for Automotive Engineering      | 4 CR |
| M-INFO-100803 | Real-Time Systems                                 | 6 CR |
| M-INFO-100829 | Stochastic Information Processing                 | 6 CR |

**4.2.7 Design of Mechatronic Systems****Credits**

Part of: Field of Specialization in Mechatronics and Information Technology

60

**Election notes**

All modules are listed with English titles, regardless of the course language.

**To see English modules with English titles and German modules with German titles visit the [German website](#).**

The primarily mentioned modules (alphabetically ordered) are given in English, the further below mentioned ones in German (alphabetically ordered).

-----

During summer term 2025 modules will be added in "**Internship/Lab Course**".



| <b>Mandatory Electives – Methodical (Election: at least 8 credits)</b> |  |       |
|--|--|-------|
|  | <b>- Modules in German Language -</b>  |       |
| M-MACH-105307  | Data Analytics for Engineers   | 5 CR  |
| M-MACH-107142  | Leadership in Interdisciplinary Teams  | 4 CR  |
| M-MACH-107144  | Power Tool Design  | 4 CR  |
| M-MACH-102718  | Product Development – Methods of Product Engineering                               | 6 CR  |
| <b>Mandatory Electives – General (Election: at least 16 credits)</b>   |  |       |
|  | <b>- Modules in English Language -</b>   |       |
| M-MACH-107190  | Drive System Engineering B: Stationary Machinery                                   | 4 CR  |
|  | <b>- Modules in German Language -</b>  |       |
| M-MACH-105307  | Data Analytics for Engineers   | 5 CR  |
| M-MACH-107142  | Leadership in Interdisciplinary Teams  | 4 CR  |
| M-MACH-105107  | Machine Tools and Industrial Handling  | 8 CR  |
| M-MACH-107041  | Mobile Machines  | 8 CR  |
| M-MACH-105292  | Novel Actuators and Sensors  | 4 CR  |
| M-MACH-102702  | Organ Support Systems  | 4 CR  |
| M-MACH-107144  | Power Tool Design  | 4 CR  |
| M-ETIT-100394  | Practical Aspects of Electrical Drives   | 4 CR  |
| M-MACH-102718  | Product Development – Methods of Product Engineering                               | 6 CR  |
| M-ETIT-104475  | Project Management in the Development of Products for Safety-Critical Applications | 4 CR  |
| <b>Internship/Lab Course (Election: 1 item)</b>                        |  |       |
|  | <b>- Modules in English Language -</b>   |       |
| M-MACH-105725  | Seamless Engineering   | 9 CR  |
|  | <b>- Modules in German Language -</b>  |       |
| M-MACH-102684  | CAE-Workshop   | 4 CR  |
| M-ETIT-100460  | Laboratory in Software Engineering   | 6 CR  |
| M-MACH-102699  | Laboratory Mechatronics  | 4 CR  |
| M-MACH-107145  | Power Tool Design Project Work   | 8 CR  |
| M-MACH-102711  | Production Techniques Laboratory   | 4 CR  |
| M-MACH-106050  | Reliability and Test Engineering   | 5 CR  |
| M-MACH-105475  | Virtual Engineering Lab  | 4 CR  |
| <b>Additive Electives (Election: )</b>                                 |  |       |
|  | <b>- Modules in English Language -</b>   |       |
| M-ETIT-106040  | Digital Twin Engineering   | 4 CR  |
| M-MACH-107190  | Drive System Engineering B: Stationary Machinery                                   | 4 CR  |
| M-MACH-107188  | Innovation2Business – Innovation Strategy in the Industrial Corporate Practice     | 4 CR  |
| M-ETIT-100450  | Software Engineering   | 3 CR  |
| M-ETIT-100537  | Systems and Software Engineering   | 5 CR  |
| M-INFO-107161  | Ubiquitous Computing   | 5 CR  |
| M-MACH-107143  | Validation of Technical Systems  | 4 CR  |
| M-INFO-107113  | Wearable Robotic Technologies  | 4 CR  |
|  | <b>- Modules in German Language -</b>  |       |
| M-ETIT-100466  | Analog Circuit Design  | 4 CR  |
| M-MACH-105968  | Artificial Intelligence in Production  | 8 CR  |
| M-ETIT-100532  | Batteries and Fuel Cells   | 5 CR  |
| M-MACH-106468  | Control of Mobile Machines   | 4 CR  |
| M-MACH-105307  | Data Analytics for Engineers   | 5 CR  |
| M-ETIT-100473  | Digital Circuit Design   | 4 CR  |
| M-MACH-105612  | Dynamics of Electro-Mechanical Systems   | 5 CR  |
| M-ETIT-103264  | Information Fusion   | 4 CR  |
| M-ETIT-100474  | Integrated Systems and Circuits  | 4 CR  |
| M-MACH-107141  | Integrated Product Development   | 18 CR |

|               |  |      |
|---------------|--|------|
| M-MACH-106525 | Introduction to Bionics  | 4 CR |
| M-MACH-107142 | Leadership in Interdisciplinary Teams  | 4 CR |
| M-MACH-102696 | Lightweight Engineering Design   | 4 CR |
| M-MACH-102694 | Machine Dynamics   | 5 CR |
| M-MACH-105107 | Machine Tools and Industrial Handling  | 8 CR |
| M-MACH-107041 | Mobile Machines  | 8 CR |
| M-MACH-105292 | Novel Actuators and Sensors  | 4 CR |
| M-MACH-102702 | Organ Support Systems  | 4 CR |
| M-MACH-107144 | Power Tool Design  | 4 CR |
| M-ETIT-100394 | Practical Aspects of Electrical Drives   | 4 CR |
| M-MACH-102718 | Product Development – Methods of Product Engineering   | 6 CR |
| M-ETIT-104475 | Project Management in the Development of Products for Safety-Critical Applications   | 4 CR |
| M-MACH-105418 | ProVIL - Product Development in a Virtual Idea Laboratory  | 4 CR |
| M-MACH-105332 | Quality Management   | 4 CR |
| M-MACH-106662 | Re:Invent - Revolutionary Business Models as the Basis for Product Innovations   | 4 CR |
| M-MACH-107140 | Strategic Product Development - Identification of Potentials of Innovative Products  | 4 CR |
| M-MACH-100291 | Structural Materials   | 6 CR |
| M-MACH-107189 | Sustainable Product Engineering: Sustainable Product Design - Long-term Business Success with Sustainably Developed Products | 4 CR |

### 4.3 Elective Area in Mechatronics and Information Technology

Credits  
22

#### Election notes

All modules are listed with English titles, regardless of the course language.

To see **English modules with English titles and German modules with German titles** visit the [German website](#).

The primarily mentioned modules (alphabetically ordered) are given in English, the further below mentioned ones in German (alphabetically ordered).

| Elective Area in Mechatronics and Information Technology (Election: ) |   |      |
|---|---|------|
|   | - Modules in English Language -   |      |
| M-ETIT-103802   | Adaptive Optics   | 3 CR |
| M-INFO-107198   | Advanced Artificial Intelligence  | 6 CR |
| M-ETIT-106815   | Advanced Communications Engineering   | 6 CR |
| M-ETIT-106956   | Antennas and Beamforming  | 4 CR |
| M-MACH-107148   | Automotive Vision   | 6 CR |
| M-MACH-106903   | Biologically Inspired Robots  | 3 CR |
| M-ETIT-105616   | Channel Coding: Algebraic Methods for Communications and Storage                    | 3 CR |
| M-MACH-107062   | Combined Cycle Power Plants   | 6 CR |
| M-ETIT-100539   | Communication Systems and Protocols   | 5 CR |
| M-ETIT-106689   | Components of Power Systems   | 3 CR |
| M-MACH-107157   | Computational Fluid Dynamics (CFD) for Energy Technologies                          | 4 CR |
| M-MACH-105296   | Computational Intelligence  | 4 CR |
| M-ETIT-106953   | Cyber-Physical Modeling   | 6 CR |
| M-MACH-107151   | Data-Driven Algorithms in Vehicle Technology  | 4 CR |
| M-MACH-106926   | Decision-Making and Motion Planning for Automated Driving                           | 6 CR |
| M-INFO-107197   | Deep Learning and Neural Networks   | 6 CR |
| M-MACH-107088   | Deep Learning for Engineers   | 6 CR |
| M-ETIT-106040   | Digital Twin Engineering  | 4 CR |
| M-MACH-107190   | Drive System Engineering B: Stationary Machinery                                    | 4 CR |
| M-ETIT-106971   | Electric Drives for E-Mobility  | 4 CR |
| M-ETIT-105394   | Electric Power Transmission & Grid Control  | 6 CR |
| M-ETIT-105883   | Electrocatalysis  | 5 CR |
| M-ETIT-101969   | Energy Storage and Network Integration  | 4 CR |
| M-MACH-107066   | Engineering Materials for the Energy Transition                                     | 4 CR |
| M-ETIT-100566   | Field Propagation and Coherence   | 4 CR |
| M-MACH-107117   | Fundamentals of Combustion II   | 4 CR |
| M-ETIT-100449   | Hardware Modeling and Simulation  | 4 CR |
| M-ETIT-106963   | Hardware Synthesis and Optimization   | 6 CR |
| M-MACH-107089   | Hot Research Topics in AI for Engineering Applications                              | 4 CR |
| M-INFO-107152   | Humanoid Robots - Seminar   | 3 CR |
| M-MACH-107188   | Innovation2Business – Innovation Strategy in the Industrial Corporate Practice      | 4 CR |
| M-ETIT-105461   | Introduction to Automotive and Industrial Lidar Technology                          | 3 CR |
| M-ETIT-106789   | IT/OT-Security Seminar  | 4 CR |
| M-WIWI-105403   | Liberalised Power Markets   | 6 CR |
| M-WIWI-106604   | Machine Learning and Optimization in Energy Systems                                 | 4 CR |
| M-MACH-106457   | Machine Learning for Robotic Systems 1  | 5 CR |
| M-MACH-106652   | Machine Learning for Robotic Systems 2  | 5 CR |
| M-INFO-107169   | Machine Learning - Foundations and Algorithms                                       | 6 CR |
| M-MACH-101923   | Machine Vision  | 8 CR |
| M-MACH-107223   | Magnet Technology of Fusion Reactors  | 4 CR |
| M-MACH-107032   | Mathematical Methods in Fluid Mechanics   | 6 CR |
| M-MACH-107185   | Mechanical Properties of Nanomaterials and Microsystems                             | 4 CR |
| M-ETIT-106672   | Medical Image Processing for Guidance and Navigation                                | 9 CR |
| M-MACH-102714   | Microenergy Technologies  | 4 CR |
| M-ETIT-100535   | Microwave Engineering   | 5 CR |
| M-ETIT-107007   | Microwaves Measurement Techniques<br><i>First usage possible from Apr 01, 2026.</i> | 4 CR |
| M-ETIT-106921   | Modern VLSI Technologies  | 6 CR |
| M-INFO-102555   | Motion in Human and Machine - Seminar   | 3 CR |
| M-ETIT-105604   | Nano- and Quantum Electronics   | 6 CR |
| M-ETIT-100430   | Nonlinear Optics  | 6 CR |

|               |   |      |
|---------------|---|------|
| M-MATH-105831 | Numerical Methods   | 5 CR |
| M-MATH-106972 | Numerical Methods with Programming Practice                               | 6 CR |
| M-ETIT-106974 | Optical Engineering and Machine Vision                                    | 6 CR |
| M-ETIT-100436 | Optical Transmitters and Receivers  | 6 CR |
| M-ETIT-100506 | Optical Waveguides and Fibers   | 4 CR |
| M-ETIT-100531 | Optimization of Dynamic Systems   | 5 CR |
| M-ETIT-104485 | Photonics and Communications Lab  | 6 CR |
| M-MACH-107183 | Polymers in MEMS A: Chemistry, Synthesis and Applications                 | 4 CR |
| M-MACH-107035 | Polymers in MEMS B: Physics, Microstructuring and Applications            | 4 CR |
| M-MACH-107085 | Polymers in MEMS C: Biopolymers and Bioplastics                           | 4 CR |
| M-ETIT-104567 | Power Electronics   | 6 CR |
| M-ETIT-106780 | Practical Tools for Control Engineers                                     | 4 CR |
| M-MACH-107074 | Project Workshop: Automotive Engineering                                  | 6 CR |
| M-ETIT-105606 | Quantum Detectors and Sensors   | 6 CR |
| M-MACH-107165 | Quantum Machines II   | 4 CR |
| M-MACH-107164 | Quantum Machines I  | 4 CR |
| M-ETIT-106955 | Radio-Frequency Electronics   | 6 CR |
| M-INFO-105623 | Reinforcement Learning  | 6 CR |
| M-WIWI-100500 | Renewable Energy-Resources, Technologies and Economics                    | 4 CR |
| M-INFO-107123 | Robotics II - Humanoid Robotics   | 3 CR |
| M-INFO-107130 | Robotics III - Sensors and Perception in Robotics                         | 3 CR |
| M-MACH-106902 | Seminar: Bionic Algorithms and Robot Technologies                         | 3 CR |
| M-ETIT-103447 | Seminar Novel Concepts for Solar Energy Harvesting                        | 3 CR |
| M-ETIT-106899 | Signal Processing Methods   | 6 CR |
| M-ETIT-106675 | Signal Processing with Nonlinear Fourier Transforms and Koopman Operators | 6 CR |
| M-INFO-106504 | Simulation and Optimization in Robotics and Biomechanics                  | 6 CR |
| M-ETIT-100450 | Software Engineering  | 3 CR |
| M-ETIT-100524 | Solar Energy  | 6 CR |
| M-MACH-101924 | Solar Thermal Energy Systems  | 4 CR |
| M-ETIT-103042 | Spaceborne Radar Remote Sensing   | 6 CR |
| M-ETIT-106684 | Superconducting Magnet Technology   | 4 CR |
| M-ETIT-106683 | Superconducting Power Systems   | 4 CR |
| M-ETIT-100537 | Systems and Software Engineering  | 5 CR |
| M-MACH-107219 | Thermal Turbomachines I   | 8 CR |
| M-INFO-107161 | Ubiquitous Computing  | 5 CR |
| M-MACH-107143 | Validation of Technical Systems   | 4 CR |
| M-MACH-101283 | Virtual Engineering A   | 9 CR |
| M-INFO-107113 | Wearable Robotic Technologies   | 4 CR |
| M-ETIT-107147 | Workshop Finite Element Method in Electromagnetics                        | 3 CR |
|               | <b>- Modules in German Language -</b>                                     |      |
| M-MACH-102698 | Actuators and Sensors in Nanotechnology                                   | 4 CR |
| M-ETIT-100466 | Analog Circuit Design   | 4 CR |
| M-MACH-107031 | Analysis Tools for Combustion Diagnostics                                 | 4 CR |
| M-ETIT-100444 | Applied Information Theory  | 6 CR |
| M-MACH-105968 | Artificial Intelligence in Production                                     | 8 CR |
| M-INFO-100826 | Automated Visual Inspection and Image Processing                          | 6 CR |
| M-MACH-100501 | Automotive Engineering I  | 8 CR |
| M-MACH-100502 | Automotive Engineering II   | 4 CR |
| M-MACH-102693 | Automotive Vision   | 6 CR |
| M-ETIT-100400 | Basics of Converter Control   | 3 CR |
| M-MACH-105302 | Basics of Technical Logistics II  | 6 CR |
| M-ETIT-100532 | Batteries and Fuel Cells  | 5 CR |

|               |  |      |
|---------------|--|------|
| M-ETIT-100377 | Battery and Fuel Cells Systems   | 3 CR |
| M-ETIT-100549 | Bioelectric Signals  | 3 CR |
| M-MACH-105484 | BioMEMS - Microfluidic Chipsystems V   | 4 CR |
| M-MACH-100489 | BioMEMS - Microsystems Technologies for Life Sciences and Medicine I                     | 4 CR |
| M-MACH-100490 | BioMEMS - Microsystems Technologies for Life Sciences and Medicine II                    | 4 CR |
| M-MACH-100491 | BioMEMS - Microsystems Technologies for Life Sciences and Medicine III                   | 4 CR |
| M-MACH-105483 | BioMEMS - Microsystemtechnology for Life-Science and Medicine IV                         | 4 CR |
| M-MACH-107059 | Development of Oil-Hydraulic Powertrain Systems  | 4 CR |
| M-MACH-107060 | CO <sub>2</sub> -Neutral Combustion Engines and their Fuels I                            | 4 CR |
| M-MACH-107180 | CO <sub>2</sub> -Neutral Combustion Engines and their Fuels II                           | 5 CR |
| M-MACH-105180 | Continuum Mechanics  | 5 CR |
| M-ETIT-100374 | Control of Linear Multivariable Systems  | 6 CR |
| M-MACH-106468 | Control of Mobile Machines   | 4 CR |
| M-ETIT-105915 | Control of Power-Electronic Systems  | 6 CR |
| M-MACH-105348 | Control Technology   | 4 CR |
| M-MACH-105485 | Current Topics on BioMEMS  | 4 CR |
| M-MACH-105307 | Data Analytics for Engineers   | 5 CR |
| M-INFO-105753 | Deep Learning for Computer Vision I: Basics  | 3 CR |
| M-INFO-105755 | Deep Learning for Computer Vision II: Advanced Topics                                    | 3 CR |
| M-MACH-107055 | Design and Development of Mobile Machines  | 4 CR |
| M-MACH-107082 | Design and Optimization of Conventional and Electrified Automotive Transmissions         | 4 CR |
| M-ETIT-100515 | Design of Electrical Machines  | 5 CR |
| M-MACH-102712 | Design with Plastics   | 4 CR |
| M-MACH-107020 | Development of Automated Production Systems  | 4 CR |
| M-MACH-107078 | Development of Hybrid Powertrains  | 4 CR |
| M-ETIT-105415 | Digital Beam-Forming for Imaging Radar   | 4 CR |
| M-ETIT-100473 | Digital Circuit Design   | 4 CR |
| M-MACH-107045 | Digital Control  | 4 CR |
| M-MACH-105476 | Digitalization of Products, Services & Production  | 4 CR |
| M-ETIT-100361 | Distributed Discrete Event Systems   | 4 CR |
| M-MACH-105800 | Drive Train of Mobile Machines   | 4 CR |
| M-MACH-105612 | Dynamics of Electro-Mechanical Systems   | 5 CR |
| M-MACH-102700 | Dynamics of the Automotive Drive Train   | 4 CR |
| M-MACH-102688 | Elements of Technical Logistics  | 4 CR |
| M-MACH-105015 | Elements of Technical Logistics incl. Project  | 6 CR |
| M-MACH-107139 | Energy Systems I - Renewable Energy  | 4 CR |
| M-MACH-107061 | Energy Topology and Resilience   | 4 CR |
| M-MACH-107160 | Engine Measurement Techniques  | 4 CR |
| M-MACH-105478 | Fabrication Processes in Microsystem Technology  | 4 CR |
| M-MACH-107120 | Flows and Heat Transfer in Energy Technology   | 4 CR |
| M-MACH-105824 | Fundamentals in the Development of Commercial Vehicles                                   | 4 CR |
| M-MACH-102707 | Fundamentals of Combustion I   | 4 CR |
| M-MACH-107150 | Fundamentals of Reactor Safety for the Operation and Dismantling of Nuclear Power Plants | 4 CR |
| M-MACH-102690 | Fundamentals of Energy Technology  | 8 CR |
| M-MACH-107124 | Fusion Technology A  | 4 CR |
| M-MACH-107154 | Fusion Technology B  | 4 CR |
| M-MACH-105288 | Handling Characteristics of Motor Vehicles I   | 4 CR |
| M-MACH-107073 | Handling Characteristics of Motor Vehicles II  | 4 CR |
| M-ETIT-100453 | Hardware/Software Co-Design  | 4 CR |
| M-MACH-102717 | Heat and Mass Transfer   | 4 CR |
| M-MACH-107075 | Heat Pumps   | 4 CR |

|               |   |       |
|---------------|---|-------|
| M-ETIT-105060 | High-Voltage Technology   | 6 CR  |
| M-ETIT-100417 | High-Voltage Test Technique   | 4 CR  |
| M-MACH-107097 | Holistic Approach of Managing Power Plant Operation under Uncertainty and Volatility                                  | 4 CR  |
| M-INFO-100725 | Human Brain and Central Nervous System: Anatomy, Information Transfer, Signal Processing, Neurophysiology and Therapy | 3 CR  |
| M-INFO-100824 | Human-Machine-Interaction in Anthropomatics: Basics   | 3 CR  |
| M-MACH-107158 | Hydrogen and reFuels - Energy Conversion in Combustion Engines  | 4 CR  |
| M-ETIT-103264 | Information Fusion  | 4 CR  |
| M-INFO-100895 | Information Processing in Sensor Networks   | 6 CR  |
| M-MACH-105281 | Information Systems and Supply Chain Management   | 3 CR  |
| M-ETIT-100367 | Information Technology in Industrial Automation Systems   | 3 CR  |
| M-MACH-106514 | Innovation and Project Management in Rail Vehicle Engineering   | 4 CR  |
| M-INFO-100791 | Innovative Concepts for Programming Industrial Robots   | 4 CR  |
| M-MACH-107119 | Innovative Nuclear Systems  | 4 CR  |
| M-ETIT-100457 | Integrated Intelligent Sensors  | 3 CR  |
| M-MACH-107141 | Integrated Product Development  | 18 CR |
| M-ETIT-100474 | Integrated Systems and Circuits   | 4 CR  |
| M-MACH-105109 | International Production Engineering  | 8 CR  |
| M-WIWI-100498 | Introduction into Energy Economics  | 5 CR  |
| M-MACH-106525 | Introduction to Bionics   | 4 CR  |
| M-MACH-102691 | Introduction to Microsystem Technology I  | 4 CR  |
| M-MACH-102706 | Introduction to Microsystem Technology II   | 4 CR  |
| M-MACH-107207 | Introduction to Nanotechnology  | 4 CR  |
| M-MACH-107122 | Introduction to Nuclear Energy  | 4 CR  |
| M-ETIT-100399 | Industrial Circuitry  | 3 CR  |
| M-MACH-105282 | IT-Fundamentals of Logistics: Opportunities for Digital Transformation  | 4 CR  |
| M-MACH-107142 | Leadership in Interdisciplinary Teams   | 4 CR  |
| M-ETIT-100485 | Lighting Engineering  | 4 CR  |
| M-MACH-102696 | Lightweight Engineering Design  | 4 CR  |
| M-INFO-100840 | Localization of Mobile Agents   | 6 CR  |
| M-MACH-105298 | Logistics and Supply Chain Management   | 9 CR  |
| M-MACH-102694 | Machine Dynamics  | 5 CR  |
| M-WIWI-105003 | Machine Learning 1  | 5 CR  |
| M-WIWI-105006 | Machine Learning 2  | 5 CR  |
| M-MACH-105107 | Machine Tools and Industrial Handling   | 8 CR  |
| M-MACH-104984 | Material Flow in Logistic Systems   | 9 CR  |
| M-MACH-102727 | Materials for Lightweight Construction  | 4 CR  |
| M-MACH-107043 | Materials Recycling and Sustainability  | 4 CR  |
| M-MACH-106210 | Mathematical Methods in Continuum Mechanics   | 6 CR  |
| M-MACH-107210 | Mathematical Methods in Hydraulics  | 6 CR  |
| M-MACH-105486 | Micro System Simulation   | 4 CR  |
| M-MACH-100487 | Microactuators  | 4 CR  |
| M-ETIT-100454 | Microsystem Technology  | 3 CR  |
| M-ETIT-100424 | Microwaves Measurement Techniques<br><i>First usage possible until Mar 31, 2026.</i>                                  | 4 CR  |
| M-MACH-107063 | Miniaturized Heat Transfer  | 4 CR  |
| M-MACH-107041 | Mobile Machines   | 8 CR  |
| M-MACH-105308 | Modern Control Concepts I   | 4 CR  |
| M-MACH-105313 | Modern Control Concepts II  | 4 CR  |
| M-MACH-105314 | Modern Control Concepts III   | 4 CR  |
| M-ETIT-100427 | Modern Radio Systems Engineering  | 6 CR  |
| M-ETIT-100371 | Nonlinear Control Systems   | 3 CR  |
| M-MACH-105292 | Novel Actuators and Sensors   | 4 CR  |

|               |  |      |
|---------------|--|------|
| M-MACH-107042 | Nuclear Power and Reactor Technology   | 4 CR |
| M-MACH-107121 | Nuclear Power Plant Technology   | 4 CR |
| M-MACH-107036 | Numerical Fluid Mechanics  | 4 CR |
| M-ETIT-102310 | Optimal Control and Estimation   | 3 CR |
| M-ETIT-100484 | Optoelectronic Measurement Engineering   | 3 CR |
| M-MACH-102702 | Organ Support Systems  | 4 CR |
| M-INFO-100825 | Pattern Recognition  | 6 CR |
| M-ETIT-100513 | Photovoltaics  | 6 CR |
| M-MACH-107064 | Physical Basics of Laser Technology  | 5 CR |
| M-ETIT-100481 | Plasma Sources   | 4 CR |
| M-ETIT-106067 | Power Electronic Systems in Energy Technology  | 6 CR |
| M-ETIT-102261 | Power Electronics for Photovoltaics and Wind Energy<br><i>First usage possible until Sep 30, 2025.</i>                       | 3 CR |
| M-ETIT-100413 | Power Systems and Economy  | 3 CR |
| M-ETIT-106506 | Power System Protection and Automation   | 3 CR |
| M-MACH-107144 | Power Tool Design  | 4 CR |
| M-ETIT-100394 | Practical Aspects of Electrical Drives   | 4 CR |
| M-ETIT-106673 | Practical Machine Learning   | 6 CR |
| M-MACH-105289 | Principles of Whole Vehicle Engineering I  | 2 CR |
| M-MACH-105290 | Principles of Whole Vehicle Engineering II   | 2 CR |
| M-MACH-107087 | Probabilistic Measurement and Estimation   | 4 CR |
| M-MACH-105346 | Product- and Production-Concepts for modern Automobiles  | 4 CR |
| M-MACH-102718 | Product Development – Methods of Product Engineering   | 6 CR |
| M-ETIT-104475 | Project Management in the Development of Products for Safety-Critical Applications   | 4 CR |
| M-MACH-105418 | ProVIL - Product Development in a Virtual Idea Laboratory  | 4 CR |
| M-MACH-107072 | Python Algorithms for Automotive Engineering   | 4 CR |
| M-MACH-105332 | Quality Management   | 4 CR |
| M-MACH-103232 | Rail System Technology   | 4 CR |
| M-MACH-102683 | Rail Vehicle Technology  | 4 CR |
| M-MACH-106513 | Railway System Digitalisation  | 4 CR |
| M-MACH-107044 | Railways in the Transportation Market  | 4 CR |
| M-MACH-106662 | Re:Invent - Revolutionary Business Models as the Basis for Product Innovations   | 4 CR |
| M-MACH-107071 | Reactor Physics  | 4 CR |
| M-MACH-107116 | Reactor Safety 1: Fundamentals   | 4 CR |
| M-ETIT-105916 | Real Time Control of Electrical Drives   | 6 CR |
| M-INFO-100803 | Real-Time Systems  | 6 CR |
| M-MACH-105477 | Seminar Data-Mining in Production  | 3 CR |
| M-ETIT-105629 | Seminar Electrocatalysis   | 3 CR |
| M-ETIT-100455 | Seminar Embedded Systems   | 4 CR |
| M-MACH-104197 | Seminar for Rail System Technology   | 3 CR |
| M-ETIT-106970 | Seminar Industrial Process and Plant Engineering   | 4 CR |
| M-INFO-102212 | Seminar Intelligent Industrial Robots  | 3 CR |
| M-ETIT-100396 | Seminar New Components and Systems of Power Electronics  | 4 CR |
| M-ETIT-100378 | Sensors  | 3 CR |
| M-MACH-107053 | Simulation with Lumped Parameters  | 4 CR |
| M-INFO-100829 | Stochastic Information Processing  | 6 CR |
| M-MACH-107140 | Strategic Product Development - Identification of Potentials of Innovative Products  | 4 CR |
| M-MACH-107189 | Sustainable Product Engineering: Sustainable Product Design - Long-term Business Success with Sustainably Developed Products | 4 CR |
| M-ETIT-106026 | System Integration and Communication Structures in Industry 4.0 and IoT  | 3 CR |
| M-MACH-105315 | System Integration in Micro- and Nanotechnology  | 4 CR |
| M-MACH-105316 | System Integration in Micro- and Nanotechnology 2  | 4 CR |
| M-MACH-105318 | Technical Design in Product Development  | 4 CR |



|   |   |       |
|---|---|-------|
| M-ETIT-100538   | Technical Optics  | 5 CR  |
| M-MACH-102388   | Thermal Solar Energy  | 4 CR  |
| M-MACH-107112   | Thermal-Fluid-Dynamics  | 4 CR  |
| M-MACH-107070   | Tires and Wheel Development for Passenger Cars  | 4 CR  |
| M-MACH-107058   | Tractors  | 4 CR  |
| M-MACH-107056   | Vehicle Drive Technology  | 4 CR  |
| M-MACH-102703   | Vehicle Lightweight Design - Strategies, Concepts, Materials                          | 4 CR  |
| M-MACH-106515   | Vehicle Systems for Urban Mobility  | 4 CR  |
| M-MACH-105293   | Virtual Engineering 1   | 4 CR  |
| M-MACH-105732   | Windpower   | 4 CR  |
| <b>Internship/Lab Course (Election: at most 1 item)</b> |   |       |
| <b>- Modules in English Language -</b>                  |   |       |
| M-MACH-106905   | CAD Engineering Project for Intelligent Systems                                       | 3 CR  |
| M-ETIT-107136   | Communications Engineering Laboratory   | 6 CR  |
| M-ETIT-102266   | Digital Hardware Design Laboratory  | 6 CR  |
| M-ETIT-107138   | Electric Drives and Power Electronics Lab   | 6 CR  |
| M-ETIT-107137   | Electrical Energy Systems Lab   | 6 CR  |
| M-MACH-106830   | Industrial Mobile Robotics Lab  | 4 CR  |
| M-ETIT-106973   | Microwave Engineering Lab   | 6 CR  |
| M-ETIT-105464   | MMIC Design Laboratory  | 6 CR  |
| M-ETIT-100464   | Optical Design Lab  | 6 CR  |
| M-MACH-107034   | Practical Course Polymers in MEMS   | 2 CR  |
| M-INFO-105955   | Practical Course: Smart Energy System   | 6 CR  |
| M-MACH-106904   | Practical Course: Software Development and Application of Mobile, Bio-Inspired Robots | 6 CR  |
| M-INFO-107155   | Robotics - Practical Course   | 6 CR  |
| M-MACH-105725   | Seamless Engineering  | 9 CR  |
| M-ETIT-106633   | Signal Processing Lab   | 6 CR  |
| M-ETIT-105073   | Student Innovation Lab  | 15 CR |
| <b>- Modules in German Language -</b>                   |   |       |
| M-ETIT-100381   | Batteries and Fuel Cells Laboratory   | 6 CR  |
| M-MACH-102684   | CAE-Workshop  | 4 CR  |
| M-MACH-106744   | Cognitive Automobiles - Laboratory  | 6 CR  |
| M-ETIT-105467   | Control Theory Laboratory   | 6 CR  |
| M-ETIT-102264   | Digital Hardware Design Laboratory  | 6 CR  |
| M-MACH-105291   | Lab Computer-Aided Methods for Measurement and Control                                | 4 CR  |
| M-ETIT-100468   | Lab Course on Nanoelectronics   | 6 CR  |
| M-ETIT-100470   | Laboratory FPGA Based Circuit Design  | 6 CR  |
| M-ETIT-100460   | Laboratory in Software Engineering  | 6 CR  |
| M-ETIT-107159   | Laboratory Information Systems in Power Engineering                                   | 6 CR  |
| M-ETIT-103448   | Laboratory Mechatronic Measurement Systems  | 6 CR  |
| M-MACH-102699   | Laboratory Mechatronics   | 4 CR  |
| M-ETIT-100478   | Laboratory Nanotechnology   | 6 CR  |
| M-ETIT-100477   | Laboratory Optoelectronics  | 6 CR  |
| M-ETIT-102350   | Laboratory Solar Energy   | 6 CR  |
| M-MACH-102695   | Motor Vehicle Laboratory  | 4 CR  |
| M-MACH-107145   | Power Tool Design Project Work  | 8 CR  |
| M-MACH-107052   | Practical Course: Autonomous Driving  | 6 CR  |
| M-INFO-105958   | Practical Course: Machine Learning and Intelligent Systems                            | 8 CR  |
| M-ETIT-106673   | Practical Machine Learning  | 6 CR  |
| M-INFO-102224   | Practical Project Robotics and Automation I (Software)                                | 6 CR  |
| M-INFO-102230   | Practical Project Robotics and Automation II (Hardware)                               | 6 CR  |

|               |  |      |
|---------------|--|------|
| M-MACH-105479 | Practical Training in Basics of Microsystem Technology | 4 CR |
| M-MACH-102711 | Production Techniques Laboratory                       | 4 CR |
| M-MACH-106050 | Reliability and Test Engineering                       | 5 CR |
| M-ETIT-100451 | System-on-Chip Laboratory                              | 6 CR |
| M-MACH-105475 | Virtual Engineering Lab                                | 4 CR |

#### 4.4 Interdisciplinary Qualifications

Credits

8

|                  |                                  |      |
|------------------|----------------------------------|------|
| <b>Mandatory</b> |                                  |      |
| M-ETIT-107193    | Interdisciplinary Qualifications | 8 CR |

## 5 Notes on modules and courses

### Level indication for the modules

Level 1 = 1st + 2nd semester Bachelor

Level 2 = 3rd + 4th semester Bachelor

Level 3 = 5th + 6th semester Bachelor

Level 4 = Master

### Versions of modules and courses

This specification provides information about the currently valid version of the module or the course. A new version is generated, for example, if an adjustment of the CR was carried out in the module or course. You will automatically receive the valid version in your curriculum. If you have already started a module, you can complete the module in the version you have started (grandfathering).

### Course type

Describes the type of competence certificate according to the ETIT study and examination regulations § 4. Competence certificates are subdivided into course works or examinations.

**Examinations** are graded

1. written examinations,
2. oral examinations, or
3. examinations of another type

**Course works** are ungraded written, oral, or practical achievements that students usually complete during the course.

### Events (lectures, exercises, tutorials, seminars)

In the chapter "Courses" the corresponding events of the current and the previous semester are shown in tabular form. For modules that are not offered every semester, you will thus receive complete information on the associated courses.

### Registration and admission to module examinations

In order to take module examinations, students must register for the examination online in the [student portal](#).

Registration deadlines for the competence certificates may be set by the examiners. Where elective options exist, students make a binding declaration of module choice when registering for the examination. Upon application of the student to the examination board, the choice or assignment may be changed subsequently. Each module and competence certificate may be assessed only once in the same degree program.

An examination will be passed, if the grade is at least "sufficient" (4.0).

A module will be passed if all required courses are passed.

## 6 Publisher

KIT-Department of Electrical Engineering and Information Technology

KIT-Department of Mechanical Engineering

Karlsruhe Institute of Technology (KIT)

76128 Karlsruhe

<http://www.stg-mit.kit.edu>

### **Deans of Studies:**

Prof. Dr.-Ing. Martin Doppelbauer, [Martin.Doppelbauer@kit.edu](mailto:Martin.Doppelbauer@kit.edu)

Prof. Dr.-Ing. Marcus Geimer, [Marcus.Geimer@kit.edu](mailto:Marcus.Geimer@kit.edu)

**Program Service Master ETIT and MIT**, [master-info@etit.kit.edu](mailto:master-info@etit.kit.edu)

„Altes Maschinenbaugebäude“ (Ehrenhof), Building 10.91, 3<sup>rd</sup> floor, room 223.1

Office hours: [https://www.etit.kit.edu/english/studiengangservice\\_master\\_etit\\_und\\_mit.php](https://www.etit.kit.edu/english/studiengangservice_master_etit_und_mit.php)

Tel.: 0721/608-42469, -47516 oder -42746

### **Module Coordination:**

Dr. Andreas Barth, [modulkoordination@etit.kit.edu](mailto:modulkoordination@etit.kit.edu)

## 7 Modules

### M

## 7.1 Module: Actuators and Sensors in Nanotechnology [M-MACH-102698]

**Responsible:** Prof. Dr. Manfred Kohl  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |   |      |      |
|---------------|---|------|------|
| T-MACH-105238 | <a href="#">Actuators and Sensors in Nanotechnology</a> | 4 CR | Kohl |

### Competence Certificate

oral exam: 45 min

### Prerequisites

keine

### Competence Goal

The students can:

- describe the principles of actuation and sensing and exemplify them
- describe important nano fabrication technologies and assess the influence of process parameters
- illustrate the layout and function of nano actuators and sensors and determine their characteristic properties (time constants, sensitivities, forces, etc.)
- evaluate their suitability for specific applications

### Content

- Physical principles of actuation and sensing
- Scaling and size effects
- Fabrication technologies
- Selected developments
- Applications

The lecture includes amongst others the following topics:

- Nano technologies
- Nano electro mechanical systems (NEMS)
- Nano magneto mechanical and multiferroic systems
- Polymer-based nano actuators
- Nano motors, molecular systems
- Adaptive nano optical systems
- Nanosensors: concepts, materials, fabrication
- Examples on different categories of materials and applications:
  - C-based, MeOx-based nano sensors
  - Physical, chemical, biological nano sensors
- Multivariant data analysis / interpretation

### Module grade calculation

Module grade calculation

The module grade is the grade of the written exam.

**Workload**

|                            |                     |
|----------------------------|---------------------|
| Time of attendance:        | 15 * 1,5 h = 22,5 h |
| Preparation and follow up: | 15 * 5,5 h = 82,5 h |
| Exam Preparation and Exam: | 15 h                |
| Total:                     | 120 h = 4 LP        |

**Recommendation**

The lecture addresses students in the fields of mechanical engineering, mechatronics and information technology, materials science and engineering, physics, electrical engineering and economic sciences. A comprehensive introduction is given in the basics and current developments on the nanoscopic length scale.

**Literature**

- Lecture notes
- 2. Balzani, V., Credi, A., & Venturi, M., Molecular devices and machines: concepts and perspectives for the nanoworld, 2008
- „Nanowires and Nanobelts, - Materials, Properties and Devices -, Volume 2: Nanowires and Nanobelts of Functional Materials“, Edited by Zhong Lin Wang, Springer, 2003, ISBN 10 0-387-28706-X
- „Sensors Based on Nanostructured Materials“, Edited by Francisco J. Arregui, Springer, 2009, ISBN: 978-0-387-77752-8
- “Multivariate Datenanalyse – Methodik und Anwendungen in der Chemie“, R. Henrion, G. Henrion, Springer 1994, ISBN 3-540-58188-X

## M

## 7.2 Module: Adaptive Optics [M-ETIT-103802]

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Dr. Szymon Gladysz<br>Prof. Dr. Ulrich Lemmer   |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 3              | Grade to a tenth     | Each winter term  | 1 term          | English         | 4            | 3              |

|                  |                 |      |                 |
|------------------|-----------------|------|-----------------|
| <b>Mandatory</b> |                 |      |                 |
| T-ETIT-107644    | Adaptive Optics | 3 CR | Gladysz, Lemmer |

**Competence Certificate**

Type of Examination: Oral examination

Duration of Examination: approx. 30 Minutes

Modality of Exam: The oral exam will be scheduled during the semester break.

**Prerequisites**

None.

**Competence Goal**

The students will:

- get familiar with Fourier description of imaging through aberrated optical systems and random media,
- understand the description of aberrations through Zernike modes,
- learn how to analytically compute the effects of turbulence on various optical observables such as image/beam motion, temporal power spectra, Zernike modes, scintillation, etc.,
- understand the effect of noise on various quantities and metrics pertinent to the design of adaptive optical systems,
- understand the advantages and disadvantages of various schemes for wavefront sensing and correction,
- learn how to simulate and design simple adaptive optics systems.

**Content**

Adaptive optics is a technology of correcting the effect of atmospheric turbulence on images of space objects and on laser beams propagating through random and highly aberrated media such as turbulence, tissue, and the inside of the human eye, to name just a few applications. The course will familiarize the students with theoretical basics of light propagation through random media, principles of wavefront sensing and reconstruction, as well as wavefront correction with deformable mirrors. The students will also receive solid introduction to statistical optics, the Kolmogorov theory of turbulence, practical aspects of turbulence simulation and modelling of adaptive optics.

1. Theory of turbulence (covariances, structure functions, power spectra, inertial range, dimensional argument of Kolmogorov)
2. Fourier optics (point-spread function, modulation transfer function)
3. Statistical optics (characteristic function, probability density function)
4. Sources and description of aberrations (Zernike polynomials, orthogonality, Marechal criterion)
5. Adaptive optics systems (open- and closed-loop systems, error budgets, tip-tilt correction)
6. Wavefront sensing (Shack-Hartmann wavefront sensor, wavefront reconstruction, wavefront-sensorless AO)
7. Wavefront correction (tip-tilt mirrors, deformable mirrors, piezoelectric effect, microelectromechanical systems, electrostatic actuation)
8. Simulation of adaptive optical systems (analytic vs. end-to-end modelling)
9. Propagation of laser beams through atmospheric turbulence (Gaussian beams, Rytov theory, scintillation index, beam wander)
10. Modelling of free-space optical communication systems (aperture averaging, mean signal-to-noise ratio, false-alarm rate and fade probability, bit error-rate)

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

total 90 h, hereof 30 h contact hours and 60 h homework and self-studies

**Recommendation**

Basic knowledge of statistics.

**Literature**

Robert K. Tyson, Principles of Adaptive Optics, CRC Press

Michael C. Roggemann, Byron M. Welsh, Imaging through Turbulence, CRC Press



## M

## 7.3 Module: Advanced Artificial Intelligence [M-INFO-107198]

|                      |  |
|----------------------|--|
| <b>Responsible:</b>  | Prof. Dr. Jan Niehues  |
| <b>Organisation:</b> | KIT Department of Informatics  |
| <b>Part of:</b>      | <a href="#">Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – Methodical )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – General)</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – General)</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )</a><br><a href="#">Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)</a> |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 6              | Grade to a tenth     | Each summer term  | 1 term          | English         | 4            | 1              |

|                  |  |      |         |
|------------------|--|------|---------|
| <b>Mandatory</b> |  |      |         |
| T-INFO-114220    | <a href="#">Advanced Artificial Intelligence</a> | 6 CR | Niehues |

**Competence Certificate**

See partial achievements (Teilleistung)

**Prerequisites**

See partial achievements (Teilleistung)

**Competence Goal**

- The students know the relevant elements of a technical cognitive system.
- The students understand the algorithms and methods of AI to model cognitive systems.
- The students are able to understand the different sub-components to develop and analyze a system .
- The students can transfer this knowledge to new applications, as well as analyze and compare different methods.

**Content**

Due to the successes in research, AI systems are increasingly integrated into our everyday lives. These are, for example, systems that can understand and generate language or analyze images and videos. In addition, AI systems are essential in robotics in order to be able to develop the next generation of intelligent robots .

Based on the knowledge of the lecture "Introduction to AI", the students learn to understand, develop and evaluate these systems.

In order to bring this knowledge closer to the students, the lecture is divided into 4 parts. First, the lecture investigates method of perception using different modalities. The second part deals with advanced methods of learning that go beyond supervised learning. Then methods are discussed that are required for the representation of knowledge in AI systems. Finally, methods that enable AI systems to generate content are presented.

**Workload**

Lecture with 3 SWS + 1 SWS exercise , 6 CP.  
 6 LP corresponds to approx. 180 hours, of which  
 approx. 45 hours lecture attendance  
 approx. 15 hours exercise visit  
 approx. 90 hours post-processing and processing of the exercise sheets  
 approx. 30 hours exam preparation

## M

## 7.4 Module: Advanced Communications Engineering [M-ETIT-106815]

**Responsible:** Dr.-Ing. Holger Jäkel

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-113676 | <a href="#">Advanced Communications Engineering</a> | 6 CR | Jäkel |

### Competence Certificate

The assessment takes place in the form of a written examination lasting 120 min,

### Prerequisites

none

### Competence Goal

The students are able to analyze and assess properties of communication systems and consider aspects of implementation. They can use mathematical methods in the context of communication systems for understanding involved derivations in the research literature; deriving and autonomously elaborating theoretical results, and checking their viability by simulations.

### Content

The module is introducing and deriving results covering, but not being limited to, properties of linear modulation, channel description and diversity schemes, and processing of receiver signals, all based on detailed theoretical concepts. Topics already covered in previous modules are deduced thoroughly and mathematical derivations and reasoning are provided.

### Module grade calculation

The module grade is the grade of the written exam.

### Annotation

Starting winter term 25/26

### Workload

1. Attendance to the lecture:  $20 * 1,5 \text{ h} = 30 \text{ h}$
2. Preparation and review:  $20 * 3 \text{ h} = 60 \text{ h}$
3. Attendance to the tutorial:  $6 * 1,5 \text{ h} = 9 \text{ h}$
4. Preparation and review:  $6 * 3,5 \text{ h} = 21 \text{ h}$
5. Preparation for the exam: 60 h

In total: 180 h = 6 LP

### Recommendation

Basics knowledge of communication systems, as, e.g., provided in KIT's Bachelor courses "Grundlagen der Datenübertragung" and "Nachrichtensysteme", is supposed. Furthermore, working knowledge in the areas of system theory and probability theory is assumed.

### Learning type

Lecture: 3 SWS, Exercise: 1 SWS

## M

**7.5 Module: Analog Circuit Design [M-ETIT-100466]**

**Responsible:** Prof. Dr. Ivan Peric  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |                                       |      |       |
|---------------|---------------------------------------|------|-------|
| T-ETIT-100973 | <a href="#">Analog Circuit Design</a> | 4 CR | Peric |

**Annotation**

Will be changed to English in winter term 25/26.

## M

**7.6 Module: Analysis Tools for Combustion Diagnostics [M-MACH-107031]**

**Responsible:** Dr.-Ing. Heiko Kubach  
Jürgen Pfeil

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-MACH-105167 | <a href="#">Analysis Tools for Combustion Diagnostics</a> | 4 CR | Pfeil |

**Competence Certificate**

see individual course

**Competence Goal**

After completing the course, students will be able to

- Design and create optical accesses to combustion engines.
- Model, analyze and evaluate an engine process thermodynamically.
- Name and explain modern methods for analyzing processes in combustion engines and special measurement methods such as optical measurements and laser measurement techniques.
- Differentiate which experimental method is particularly suitable for a specific analysis question due to its advantages and disadvantages.

Translated with DeepL.com (free version)

**Content**

- Pressure indexing
- Energy balance on the engine
- Energy conversion in the combustion chamber
- Thermodynamic models for calculating the energy conversion
- Optical accesses for engines
- Methods for determining flow velocities
- Measurement of flame propagation
- Special measurement methods (2-color method, spectroscopy, LIF,...)

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

(for details see individual course)

## M

**7.7 Module: Antennas and Beamforming [M-ETIT-106956]****Responsible:** Prof. Dr.-Ing. Thomas Zwick**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-113920 | <a href="#">Antennas and Beamforming</a> | 4 CR | Zwick |

**Competence Certificate**

The examination takes place in form of a written examination lasting 120 minutes.

**Prerequisites**

none

**Competence Goal**

After successfully participating in this course, students have in-depth knowledge of antennas, antenna systems and beamforming methods. This includes functionality, calculation methods as well as aspects of practical implementation. They are able to understand how typical electromagnetic radiators work and to develop and dimension them with specified properties. Students understand the principle and function of beamforming and the differences between digital, analog and hybrid beamforming. They know the theory, procedures and algorithms for beamforming. They can understand how beamforming is used for radio communication and radar.

**Content**

The lecture begins with a brief review of the basic knowledge of antennas and antenna arrays from the Bachelor's course. This is followed by a detailed discussion of all major antenna types (functionality, specifics). Furthermore, antenna measurement methods are presented. In the second part, the basic knowledge of noise, radio transmission and radar ambiguities is briefly refreshed, followed by a detailed presentation of the various beamforming algorithms, each with reference to radio communication and radar systems. Aspects such as digital and hybrid beamforming, as well as MIMO and equivalent virtual antenna configuration are explained.

The lecture will be accompanied by exercises. These are discussed in a room exercise and the corresponding solutions are presented in detail.

**Module grade calculation**

The module grade is the grade of the written exam.

**Workload**

The workload includes:

- Attendance study time lecture: 30 h
- Attendance study time exercise: 15 h
- Self-study time including exam preparation: 75 h

A total of 120 h

**Recommendation**

Knowledge of the basics of radio frequency technology and some basic knowledge on communication and radar systems is recommended.

## M

## 7.8 Module: Applied Information Theory [M-ETIT-100444]

**Responsible:** Dr.-Ing. Holger Jäkel

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-100748 | <a href="#">Applied Information Theory</a> | 6 CR | Jäkel |

#### Competence Certificate

The success control takes place in the form of an oral examination lasting 25 minutes. Before the examination, there is a preparation phase of 15 minutes in which preparatory tasks are solved.

#### Prerequisites

none

## M

**7.9 Module: Artificial Intelligence in Production [M-MACH-105968]**

**Responsible:** Prof. Dr.-Ing. Jürgen Fleischer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 8       | Grade to a tenth | Each term  | 2 terms  | German   | 4     | 1       |

| Mandatory     |  |      |           |
|---------------|--|------|-----------|
| T-MACH-112115 | <a href="#">Artificial Intelligence in Production</a>                        | 4 CR | Fleischer |
| T-MACH-112121 | <a href="#">Seminar Application of Artificial Intelligence in Production</a> | 4 CR | Fleischer |

**Competence Certificate**

T-MACH-112115 - Written Exam (90 min)

T-MACH-112121 - Alternative test achievement (graded)

**Prerequisites**

none

**Competence Goal**

The Students understand

- the relevance for the application of artificial intelligence in production and know the main drivers and challenges.
- the CRISP-DM process for implementing AI projects in production.
- the most important methods within the CRISP-DM phases and can theoretically select and practically apply them holistically based on practical issues.

**Content**

The module AI in Production is designed to teach students the practical, holistic integration of machine learning methods in production. The course is oriented towards the phases of the CRISP-DM process with the aim of developing a deep understanding of the necessary steps and content-related aspects (methods) within the individual phases. In addition to teaching the practical aspects of integrating the most important machine learning methods, the focus is primarily on the necessary steps for data generation and data preparation as well as the implementation and validation of the methods in an industrial environment. The focus of the module is on the practical teaching of the contents, based on production engineering issues. The necessary theoretical basics are taught in the course "Lecture AI in Production". In the course "Project internship Application of AI in Production", practice-relevant architectures of machine learning are used to solve current practical problems in the production environment. The implementation here is also oriented to the phases of the CRISP-DM.

**Module grade calculation**

The overall grade for the module is calculated from the LP-weighted grades of the partial examinations and cut off after the first decimal place.

**Workload**

**Artificial Intelligence in Production**

***MACH:***

regular attendance: 31,5 hours

self-study: 88,5 hours

***WING:***

regular attendance: 31,5 hours

self-study: 118,5 hours

**Seminar Application of Artificial Intelligence in Production**

regular attendance: 21 hours

self-study: 99 hours

**Learning type**

Lecture, Seminar



**M****7.10 Module: Automated Visual Inspection and Image Processing (24169) [M-INFO-100826]****Responsible:** Prof. Dr.-Ing. Jürgen Beyerer**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-INFO-101363 | <a href="#">Automated Visual Inspection and Image Processing</a> | 6 CR | Beyerer |

## M

**7.11 Module: Automotive Engineering I [M-MACH-100501]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 8       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-MACH-100092 | <a href="#">Automotive Engineering I</a> | 8 CR | Gießler |

**Competence Certificate**

written exam; duration approximately 2 hours

**Prerequisites**

Only one out of the two moduls "M-MACH-100501 - Grundlagen der Fahrzeugtechnik I" and "M-MACH-102686 - Automotive Engineering I" is allowed.

**Competence Goal**

The students know the movements and the forces at the vehicle and are familiar with active and passive security. They have proper knowledge about operation of engines and alternative drives, the necessary transmission between engine and drive wheels and the power distribution, so that they can apply their knowledge effectively in actual practise. They have an overview of the components necessary for the drive and have the basic knowledge, to analyze, to judge and to develop the complex system "vehicle".

**Content**

The module provides an overview of:

1. History and future of the automobile
2. Driving mechanics: driving resistances and driving performances, mechanics of the longitudinal and transverse forces, passive safety
3. Engines: combustion engine, alternative drives (e.g. electric motor, fuel cell)
4. Transmission: clutches (e.g. friction clutch, visco clutch), transmission (e.g. mechanical transmission, hydraulic fluid transmission)
5. Power transmission and distribution: drive shafts, cardon joints, differentials

**Workload**

1. regular attendance lecture:  $15 * 2 * 2 \text{ h} = 60 \text{ h}$
  2. pre and post processing lecture:  $15 * 2 * 3 \text{ h} = 90 \text{ h}$
  3. examination preparation and presence in examination: 90 h
- In total: 240 h = 8 LP

**Literature**

1. Mitschke, M./ Wallentowitz, H.: Dynamik der Kraftfahrzeuge, Springer-Verlag, Berlin, 2004
2. Braes, H.-H.; Seiffert, U.: Handbuch Kraftfahrzeugtechnik, Vieweg&Sohn Verlag, 2005
3. Gnadler, R.: Script to the lecture 'Automotive Engineering I'

## M

## 7.12 Module: Automotive Engineering II [M-MACH-100502]

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
Dr.-Ing. Martin Gießler

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-MACH-102117 | <a href="#">Automotive Engineering II</a> | 4 CR | Gießler |

**Competence Certificate**

Written exam; duration approximately 1,5 h

**Prerequisites**

none

**Competence Goal**

The students have an overview of the modules, which are necessary for the road holding of a motor vehicle and the power transmission between vehicle bodywork and roadway. They have knowledge of different wheel suspensions, the tyres, the steering elements and the brakes. They know different execution forms, the function and the influence on the driving or brake behavior. They can apply their knowledge effectively in actual practise. They are able to develop the appropriate components correctly. They are ready to analyze, to judge and to optimize the complex relationship of the different components under consideration of boundary conditions.

**Content**

The module provides an overview of:

1. Chassis: Wheel suspensions (rear axles, front axles, kinematics of axles), tyres, springs, damping devices
2. Steering elements: Manual steering, servo steering, steer by wire
3. Brakes: Disc brake, drum brake, comparison of the designs

**Workload**

1. regular attendance lecture:  $15 * 2 \text{ h} = 30 \text{ h}$
2. pre and postprocessing lecture:  $15 * 3 \text{ h} = 45 \text{ h}$
3. examination preparation and presence in examnation: 45 h

In total: 120 h = 4 LP

**Literature**

1. Heiing, B./Ersoy, M.: Fahrwerkhandbuch: Grundlagen, Fahrdynamik, Komponenten, Systeme, Mechatronik, Perspektiven, Vieweg-Verlag, Wiesbaden, 2011
2. Breuer, B./Bill, K.-H.: Bremsenhandbuch: Grundlagen - Komponenten - Systeme - Fahrdynamik, Vieweg-Verlag, Wiesbaden, 2012
3. Gnadler, R.: Script to the lecture 'Automotive Engineering II'

## M

## 7.13 Module: Automotive Vision [M-MACH-107148]

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Dr. Martin Lauer<br>Prof. Dr.-Ing. Christoph Stiller  |
| <b>Organisation:</b> | KIT Department of Mechanical Engineering  |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |                   |      |                |
|---------------|-------------------|------|----------------|
| T-MACH-114149 | Automotive Vision | 6 CR | Lauer, Stiller |

**Competence Certificate**

Type of Examination: written exam

Duration of Examination: 60 minutes

**Prerequisites**

none

**Competence Goal**

After having participated in the lecture the participants have gained knowledge on modern techniques of signal processing and artificial intelligence which can be used to evaluate video sequences, to relate the image content to a spatial context and to interpret the content semantically. This comprises, binocular reconstruction, recognition of movements in video sequences, state space modeling and Bayesian filters, and the recognition of road surfaces and object behavior. The participants have learned to analyze the algorithms mathematically, to implement them in software, and to apply them to tasks in autonomous driving and mobile robots. The participants are able to analyze problems in the areas mentioned before and to develop appropriate solutions.

**Content**

Sensory detection and interpretation of the environment form the basis for generating intelligent behavior. The ability to see opens up completely new perspectives for vehicles and represents a rapidly growing field of research and innovation in automotive technology. The first so-called driver assistance systems have already achieved respectable improvements in terms of comfort, safety and efficiency. However, it will probably take several decades of intensive research before automobiles have a performance comparable to the human visual system.

The lecture is aimed at students of mechanical engineering and related courses, who wish to acquire an interdisciplinary qualification. It provides a holistic overview of the field of vehicle vision, from the basics of image acquisition and kinematic vehicle models to innovative metrological methods of image processing for seeing vehicles. The derivation of metrological methods of image processing is deepened and illustrated using current, practice-relevant application examples.

**Module grade calculation**

see individual course

**Workload**

180 hours

composed out of

hours of lecture:  $15 \cdot 3 \text{ h} = 45 \text{ h}$

preparation time prior to and after lecture:  $15 \cdot 5 \text{ h} = 75 \text{ h}$

exam preparation and exam: 60 h

**Learning type**

Lecture

**Literature**

TBA

## M

**7.14 Module: Automotive Vision [M-MACH-102693]**

**Responsible:** Dr. Martin Lauer  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 2       |

| Mandatory     |                                   |      |                |
|---------------|-----------------------------------|------|----------------|
| T-MACH-105218 | <a href="#">Automotive Vision</a> | 6 CR | Lauer, Stiller |

**Competence Certificate**

Type of Examination: written exam

Duration of Examination: 60 minutes

**Prerequisites**

none

**Competence Goal**

After having participated in the lecture the participants have gained knowledge on modern techniques of signal processing and artificial intelligence which can be used to evaluate video sequences, to relate the image content to a spatial context and to interpret the content semantically. This comprises, binocular reconstruction, recognition of movements in video sequences, state space modeling and Bayesian filters, and the recognition of road surfaces and object behavior. The participants have learned to analyze the algorithms mathematically, to implement them in software, and to apply them to tasks in autonomous driving and mobile robots. The participants are able to analyze problems in the areas mentioned before and to develop appropriate solutions.

**Content**

Machine perception and interpretation of the environment forms the basis for the generation of intelligent behavior. Especially visual perception opens the door to novel automotive applications. Driver assistance systems already improve safety, comfort and efficiency in vehicles. Yet, several decades of research will be required to achieve an automated behavior with a performance equivalent to a human operator. The lecture addresses students in mechanical engineering and related subjects who intend to get an interdisciplinary knowledge in a state-of-the-art technical domain. Machine vision and advanced information processing techniques are presented to provide a broad overview on seeing vehicles. Application examples from cutting-edge and future driver assistance systems illustrate the discussed subjects. The lecture consists out of 2 hours/week of lecture and 1 hour/week of computer exercises. In the computer exercises methods introduced in the lecture will be implemented in MATLAB and tested experimentally.

**Workload**

180 hours

composed out of

hours of lecture:  $15 \cdot 3 \text{ h} = 45 \text{ h}$

preparation time prior to and after lecture:  $15 \cdot 5 \text{ h} = 75 \text{ h}$

exam preparation and exam: 60 h

**Learning type**

Lecture

**Literature**

TBA

## M

## 7.15 Module: Basics of Converter Control [M-ETIT-100400]

**Responsible:** Dr.-Ing. Andreas Liske

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-100717 | <a href="#">Basics of Converter Control</a> | 3 CR | Liske |

**Prerequisites**

none

## M

**7.16 Module: Basics of Technical Logistics II [M-MACH-105302]****Responsible:** Prof. Dr.-Ing. Kai Furmans**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 3       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-MACH-109920 | <a href="#">Basics of Technical Logistics II</a> | 6 CR | Furmans |

**Competence Certificate**

The assessment consists of an oral or a written exam according to Section 4 (2), 1 or 2 of the examination regulation.

**Prerequisites**

none

**Competence Goal**

The student is able to

- describe and design processes and process networks in intralogistics,
- model and analyse the material flow between processes,
- describe material flow elements and apply them in a systematic way,
- check material flow elements for their safety.

**Content**

The aim of this lecture is to give an overview of the three major topics of technical logistics:

- Processes in intralogistic systems
- Technology of technical logistics
- Organization and control of intralogistic processes

Using the example of an intralogistics system, the various topics are presented over the course of the lecture period, so that students are in the end able to understand and describe such an overall system in detail.

**Workload**

Attendance: 36 hours

Rework: 114 hours

**Recommendation**

Basics knowledge of technical logistics I is preconditioned

**Learning type**

Lectures



## M

**7.17 Module: Batteries and Fuel Cells [M-ETIT-100532]**

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Ulrike Krewer  |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 5              | Grade to a tenth     | Each winter term  | 1 term          | German          | 4            | 2              |

|                  |                          |      |        |
|------------------|--------------------------|------|--------|
| <b>Mandatory</b> |                          |      |        |
| T-ETIT-100983    | Batteries and Fuel Cells | 5 CR | Krewer |

**Competence Certificate**

Success is assessed in the form of a written examination lasting 120 minutes

**Prerequisites**

none

**Competence Goal**

Students gain an understanding of the structure and mode of operation of batteries and fuel cells. They acquire in-depth knowledge of materials, construction concepts, measurement methods, measurement data analysis and modeling, which gives them a practical insight into current areas of application and research topics of electrochemical energy storage and conversion (fuel cells). They are able to communicate with specialists from related disciplines in the field of batteries and fuel cells and can actively contribute to the opinion-forming process in society with regard to energy technology issues.

**Content**

Fuel cells and batteries used in innovative energy and environmental technology applications will be covered. The course is divided into three sections. Firstly, the basics of thermodynamics, electrochemistry and the lossy mass transport processes involved in energy conversion are discussed. The second section deals with the structure and functional principle of fuel cells and presents the most important approaches to electrical characterization and modelling. Applications in mobile and stationary systems in transportation and energy technology are discussed. The third section deals with electrochemical energy storage systems, with a focus on high-performance batteries for electric traction. Developments to increase energy density and power density are presented here, as well as the electrical characterization and modelling of batteries.

**Module grade calculation**

The module grade is the grade of the written examination.

**Annotation**

Will be changed to 6 CR in winter term 25/26 an provided in English.

**Workload**

1. lecture attendance time:  $15 * 2 \text{ h} = 30 \text{ h}$
2. Preparation and follow-up time for lecture:  $15 * 6 \text{ h} = 90 \text{ h}$
3. Exercise attendance time:  $5 * 2 \text{ h} = 10 \text{ h}$
4. Preparation and follow-up time for exercise:  $5 * 4 \text{ h} = 20 \text{ h}$
5. Exam preparation and attendance: included in preparation and follow-up time.

Total: 150 h = 5 CP

## M

## 7.18 Module: Batteries and Fuel Cells Laboratory [M-ETIT-100381]

**Responsible:** Dr.-Ing. Andre Weber

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Internship/Lab Course \)](#)

[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Internship/Lab Course \)](#)

[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German/English | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-100708 | <a href="#">Batteries and Fuel Cells Laboratory</a> | 6 CR | Weber |

**Prerequisites**

none

## M

## 7.19 Module: Battery and Fuel Cells Systems [M-ETIT-100377]

**Responsible:** Dr.-Ing. Andre Weber

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-100704 | <a href="#">Battery and Fuel Cells Systems</a> | 3 CR | Weber |

## M

## 7.20 Module: Bioelectric Signals [M-ETIT-100549]

**Responsible:** Dr.-Ing. Axel Loewe

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |                                     |      |       |
|---------------|-------------------------------------|------|-------|
| T-ETIT-101956 | <a href="#">Bioelectric Signals</a> | 3 CR | Loewe |

### Competence Certificate

The success control is carried out as part of a written test of 90 minutes.

### Prerequisites

none

### Module grade calculation

The module grade is the grade of the written exam. The submission of the workshop tasks is a prerequisite for taking the written exam. If there is a very good oral discussion of the workshop tasks, 5 points can be earned for each of the two workshop parts (from 100). The bonus points are only taken into account if the exam is passed. Bonus points do not expire and are retained for examinations that may be taken at a later date. The final assessment of the bonus performance is carried out by the examiner and is documented.

### Workload

Attendance time lecture:  $8 * 1.5h = 12h$

Preparation / follow-up lecture:  $8 * 1h = 8h$

Workshop tasks:  $20h + 15h = 35h$

Exam preparation and attendance in the same: 35h

Total: 90h

### Recommendation

Knowledge of the basics of signal processing and physiology is helpful.

Fundamentals of linear electrical networks, Fourier transformation as well as differential equations and systems of linear equations and numerical solution methods

## M

## 7.21 Module: Biologically Inspired Robots [M-MACH-106903]

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Arne Rönnau  |
| <b>Organisation:</b> | KIT Department of Mechanical Engineering  |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 3              | Grade to a tenth     | Each summer term  | 1 term          | English         | 4            | 2              |

| Mandatory     |                              |      |        |
|---------------|------------------------------|------|--------|
| T-MACH-113856 | Biologically Inspired Robots | 3 CR | Rönnau |

**Competence Certificate**

See partial achievement

**Prerequisites**

None

**Competence Goal**

Students are familiar with various design principles of the "bionics" method in robotics and can analyze and evaluate models for kinematics, mechanics, control, perception and cognition.

Students understand the lightweight construction concepts and material properties of natural models. They are familiar with the concepts and methods of lightweight robotics and can describe the resulting effects on the energy efficiency of mobile robot systems.

Students can distinguish between different natural muscle types and how they function. They also know the corresponding artificial muscle systems and can derive the underlying muscle model.

Students know the most important human senses and the associated stimulus processing and information coding. They can derive technological sensors that perform the same function in robotics.

Students can differentiate the function of a central pattern generator (CPG) from a reflex. They can theoretically derive neuro-oscillators and explain how they control the movement of a robot. Furthermore, they can generate walking patterns for six-legged robots based on the "Cruse rules".

Students can distinguish between different types of locomotion and suitable stability criteria for walking movements. They know the most important walking patterns for multi-legged walking robots and can represent these in a gait diagram.

Students know the most important algorithms for machine learning methods and can explain their advantages and disadvantages in robotics.

Students know the subsumption system architecture and can evaluate the advantages of a reactive system architecture. They can combine "behaviors" for biologically inspired robots into behavior networks.

Students can apply Mendel's laws and explain the differences between meiosis and mitosis. They can also explain the basic genetic algorithm.

Students can identify the greatest challenges in the development of innovative, humanoid robot systems and are familiar with possible solutions and successful implementations.

**Content**

The lecture biologically inspired robots deals intensively with robots whose mechanical design, sensor concepts or control architecture were inspired by nature. In detail, we will look at solutions from nature (e.g. lightweight construction concepts using honeycomb structures, human muscles) and then at robot technologies that utilize these principles to solve similar tasks (lightweight 3D printed parts or artificial muscles in robotics).

After discussing these biologically inspired technologies, concrete robotic systems and applications from current research that successfully utilize these technologies will be presented. In particular, multi-legged walking robots, snake-like and humanoid robots are presented and their sensor and drive concepts are discussed.

The lecture focuses on the concepts of control and system architectures (e.g. behavior-based systems) of these robotic systems, with locomotion being the main focus. The lecture ends with an outlook on future developments and the development of commercial applications for these robots.

**Workload**

90 working hours, of which approx:

- 30h for attendance time in lectures
- 30h for preparation and follow-up time
- 30h for exam preparation and participation in the oral exam

## M

## 7.22 Module: BioMEMS - Microfluidic Chipsystems V [M-MACH-105484]

**Responsible:** Prof. Dr. Andreas Guber  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German/English | 4     | 1       |

| Mandatory     |  |      |               |
|---------------|--|------|---------------|
| T-MACH-111069 | <a href="#">BioMEMS - Microfluidic Chipsystems V</a> | 4 CR | Guber, Rajabi |

**Competence Certificate**

Oral exam (20 min)

**Prerequisites**

none

**Competence Goal**

The students master the basics of microfluidics. They are able to develop, manufacture and test microfluidic systems in an application-oriented manner. They master applications such as Lab-on-chip, Organ-on-chip, Body-on-chip.

**Content**

Introduction in microtechnical production processes and biomaterials. Detailed application examples from the fields of lab-on-chip, organ-on-chip and body-on-chip.

**Workload**

Literature: 19 h

Lessions: 21 h

Preparation and Review: 50 h

Exam preparation: 30 h

**Learning type**

Lecture

**Literature**

Menz, W., Mohr, J., O. Paul: Mikrosystemtechnik für Ingenieure, VCH-Verlag, Weinheim, 2005

M. Madou

Fundamentals of Microfabrication

Taylor & Francis Ltd.; Auflage: 3. Auflage. 2011

## M

## 7.23 Module: BioMEMS - Microsystems Technologies for Life Sciences and Medicine I [M-MACH-100489]

**Responsible:** Prof. Dr. Andreas Guber

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-100966 | <a href="#">BioMEMS - Microsystems Technologies for Life-Sciences and Medicine I</a> | 4 CR | Guber |

### Competence Certificate

Written exam (75 min)

### Prerequisites

none

### Competence Goal

The lecture will first address relevant microtechnical manufacturing methods. Then, selected biomedical applications will be presented, as the increasing use of microstructures and microsystems in Life-Sciences und in medicine leads to improved medico-technical products, instruments, and operation and analysis systems.

### Content

Introduction into various microtechnical manufacturing methods: LIGA, Micro milling, Silicon Micromachining, Laser Microstructuring,  $\mu$ EDM, Metal-Etching  
 Biomaterials, Sterilisation.

Examples of use in the life science sector: basic micro fluidic structures: micro channels, micro filters, micromixers, micropumps, microvalves, Micro and nanotiter plates, Microanalysis systems ( $\mu$ TAS),  
 Lab-on-chip applications.

### Workload

Literature: 20 h

Lessions: 21 h

Preparation and Review: 50 h

Exam preparation: 30 h

### Literature

Menz, W., Mohr, J., O. Paul: Mikrosystemtechnik für Ingenieure, VCH-Verlag, Weinheim, 2005

M. Madou

Fundamentals of Microfabrication

Taylor & Francis Ltd.; Auflage: 3. Auflage. 2011



## M

## 7.24 Module: BioMEMS - Microsystems Technologies for Life Sciences and Medicine II [M-MACH-100490]

**Responsible:** Prof. Dr. Andreas Guber

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-MACH-100967 | <a href="#">BioMEMS - Microsystems Technologies for Life-Sciences and Medicine II</a> | 4 CR | Guber |

### Competence Certificate

Written exam (75 min)

### Prerequisites

None

### Competence Goal

The lecture will first shortly address some relevant microtechnical manufacturing methods. Then, selected biomedical applications will be presented, as the increasing use of microstructures and microsystems in Life-Sciences und in medicine leads to improved medico-technical products, instruments, and operation and analysis systems.

### Content

Examples of use in Life-Sciences and biomedicine: Microfluidic Systems:

LabCD, Protein Crystallisation

Microarrays

Tissue Engineering

Cell Chip Systems

Drug Delivery Systems

Micro reaction technology

Microfluidic Cells for FTIR-Spectroscopy

Microsystem Technology for Anesthesia, Intensive Care and Infusion

Analysis Systems of Person's Breath

Neurobionics and Neuroprosthesis

Nano Surgery

### Workload

Literature: 20 h

Lessions: 21 h

Preparation and Review: 50 h

Exam preparation: 30 h

### Literature

Menz, W., Mohr, J., O. Paul: Mikrosystemtechnik für Ingenieure, VCH-Verlag, Weinheim, 2005

Buess, G.: Operationslehre in der endoskopischen Chirurgie, Band I und II;

Springer-Verlag, 1994

M. Madou

Fundamentals of Microfabrication

## M

**7.25 Module: BioMEMS - Microsystems Technologies for Life Sciences and Medicine III [M-MACH-100491]****Responsible:** Prof. Dr. Andreas Guber**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-100968 | <a href="#">BioMEMS - Microsystems Technologies for Life-Sciences and Medicine III</a> | 4 CR | Guber |

**Competence Certificate**

Written exam (75 min)

**Prerequisites**

none

**Competence Goal**

The lecture will first shortly address some relevant microtechnical manufacturing methods. Then, selected biomedical applications will be presented, as the increasing use of microstructures and microsystems in Life-Sciences und in medicine leads to improved medico-technical products, instruments, and operation and analysis systems.

**Content**

Examples of use in minimally invasive therapy  
 Minimally invasive surgery (MIS)  
 Endoscopic neurosurgery  
 Interventional cardiology  
 NOTES  
 OP-robots and Endosystems  
 License of Medical Products and Quality Management

**Workload**

Literature: 20 h  
 Lessons: 21 h  
 Preparation and Review: 50 h  
 Exam preparation: 30 h

**Literature**

Menz, W., Mohr, J., O. Paul: Mikrosystemtechnik für Ingenieure, VCH-Verlag, Weinheim, 2005  
 Buess, G.: Operationslehre in der endoskopischen Chirurgie, Band I und II; Springer-Verlag, 1994  
 M. Madou  
 Fundamentals of Microfabrication

## M

## 7.26 Module: BioMEMS - Microsystemtechnology for Life-Science and Medicine IV [M-MACH-105483]

**Responsible:** Prof. Dr. Andreas Guber

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German/English | 4     | 1       |

| Mandatory     |   |      |               |
|---------------|---|------|---------------|
| T-MACH-106877 | <a href="#">BioMEMS - Microsystems Technologies for Life-Sciences and Medicine IV</a> | 4 CR | Ahrens, Guber |

### Competence Certificate

Oral exam (20 min)

### Prerequisites

none

### Competence Goal

The students get to know selected areas of application in the life sciences. They will be able to design and develop novel products for different fields of application in the life sciences, as well as implement them in production technology.

### Content

Examples from the life science sector: biosensor technology, microfluidic basic structures and systems, micro-assembly, medical implants, micro-process engineering, optofluidics, medical products law.

### Workload

Literature: 19 h

Lessions: 21 h

Preparation and Review: 50 h

Exam preparation: 30 h

### Literature

Menz, W., Mohr, J., O. Paul: Mikrosystemtechnik für Ingenieure, VCH-Verlag, Weinheim, 2005

M. Madou

Fundamentals of Microfabrication

Taylor & Francis Ltd.; Auflage: 3. Auflage. 2011

## M

**7.27 Module: CAD Engineering Project for Intelligent Systems [M-MACH-106905]****Responsible:** Prof. Dr.-Ing. Arne Rönnau**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each term  | 1 term   | English  | 4     | 2       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-113857 | <a href="#">CAD Engineering Project for Intelligent Systems</a> | 3 CR | Rönnau |

**Competence Certificate**

See partial achievement

**Prerequisites**

None

**Competence Goal**

Students are able to use CAD tools for design and 3D printing as a manufacturing process for intelligent systems such as biologically inspired robots.

**Content**

In this design project, students work in small groups using an agile approach to develop an innovative mechatronic component that meets previously defined requirements for an intelligent system.

To this end, students get to know a current CAD development environment and learn how to design the corresponding parts. The typical design and development process is followed from the idea to the finished model. The focus is on independent solution finding, teamwork, (robotic) functional fulfillment, 3D printing and manufacturing and biologically inspired design. The project results are presented at the end of the semester.

**Workload**

90h

- Initial design / idea of a (biologically inspired) mechatronic component: 15h
- Construction using CAD system and overall system design: 30h
- 3D printing, assembly, integration of electronics and functional tests: 30h
- Documentation and report: 5h
- Meetings: Kickoff, interim and final presentation and discussions as well as meetings with supervisors: 10h

## M

**7.28 Module: CAE-Workshop [M-MACH-102684]**

**Responsible:** Prof. Dr.-Ing. Tobias Düser  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 3       |

| Mandatory     |                              |      |       |
|---------------|------------------------------|------|-------|
| T-MACH-105212 | <a href="#">CAE-Workshop</a> | 4 CR | Düser |

**Competence Certificate**

Written examination (with practical part on the computer), duration 60 min

**Prerequisites**

None

**Competence Goal**

The students are able to ...

- name the purposes and limits of numerical simulation and optimization of the virtual product development.
- solve simple realistic tasks in the field of finite element analysis and structure optimization with industrial common software.
- evaluate and to question the results of a simulation.
- identify and improve the mistakes of a simulation or optimization.

**Content**

- introduction to the finite element analysis (FEA)
- stress and modal analysis of finite element models using Abaqus/CAE as a preprocessor and Abaqus solver
- introduction to topology and shape optimization
- creation and calculation of various optimization models with the optimization package of Abaqus

**Workload**

regular attendance: 31.5 h

self-study: 88,5 h

independent work with different software tools (supported by tutors and assistants)

discussing and presenting results in small groups

**Learning type**

Seminar

**Literature**

The workshop script will be allocated at Ilias.

## M

## 7.29 Module: Channel Coding: Algebraic Methods for Communications and Storage [M-ETIT-105616]

**Responsible:** Prof. Dr.-Ing. Laurent Schmalen

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-ETIT-111244 | <a href="#">Channel Coding: Algebraic Methods for Communications and Storage</a> | 3 CR | Schmalen |

### Competence Certificate

*The exam is held as an oral exam of approx. 20 min.*

### Competence Goal

*The students are able to analyse and assess problems of algebraic channel coding. They can apply methods of algebraic coding theory in the context of communication systems for data transmission and data storage and are able to assess their implementation. Additionally, they will get knowledge to current research topics and research results.*

### Content

*This course focuses on the formal and mathematical basics for the design of coding schemes in digital communication systems. These include schemes for data transmission, data storage and networking. The course starts by introducing the necessary fundamentals of algebra which are then used to derive codes for different applications. Besides codes that are important for data transmission applications, e.g., BCH and Reed-Solomon-Codes, we also investigate codes for the efficient storage and reconstruction of data in distributed systems (locally repairable codes) and codes that increase the throughput in computer networks (network codes). Real applications are always given to discuss practical aspects and implementations of these coding schemes. Many of these applications are illustrated by example code in software (python/MATLAB).*

### Module grade calculation

*Grade of the module corresponds to the grade of the oral exam.*

### Workload

1. Attendance to the lecture:  $15 * 2 h = 30 h$
2. Preparation and review:  $15 * 4 h = 60 h$
3. Preparation for the exam: included in preparation and review
4. In total:  $90 h = 3 LP$

### Recommendation

*Knowledge of basic engineering as well as basic knowledge of communications engineering.*

*Previous attendance of the lectures "Communication Engineering I" and "Probability Theory" is recommended.*

## M

**7.30 Module: CO2-Neutral Combustion Engines and their Fuels I [M-MACH-107060]****Responsible:** Prof. Dr. Thomas Koch**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |      |
|---------------|--|------|------|
| T-MACH-111550 | <a href="#">CO2-Neutral Combustion Engines and their Fuels I</a> | 4 CR | Koch |

**Competence Certificate**

oral exam, approx. 20 min.

**Competence Goal**

Students can explain the principle of an internal combustion engine. They can name and describe different engine concepts and their fuels and explain the difference between the concepts. They can analyze the engine concepts and evaluate them with regard to specific areas of application.

**Content**

- Introduction
- Principle of the internal combustion engine
- Characteristic parameters
- Components of the combustion engine
- Crank mechanism
- Fuels: Overview, properties
- reFuels and hydrogen: production, processes, potentials
- Conventional gasoline engine
- Conventional diesel engine
- Hydrogen engines
- Ammonia engines
- Methanol engines
- Diesel engines in HVO operation

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120 h

(for details see individual course)

## M

**7.31 Module: CO2-Neutral Combustion Engines and their Fuels II [M-MACH-107180]****Responsible:** Prof. Dr. Thomas Koch**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |   |      |      |
|---------------|---|------|------|
| T-MACH-111560 | <a href="#">CO2-Neutral Combustion Engines and their Fuels II</a> | 5 CR | Koch |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

The students can:

- Name, describe and explain boost systems
- Analyze engine maps
- Evaluate emissions and select suitable aftertreatment systems
- Explain the processes of transient operation and application
- Describe electrification and alternative drives

**Content**

- Boosting and air management
- Engine maps
- Exhaust emissions
- Exhaust gas aftertreatment
- Transient engine operation / Emission & application
- Application
- Electrification and alternative drives

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

150h

(for details see individual course)



## M

**7.32 Module: Cognitive Automobiles - Laboratory [M-MACH-106744]**

**Responsible:** Dr. Martin Lauer  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |                |
|---------------|--|------|----------------|
| T-MACH-105378 | <a href="#">Cognitive Automobiles - Laboratory</a> | 6 CR | Lauer, Stiller |

**Competence Certificate**

see partial performance

**Prerequisites**

none

**Competence Goal**

After attending the course, participants will be familiar with modern technologies in the field of automated driving and will be able to use them independently. This includes techniques for recording the vehicle environment and vehicle control. Furthermore, students will be able to organize an automation project in a project team and carry it out independently.

**Content**

The course is designed as an interactive laboratory in which the participants independently develop a technical solution for the automation of a model vehicle. The work is carried out in small groups, which design and implement their technical solution together. At the end of the semester, the technical solution is evaluated as part of a race.

The technical tasks to be solved include

- the development of a camera-based environment detection system
- the development of behavior and trajectory planning
- the development of a vehicle control system

The development is carried out in the programming language C++ within the robot control environment ROS (robot operating system).

In addition to solving the technical tasks, each small group must also organize its project collaboration. This includes

- the development of a project plan
- structuring the collaboration within the group
- presenting the interim and final results
- developing a technical concept for solving the task at hand

At the beginning of the course, participants are taught basic knowledge of programming in C++, the robot control environment ROS, software version management and structured programming in software projects in several tutorials.

**Module grade calculation**

The module grade is the grade of the oral examination of the partial performance.

**Annotation**

The number of participants is limited to 20. If necessary, a selection procedure will be carried out. Places will be allocated according to prior knowledge. Details will be announced on the course homepage (ILIAS).

**Workload**

180 hours, of which

Attendance time during the presentations and meetings: 15 h

Follow-up of the content presented in the presentations: 15 h

Independent development of the contents of the lab in the form of research, programming, testing and creating presentations: 135 h

Exam preparation and presentation: 15 h

**Recommendation**

It is recommended to attend the courses Vehicle Vision or Behavior Generation for Vehicles before or at the same time. Programming skills in C++ are an advantage.

It is recommended to register early for the course.

## M

**7.33 Module: Combined Cycle Power Plants [M-MACH-107062]****Responsible:** Prof. Dr.-Ing. Daniel Banuti**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |                     |
|---------------|---|------|---------------------|
| T-MACH-105444 | <a href="#">Combined Cycle Power Plants</a>                     | 4 CR | Banuti, Schulenberg |
| T-MACH-105445 | <a href="#">Simulator Exercises Combined Cycle Power Plants</a> | 2 CR | Banuti, Schulenberg |

**Competence Certificate**

oral

Duration approx. 30 minutes

**Prerequisites**

We recommend to combine the lecture with the Simulator Exercises for Combined Cycle Power Plants (T-MACH-105445).

**Competence Goal**

On this basis, they can describe and analyze the specific behavior of the power plant components as well as the entire power plant in the grid. Participants in the lecture have a trained analytical thinking and judgment in power plant design.

**Content**

Layout of a combined cycle power plant, design and operation of gas turbines, of the heat recovery steam generator, of the feedwater system and cooling systems. Design and operation of steam turbines, of the generator and its electrical systems. System response to challenging grids, protection systems, water make-up and water chemistry. Design concepts of different power plant manufacturers, innovative power plant concepts.

**Module grade calculation**

see individual courses

**Workload**

180h

Attendance time. 60h

Self-study: 120h

## M

**7.34 Module: Communication Systems and Protocols [M-ETIT-100539]**

**Responsible:** Dr.-Ing. Jens Becker  
Prof. Dr.-Ing. Jürgen Becker

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |                |
|---------------|---|------|----------------|
| T-ETIT-101938 | <a href="#">Communication Systems and Protocols</a> | 5 CR | Becker, Becker |

**Competence Certificate**

The examination consists of a written examination of 120 min.

**Prerequisites**

none

**Competence Goal**

The students are able to:

- know basic communication systems and to name them
- categorize different communication systems in regards to possible constraints
- name basic mechanisms of communication systems
- carry out these mechanisms
- choose valid mechanisms suitable under given constraints
- design a communication system adhering to constraints, specifications and be able to choose suitable methods, components, and subsystems
- know current communication systems and know about their properties, mechanisms and application.

**Content**

The lecture will present the physical and technical basics for the design and construction of communication systems. Procedures and technical implementations for communication between electronic devices are presented. This includes, among other things, modulation methods, line model, arbitration, synchronization mechanisms, error correction mechanisms, multiplexing, communication systems, bus systems and on-chip communication. On the basis of selected practical examples, the application of the lecture contents in real systems is demonstrated.

- Information: Definition, Representation, Communication
- Physics: Media, Signals, Mathematical Descriptions, Line Coupling & Termination, AD Conversion & Sampling, Line Codes, Modulation
- Data Transmission: Definition & Requirements, Transmission Channels, MultiUse of Channels, Multiplexing, Multiple Senders (Arbitration), Multiple Receivers (Addressing), Classification, Interfaces
- Bus Systems: Definitions, Protocols, Transmission of Dataframes, Classification
- Error Protection: Fundamentals, Errors, Error Detection/Correction: Error Handling
- Topologies: physical, logical, examples
- Networks: networks vs. busses, structure, Network specific topologies, routing, OSI Model, TCP/IP, Ethernet
- Classification of Com.Systems
- Real World Systems: Automotive Busses, PC Busses, Field Busses, Networks

**Module grade calculation**

The module grade is the grade of the written exam.

**Workload**

The workload includes:

1. Attendance in 15 lectures and 7 exercises: 33 h
2. Preparation / follow-up: 66 h (2 h per unit)
3. Preparation of and attendance in examination: 24 h + 2 h

A total of 125 h = 5 LP

## M

**7.35 Module: Communications Engineering Laboratory [M-ETIT-107136]****Responsible:** Dr.-Ing. Holger Jäkel**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)**Credits**  
6**Grading scale**  
Grade to a tenth**Recurrence**  
Each term**Duration**  
1 term**Language**  
German/English**Level**  
4**Version**  
1

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-114159 | <a href="#">Communications Engineering Laboratory</a> | 6 CR | Jäkel |

**Competence Certificate**

The examination consists of the participation in the experiments and an oral examination. The overall impression is rated.

**Prerequisites**

none

**Competence Goal**

Students are able to apply methods of signal processing and communications engineering in the implementation of communication systems.

They are able to carry out communications engineering calculations and use the tools required for simulations methodically and appropriately. This enables students to classify the components involved in a communication system in terms of their performance and to understand their interaction in an overall system.

**Content**

The practical course consists of 11 experiments and covers the following topics:

Introduction to Python, DFT, the sampling theorem, filter design and multirate filters, stochastic signals, digital modulation methods, source coding, channel coding, GNU Radio and Software Defined Radio, OFDM, synchronization algorithms and optimization.

**Module grade calculation**

The module grade results of the participation in the experiments and an oral examination. Details will be given during the lecture.

**Annotation**

Attendance is compulsory during all laboratory sessions, including the introductory session. Compulsory attendance is necessary both for carrying out the work in the team on site and for the practical teaching of techniques and skills that cannot be learned in pure self-study

**Workload**

- Attendance time practical course:  $11 * 4 \text{ h} = 44 \text{ h}$
  - Lecture preparation and follow-up:  $11 * 8 \text{ h} = 88 \text{ h}$
  - Exam preparation and attendance of exam: 48 h
- Total: 180 h

**Recommendation**

Previous attendance of the lectures "Signals and Systems" and "Communications Engineering I".

## M

## 7.36 Module: Components of Power Systems [M-ETIT-106689]

**Responsible:** Prof. Dr.-Ing. Thomas Leibfried

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |           |
|---------------|---|------|-----------|
| T-ETIT-113445 | <a href="#">Components of Power Systems</a> | 3 CR | Leibfried |

#### Competence Certificate

The examination takes place in form of an oral examination lasting approx. 20 minutes.

#### Prerequisites

none

#### Competence Goal

Students know the main components of electrical networks and how they interact. Students understand the structure of cable systems in AC and DC voltage technology. The procedure for insulation coordination and overvoltage protection in the high-voltage grid is introduced. They will be able to reproduce key relationships. Students are familiar with the future challenges and trends for selected components and transmission technologies of electrical grids.

## Content

- Substations
  - o Types of Substations
  - o Basic Requirements and Standardization
  - o Air Insulated Switchgears
  - o Gas Insulated Switchgears
- Principle of Inductive Equipments
  - o Magnetic Field in an Iron Circuit
  - o Basic Design of Transformers
- Transformers
  - o Overview
  - o Design and Components of Power Transformers and Reactors
- Overhead Transmission Lines
  - o Development of overhead lines system voltages
  - o Grid Development with OVH Transmission Lines
  - o Parts of an Overhead Line
  - o Comparison DC and AC OVH Transmission Lines
  - o Effects of OHL on Environment
- Cables
  - o Development of Cable Lines System Voltages
  - o Grid Development with cable systems
  - o Parts of Cables Systems
  - o Comparison DC and AC Cables Systems
  - o Offshore Cables Systems
  - o Effects of Cables on Environment
- Insulation Arresters
  - o Insulation Coordination
  - o Surge Arresters
- Circuit Breaker and Disconnectors
  - o Circuit Breakers
  - o Disconnectors
- Power Cable Accessories and Power Line Monitoring
  - o Accessories
  - o Power Line Monitoring
- Application of Power Electronics in Power System
  - o Development of Power Electronics
  - o Fundamental Principles of PE
  - o Application of PE in Power System
- Energy Innovation and Trends

## Module grade calculation

The module grade is the grade of the oral exam.

## Workload

The workload includes:

1. attendance in lectures: 30 h
2. preparation / follow-up and preparation of and attendance in examination: 60 h

A total of 90 h = 3 CR



## M

**7.37 Module: Computational Fluid Dynamics (CFD) for Energy Technologies [M-MACH-107157]****Responsible:** Dr. Ivan Otic**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |      |
|---------------|---|------|------|
| T-MACH-114187 | <a href="#">CFD for Power Engineering</a> | 4 CR | Otic |

**Competence Certificate**

Exam is oral (approx. 30 min)

**Prerequisites**

none

**Competence Goal**

At the completion of this course, students

- are able to understand fundamentals of non-linear partial differential equations.
- get working knowledge of computational techniques that can be used for solving engineering heat and mass transfer problems
- are able to understand fundamentals of statistical fluid mechanics and to derive RANS transport equations
- have learned how to computationally solve turbulent heat and mass transfer problems using Open-FOAM software
- are able to present their results in form of technical report.

**Content**

CFD Project:

- Part of this class is performing CFD simulations of turbulent heat and mass transfer using opensource CFD software OpenFOAM.
- After CFD analysis is completed students have to write a technical report.
- Projects are to be performed individually or in teams, but every student writes his own technical report.
- The technical report is part of the final examination.

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

The work load is 120 hours, corresponding to 4 credit points.

## M

## 7.38 Module: Computational Intelligence [M-MACH-105296]

|                      |  |
|----------------------|--|
| <b>Responsible:</b>  | apl. Prof. Dr. Ralf Mikut<br>apl. Prof. Dr. Markus Reischl   |
| <b>Organisation:</b> | KIT Department of Mechanical Engineering   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 4              | Grade to a tenth     | Each winter term  | 1 term          | German          | 4            | 1              |

| Mandatory     |                            |      |                              |
|---------------|----------------------------|------|------------------------------|
| T-MACH-105314 | Computational Intelligence | 4 CR | Meisenbacher, Mikut, Reischl |

**Competence Certificate**

see individual course

**Prerequisites**

None

**Competence Goal**

The students are able to apply the fundamental methods of computational intelligence (fuzzy logic, artificial neural networks, evolutionary algorithms) efficiently. They know the basic mathematical foundations and are able to transfer these methods to practical applications.

**Content**

- Terms and definitions Computational Intelligence, application fields and examples
- Fuzzy logic: fuzzy sets; fuzzification and membership functions; inference: T-norms and -conorms, operators, aggregation, activation, accumulation; defuzzification methods, structures for fuzzy control
- Artificial Neural Nets: biology of neurons, Multi-Layer-Perceptrons, Radial-Basis-Function nets, Kohonen maps, training strategies (Backpropagation, Levenberg-Marquardt)
- Evolutionary Algorithms: Basic algorithm, Genetic Algorithms and Evolution Strategies, Evolutionary Algorithm GLEAM, integration of local search strategies, memetic algorithms, application examples
- Deep Learning: History, Architectures, Training strategies, Interpretability and Explainable AI, Use Cases

**Module grade calculation**

The module grade is the grade of the written examination.

**Workload**

The work load is about 120 hours, corresponding to 4 credit points.

**Learning type**

Lecture

## M

## 7.39 Module: Continuum Mechanics [M-MACH-105180]

**Responsible:** Prof. Dr.-Ing. Thomas Böhlke  
Prof. Dr.-Ing. Bettina Frohnafel

**Organisation:**

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |   |      |                   |
|---------------|---|------|-------------------|
| T-MACH-110377 | <a href="#">Continuum Mechanics of Solids and Fluids</a>          | 4 CR | Böhlke, Frohnafel |
| T-MACH-110333 | <a href="#">Tutorial Continuum Mechanics of Solids and Fluids</a> | 1 CR | Böhlke, Frohnafel |

### Competence Certificate

written exam, 90 min. The tutorials T-MACH-110333 are prerequisites to the exam.

### Prerequisites

none

### Competence Goal

After having finished this module the students can list principles of continuum mechanics of solids and fluids. They can apply methods of tensor calculus and analysis in the framework of Continuum Mechanics for concrete examples and name numerical concepts for solving problems in modelling solids and/or fluids. Moreover, the students are able to solve problems in modelling solids and/or fluids using commercial software codes.

### Content

This module aims to teach students the theoretical and practical aspects of continuum mechanics of solids and liquids. At the beginning there is an introduction to tensor calculus and kinematics. Then the balance equations of mechanics and thermodynamics are treated. The module gives an overview of the material theory of solids and fluids. This also includes the field equations for solids and fluids. Beyond thermomechanical couplings, the module imparts knowledge in dimensional analysis.

### Annotation

none

### Workload

1. Attendance lecture and tutorials:  $15 * 2 \text{ h} + 15 * 2 \text{ h} = 60 \text{ h}$
2. Preparation and recap of lecture and tutorials:  $15 * 3 \text{ h} = 45 \text{ h}$
3. Exam preparation and presence during exam: 45 h

### Recommendation

none

### Learning type

Lecture, tutorial, consultation hours

### Literature

see contained bricks

## M

## 7.40 Module: Control of Linear Multivariable Systems [M-ETIT-100374]

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Sören Hohmann  |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology   |
| <b>Part of:</b>      | <a href="#">Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – Methodical )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – General)</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – Methodical )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – General)</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – Methodical )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – General)</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Additive Electives )</a><br><a href="#">Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)</a> |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 6              | Grade to a tenth     | Each winter term  | 1 term          | German          | 4            | 1              |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-100666 | <a href="#">Control of Linear Multivariable Systems</a> | 6 CR | Kluwe |

**Competence Certificate**

Success is checked as part of a written overall test (120 minutes) of the course.

**Prerequisites**

none

**Competence Goal**

- The students first acquired basic knowledge of the various forms of description of linear multivariable systems in the frequency and time domain with both time-continuous and time-discrete models.
- In particular, they are able to transform multi-size systems in the state space to different normal forms depending on the requirements.
- The students have an understanding of fundamental properties such as Stability, trajectory profiles, controllability and observability as well as pole / zero configuration are achieved and the systems can analyze them accordingly.
- You master the basic principles for controlling linear multi-variable systems both in the frequency domain (series decoupling) and in the time domain (pole specification with pre-filter)
- In concrete terms, the students are familiar with the design procedures modal control, decoupling control in the time domain and the complete modal synthesis.
- You are familiar with the problem of state quantity determination by state observers and the design of complete and reduced observers.
- Students are able to use advanced concepts such as output feedback and dynamic controllers if necessary.
- You can continue to counter the problems of high model orders in the state space by reducing the order based on the dominance analysis.

**Content**

The aim is to impart basic and advanced methods for the treatment of linear multi-size systems, the focus being on the state space. In this way, the students are introduced to a model that allows more modern and, in particular, non-linear processes. On the one hand, the module provides a comprehensive overview of the most important aspects in the variable description of the systems and the analysis of their characteristic properties. On the other hand, all facets of the synthesis of regulations for initial and permanent disorders and the observers often required for this are conveyed.

**Module grade calculation**

The module grade is the grade of the written exam.

**Workload**

The workload includes:

Attendance time in lecture / exercise (3 + 1 SWS: 60h = 2 CP)

Preparation / follow-up lecture / exercise (90h = 3 CP)

Preparation / attendance time written exam (30h = 1 CP)

**Recommendation**

For a deeper understanding, basic knowledge of system dynamics and control technology is absolutely necessary, as taught in the ETIT Bachelor module "System Dynamics and Control Technology" M-ETIT-102181.

## M

**7.41 Module: Control of Mobile Machines [M-MACH-106468]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |                |
|---------------|--|------|----------------|
| T-MACH-111820 | <a href="#">Control of Mobile Machines – Prerequisites</a> | 0 CR | Becker, Geimer |
| T-MACH-111821 | <a href="#">Control of Mobile Machines</a>                 | 4 CR | Becker, Geimer |

**Competence Certificate**

oral exam

**Prerequisites**

Programming skills

**Competence Goal**

Students learn the theoretical principles of data communication and the architecture of control systems in mobile machinery. They will also be able to identify influences and general conditions in use and derive practical and legal requirements for sensors and control systems. The students learn methods of machine learning for control and regulation tasks in mobile machines as well as their structure and the handling of training data. After participating in the exercise, they will be able to implement, train and validate a control system for a task.

**Content**

- Basics of sensors, controllers and control architectures in mobile machinery.
- Basics and functionalities of data communication in mobile machines (CAN-Bus, PROFIBUS, Ethernet, ...)
- Legal basis and general conditions (SIL level, ...)
- Requirements for sensors when used in mobile machines for different control tasks
- Introduction to machine learning methods and their application for the control of mobile machines
- Overview of current research and developments in the field of agricultural robotics
- Practical implementation of the lecture content by working on an assignment in the associated exercise.
- The results of the assignment will be summarized in a short report as a pre-requisite for the exam.

**Module grade calculation**

The module grade corresponds to the grade of the oral examination from T-MACH-111821 "Control of mobile machines".

**Annotation**

Basic knowledge of electrical engineering and computer science is recommended. First programming skills, preferably in Python, are necessary. The number of participants is limited, as hardware will be provided for the exercise. Prior registration is required, details will be announced on the web pages of the Institute of Vehicle Systems Engineering / Department of Mobile Machinery. In case of high registration numbers exceeding the capacities, a selection among all interested persons will take place according to qualification.

**Workload**

Attendance: 60h, Self-study: 60h

## M

## 7.42 Module: Control of Power-Electronic Systems [M-ETIT-105915]

**Responsible:** Dr.-Ing. Andreas Liske  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-111897 | <a href="#">Control of Power-Electronic Systems</a> | 6 CR | Liske |

**Prerequisites**  
none

## M

**7.43 Module: Control Technology [M-MACH-105348]**

**Responsible:** Hon.-Prof. Dr. Christoph Gönheimer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |                                    |      |           |
|---------------|------------------------------------|------|-----------|
| T-MACH-105185 | <a href="#">Control Technology</a> | 4 CR | Gönheimer |

**Competence Certificate**

Written Exam (60 min)

**Prerequisites**

None

**Competence Goal**

The students ...

- are able to name the electrical controls which occur in the industrial environment and explain their function.
- can explain fundamental methods of signal processing. This involves in particular several coding methods, error protection methods and analog to digital conversion.
- are able to choose and to dimension control components, including sensors and actors, for an industrial application, particularly in the field of plant engineering and machine tools. Thereby, they can consider both, technical and economical issues.
- can describe the approach for projecting and writing software programs for a programmable logic control named Simatic S7 from Siemens. Thereby they can name several programming languages of the IEC 1131.

**Content**

The module control technology gives an integral overview of available control components within the field of industrial production systems.

The first part of the module deals with the fundamentals of signal processing and with control peripherals in the form of sensors and actors which are used in production systems for the detection and manipulation of process states.

The second part handles with the function of electric control systems in the production environment. The main focus in this chapter is laid on programmable logic controls, computerized numerical controls and robot controls. Finally the module ends with the topic of cross-linking and decentralization with the help of bus systems.

The module is very practice-oriented and illustrated with numerous examples from different branches.

The following topics will be covered:

- Signal processing
- Control peripherals
- Programmable logic controls
- Numerical controls
- Controls for industrial robots
- Distributed control systems
- Field bus
- Trends in the area of control technology

**Workload**

regular attendance: 21 hours

self-study: 99 hours

**Learning type**

Lecture



## M

**7.44 Module: Control Theory Laboratory [M-ETIT-105467]****Responsible:** Prof. Dr.-Ing. Sören Hohmann**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-ETIT-111009 | <a href="#">Control Theory Laboratory</a> | 6 CR | Hohmann |

**Prerequisites**

None

## M

**7.45 Module: Current Topics on BioMEMS [M-MACH-105485]**

**Responsible:** Prof. Dr. Andreas Guber  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language       | Level | Version |
|---------|------------------|------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German/English | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-MACH-102176 | <a href="#">Current Topics on BioMEMS</a> | 4 CR | Guber |

**Competence Certificate**

Active participation and own presentation (30 Min.).

**Prerequisites**

none

**Competence Goal**

The students are able to work on medical-technical or biological topics. They learn the medical and biological basics and are able to transfer them to engineering sciences and find novel technical solutions.

**Content**

Topics: Minimally invasive surgery, interventional cardiology, implants, biomaterials, sterilization techniques, microanalysis systems

**Workload**

Literature: 19 h

Lessions: 21 h

Preparation and Review: 50 h

Exam preparation: 30 h

**Learning type**

Project Work

**Literature**

Menz, W., Mohr, J., O. Paul: Mikrosystemtechnik für Ingenieure, VCH-Verlag, Weinheim, 2005

M. Madou

Fundamentals of Microfabrication

Taylor & Francis Ltd.; Auflage: 3. Auflage. 2011

## M

**7.46 Module: Cyber-Physical Modeling [M-ETIT-106953]**

|                      |  |
|----------------------|--|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Mike Barth<br>Prof. Dr.-Ing. Sören Hohmann  |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology  |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |                         |      |                |
|---------------|-------------------------|------|----------------|
| T-ETIT-113908 | Cyber-Physical Modeling | 6 CR | Barth, Hohmann |

**Competence Certificate**

The examination takes place in the form of a written examination lasting 90 min.

**Prerequisites**

none

**Competence Goal**

- The students are familiar with the concepts of Cyber-Physical System.
- Students understand the need for advanced methods and services in the field of automation.
- Students can validate different information models and ontologies for their applicability in CPS.
- Students will be able to model data, information and knowledge or extract them from existing systems.
- The students know suitable modeling tools and their application.
- The students understand the general model concept as well as the characteristics of physical and data-based modeling and can describe their differences.
- They can structure complex systems and systematically analyze dependencies of subsystems.
- They can explain the general procedure of physical and data-based modeling, apply it to technical systems, and analyze the results.
- They can apply causal and non-causal modeling approaches and distinguish between them.
- Students have gained an understanding of generalized, cross-domain, physical relationships and can develop models for electrical, mechanical, pneumatic and hydraulic systems.
- They can describe the relationship between generalized, cross-domain, physical models and basic procedures of physical-based control and explain their advantages / limitations based on basic knowledge of control engineering.
- The students can estimate and judge the effects of disturbances and real conditions on the identification results.

**Content**

This course aims at engineering students that focus on a system-based engineering curriculum, including architectures, modeling & simulation for Cyber Physical Systems. The module is designed to teach students the theoretical and practical aspects of Digital Twins and their interconnection with their physical counterpart. It encompasses fundamental topics along the complete process of modeling technical systems. For this purpose, it includes the conception and construction of digital twins including their model components. In terms of modeling and simulation of physical systems, two major areas will be covered: On the one hand, physical-based modeling techniques which derive formal model equations based on analyzing the physical first-principles of technical systems. This includes, inter alia, generalized equivalent circuits, bond graphs, port-Hamiltonian systems, variational analysis (Euler-Lagrange of the first kind). Selected topics of physical-based control methods will also be briefly introduced to integrate the complete physical control design in the wider control context and highlight its possible benefits. On the other hand, data-based identification techniques will be covered which are used to identify concrete model parameters for a given technical system from experimental data sets. When combining the identification with an initial, non-physical, structural set up of model equations, the complete process is often referred to as data-based modeling or black-box modeling. Both modeling areas base on available information about the physical system which is structured in Meta- and Information-Models. Examples that are covered in this lecture are Metamodels, e.g. AutomationML or the asset administration shell principles. Also, semantic web principles and ontologies will be part of the lecture content.

**Module grade calculation**

The module grade is the grade of the written exam.

**Workload**

1. attendance in lectures and exercise: 3+1 SWS (60 h)
2. pre-/postprocessing of the lecture (90 h)
3. preparation of and attendance in the exam: (30 h)

A total of 180 h = 6 CR

**Recommendation**

Interest in Modeling and Simulation of modern Cyber-Physical Systems in combination with concepts of digital twins, system architectures and Co-Simulation.

Sound understanding of engineering mechanics, electrical, mechatronic systems / physics / Software-Engineering should be fulfilled to successfully attend the lecture, exercise tasks / case studies, and exam.

## M

## 7.47 Module: Data Analytics for Engineers [M-MACH-105307]

**Responsible:** apl. Prof. Dr. Ralf Mikut

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |                              |
|---------------|--|------|------------------------------|
| T-MACH-105694 | <a href="#">Data Analytics for Engineers</a> | 5 CR | Meisenbacher, Mikut, Reischl |

### Competence Certificate

A performance assessment is obligatory and can be oral, a written exam, or of another kind.

### Prerequisites

None

### Competence Goal

The students are able to apply the methods of data analysis efficiently. They know the basic mathematical data mining foundations for the analysis of single features and time series using classifiers, clustering and regression approaches. They are able to use various relevant methods as Bayes classifiers, Support Vector Machines, decision trees, fuzzy rulebases and they can adapt application scenarios (with data preprocessing and validation techniques) to real-world applications.

### Content

- Introduction and motivation
- Terms and definitions (types of multidimensional features - time series and images, problem classes)
- Scenario: Problem formulation, feature extraction, evaluation, selection and transformation, distance measures, Bayes classifiers, Support-Vector-Machines, decision trees, clustering, regression, validation
- Biweekly computer exercises (Software practice with SciXMiner and Python): Data import, benchmark datasets, control of hand prostheses, energy prediction

### Workload

The work load is about 150 hours, corresponding to 5 credit points.

### Learning type

Lecture

## M

**7.48 Module: Data-Driven Algorithms in Vehicle Technology [M-MACH-107151]**

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Dr.-Ing. Martin Gießler<br>Dr.-Ing. Stefan Scheubner  |
| <b>Organisation:</b> | KIT Department of Mechanical Engineering  |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 4              | Grade to a tenth     | Each winter term  | 1 term          | English         | 4            | 1              |

| Mandatory     |  |      |           |
|---------------|--|------|-----------|
| T-MACH-112126 | <a href="#">Data-Driven Algorithms in Vehicle Technology</a> | 4 CR | Scheubner |

**Competence Certificate**

written exam, 90 min

**Prerequisites**

none

**Competence Goal**

Goal of the Course: Students have a basic understanding of data-driven algorithms such as Markov Models, Machine Learning or Monte-Carlo Methods. The approach for building data-driven models in automobile technology are known to students and they are able to test algorithms in the programming language "Python". Furthermore, students have learnt how to analyse the algorithm performance.

**Content**

Course Syllabus:

Motivation for the Course: Nowadays, engineers often develop technical systems using a combination of hard- and software. This is true especially for modern passenger vehicle development. In a digitalized world, such developments are built on knowledge gained from relevant data sources, e.g. the vehicle sensors. Therefore, engineers in automobile technology need qualifications from data science to successfully create new functionalities in the cars. To prevent remaining purely theoretical, the algorithms in this course are explained using a real-world problem of "EV Routing". Students have the opportunity to test methods in Python with frequent exercises presented.

Content:

1. Introduction to function development as well as the prerequisites for the course (e.g. Fundamentals for running Python code)
2. Fundamentals for EV Routing and relevant data sources
3. Parameter estimation and state classification algorithms to determine the current situation of the vehicle
4. Learning methods for driver behaviour
5. Forecast algorithms to predict future energy consumption of an electric vehicle

**Module grade calculation**

see individual course

**Workload**

120h

(for details see individual course)

## M

**7.49 Module: Decision-Making and Motion Planning for Automated Driving [M-MACH-106926]**

**Responsible:** Dr.-Ing. Maximilian Naumann  
apl. Prof. Dr. Moritz Werling

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |                  |
|---------------|---|------|------------------|
| T-MACH-113597 | <a href="#">Decision-Making and Motion Planning for Automated Driving</a> | 6 CR | Naumann, Werling |

**Competence Certificate**

Written exam, duration 60 minutes.

**Prerequisites**

None

**Competence Goal**

After successful completion of the course, students will be familiar with both foundational and modern methods in driver assistance, decision-making, and motion planning within the field of automated driving. They will learn how to develop intelligent systems capable of making safe and reliable real-time decisions. Participants will be able to analyze complex scenarios and driving environments and create algorithmic solutions based on their analyses. Additionally, they will gain the skills to theoretically analyze these methods, implement them in software, and apply them to current challenges in vehicle automation.

**Content**

Automated driving is rapidly evolving from basic assistance systems, like ABS and ESP, to advanced autonomous systems that will reshape how we interact with vehicles. The future of driving lies in the seamless integration of advanced technologies that take over tasks such as steering, braking, and acceleration, providing new standards of safety and comfort.

This course explores the exciting transition from driver support to full vehicle automation, focusing on how intelligent systems can make real-time decisions to ensure smooth, safe, and predictable driving even in complex, uncertain environments. Along the way, it introduces AI-driven techniques like reinforcement learning and imitation learning, which are key to enhancing decision-making capabilities. If you're passionate about cutting-edge automotive technology and want to understand how vehicles of tomorrow will think, plan, and navigate, this course will give you the tools to dive into the world of autonomous driving.

**Workload**

180 hours

**Recommendation**

Basic knowledge of control engineering and systems theory should be available from "Measurement and Control Systems" or from other lectures.

## M

## 7.50 Module: Deep Learning and Neural Networks [M-INFO-107197]

**Responsible:** Prof. Dr. Jan Niehues

**Organisation:** KIT Department of Informatics

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-INFO-114219 | <a href="#">Deep Learning and Neural Networks</a> | 6 CR | Niehues |

#### Competence Certificate

See partial achievements (Teilleistung)

#### Prerequisites

See partial achievements (Teilleistung)

#### Competence Goal

Students will learn about the structure and function of different types of neural networks.

Students should learn the methods for training the various networks and their application to problems.

Students should learn the areas of application of the different types of networks.

Given a concrete scenario, students should be able to select the appropriate type of neural network.

#### Content

This module introduces the use of neural networks for the solution of solving various problems in the field of machine learning, such as classification, prediction, control or inference. or inference. Different types of neural networks are covered and their areas of application are illustrated using examples.

#### Workload

180h.

#### Recommendation

Prior successful completion of the core module "Cognitive Systems" is recommended.



## M

## 7.51 Module: Deep Learning for Computer Vision I: Basics [M-INFO-105753]

**Responsible:** Prof. Dr.-Ing. Rainer Stiefelhagen

**Organisation:** KIT Department of Informatics

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German/English | 4     | 1       |

| Mandatory     |   |      |              |
|---------------|---|------|--------------|
| T-INFO-111491 | <a href="#">Deep Learning for Computer Vision I: Basics</a> | 3 CR | Stiefelhagen |

### Competence Goal

Students should be able to grasp the underlying concepts in the field of deep learning and its various applications.

- Understand the theoretical basis of deep learning
- Understand the Convolutional Neural Networks (CNN)
- Develop basis for the concepts and algorithms used in building and training the CNNs.
- Able to apply deep learning in different computer vision applications.

### Content

In recent years tremendous progress has been made in analysing and understanding image and video content. The dominant approach in Computer Vision today are deep learning approaches, in particular the usage of Convolutional Neural Networks.

The lecture introduces the basics, as well as advanced aspects of deep learning methods and their application for a number of computer vision tasks. The following topics will be addressed in the lecture:

- Introduction to Deep Learning
- Convolutional Neural Networks (CNN): Background
- CNNs: basic architectures and learning algorithms
- Object Recognition with CNN
- Image Segmentation with CNN
- Recurrent Neural Networks
- Generating image descriptions (Image Captioning)
- Automatic question answering (Visual Question Answering)
- Generative Adversarial Networks (GAN) and their applications
- Deep Learning platforms and tools

### Annotation

The course is partially given in German and English.

**M****7.52 Module: Deep Learning for Computer Vision II: Advanced Topics [M-INFO-105755]****Responsible:** Prof. Dr.-Ing. Rainer Stiefelhagen**Organisation:** KIT Department of Informatics**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

|                     |  |                                       |                           |                                   |                   |                     |
|---------------------|--|---------------------------------------|---------------------------|-----------------------------------|-------------------|---------------------|
| <b>Credits</b><br>3 | <b>Grading scale</b><br>Grade to a tenth | <b>Recurrence</b><br>Each winter term | <b>Duration</b><br>1 term | <b>Language</b><br>German/English | <b>Level</b><br>4 | <b>Version</b><br>3 |
|---------------------|--|---------------------------------------|---------------------------|-----------------------------------|-------------------|---------------------|

| Mandatory     |   |      |              |
|---------------|---|------|--------------|
| T-INFO-111494 | <a href="#">Deep Learning for Computer Vision II: Advanced Topics</a> | 3 CR | Stiefelhagen |

## M

**7.53 Module: Deep Learning for Engineers [M-MACH-107088]****Responsible:** Prof. Dr.-Ing. Christoph Stiller**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-MACH-113882 | <a href="#">Deep Learning for Engineers</a> | 6 CR | Stiller |

**Competence Certificate**

written exam

60 min

**Prerequisites**

none

**Competence Goal**

Students are able to

- explain fundamentals of deep neural networks
- outline and to explain alternative architectures for deep neural networks
- explain training methods and their properties
- design, train and apply deep neural networks for basic engineering problems like machine vision, automotive control and robotics
- transfer this knowledge to other domains of applications

**Content**

- Introduction
- Multi-Layer Perceptrons
- Convolutional Neural Networks
- Backpropagation
- Uncertainties in Neural Networks
- Graph Neural Networks
- Transformers Reinforcement Learning
- Applications

**Module grade calculation**

see individual course

**Workload**

In total 180h:

Attendance time. 45h

Self-study: 135h

**Literature**

available in ILIAS

## M

## 7.54 Module: Design and Development of Mobile Machines [M-MACH-107055]

**Responsible:** Prof. Dr.-Ing. Marcus Geimer

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)

[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |   |      |                 |
|---------------|---|------|-----------------|
| T-MACH-105311 | <a href="#">Design and Development of Mobile Machines</a>           | 4 CR | Geimer          |
| T-MACH-108887 | <a href="#">Design and Development of Mobile Machines - Advance</a> | 0 CR | Geimer, Siebert |

### Competence Certificate

The assessment consists of an oral exam (20 min) taking place in the recess period. The exam takes place in every semester. Re-examinations are offered at every ordinary examination date (T-MACH-105311).

A registration is mandatory, the details will be announced on the webpages of the *Institute of Vehicle System Technology / Institute of Mobile Machines*. In case of too many applications, attendance will be granted based on pre-qualification.

The course will be replenished by interesting lectures of professionals from leading hydraulic companies.

The prerequisite for the oral examination is the preparation of a semester report (T-MACH-108887).

### Prerequisites

none

### Content

Wheel loaders and excavators are highly specialized mobile machines. Their function is to detach, pick up and deposit materials near by. Significant size for dimensioning of the machines is the content of their standard shovel. In this lecture the main steps in dimensioning a wheel loader or excavator are being thought. This includes among others:

- Defining the size and dimensions,
- the dimensioning of the electric drive train,
- the dimensioning of the primary energy supply,
- Determining the kinematics of the equipment,
- the dimension of the working hydraulics and
- Calculations of strength

The entire design process of these machines is strongly influenced by the use of standards and guidelines (ISO/DIN-EN). Even this aspect is dealt with.

The lecture is based on the knowledge from the fields of mechanics, strength of materials, machine elements, propulsion and fluid technique. The lecture requires active participation and continued collaboration.

### Module grade calculation

see individual course

### Workload

- Attendance time: 21 hours
- Self-study: 99 hours

### Recommendation

Knowledge in Fluid Power Systems (LV 2114093)

## M

**7.55 Module: Design and Optimization of Conventional and Electrified Automotive Transmissions [M-MACH-107082]****Responsible:** Dr.-Ing. Hartmut Faust**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-110958 | <a href="#">Design and Optimization of Conventional and Electrified Automotive Transmissions</a> | 4 CR | Faust |

**Competence Certificate**

See individual course

**Prerequisites**

None

**Competence Goal**

Students acquire knowledge from current transmission, hybrid and pure electric drive developments about ...

- the functionality and design of conventional and electrified vehicle transmissions and their components
- design and functional principles of the most important components of manual, dual-clutch, continuously variable and planetary automatic transmissions
- Comfort-relevant correlations and remedial measures
- the hybridization and electrification of drivetrains on the basis of known transmission types and with special so-called Dedicated Hybrid Transmissions (DHT) as well as evaluation of the concepts at system level.

**Content**

- Transmission types: Manual (MT) & automated manual transmissions (AMT), planetary torque converter automatics (AT), dual clutch (DCT), continuously variable (CVT) and shared neutral transmissions (IVT), hybrid transmissions (serial, parallel, multimode, powersplit hybrids), e-axles
- Torsional vibration damper: Damped clutch disk, dual-mass flywheel, centrifugal pendulum-type absorber (FKP), lock-up damper for torque converters
- Starting elements: Dry single clutch, dry and wet double clutch, hydrodynamic torque converter, special forms, e-motorized
- Power transmission: Countershaft gearbox, planetary set, variator, synchronization, clutches, differentials, integration of electric motors
- Transmission control: actuators, hydraulic control, electronic control (TCU)
- Software application for tuning comfort & sportiness & for hybrid functionality
- Special designs: Drivetrains of commercial vehicles, hydrostat with power split, torque vectoring
- E-mobility:
  - 5 expansion stages of electrification, 4 hybrid configurations, 7 parallel hybrid architectures
  - Hybridized transmissions (P2, P2.5, P3, P4), Dedicated Hybrid Transmission (DHT; serial/parallel/multimode, power split, new concepts)
  - E-axle transmissions for pure electric vehicles (EV)

**Module grade calculation**

The module grade corresponds to the grade from the individual course.

**Annotation**

None

**Workload**

Attendance: 30h

Self-study: 90h

**Recommendation**

None

**Learning type**

Lecture

**Literature**

None

**Base for**

None

## M

## 7.56 Module: Design of Electrical Machines [M-ETIT-100515]

**Responsible:** Prof. Dr. Martin Doppelbauer

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )  
 Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |                               |      |             |
|---------------|-------------------------------|------|-------------|
| T-ETIT-100785 | Design of Electrical Machines | 5 CR | Doppelbauer |

#### Prerequisites

none

#### Recommendation

Modul: Elektrische Maschinen und Stromrichter

## M

**7.57 Module: Design with Plastics [M-MACH-102712]****Responsible:** Dipl.-Ing. Markus Liedel**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |                                      |      |        |
|---------------|--------------------------------------|------|--------|
| T-MACH-105330 | <a href="#">Design with Plastics</a> | 4 CR | Liedel |

**Competence Certificate**

Oral exam, about 20 minutes

**Prerequisites**

none

**Competence Goal**

Students will be able to

- distinguish polymer compounds from other construction materials regarding chemical differences, thermal behaviour and solid conditions.
- discuss main plastics processes regarding advantages and disadvantages of materials selection and part geometry design and to make appropriate selections.
- analyze complex application requirements concerning material impacts on strength and to use the classic dimensioning method specific to the application to evaluate the lifetime part strength limit.
- evaluate part tolerances and geometry by appropriate methods considering molding shrinkage, production tolerances, post shrinkage, heat expansion, swelling, elastic and creep deformation.
- design plastic specific joining geometries like snap fits, screw bosses, weld seams and film hinges.
- detect classic molding failures and understand potential causes as well as to reduce the probability of molding failures by defining an optimized design.
- understand benefits and limits of selected simulation tools in the plastic technology discipline (strength, deformation, filling, warpage).
- assess polymer classes and plastic part designs with respect to suitable recycling concepts and ecological consequences.

**Content**

In module Design with Plastics, students learn the structure and properties of plastics, their processing process and their behaviour under environmental conditions. In addition, they deal with aspects of dimensioning in regard to strength and geometry, discuss design guidelines which are suitable for plastics and see several examples. Furthermore, basics regarding the joining of plastic components, structural foams, supporting simulation tools and trends in plastic technology are shown.

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

The workload for the lecture "Design with Plastics" is 120 h per semester and consists of the presence during the lectures (21 h), preparation and rework time at home (50 h) and preparation time for the oral exam (49 h).

**Recommendation**

Polymerengineering I

**Learning type**

Lectures (Obligatory)



## M

**7.58 Module: Development of Automated Production Systems [M-MACH-107020]****Responsible:** Prof. Dr.-Ing. Jürgen Fleischer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |           |
|---------------|---|------|-----------|
| T-MACH-113999 | <a href="#">Seminar Development of Automated Production Systems</a> | 4 CR | Fleischer |

**Competence Certificate**

Alternative test achievement (graded):

- Presentation of the results (approx. 20 min) followed by a colloquium (approx. 15 min) with weighting 25%
- Written processing of the results with weighting 75%

**Competence Goal**

The students...

- are able to name and describe the automation tasks in production plants and the components required for implementation.
- understand the challenges that can arise when using automation solutions in production.
- are able to independently analyse a practical problem in production with regard to the application of automation.
- are able to assess the results of automation problems and, based on this, develop and apply practical solutions.

**Content**

The course 'Development of Automated Production Systems' aims at the practical project planning of automated production systems based on realistic industrial use cases. The content framework of the course results from the holistic, practical project planning task of an automated production plant. Firstly, the basics of production automation are taught as an introduction. The aspects of multi-machine systems and project planning are then examined in depth. An interdisciplinary approach to these sub-areas results in interfaces to Industry 4.0 approaches. The core of the course is the project planning of a use case based on the procedure taught. In doing so, the students should apply the methods taught in a problem-related and results-orientated manner and thus develop an automation solution.

**Workload**

The work load is about 120 hours, corresponding to 4 credit points.

## M

**7.59 Module: Development of Hybrid Powertrains [M-MACH-107078]**

**Responsible:** Prof. Dr. Martin Doppelbauer  
Prof. Dr. Thomas Koch

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |      |
|---------------|---|------|------|
| T-MACH-110817 | <a href="#">Development of Hybrid Drivetrains</a> | 4 CR | Koch |

**Competence Certificate**

oral exam, approx. 20 min.

**Competence Goal**

Students will be able to name and describe alternative drive concepts. They can explain the basics of hybridization. They can name and describe electrical components and explain how they work. They can analyse interactions between the components of the drivetrain and evaluate them in relation to system optimization.

**Content**

1. Introduction and Goal
2. Alternative Powertrains
3. Fundamentals of Hybrid Powertrains
4. Fundamentals of Electric Components of Hybrid Powertrains
5. Interactions in Hybrid Powertrain Development
6. Overall System Optimization

**Module grade calculation**

see individual course

**Workload**

120 h

(for details see individual course)

## M

## 7.60 Module: Development of Oil-Hydraulic Powertrain Systems [M-MACH-107059]

**Responsible:** Hon.-Prof. Dr. Gerhard Ruben Geerling

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)

[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |                  |
|---------------|---|------|------------------|
| T-MACH-105441 | <a href="#">Development of Oil-Hydraulic Powertrain Systems</a> | 4 CR | Geerling, Geimer |

### Competence Certificate

oral exam (approx. 20 min)

### Prerequisites

none

### Competence Goal

After completing this part of the course, students will be able to evaluate how oil-hydraulic **drive and control systems** (Drive & Control of Fluid Power Systems) can be used sensibly and which **system architectures** are better and less suitable for a given problem.

They can create a **hydraulic circuit diagram** for a given task and can carry out calculations for the overall **system design** as well as sub-modules and machine elements and solve them on the basis of **model approaches**.

You will acquire in-depth knowledge of how an **oil hydraulic system** can be **planned and developed** holistically and iteratively in **product development processes (PEP)** using **project management approaches**.

In addition, you will be able to **set up and commission** the first simple oil hydraulic drive and circuit architectures and **measure the main status parameters** in a **practical laboratory exercise** at KIT/FAST/MOBIMA.

### Content

The block course offered by the Chair of Mobile Machinery (Mobima) teaches the basics of project planning and the development of mobile and stationary hydrostatic systems. The lecturer comes from a market-leading company in the field of fluid drive and control technology and provides in-depth insights into the project planning and development process of hydrostatic systems using practical examples. The contents of the lecture are:

- Marketing, planning, project planning
- Circuit types, oil hydrostatics, heat balance, hydraulic accumulators
- Filtration, noise reduction
- Design exercises, practical laboratory

### Module grade calculation

see individual course

### Annotation

Knowledge of fluid technology advantageous

### Workload

120h

Attendance time: 20 hours

Self-study: 100 hours

### Recommendation

Knowledge of fluid technology

## M

## 7.61 Module: Digital Beam-Forming for Imaging Radar [M-ETIT-105415]

**Responsible:** Prof. Dr.-Ing. Thomas Zwick  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-110940 | <a href="#">Digital Beam-Forming for Imaging Radar</a> | 4 CR | Zwick |

**Competence Certificate**

The examination consists of a written exam (approx. 120 min.) and weekly exercises. The overall impression is rated.

**Prerequisites**

The lecture builds upon Spaceborne Radar Remote Sensing (engl.). The basic principles will be repeated in the lecture. The following lectures are helpful for a comprehensive understanding: Radar System Engineering (engl.), Antennen und Mehrantennensysteme, , Modern Radio System Engineering (engl.).

**Competence Goal**

Students have a basic knowledge of antenna arrays, radar, multipath propagation and noise. They understand the principle and functionality of beam shaping and the differences between digital, analog and hybrid beam-forming. They know the theory, methods, and algorithms of beam-forming. They can understand how beam-forming is applied to radar. You can explain basic radar system concepts and summarize the various applications.

**Content**

The lecture is (inherently) interdisciplinary and ideally suited to teach students the combination of signal processing for imaging radar and digital beam-forming. The basic knowledge about antennas & antenna arrays, radar ambiguities and noise is explained in the lecture. This is followed by a details on various beam forming algorithms with reference to imaging radar systems and with application examples from spaceborne synthetic aperture radar (SAR). Aspects such as digital and hybrid beam forming, as well as MIMO and equivalent virtual antenna configuration are explained. Lecture notes (english) are offered to the participants to consolidated the study material.

The lecture is accompanied by exercises on the lecture material. These are discussed in a room exercise and the associated solutions are presented in detail.

**Module grade calculation**

The module grade results of the assessment of the written exam and the weekly exercises. Details will be given during the lecture.

**Workload**

- Attendance time in lectures (1.5 h per 15 dates) and exercises (1.5 h per 7 dates) = 33 h
- Preparation / revision: 15 weeks each 3 h = 45 h
- Exam preparation and presence in the exam: 1 week à 40 h = 40 h
- Total effort approx. 120 hours = 4 LP

**Recommendation**

Basics of signal processing and radar techniques are useful.

## M

## 7.62 Module: Digital Circuit Design [M-ETIT-100473]

**Responsible:** Prof. Dr. Ivan Peric

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-100974 | <a href="#">Digital Circuit Design</a> | 4 CR | Peric |

**Annotation**

Will be changed to English in summer term 25.

## M

## 7.63 Module: Digital Control [M-MACH-107045]

**Responsible:** Prof. Dr.-Ing. Michael Knoop  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |                                 |      |       |
|---------------|---------------------------------|------|-------|
| T-MACH-105317 | <a href="#">Digital Control</a> | 4 CR | Knoop |

**Competence Certificate**

written exam

1 h

**Prerequisites**

none

**Competence Goal**

The lecture introduces key methods for the analysis and design of digital feedback control systems. Starting point is the discretisation of linear, continuous-time models. State space based and z-transform based controller design techniques are presented for discrete-time, single-input single-output systems. Furthermore, plants with dead-time and deadbeat design are covered.

**Content**

1. Introduction into digital control:

Motivation for digital implementation of controllers Structure of digital feedback control loops Sample and hold units

2. State space analysis and design:

Discretisation of continuous-time systems Discrete-time state space equations

Stability - definition and criteria State feedback design by eigenvalue assignment PL state feedback controller Luenberger observer, separation theorem Systems with dead-time Deadbeat design

3. Analysis and design based on z-transform: z-transform - definition and theorems

Control loop description in the z domain

Stability criteria Root locus controller design Transfer of continuous-time controllers into discrete time controllers

**Module grade calculation**

see individual course

**Workload**

120h

**Learning type**

Lecture

**Literature**

Lunze, J.: Regelungstechnik 2, 9. Auflage, Springer Verlag, Berlin Heidelberg 2016.

Unbehauen, H.: Regelungstechnik, Band 2: Zustandsregelungen, digitale und nichtlineare Regelsysteme, 8. Auflage, Vieweg Verlag, Braunschweig 2000

Föllinger, O.: Lineare Abtastsysteme. 4. Auflage, R. Oldenbourg Verlag, München Wien 1990

Ogata, K.: Discrete-Time Control Systems. 2nd edition, Prentice-Hall, Englewood Cliffs 1994

Ackermann, J.: Abtastregelungen, Band I, Analyse und Synthese. 3. Auflage, Springer Verlag, Berlin Heidelberg 1988

## M

**7.64 Module: Digital Hardware Design Laboratory [M-ETIT-102266]**

**Responsible:** Prof. Dr.-Ing. Jürgen Becker  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-ETIT-104571 | <a href="#">Digital Hardware Design Laboratory</a> | 6 CR | Becker |

**Competence Certificate**

Control of success is carried out in an oral examination as well as during the laboratory exercises in form of laboratory reports and/or oral interrogations.

**Prerequisites**

none

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The module [M-ETIT-102264 - Digital Hardware Design Laboratory](#) must not have been started.

**Competence Goal**

The students

- know the practical usage of FPGAs
- are able to efficiently use modern hardware development tools
- know how to describe hardware in VHDL
- can self dependently draft and implement VHDL-Components based on given specifications
- are able to practically apply common concepts and principles in hardware development (e.g. pipelining)

**Content**

Grouped in teams of two, the students are introduced to the design of complex hardware/software systems. The laboratory takes place in weekly 4 hour laboratory sessions. During the first few sessions, the students are introduced to the implementation of VHDL-components, the usage of modern synthesis and simulation tools as well as basic knowledge on FPGAs.

Based on those fundamentals, students develop the different components of an image processing system in the second part of the laboratory. This includes implementation and testing steps for the individual components as well as the integration to an overall system. Finally, the hardware system can be realized on FPGA-Hardware and tested with live camera images.

**Module grade calculation**

The module grade is composed of the result of the oral examination and the effected performance during the laboratory sessions (e.g. reports, oral interrogations, etc.).

**Annotation**

The module ETIT-102264 („Praktikum Entwurf digitaler Systeme“) must not have been started or completed.

**Workload**

The amount of work is distributed as follows:

- time of presence during the laboratory sessions: 11 sessions with 4h = 44h
- Preparation and wrap-up: 6h per laboratory session = 66h
- Preparation for the examination: 40h

In total 150h (25h per credit point).

**Recommendation**

Previous knowledge in design and design automation for electronic systems (e.g. from the lectures HSO, No. 2311619 or HMS, No. 2311608) is recommended.

## M

## 7.65 Module: Digital Hardware Design Laboratory [M-ETIT-102264]

**Responsible:** Prof. Dr.-Ing. Jürgen Becker

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-ETIT-104570 | <a href="#">Digital Hardware Design Laboratory</a> | 6 CR | Becker |

**Prerequisites**

none

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The module [M-ETIT-102266 - Digital Hardware Design Laboratory](#) must not have been started.



## M

**7.66 Module: Digital Twin Engineering [M-ETIT-106040]****Responsible:** Prof. Dr.-Ing. Mike Barth**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |  |
|---------------|--|------|--|
| T-ETIT-112224 | <a href="#">Digital Twin Engineering</a> | 4 CR |  |

**Competence Certificate**

The examination takes place in form of other types of examination. It consists of a model library developed in the course of a semester-long project in the modeling language Modelica and a presentation of the library lasting 25 minutes. The quality of the model library is evaluated within the framework of the criteria: documentation, formal correctness, functionality, usability, HMI and modeling level of detail. The presentation is evaluated as an additional aspects. The overall impression is evaluated.

**Prerequisites**

none

**Competence Goal**

- The students will be able to analyze, structure and formally describe problems in the area of object-oriented physical system modeling.
- The students will be able to understand, apply and further develop the Modelica modeling language.
- The students are able to transfer bidirectionally acting systems into a model.
- The students are able to transfer physical equations into the modeling environment.
- The students are able to critically evaluate the different numerical integration methods for their applicability and to use them sensibly.
- The students are able to create system models and co-simulations using functional mockup units.
- The students will be able to implement a real system at the appropriate modeling depth for the task.
- The students will be able to abstract real system properties and, if necessary, decide whether they need to be modeled.
- The students know suitable simulation tools and their application.

**Content**

- This module is designed to provide students with the theoretical and practical aspects of object-theoretic equation-based modeling.
- This module also provides a definition of the digital twin and its aspects of the management shell.
  - In this context, a classification of simulation models in the I4.0 VWS takes place.
- Both system simulation in the Open Modelica Editor (OME) and co-simulation with Functional Mockup Units (FMU) will be covered.
- Students create a new model library of a mechatronic system in a semester-long project (teams of 3-4 students).
- The module provides an overview of modern system simulation methods based on bidirectional flow and potential modeling.
- Beyond theoretical and practical modeling, the module imparts the knowledge about practice-relevant modeling levels or depths.
- Furthermore, quality standards for simulation models with focus on the engineering of plants/systems are discussed.

**Module grade calculation**

The assessment of the developed model library and the presentation of the library will be included in the module grade. More details will be given at the beginning of the course.

**Workload**

The workload includes:

1. attendance in lectures and exercises:  $10 \cdot 1,5 \text{ h} = 15 \text{ h}$
2. preparation / follow-up:  $15 \cdot 2 \text{ h} = 30 \text{ h}$
3. Implementation of the model library: 60 h
4. preparation of and attendance in the final presentation: 15 h

A total of 120 h = 4 CR

## M

**7.67 Module: Digitalization of Products, Services & Production [M-MACH-105476]****Responsible:** Dr.-Ing. Bernd Pätzold**Organisation:** KIT Department of Mechanical Engineering**Part of:** Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-MACH-108491 | Digitalization of Products, Services & Production | 4 CR | Pätzold |

**Competence Certificate**

Alternative exam assessment.

Two presentations in team work and two written compositions.

**Prerequisites**

None

**Competence Goal**

Students are able to

- describe the fundamental challenges and objectives of the progressive digitalization of products, service and production. In context of these challenges, students can name and explain the essential terms.
- illustrate the key drivers and fundamental technologies behind the digitalization of products, services and processes.
- describe the challenges of the ongoing digitalization and the corresponding changes in business processes and distinguish between them in regards to time and place. Furthermore, students are able to assign the IT-Architecture and systems to the corresponding process steps.
- highlight the requirement for future information management in networks of product development and production institutions and can clarify how to validated and safeguard the corresponding IT processes.
- to analyze the challenges of digitalization and present potential solution approaches via self-created scenarios for future developments.

**Content**

- Digitalization of products, services and production in the context of Industry 4.0 .
- Key drivers for ongoing digitalization and their impact on future product development and manufacturing.
- Methods and procedures to design the according transformation process.
- Intensive group discussions of use-case scenarios using practical examples from the industry.

**Workload**

120 hour

**Learning type**

Seminar

## M

**7.68 Module: Distributed Discrete Event Systems [M-ETIT-100361]****Responsible:** Prof. Dr.-Ing. Michael Heizmann**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-ETIT-100960 | <a href="#">Distributed Discrete Event Systems</a> | 4 CR | Heizmann |

**Prerequisites**

none

## M

**7.69 Module: Drive System Engineering B: Stationary Machinery [M-MACH-107190]****Responsible:** Sascha Ott**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |     |
|---------------|--|------|-----|
| T-MACH-114000 | <a href="#">Drive System Engineering B: Stationary Machinery</a> | 4 CR | Ott |

**Competence Certificate**

See individual course

**Prerequisites**

None

**Competence Goal**

Students acquire the basic skills required to develop future energy-efficient and safe drive system solutions for use in industrial environments. Holistic development methods and evaluations of drive systems are considered.

**Content**

The focus can be divided into the following chapters:

- Drive train system
- Operator system
- System environment
- System components
- Development process

**Module grade calculation**

The module grade corresponds to the grade from the individual course.

**Annotation**

None

**Workload**

Attendance: 30h

Self-study: 90h

**Recommendation**

Attendance of the course Drive System Engineering A: Automotive Systems

**Learning type**

Lecture

**Literature**

VDI-2241: "Schaltbare fremdbetätigte Reibkupplungen und -bremsen", VDI Verlag GmbH, Düsseldorf

Geilker, U.: "Industriekupplungen - Funktion, Auslegung, Anwendung", Die Bibliothek der Technik, Band 178, verlag moderne industrie, 1999

**Base for**

None

## M

**7.70 Module: Drive Train of Mobile Machines [M-MACH-105800]****Responsible:** Prof. Dr.-Ing. Marcus Geimer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 2 terms  | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-105307 | <a href="#">Drive Train of Mobile Machines</a> | 4 CR | Geimer |

**Competence Certificate**

The final assessment will be an oral examination (appr. 20 min) taking place during the recess period. The examination will be offered in every semester and can be repeated at any regular examination date.

**Prerequisites**

None

**Competence Goal**

At the end of the lecture, participants can explain the structure and function of all discussed drive trains of mobile machines. They can analyze complex gearbox schematics and synthesize simple transmission functions using rough calculations.

**Content**

In this course the different drive trains of mobile machinery will be discussed.

The focus of this course is:

- mechanical gears
- torque converter
- hydrostatic drives
- power split drives
- electrical drives
- hybrid drives
- axles
- terra mechanics

**Workload**

120 h

**Learning type**

Lecture

**Literature**

Literature: Download of lecture slides from ILIAS. Further literature recommendations during lectures.

## M

**7.71 Module: Dynamics of Electro-Mechanical Systems [M-MACH-105612]**

**Responsible:** Prof. Dr.-Ing. Alexander Fidlin  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |               |
|---------------|--|------|---------------|
| T-MACH-111260 | <a href="#">Dynamics of Electro-Mechanical Systems</a> | 5 CR | Altoé, Fidlin |

**Competence Certificate**

Written examination, 120 minutes

**Prerequisites**

None

**Competence Goal**

The students are able to describe the dynamical behaviour of electro-mechanical systems using uniform mathematical approach. They are able to analyse interactions between mechanical and electro-mechanical subsystems. They are familiar with the essential retroactive effects, are able to identify them and calculate their impact. The students become acquainted with the basic non-linear effects in the coupled electro-mechanical systems and are able to analyse them by means of appropriate simulation tools.

**Content**

The lecture conveys two kinds of describing electro-mechanical systems. The first one (described shortly) is based on state and flow variables, the second one (which is in focus of the course) is based on an energetic description and the Lagrange-Maxwell-Formalism. These methods are then applied in order to analyse the most important electro-mechanical systems. These include

- Dynamics of electro-mechanical converter and vibration exciters taking into account the load in resonance operation
- Dynamics of electrical machines taking into account the rotordynamic effects (imbalance, loss of stability, passage through resonance)
- Dynamics of piezo-electrical converters in sensor and actor operation

**Learning type**

Lecture and Tutorial

**Literature**

J. H. Williams: Fundamentals of Applied Dynamics, MIT Press, 2019

## M

**7.72 Module: Dynamics of the Automotive Drive Train [M-MACH-102700]**

**Responsible:** Prof. Dr.-Ing. Alexander Fidlin  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-105226 | <a href="#">Dynamics of the Automotive Drive Train</a> | 4 CR | Fidlin |

**Competence Certificate**

A performance assessment is an oral exam (approx. 30 minutes).

**Prerequisites**

none

**Competence Goal**

After having attended this lecture students will be able to understand typical vibration phenomena in a vehicle powertrain and to simulate the essential components of the vehicle powertrain including components of the engine steering. The method of the simulation-based concept choice and the necessary interaction between OEMs and the delivering industry is part of the taught knowledge. The students will also gain experience in the application of numerical simulation methods for solving practical problems of torsion vibrations in highly non-linear systems.

**Content**

Lectures: The concept of a simulation- based optimization of the vehicle powertrain and its components. Modelling of the components of the power system including internal-combustion engine, torsional vibration damper (two mass flywheel, centrifugal force pendulum, internal damper/torsion damped clutch disc), hydrodynamical transformer, gear, Kardan wave, differential, wheels, driving manoeuvre and its appraisal incl. start, neutral gear, approach, acceleration drive, load alteration, gear alteration, shearing force, stop, and different special manoeuvres like change of intentions or misuse.

Exercise: Elementary numerical proceedings to simulate nonlinear dynamic systems. Modelling of the powertrain in a simulation environment SimulationX or MapleSim.

**Workload**

Each credit point is equivalent to 25-30 hours of workload (per student). This refers to an average student who shows an average performance. The workload is as follows:

- time of attendance lectures: 30 h
- time of attendance exercise: 30h
- self-study including exam preparation: 60

total 120 h - 4 credit points

**Recommendation**

Basic knowledge of the powertrain technology and elementary vibration knowledge are advantageous. The lectures refer to the book

H. Dresig, A. Fidlin: Schwingungen Mechanischer Antriebssysteme, 4. Auflage, Springer: Berlin - Heidelberg - New York, 2020, 655 S., ISBN: 978-3-662-59137-6

Especially chapter 6 and 7 are recommended.

**Literature**

- Dresig H. Schwingungen mechanischer Antriebssysteme, 2. Auflage, Springer, 2006
- Pfeiffer F., Mechanical System Dynamics, Springer, 2008
- Laschet A., Simulation von Antriebssystemen:Modellbildung der Schwingungssysteme und Beispiele aus der Antriebstechnik, Springer, 1988



## M

**7.73 Module: Electric Drives and Power Electronics Lab [M-ETIT-107138]****Responsible:** Prof. Dr. Martin Doppelbauer**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Internship/Lab Course \)](#)[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Internship/Lab Course \)](#)[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German/English | 4     | 1       |

| Mandatory     |   |      |             |
|---------------|---|------|-------------|
| T-ETIT-114162 | <a href="#">Electric Drives and Power Electronics Lab</a> | 6 CR | Doppelbauer |

**Competence Certificate**

Success control takes place in the form of other types of examination. It consists of one oral examination per experiment. The overall impression is assessed.

**Prerequisites**

none

**Competence Goal**

Students are able to connect power converters and electrical machines to the electrical grid and operate them correctly. They implement current control in a rotating coordinate system. They analyze and document the operating characteristics of direct current, induction and synchronous machines through measurements. You will know and operate measuring devices with which characteristic values, characteristic curves and time curves of electrical and mechanical variables are recorded and saved.

**Content**

The aim of the practical course is to use selected examples to guide students in applying and deepening the theoretical knowledge acquired in lectures in practice. In almost all experiments, the students deal with the combination of analog and digital electrical signal processing, control engineering methods, a power electronic actuator and an electrical machine to be driven. Specifically, the following 8 experiments are carried out:

- Experiment SoC: "Space vector transformation and current control with digital signal processing system (system on chip)"
- Experiment LH: "Power semiconductors - measurement of static and dynamic properties of an IGBT and a SiC MOSFET"
- Experiment PSM: "Permanently excited synchronous machine - speed control with subordinate current control in the constant flux and field weakening range"
- Experiment FAM: "Field-oriented control of the three-phase induction machine"
- Experiment DAB: "Getting to know topology, modulation methods and modeling"
- PV experiment: "Operation of solar modules at the point of maximum energy yield and integration of a lithium-ion storage system"
- MMC experiment: "Implementation of a cascaded MMC control system consisting of energy and current controllers"
- VASM experiment: "Measurement of the induction machine on the test bench to determine the machine parameters"

**Module grade calculation**

The assessments of the oral examinations are included in the module grade. Further details will be provided at the beginning of the course.

**Workload**

180h

- Attendance time in the internship with interview: 40 h
- Preparation time: 125 h
- Follow-up time: 15h

**Recommendation**

The courses

- Regelung elektrischer Antriebe und
- Leistungselektronik

should have been completed or at least heard in parallel to the practical course.

## M

**7.74 Module: Electric Drives for E-Mobility [M-ETIT-106971]**

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr. Martin Doppelbauer  |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |                                |      |             |
|---------------|--------------------------------|------|-------------|
| T-ETIT-113936 | Electric Drives for E-Mobility | 4 CR | Doppelbauer |

**Competence Certificate**

The success control takes place in the form of an oral examination of approximately 30 minutes.

**Prerequisites**

none

**Competence Goal**

The students will be able to assess the structure, performance and behavior of full-electric and hybrid drive systems for all types of traction applications from pedelecs to cars, utility vehicles, railroads and even large propulsion systems in ships. They can critically evaluate the different drive systems and components.

The students will be able to understand the latest developments in electric drive technology and future possibilities.

**Content**

This module is designed to provide students with the theoretical and practical aspects of electric drives for electric traction applications.

Table of content:

- Overview: Electric Drives in Hybrid and Electric Vehicles
- Fundamentals of Rotary Field Machines
- Fundamentals of Power Electronics
- Design of Synchronous Machines
- Design of Induction Machines
- Noise, Vibration and Harshness (NVH)
- Thermodynamics of Electric Machines

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

The workload includes (3 SWS):

1. attendance in lectures 15\*2 h = 30 h
2. Attendance in exercises: 15\*1 h = 15 h
3. preparation / follow-up: 15\*3 h = 45 h
4. preparation of and attendance in examination: 30 h

A total of 120 h

**Recommendation**

Basic knowledge in the field of electric machines and drives is helpful, for example by attending the course "Elektrische Maschinen und Stromrichter (EMS)" in the KIT-Bachelor.

Basic knowledge in the field of hybrid and electric vehicles is helpful, for example by attending the course "Hybridelektrische Fahrzeuge HEF)" in the KIT-Bachelor.

## M

**7.75 Module: Electric Power Transmission & Grid Control [M-ETIT-105394]**

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Thomas Leibfried   |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 2       |

| Mandatory     |  |      |           |
|---------------|--|------|-----------|
| T-ETIT-110883 | Electric Power Transmission & Grid Control | 6 CR | Leibfried |

**Competence Certificate**

The examination takes place in form of a written examination lasting 120 minutes.

**Prerequisites**

none

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The module [M-ETIT-105394 - Electric Power Transmission & Grid Control](#) must not have been started.

**Competence Goal**

Students are familiar with the functionality and physical basics as well as the components of AC and DC of electric power transmission systems. They will be able to calculate transmission characteristics and carry out a basic design. They are also familiar with the functioning of grid control.

**Content**

The lecture initially deals with the characteristics and stability of electrical energy transmission. A central chapter deals with HVDC technology as a method for transmitting high power. FACTS elements, which are used to make energy transmission more flexible, are then dealt with. Finally, the dynamics of power plants and grids are discussed.

**Module grade calculation**

The module grade is the grade of the written exam.

**Workload**

The workload includes:

1. attendance in lectures and exercises: 30 + 30 h = 60 h
2. preparation / follow-up: 120 h

A total of 180 h = 6 CR

**Recommendation**

- Basic Knowledge in electrical network analysis
- Basic Knowledge about the functionality of electric grid components
- Basic Knowledge about the calculations of three-phase systems
- Basic Knowledge about symmetrical components, Park-transform and Clark-transform

## M

**7.76 Module: Electrical Energy Systems Lab [M-ETIT-107137]**

**Responsible:** Prof. Dr. Martin Doppelbauer  
Prof. Dr.-Ing. Thomas Leibfried

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German/English | 4     | 1       |

| Mandatory     |   |      |                                |
|---------------|---|------|--------------------------------|
| T-ETIT-114160 | <a href="#">Electrical Energy Systems Lab</a> | 6 CR | Badent, Doppelbauer, Leibfried |

**Competence Certificate**

Success control takes place in the form of other types of examinations consisting of questions on the content of the experiments with written and oral components. The overall impression is assessed.

**Prerequisites**

none

**Competence Goal**

Students can calculate and use induction machines, transformers, uncontrolled rectifier circuits, variable-speed drive systems and high-voltage generators. They can carry out partial discharge measurements.

**Content**

Building on the basic lectures on electrical machines, power electronics and electrical energy systems, students gain an insight into the fundamental systems of electrical power engineering.

**Module grade calculation**

The questions on the individual experiments are included in the module grade. Further details will be provided at the beginning of the course.

**Annotation**

Joint event of IEH and ETI.

**Workload**

The workload is 180 hours and is made up as follows:

- Attendance time 40 h
- Self-study time 140 h

## M

## 7.77 Module: Electrocatalysis [M-ETIT-105883]

**Responsible:** Prof. Dr. Ulrike Krewer  
Dr. Philipp Röse

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 3       |

| Mandatory     |                                  |      |      |
|---------------|----------------------------------|------|------|
| T-ETIT-111831 | <a href="#">Electrocatalysis</a> | 5 CR | Röse |

### Competence Certificate

The examination takes place in form of a written examination lasting 120 minutes.

### Prerequisites

none

### Competence Goal

Students have a well-grounded knowledge of electrocatalytic energy technologies for the conversion and storage of electrical energy in chemicals (Power-to-X). They know the functional principle of state-of-the-art electrocatalysts in fuel cells and electrolysis and understand the underlying electrochemical and physical processes. Participation in the course enables the students to assess and understand the relationship between electrode structure and their selectivity, performance and stability. Furthermore, the students learn the theoretical basics of experimental methods that are relevant for the investigation of model electrodes and technical cells.

### Content

Lecture:

- **Basics, concepts and definitions within the Power-to-X context:** Catalysis and electrocatalysis; activity and selectivity; fundamentals of electrochemical processes, elementary steps involving adsorbed intermediates.
- **The role of intermediates:** Electron transfer without intermediates, multi-electron transfer with intermediates; differences in adsorption energies of intermediates and active surfaces
- **Theoretical treatment of electron transfer reactions:** Tunneling processes at electrodes; electron transfer reactions (Marcus theory); role of electrode material on rate of electrode reaction.
- **Measurement methods for the investigation of electrocatalytic reactions:** Determination of the effective surface; Determination of the activity of electrochemically active species; Determination of the selectivity; Operando measurement methods
- **Technically important electrocatalytic reactions and processes:** The oxygen reduction reaction (ORR) and evolution reaction (OER); the chlorine evolution reaction.

### Module grade calculation

The module grade is the grade of the written examination.

### Workload

attendance in lectures: 30 \* 45 min. = 22,5 h

attendance in exercises: 15 \* 45 min. = 11,25 h

preparation and follow up of the lectures and practice: 76.25 hours (approx. 1.75 hours per lecture or exercise)

preparation of examination and attendance in examination: 40 h

A total of 150 h = 5 CR

### Recommendation

The participation of the module "Electrochemical Energy Technologies" is helpful.

## M

## 7.78 Module: Elements of Technical Logistics [M-MACH-102688]

**Responsible:** Dr.-Ing. Martin Mittwollen

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |                     |
|---------------|---|------|---------------------|
| T-MACH-102159 | <a href="#">Elements and Systems of Technical Logistics</a> | 4 CR | Fischer, Mittwollen |

### Competence Certificate

The assessment consists of an oral examination (approx. 20min) .

### Prerequisites

none

### Competence Goal

Students are able to:

- Describe elements and systems of technical logistics,
- Model and calculate structures and functions of special conveying machines,
- Describe interdependence of material flow systems and technique quantitatively and qualitatively and
- Equip material flow systems with appropriate machines.

### Content

material flow systems and their (conveying) technical components

mechanical behaviour of conveyors;

structure and function of conveyor machines; elements of intralogistics (belt conveyor, racks, automatic guided vehicles, fan-in, bifurcation, and etc.)

sample applications and calculations in addition to the lectures inside practical lectures

### Workload

Lecture and exercise: 4 LP = 120 h

1. Attendance time lecture: 28 h
2. Preparation/follow-up lecture: 56 h
3. Attendance time exercise: 12 h
4. Preparation/follow-up exercise: 24 h

## M

**7.79 Module: Elements of Technical Logistics incl. Project [M-MACH-105015]****Responsible:** Dr.-Ing. Martin Mittwollen**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |                     |
|---------------|---|------|---------------------|
| T-MACH-102159 | <a href="#">Elements and Systems of Technical Logistics</a>           | 4 CR | Fischer, Mittwollen |
| T-MACH-108946 | <a href="#">Elements and Systems of Technical Logistics - Project</a> | 2 CR | Fischer, Mittwollen |

**Competence Certificate**

The assessment consists of an oral exam (20min) and presentation of performed project and defense (approx. 30min)

**Prerequisites**

none

**Competence Goal**

Students are able to:

- Describe elements and systems of technical logistics,
- Model and calculate structures and functions of special conveying machines,
- Describe interdependence of material flow systems and technique quantitatively and qualitatively and
- Equip material flow systems with appropriate machines.

**Content**

material flow systems and their (conveying) technical components

mechanical behaviour of conveyors;

structure and function of conveyor machines; elements of intralogistics (belt conveyor, racks, automatic guided vehicles, fan-in, bifurcation, and etc.)

sample applications and calculations in addition to the lectures inside practical lectures

**Workload**

Lecture and exercise: 6 LP = 180 h

1. Attendance time lecture: 28 h
2. Preparation/follow-up lecture: 56 h
3. Attendance time exercise: 12 h
4. Preparation/follow-up exercise: 24 h
5. Attendance time project: 4 h
6. Preparation/follow-up project: 56 h

**Learning type**

Lecture, tutorial, project



## M

## 7.80 Module: Energy Storage and Network Integration [M-ETIT-101969]

**Responsible:** Prof. Dr.-Ing. Giovanni De Carne  
apl. Prof. Dr. Francesco Grilli  
Prof. Dr.-Ing. Mathias Noe

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |     |
|---------------|--|------|-----|
| T-ETIT-104644 | <a href="#">Energy Storage and Network Integration</a> | 4 CR | Noe |

**Competence Certificate**

Type of Examination: Oral exam

Duration of Examination: approx. 30 minutes

**Prerequisites**

see course (Teilleistung)

**Competence Goal**

Students understand the different types of energy storage and apply their knowledge for the selection and principal dimensioning of relevant energy storage tasks.

Furthermore, students can reflect the state-of-the-art of most important energy storage types, their fundamental characteristics and viability at given boundary conditions; they are enabled to elaborate and apply basic integration issues dependent on the grid structure for the different network types.

Practical work: The students are able to analyse real applications of energy storage and calculate basic design examples for the various storage options.

The students are able to discuss topic-related aspects in English using the technical terminology of the field of study.

**Content**

The lecture provides an overview of the different storage types and their fundamental integration into the power supply grid.

Thereby, within the scope of this lecture, the necessity and the motivation for converting and storing energy will be given. Starting from the definition of fundamental terms different physical and chemical storage types along with their theoretical and practical basis are described. In particular, the decoupling of energy production and energy consumption, and the provision of different energy scales (time, power, density) will be discussed. Furthermore, the challenge of energy transport and re-integration into the different grid types is considered.

## 1. Motivation for the need of energy storage in energy systems

- a. National and international situation
- b. Storage motivation

## 2. Terms and definitions

- a. Different energy types
- b. Definitions energy content
- c. Definitions energy- and power density

## 3. Thermal energy storage

- a. Classification
- b. Sensitive heat storage
- c. Latent heat storage
- d. Reaction heat storage

## 4. Mechanical energy storage

- a. Flywheels
- b. Compressed air
- c. Pumpes storage systems

## 5. Electrodynamic energy storage

- a. Main principles
- b. Capacitive and inductive storage

## 6. Electrochemical energy storage

- a. Working principles
- b. Batteries
- c. Fuel Cells

## 7. Electric Power Systems

- a. Storage tasks
- b. Storage integration
- c. Planning reserves

The obligatory **practical work** (23689) is related to real applications of energy storage and to basic design examples for the various storage options.

The lecturer reserves the right to alter the contents of the course without prior notification.

Course material will be available on ILIAS. The link to ILIAS and Up-to-date information will be available via the ITEP-homepage prior to the beginning of the semester (<https://www.itep.kit.edu/148.php>).

**Module grade calculation**

The module grade is the grade of the oral exam.

**Annotation**

Exam and Lecture will be held in English.

**Workload**

Approximately 120h workload of the student. The workload includes:

45h - attendance in lectures an exercises

45h - preparation / follow-up

30h - preparation of and attendance in examination

**Recommendation**

Basic knowledge in the fields of Electrical Engineering and Thermodynamics is helpful.

## M

**7.81 Module: Energy Systems I - Renewable Energy [M-MACH-107139]****Responsible:** apl. Prof. Dr. Ron Dagan**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German/English | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-105408 | <a href="#">Energy Systems I: Renewable Energy</a> | 4 CR | Dagan |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

The student knows the principles of the feasibility of energy gain by means of renewable energies, in particular the solar energy.

**Content**

The course deals with fundamental aspects of renewable energies.

1. The first part deals with the basic concepts of absorbing solar beams, in an efficient manner accounting for the minimization of heat losses. In this context, selective topics on thermodynamics as well as fluid dynamics are introduced. In the second part few applications are discussed and optimizations techniques of solar collectors construction and their heat transfer are presented.
2. The use of solar energy as a source for heat generation is followed by the idea of electricity generation. Introductory aspects of Photovoltaic technologies are illuminated.
3. The last part presents additional regenerative energy sources such as wind and geothermal energy.

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

(for details see individual course)

## M

## 7.82 Module: Energy Topology and Resilience [M-MACH-107061]

**Responsible:** Dr. Sadeeb Simon Ottenburger

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |             |
|---------------|--|------|-------------|
| T-MACH-112755 | <a href="#">Energy Topology and Resilience</a> | 4 CR | Ottenburger |

### Competence Certificate

Oral

Duration approx. 30 minutes

### Prerequisites

No auxiliary meand

### Competence Goal

After successful completion, students are able to distinguish resilience from other concepts such as sustainability and reliability, as well as to design initial approaches to graph-based resilience analysis for application in the planning of energy networks.

### Content

After an introduction to resilience research, this lecture addresses current questions on the impact of utility grid design on supply security from a mathematical-physical perspective in the context of the energy transition and smart grids. With the addition of socio-economic constraints, solution approaches lead to hard optimization problems, since there are, e.g., many degrees of freedom in spatial-topological planning in addition to questions about the grid-intrinsic design. Resilience metrics are derived from an analytical understanding on systemic vulnerability and on systemic risks related to utility networks, which are then used in the formulation of optimization problems to identify resilient and techno-economically feasible utility networks.

### Module grade calculation

see individual course

### Workload

120h

(for details see individual course)

## M

## 7.83 Module: Engine Measurement Techniques [M-MACH-107160]

**Responsible:** Dr.-Ing. Sören Bernhardt

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |           |
|---------------|---|------|-----------|
| T-MACH-105169 | <a href="#">Engine Measurement Techniques</a> | 4 CR | Bernhardt |

### Competence Certificate

see individual course

### Prerequisites

none

### Competence Goal

- Understand and explain the basic structure of a combustion engine test. Name important parameters that influence the test.

- Understand and be able to explain measured variables and measurement principles for the physical phenomena of temperature, pressure, humidity, flow, torque and speed.

- Select the sensors suitable for a measurement task for a task with real-life relevance. Take into account the practical experience gained.

- Evaluate the usefulness of a measurement chain, especially with regard to the measurement accuracy of individual components and the measurement results.

### Content

- System boundaries
- Test stand design
- Measuring principle bridge circuit
- Measured variables and measuring principles
  - Torque
  - rotational speed
  - Temperature
  - humidity
  - pressure
  - Flow rate
- Calculated variables

### Module grade calculation

see individual course

### Workload

120h

(for details see individual course)

## M

**7.84 Module: Engineering Materials for the Energy Transition [M-MACH-107066]****Responsible:** Prof. Dr. Hans Jürgen Seifert**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-MACH-112691 | <a href="#">Engineering Materials for the Energy Transition</a> | 4 CR | Seifert |

**Competence Certificate**

The assessment consists of an oral exam (about 30 minutes).

**Prerequisites**

none

**Competence Goal**

The students will be enabled to evaluate the physical and chemical properties of engineering materials and their (potential) applications in technical systems relevant for the Energy Transition. They can quantitatively describe the functional behavior of the materials used for energy storage and conversion. The students are qualified for rational selection of materials to be used for specific applications in the field of interest.

**Content**

The success of the Energy Transition in Germany and worldwide requires the design and construction of innovative technical facilities in the sectors e.g. Electricity, Transportation and Heating. This concerns the exploitation of primary energy but also the energy conversion, storage and usage, respectively. By this means, a climate-neutral and sustainable energy supply is ensured. Groundbreaking modern engineering materials are an indispensable inherent part of the required technical innovation and value chains. This course first introduces the students into the fundamental physical terms and target values of engineering materials and systems related to the Energy Transition. Examples for new materials developments in areas of renewable energies (wind power, photovoltaics, concentrated solar power), lithium-ion and post-lithium batteries, supercapacitors and thermal storage systems. The essential materials properties are discussed and the resulting contributions to the development of energy engineering systems are introduced. The advantages and disadvantages of alternative materials solutions are discussed.

**Module grade calculation**

The module grade is equal to the grade of the oral exam.

**Workload**

The workload for the module is 120 h per semester and consists of the presence during the lectures (21 h) as well as self-study for the lecture (99 h).

**Recommendation**

Knowledge of Materials Science

**Learning type**

Lectures

**Literature**

Handbook of Energy Storage; M. Sterner, I. Stadler (eds.); Springer Vieweg (2019).

Energiespeicher, M. Sterner, I. Stadler (Editoren); 2. Auflage; Springer Vieweg (2017).

Elektrochemische Speicher, P. Kurzweil, O.K. Dietlmeier; 2. Auflage; Springer Vieweg (2018).

## M

**7.85 Module: Fabrication Processes in Microsystem Technology [M-MACH-105478]****Responsible:** Dr. Klaus Bade**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language       | Level | Version |
|---------|------------------|------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German/English | 4     | 1       |

| Mandatory     |   |      |      |
|---------------|---|------|------|
| T-MACH-102166 | <a href="#">Fabrication Processes in Microsystem Technology</a> | 4 CR | Bade |

**Competence Certificate**

Oral exam

**Prerequisites**

none

**Competence Goal**

Students of the course can

- outline and discuss a self-selected microtechnical process chain for a submitted microtechnical product or tool
  - Explain process steps in detail
  - Recognize connections between individual process steps
- reflect relevant interdisciplinary knowledge from chemistry, engineering and physics
- Describe typical tools (masks, mould inserts) and their production

**Content**

The lecture offers a specialization in manufacturing technology for structure generation in microtechnology, preferably with large height or high aspect ratio. For this purpose, the lithographic process chain (UV-, X-ray, electron beam, 2-photon lithography) is presented intensively in the first half of the lecture. Starting with typical substrates and resists, resist processing, exposure and development are treated. Micro electroplating is discussed to build metallic microstructures. In the second half of the lecture, production methods for typical tools such as masks and mold inserts are a main focus. Furthermore, newer concepts for micro- and nanostructuring based on self-organisation are presented.

Throughout the lecture the description of the process steps by simple and deeper reaching models at the interface between engineering, chemistry and physics is used for a deeper understanding. The role of recurring ideas, such as the role of mass transfer or kinetic control in the individual process steps, will be taught and simple rules for process control and plant design will be derived. Attention is drawn to similarities and differences with microelectronic manufacturing processes. Special attention is paid to the interactions between different manufacturing steps in the complex process chain with regard to cause-and-effect. The technically important guarantee of homogeneity in the surface and freedom from defects of the process result is discussed by means of some manufacturing steps.

Translated with [www.DeepL.com/Translator](http://www.DeepL.com/Translator) (free version)**Workload**

Literature: 19 h

Lessons: 21 h

Preparation and Review: 50 h

Exam preparation: 30 h

**Learning type**

Lecture

**Literature**

Menz, W., Mohr, J., O. Paul: Mikrosystemtechnik für Ingenieure, VCH-Verlag, Weinheim, 2005

M. Madou

Fundamentals of Microfabrication

Taylor &amp; Francis Ltd.; Auflage: 3. Auflage. 2011

## M

**7.86 Module: Field Propagation and Coherence [M-ETIT-100566]****Responsible:** Prof. Dr. Wolfgang Freude**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)**Credits**  
4**Grading scale**  
Grade to a tenth**Recurrence**  
Each winter term**Duration**  
1 term**Language**  
English**Level**  
4**Version**  
1

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-ETIT-100976 | <a href="#">Field Propagation and Coherence</a> | 4 CR | Freude |

**Competence Certificate**

Type of Examination: oral exam

Duration of Examination: approx. 30 minutes

Modality of Exam: Oral examination, usually one examination day per month during the summer and winter terms. An extra questions-and-answers session will be held for preparation if students wish so.

**Prerequisites**

none

**Competence Goal**

Presenting in a unified approach the common background of various problems and questions arising in general optics and optical communications

The students

- know the common properties of counting of modes, density of states and the sampling theorem
- comprehend the relationship between propagation in multimode waveguides, mode coupling, MMI and speckles
- can analyze propagation in homogeneous media with respect to system theory, antennas, and the resolution limit of optical instruments
- understand that coherence as a general concept comprises coherence in time, in space and in polarisation
- comprehend the implication of complete spatial incoherence, and what is the radiation efficiency of a source with a diameter smaller than a wavelength (the mathematical Hertzian dipole, for instance)
- can assess when can two incandescent bulbs form an interference pattern in time
- know under which conditions a heterodyne radio receiver, which is based on a non-stationary interference, actually works

**Content**

The following selection of topics will be presented:

- Light waves, modes and rays: Longitudinal and transverse modes, sampling theorem, counting and density of modes ("states")
- Propagation in multimode waveguides. Near-field and far-field. Impulse response and transfer function. Perturbations and mode coupling. Multimode interference (MMI) coupler. Modal noise (speckle)
- Propagation in homogeneous media: Resolution limit. Non-paraxial and paraxial optics. Gaussian beam. ABCD matrix
- Coherence of optical fields: Coherence function and power spectrum. Polarisation, eigenstates and principal states. Measurement of coherence with interferometers (Mach-Zehnder, Michelson). Self-heterodyne and self-homodyne setups

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

total 120 h, hereof 45 h contact hours (30 h lecture, 15 h problem class), and 75 h homework and self-studies

**Recommendation**

Minimal background required: Calculus, differential equations and Fourier transform theory. Electrodynamics and field calculations or a similar course on electrodynamics or optics is recommended.



**Literature**

Detailed lecture notes as well as the presentation slides can be downloaded from the IPQ lecture pages. Additional reading:

Born, M.; Wolf, E.: Principles of optics, 6. Aufl. Oxford: Pergamon Press 1980

Ghatak, A.: Optics, 3. Ed. New Delhi: Tata McGraw Hill 2005

Hecht, E.: Optics, 2. Ed. Reading: Addison-Wesley 1974

Hecht, J.: Understanding fiber optics, 4. Ed. Upper Saddle River: Prentice Hall 2002

Iizuka, K.: Elements of photonics, Vol. I and II. New York: John Wiley & Sons 2002

Further textbooks in German (also in electronic form) can be named on request

## M

**7.87 Module: Flows and Heat Transfer in Energy Technology [M-MACH-107120]**

**Responsible:** Dr. Aurelian Florin Badea  
Prof. Dr.-Ing. Xu Cheng

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-105403 | <a href="#">Flows and Heat Transfer in Energy Technology</a> | 4 CR | Cheng |

**Competence Certificate**

A performance assessment will consist of an oral examination of approx. 20 minutes.

**Prerequisites**

none

**Competence Goal**

The objective of the module is the understanding of major processes in fluid dynamics and heat transfer in energy engineering. Through this lecture the students are capable of understanding the important physical processes and the selection of suitable methods for the analysis of the processes. With the discussion of some practical examples, the students can analyze the pressure drop and heat transfer in energy engineering systems.

**Content**

1. collection of sample applications
2. heat transfer and its application
3. convective fluid dynamics and heat transfer
4. thermal radiation and its application
5. special cases

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

(for details see individual course)

## M

**7.88 Module: Fundamentals in the Development of Commercial Vehicles [M-MACH-105824]****Responsible:** Christof Weber**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 2 terms  | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-111389 | <a href="#">Fundamentals in the Development of Commercial Vehicles</a> | 4 CR | Weber |

**Competence Certificate**

Oral exam; duration approximately 30 minutes

**Prerequisites**

None

**Competence Goal**

The students have proper knowledge about the process of commercial vehicle development starting from the concept and the underlying original idea to the real design. They are able to plan, to steer, and to handle this process. They can apply their knowledge effectively in actual practise. They know that the customer requirements, the technical realisability, the functionality and the economy are important drivers.

They are able to develop parts and components. Furthermore they have knowledge about different cab concepts, the interior and the interior design process. Consequently they are ready to analyze and to judge concepts of commercial vehicles as well as to participate competently in the commercial vehicle development.

They know the advantages and disadvantages of different drives. Furthermore they are familiar with components, such as transfer box, propeller shaft, powered and non-powered frontaxle etc. Beside other mechanical components, such as chassis, axle suspension and braking system, also electric and electronic systems are known. Consequently the student are able to analyze and to judge the general concepts as well as to adjust them precisely with the area of application. They can apply their knowledge effectively in actual practise.

**Content**

The module provides an overview of:

- 1.1. Introduction, definitions, history
- 1.2. Development tools
- 1.3. Complete vehicle
- 1.4. Cab, bodyshell work
- 1.5. Cab, interior fitting
- 1.6. Alternative drive systems
- 1.7. Drive train
- 1.8. Drive system diesel engine
- 1.9. Intercooled diesel engines
- 2.1. Gear boxes of commercial vehicles
- 2.2. Intermediate elements of the drive train
- 2.3. Axle systems
- 2.4. Front axles and driving dynamics
- 2.5. Chassis and axle suspension
- 2.6. Braking System
- 2.7. Systems
- 2.8. Excursion

**Workload**

1. regular attendance lecture:  $8 * 4 \text{ h} = 32 \text{ h}$
  2. pre and postprocessing lecture:  $8 * 6 \text{ h} = 48 \text{ h}$
  3. examination preparation and presence in examination: 40 h
- In total: 120 h = 4 LP (2 semester)

**Learning type**

Tutorial

**Literature**

1. SPECKERT, M.; RUF, N.; DRESSLER, K.; MÜLLER, R.; WEBER, C.; WEIHE, S.: Ein neuer Ansatz zur Ermittlung von Erprobungslasten für sicherheitsrelevante Bauteile; Kaiserslautern: Fraunhofer ITWM, 2009, 27 pp.; Berichte des Fraunhofer ITWM, 177; ISSN: 1434-9973
2. SPECKERT, M.; DRESSLER, K.; RUF, N.; MÜLLER, R.; WEBER, C.: Customer Usage Profiles, Strength Requirements and Test Schedules in Truck Engineering, in: Schindler, C. et al. (Eds.): Proceedings of the 1st Commercial Vehicle Technology Symposium (CVT 2010), Shaker Verlag, 2010, S. 298-307
3. TEUTSCH, R. RITTER, J.; WEBER, C.; KOLB, G.; VILCENS, B.; LOPATTA, A.: Einsatz eines Fahrerleitsystems zur Qualitätssteigerung bei der Betriebsfestigkeitserprobung, Proceedings, 1st Commercial Vehicle Technology Symposium Kaiserslautern, 16. – 18. März 2010
4. WEBER, C.; MÜLLER, R.; TEUTSCH, R.; DRESSLER, K.; SPECKERT, M.: A New Way to Customer Loads Correlation and Testing in Truck Engineering of Daimler Trucks, Proceedings of the 1st International Munich Chassis Symposium, chassis.tech, Munich, Germany, 8th - 9th Juni 2010
5. TEUTSCH, R.; WEBER, C.; MÜLLER, R.; SCHON, U.; EPPLER, R.: Einsatzspezifische Erprobung als Baustein zur Verringerung des Fahrzeuggewichts von Lastkraftwagen, DVM-Berichtsband 138, S. 189 – 201, 20

## M

**7.89 Module: Fundamentals of Combustion I [M-MACH-102707]**

**Responsible:** Prof. Dr. Ulrich Maas  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |      |
|---------------|--|------|------|
| T-MACH-105213 | <a href="#">Fundamentals of Combustion I</a> | 4 CR | Maas |

**Competence Certificate**

Written exam, graded, approx. 3 h

**Prerequisites**

none

**Competence Goal**

After completing the course, the students are able to analyze the functionality of technical combustion systems (e.g. piston engines, gas turbines, furnaces). With regard to environmental pollution, students can name the mechanisms of combustion and pollutant formation and assess concepts for reducing pollutants. They can explain the fundamental chemical and physical processes of combustion and name experimental methods for investigating flames. Furthermore, the students can also describe the differences between laminar and turbulent flames and explain the principles of ignition processes.

**Content**

The lecture gives an overview of the basic terms and phenomena of technical combustion. In a basic chapter, experimental methods for investigating flames are taught. Conservation equations for laminar flames are derived based on scientific phenomena. In addition, the laminar premixed flame and the laminar non-premixed flame are treated as examples. Knowledge of chemical reactions and their description with reaction mechanisms is conveyed. Furthermore, ignition processes are taught. The content of the lecture is deepened in exercises and applied to specific problems and tasks.

**Module grade calculation**

Grade of the written exam (100%)

**Workload**

General attendance: 30 h

Preparation time for the lecture: 30 h

General attendance (Tutorial): 30 h

Self-study: 30 h

**Recommendation**

none

**Learning type**

Lecture

Exercise course

**Literature**

Lecture notes,

Combustion - Physical and Chemical Fundamentals, Modeling and Simulation, Experiments, Pollutant Formation, authors: U. Maas, J. Warnatz, R.W. Dibble, Springer-Lehrbuch, Heidelberg 1996

## M

**7.90 Module: Fundamentals of Combustion II [M-MACH-107117]**

**Responsible:** Dr. Viatcheslav Bykov  
Prof. Dr. Ulrich Maas

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |             |
|---------------|---|------|-------------|
| T-MACH-114044 | <a href="#">Fundamentals of Combustion II</a> | 4 CR | Bykov, Maas |

**Competence Certificate**

See course

**Prerequisites**

none

**Competence Goal**

The students gain understanding of combustion fundamentals especially numerical aspects of turbulent reacting flows. The knowledge earned in this course will help them to apply these fundamentals in the various branches of mechanical engineering like computational fluid dynamics, energy and power engineering, automotive engineering, etc. This course provides basic understanding of transport equations used not only in numerical combustion but also in fluid dynamics and complex interaction between turbulence and chemical kinetics. Different tools used in simulation of turbulent reacting flows are discussed which has a practical significance to reduce the massive computational costs associated with these simulations while maintaining accuracy. Applications of turbulent combustion fundamentals are discussed to understand knocking phenomena in engines, solid and liquid combustions, and effects of combustion on atmosphere.

After completion of this course students are able to:

- understand the basic understanding of governing transport equations for turbulent reacting flows.
- apply tools used in the simulations of turbulent reacting flows.
- learn basic knowledge about solid and liquid combustion and engine knocking phenomenon.

**Content**

- Thermodynamics of combustion processes
- Transport phenomena
- Three dimensional Navier-Stokes equations for reacting flows
- Tools in turbulent reacting flows
- Turbulent non-premixed flames
- Turbulent premixed flames
- Combustion of liquid and solid fuels
- Engine knock
- Effects of Combustion Processes on the Atmosphere

**Module grade calculation**

Grade corresponds to the grade of course

**Annotation**

Lectures are offered in German and English

**Workload**

120h

(for details see individual course)

**Learning type**

Lecture and tutorial

## M

**7.91 Module: Fundamentals of Energy Technology [M-MACH-102690]**

**Responsible:** Dr. Aurelian Florin Badea  
Prof. Dr.-Ing. Xu Cheng

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 8       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |              |
|---------------|---|------|--------------|
| T-MACH-105220 | <a href="#">Fundamentals of Energy Technology</a> | 8 CR | Badea, Cheng |

**Competence Certificate**

A performance assessment will consist of a written examination of 90 minutes.

**Prerequisites**

none

**Competence Goal**

The objective of the module is to train the students on state of the art knowledge about the challenging fields of energy industry and the permanent competition between the economical profitability and the long-term sustainability. The students obtain basic knowledge on thermodynamics relevant to the energy sector and comprehensive knowledge on the energy sector: demand, energy types, energy mix, installations for energy production (conventional, nuclear and renewable), transport and energy storage, environmental impact and future tendencies. Students are able to use methods of economic efficiency optimization for the energy sector in a creative way, practice oriented, also specifically trained during the corresponding tutorial. The students are qualified for further training in energy engineering related fields and for (also research-related) professional activity in the energy sector.

**Content**

The following relevant fields of the energy industry are covered:

- Energy demand and energy situation
- Energy types and energy mix
- Basics. Thermodynamics relevant to the energy sector
- Conventional fossil-fired power plants
- Combined Cycle Power Plants
- Cogeneration
- Nuclear energy
- Regenerative energies: hydropower, wind energy, solar energy, other energy systems
- Energy demand structures. Basics of economic efficiency and calculus. Optimization
- Energy storage
- Transport of energy
- Power generation and environment. Future of the energy industry

**Module grade calculation**

The module grade is the grade of the written examination.

**Workload**

1. lectures:  $15 * 3 \text{ h} = 45 \text{ h}$
  2. preparation for lectures:  $15 * 2 \text{ h} = 30 \text{ h}$
  3. tutorials:  $15 * 2 \text{ h} = 30 \text{ h}$
  4. preparation for tutorials:  $15 * 1 \text{ h} = 15 \text{ h}$
  5. preparation for exam: 120 h
- Total: 240 h = 8 LP

## M

**7.92 Module: Fundamentals of Reactor Safety for the Operation and Dismantling of Nuclear Power Plants [M-MACH-107150]****Responsible:** Dr. Victor Hugo Sanchez-Espinoza**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German/English | 4     | 1       |

| Mandatory     |  |      |                  |
|---------------|--|------|------------------|
| T-MACH-105530 | <a href="#">Fundamentals of Reactor Safety for the Operation and Dismantling of Nuclear Power Plants</a> | 4 CR | Sanchez-Espinoza |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

The student can

- explain the basic principles of reactor safety and understand and classify the inherent safety characteristics of reactors
- understand the operating phases and types of a nuclear power plant
- understand and categorize the main mechanisms and components for heat removal and safety systems
- familiarize themselves with the main phases of dismantling a nuclear power plant
- estimate amount of radioactive materials generated in a nuclear power plant as well as the contamination and activation processes
- understand and classify the regulatory framework and radiation protection measures to minimize risks during decommissioning

**Content**

This lecture gives an introduction to reactor safety fundamentals for both the operation and the decommissioning of nuclear power plants with the focus on decommissioning. The lecture is devoted to:

- Nuclear power plants and operational aspects
- Reactor safety fundamentals as defense in depth, multi-barrier concepts
- Life cycle of a nuclear power plant and main strategies and challenges in the NPP decommissioning
- Physical processes responsible for the activation of reactor components during the operation of a nuclear power plant
- Radioactive waste generation in the core, classification and radiological relevance
- Waste classification, minimization methods and intermediate and final disposal
- Risk analysis and prevention, radiation protection issues and the regulatory framework for decommissioning
- Computational methods for the estimation of nuclei inventories, activation and dose rates of reactor components

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

(for details see individual course)



## M

**7.93 Module: Fusion Technology A [M-MACH-107124]**

**Responsible:** Dr. Sara Perez Martin  
Dr. Klaus-Peter Weiss

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German/English | 4     | 1       |

| Mandatory     |                                     |      |                     |
|---------------|-------------------------------------|------|---------------------|
| T-MACH-105411 | <a href="#">Fusion Technology A</a> | 4 CR | Perez Martin, Weiss |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

To transfer the basic physical concepts of particle physics, fusion and nuclear fission; this includes fundamental questions such as how: What is a plasma? How can it be ignited? What is the difference between magnetic and inertial fusion? Based on this, aspects of the stability of plasmas, their control and particle transport are discussed. After characterizing the plasma, the "fire" of fusion, the confinement in magnetic fields is sketched, which are built up with the help of magnetic technology. Here, knowledge of superconductivity, production and design of magnets is imparted. A reactor operation with a plasma as energy source requires a continuous operation of a tritium and fuel cycle, which is generated by the fusion reactor itself. Since fusion plasmas require small material densities, vacuum technology plays a central role. Finally, the heat generated in the fusion power plant must be converted into a power plant process and the reaction products removed. The functional basics and the structure of these fusion-typical in-vessel components are presented and the current challenges and the state of the art are demonstrated.

**Content**

The course describes the essential functional principles of a fusion reactor, beginning with plasma, magnet technology, the tritium and fuel cycle, vacuum technology and the associated material sciences. The physical basics will be taught and the engineering laws of scaling will be demonstrated. Special importance is attached to the understanding of the interfaces between the different subject areas, which essentially determine the engineering technical interpretations. Methods for identifying and evaluating the central parameters will be demonstrated. Based on the acquired perception skills, methods for the design of solution strategies will be taught and technical solutions will be identified, their weak points discussed and evaluated.

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

(for details see individual course)

## M

## 7.94 Module: Fusion Technology B [M-MACH-107154]

**Responsible:** Dr. Sara Perez Martin  
Dr. Michael Rieth

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German/English | 4     | 1       |

| Mandatory     |                                     |      |                     |
|---------------|-------------------------------------|------|---------------------|
| T-MACH-105433 | <a href="#">Fusion Technology B</a> | 4 CR | Perez Martin, Rieth |

### Competence Certificate

see individual course

### Prerequisites

Knowledge of physics, heat and mass transfer, and design theory taught in the bachelor's degree. Attendance of the lecture Fusion technology A

### Competence Goal

The lecture, which runs over 2 semesters, is aimed at students of engineering sciences and physics after the bachelor. The aim is an introduction to the current research and development on fusion and its long-term goal of a promising energy source. After a short insight into fusion physics, the lecture focuses on key technologies for a future fusion reactor.

### Content

Fusion neutronics, materials science of thermally and neutronicly highly loaded components, reactor scaling and safety as well as plasma heating and current drive. The section fusion neutronics develops the basics of fusion neutronics and its calculation methods, the nuclear physical design of a fusion reactor and the corresponding components (blankets, shielding, activation, tritium breeding ratio and dose rate). Since both neutron fluxes and area power density in a fusion power plant are significantly higher than those of other power plants, they require special materials. After an extension of existing material knowledge by fundamentals and methods for the calculation of radiation damage in materials, strategies for the material selection of functional and structural materials are shown and deepened by examples. The arrangement of components close to the plasma in a fusion power plant means changed requirements for system integration and energy conversion; these questions are the subject of the block reactor scaling and safety. In addition to the explanation of the safety objectives, the methods for achieving the objectives and the computational tools required to achieve them are dealt with in particular. To ignite the plasma, extreme temperatures of several million degrees are required. Special plasma heating methods are used for this purpose, such as electron cyclotron resonance heating (ECRH), ion cyclotron resonance heating (ICRH), current drive at the lower hybrid frequency and neutral particle injection. Their basic mode of action, design criteria, transmission options and performance are presented and discussed. In addition, the heating processes can also be used for plasma stabilization. Some considerations and limitations are presented.

### Module grade calculation

see individual course

### Workload

120h

(for details see individual course)

## M

**7.95 Module: Handling Characteristics of Motor Vehicles I [M-MACH-105288]**

**Responsible:** Dr.-Ing. Martin Gießler  
Dr.-Ing. Hans-Joachim Unrau

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-105152 | <a href="#">Handling Characteristics of Motor Vehicles I</a> | 4 CR | Unrau |

**Competence Certificate**

Oral examination, duration: approximately 30 minutes.

**Competence Goal**

The students know the basic connections between drivers, vehicles and environment. They can build up a vehicle simulation model, with which forces of inertia, aerodynamic forces and tyre forces as well as the appropriate moments are considered. They have proper knowledge in the area of tyre characteristics, since a special meaning comes to the tire behavior during driving dynamics simulation. Consequently they are ready to analyze the most important influencing factors on the driving behaviour and to contribute to the optimization of the handling characteristics.

**Content**

1. Problem definition: Control loop driver - vehicle - environment (e.g. coordinate systems, modes of motion of the car body and the wheels)
2. Simulation models: Creation from motion equations (method according to D'Alembert, method according to Lagrange, programme packages for automatically producing of simulation equations), model for handling characteristics (task, motion equations)
3. Tyre behavior: Basics, dry, wet and winter-smooth roadway

**Workload**

The total work load for this module is about 120 Hours (4 Credits). The partition of the work load is carried out according to the credit points of the courses of the module. The work load for courses with 4 credit points is about 120 hours

**Learning type**

Lecture

## M

**7.96 Module: Handling Characteristics of Motor Vehicles II [M-MACH-107073]****Responsible:** Dr.-Ing. Martin Gießler**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-MACH-105153 | <a href="#">Handling Characteristics of Motor Vehicles II</a> | 4 CR | Unrau |

**Competence Certificate**

oral examination, duration: approximately 30 minutes

**Prerequisites**

none

**Content**

1. Vehicle handling: Bases, steady state cornering, steering input step, single sine, double track switching, slalom, cross-wind behavior, uneven roadway

2. stability behavior: Basics, stability conditions for single vehicles and for vehicles with trailer

Learning Objectives:

The students have an overview of common test methods, with which the handling of vehicles is gauged. They are able to interpret results of different stationary and transient testing methods. Apart from the methods, with which e.g. the driveability in curves or the transient behaviour from vehicles can be registered, also the influences from cross-wind and from uneven roadways on the handling characteristics are well known. They are familiar with the stability behavior from single vehicles and from vehicles with trailer. Consequently they are ready to judge the driving behaviour of vehicles and to change it by specific vehicle modifications.

**Module grade calculation**

see individual course

**Workload**

120h

(for details see individual course)

**Literature**

1. Zomotor, A.: Fahrwerktechnik: Fahrverhalten, Vogel Verlag, 1991
2. Mitschke, M./Wallentowitz, H.: Dynamik von Kraftfahrzeugen, Springer-Verlag, Berlin, 2004
3. Gnadler, R.; Unrau, H.-J.: Umdrucksammlung zur Vorlesung Fahreigenschaften von Kraftfahrzeugen II

## M

**7.97 Module: Hardware Modeling and Simulation [M-ETIT-100449]**

**Responsible:** Dr.-Ing. Jens Becker  
Prof. Dr.-Ing. Jürgen Becker

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 2       |

| Mandatory     |  |      |                |
|---------------|--|------|----------------|
| T-ETIT-100672 | <a href="#">Hardware Modeling and Simulation</a> | 4 CR | Becker, Becker |

**Competence Certificate**

Achievement is examined in the form of a written examination lasting 120 minutes.

**Prerequisites**

none

**Competence Goal**

After completing this module, students will be familiar with different hardware description languages and their applications in various abstraction levels. They will gain knowledge of the SPICE Hardware Description Language and become proficient in building and deriving the analog matrix for spice simulation. In the realm of digital design, they will develop a comprehensive understanding of the hardware description language VHDL, encompassing the VHDL Standard and its extensions, such as VHDL 2008, the 9-valued logic, and the VHDL-AMS standard. Furthermore, students will achieve a profound comprehension of simulator principles, particularly the delta cycle model. They will also grasp the fundamentals of fault simulations for testing fabricated circuits and learn to derive test vectors. Additionally, students will acquire an understanding of higher-level hardware construction languages like Chisel and SystemC.

**Content**

In order to address the complexity of modern chips during development, it is essential to utilize modern hardware description languages. This course offers insights into the various levels of abstraction in these languages. It starts by covering the fundamentals of analog description using SPICE and then progresses through VHDL, VHDL-AMS, and Verilog. Additionally, the course introduces more abstract languages like Chisel and SystemC.

Topics covered in the course are:

- Design Process
- Basics of Modeling and Simulation
- Low Level Modeling
- VHDL
  - VHDL-AMS
  - 9-valued logic
  - Delta cycle simulation
  - Fault simulation
- Verilog
- Chisel
- SystemC

**Module grade calculation**

The module grade results from the grade of the written examination.

**Workload**

The workload is covered by:

1. Participating in lectures and tutorials: 33h
2. Preparing and wrap up of the above named units: 66h
3. Exam preparation and presence: 21h

Sum: 120h = 4 LP

## M

**7.98 Module: Hardware Synthesis and Optimization [M-ETIT-106963]****Responsible:** Prof. Dr.-Ing. Jürgen Becker**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-ETIT-113922 | <a href="#">Hardware Synthesis and Optimization</a> | 6 CR | Becker |

**Competence Certificate**

The examination takes place within the framework of an oral overall examination (approx. 30 minutes)

**Prerequisites**

none

**Competence Goal**

Students know the basic steps required for the automated design of optimized digital circuits. They are able to classify them in the Y-chart and assess their complexity.

They will be able to name and explain the most important approaches for these design steps and evaluate them with regard to optimality and computational effort. This includes the ability to use algorithms for these approaches, e.g. selected graph algorithms, metaheuristics such as simulated annealing. The students are also able to determine their respective runtime complexities.

In addition, they can solve given problems from the field of design automation by selecting a suitable approach based on certain optimization criteria and applying it to the respective problem.

**Content**

The module focuses on teaching the formal and methodological foundations for the automated design of optimized electronic systems. The relevant scientific and methodological properties of the methods used are discussed and their implementation in industrial practice is also taught.

The following topics are covered:

- Graph Algorithms and Complexity
- High-Level Synthesis
- Algorithms for Scheduling, Allocation and Binding Problems
- Register-Transfer-Level Synthesis
- Retiming Algorithms
- Logic Optimization
- Technology Mapping for Standard Cells and FPGAs
- Physical Design
- Placement of Standard Cells with ILP and Simulated Annealing
- Global and Detailed Routing

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

The workload includes (4 SWS):

1. attendance in lectures and exercises: 50 h
2. preparation / follow-up: 50 h
3. preparation of and attendance in examination: 80 h

A total of 180 h = 6 CR

**Recommendation**

Basic knowledge in the field of digital circuits, e.g. as taught in the course "Digital Technology" (2311615) is helpful.

## M

**7.99 Module: Hardware/Software Co-Design [M-ETIT-100453]**

**Responsible:** Prof. Dr.-Ing. Jürgen Becker  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-ETIT-100671 | <a href="#">Hardware/Software Co-Design</a> | 4 CR | Harbaum |

**Competence Certificate**

Success control takes place in the form of an oral examination (approx. 20 minutes).

**Prerequisites**

none

**Competence Goal**

By attending the Hardware/Software Co-Design lecture, students learn the necessary multi-criteria methods and hardware/software target architectures. Attending the lecture contributes to the understanding of these methods of hardware/software co-design and enables students to apply what they have learned to novel problems.

Students learn about the main target architectures and are able to name their advantages and disadvantages with regard to their applicability in hardware/software co-design. Students will become familiar with various methods for assessing design quality and will be able to apply these in the early phases of system design. Furthermore, students have an overview of partitioning methods for HW/SW systems, can classify them and know the respective advantages and disadvantages of the methods. Students will be able to select and apply a suitable method for typical HW/SW partitioning problems.

By attending the course, students will have a cross-component understanding of the topic of co-design. Furthermore, attending the course enables students to apply the methods presented to problems independently. Tools that are introduced in the course of the lecture can be used for this purpose.

Attending the lecture enables students to independently classify current scientific work, e.g. theses, and to work on them using the latest methods.

**Content**

- The lecture presents the theoretical principles of the interlinked design of hardware and software parts of a system. In addition, their practical application is demonstrated using various current software and hardware components.
- The accompanying exercises are intended to consolidate the knowledge acquired in the lectures. Selected topics are repeated and students learn how to apply the methods for modern system design using theoretical and practical examples.
- Hardware-software co-design is the simultaneous and interlinked design of hardware and software parts of a system. Most modern embedded systems (examples are cell phones, automotive and industrial control systems, game consoles, home cinema systems, network routers) consist of cooperating hardware and software components. Enabled by rapid advances in microelectronics, embedded systems are becoming increasingly complex with diverse application-specific criteria. The use of appropriate computer-aided design tools is not only necessary to handle the increasing complexity, but also to reduce design costs and design time. The lecture Hardware Software Co-Design deals with the necessary multi-criteria methods and hardware/software target architectures:
  - Target architectures for hardware/software systems
    - Processor design: pipelining, superscalarity, VLIW, SIMD, cache, MIMD
    - General-purpose processors (GPP), microcontrollers ( $\mu$ C), digital signal processors (DSP), graphics processors (GPU), application-specific instruction set processors (ASIP), field programmable gate arrays (FPGA), system-on-chip (SoC), bus systems, multicore and network-on-chip (NoC)
  - Assessment of the design quality
    - Hardware and software performance
  - Hardware/software partitioning methods
    - Iterative and constructive heuristics



**Module grade calculation**

The module grade is the grade of the oral examination.

**Annotation**

Will be changed to 6 CR in winter term 25/26.

**Workload**

The workload includes:

1. attendance time in 14 lectures, 7 exercises: 31.5 hrs
2. preparation and follow-up of the same: 63 hours (3 hours per unit)
3. exam preparation and attendance: 20 hours preparation and 0.5 hours exam

**Recommendation**

Knowledge of the basics of digital technology and information technology is helpful.

## M

## 7.100 Module: Heat and Mass Transfer [M-MACH-102717]

**Responsible:** Prof. Dr. Ulrich Maas

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-MACH-105292 | <a href="#">Heat and Mass Transfer</a> | 4 CR | Maas, Yu |

### Competence Certificate

Written exam, graded, approx. 3 hours

### Prerequisites

none

### Competence Goal

The students will have knowledge of the basic processes, laws and calculation methods of heat and mass transfer based on dimension analysis. Further, they can use it to analyze and derive application systems of industrial importance in the fields of mechanical engineering, energy and process engineering.

### Content

The lecture gives an overview of stationary and unsteady heat conduction phenomena in homogeneous and composite bodies; such as plates, pipe shells and spherical shells. Molecular diffusion in gases and the analogy between diffusion and heat conduction are thought. The lecture provides an overview of convective, forced heat transfer in pipes / channels with a flow, as well as plates and profiles that are flown over. In addition, the module conveys knowledge of the mass / heat transfer analogy and the multiphase, convective heat transfer (condensation, evaporation), as well as the convective mass transfer is taught. This module is intended to convey to students the theoretical and practical aspects of the radiant heat transport of solids and gases. The content of the lecture is deepened in exercises and applied to specific problems and tasks.

### Module grade calculation

Grade of the written exam (100%)

### Workload

General attendance: 30 h

Preparation time for the lecture: 30 h

General attendance (Tutorial): 30 h

Self-study: 30 h

### Recommendation

none

### Learning type

Lecture

Exercise course

### Literature

- Maas ; Vorlesungsskript "Wärme- und Stoffübertragung"
- Baehr, H.-D., Stephan, K.: "Wärme- und Stoffübertragung" , Springer Verlag, 1993
- Incropera, F., DeWitt, F.: "Fundamentals of Heat and Mass Transfer" , John Wiley & Sons, 1996
- Bird, R., Stewart, W., Lightfoot, E.: "Transport Phenomena" , John Wiley & Sons, 1960

## M

**7.101 Module: Heat Pumps [M-MACH-107075]**

**Responsible:** Prof. Dr. Ulrich Maas  
Dr. Heiner Wirbser

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |                           |      |               |
|---------------|---------------------------|------|---------------|
| T-MACH-105430 | <a href="#">Heatpumps</a> | 4 CR | Maas, Wirbser |

**Competence Certificate**

See individual course

**Prerequisites**

none

**Competence Goal**

The students:

- are able to describe the current energy situation and energy policy requirements and analyze their significance for the use of heat pumps.
- are able to characterize and evaluate the functionality and possible applications of different heat sources for heat pumps.
- can identify different types of heat pumps and analyze their respective advantages and disadvantages.
- are able to explain the thermodynamic principles of the heat pump process and understand the thermodynamic relationships. They can illustrate these using diagrams.
- have a profound understanding of the function of a heat pump and can explain the interaction of heat pumps and their components.
- are able to explain the functionality and possible applications of absorption and adsorption heat pumps.
- are able to assess the economic and ecological aspects of heat pump systems.
- are able to carry out basic calculations for the design of a heat pump system and carry out economic feasibility studies.
- are able to explain the function, possible applications and different types of heat accumulators in connection with heat pump systems.

**Content**

The aim of the lecture is to analyze the heat pump as a potential heating system for small and medium-sized systems and to make a well-founded assessment of its advantages and disadvantages. After considering the current energy situation and the resulting energy policy requirements, the central technical, economic and ecological aspects of heat pumps are examined. The requirements for different heat sources, the components of a heat pump and different types of heat pumps are systematically analyzed. In addition, environmental and economic aspects are evaluated. Finally, the integration of heat pumps with heat storage tanks in heating systems is discussed.

**Module grade calculation**

Grade corresponds to the grade of course

**Workload**

120h

(for details see individual course)

**Learning type**

Lecture

**M****7.102 Module: High-Voltage Technology [M-ETIT-105060]****Responsible:** Dr.-Ing. Rainer Badent**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-ETIT-110266 | <a href="#">High-Voltage Technology</a> | 6 CR | Badent |

## M

## 7.103 Module: High-Voltage Test Technique [M-ETIT-100417]

**Responsible:** Dr.-Ing. Rainer Badent

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-ETIT-101915 | <a href="#">High-Voltage Test Technique</a> | 4 CR | Badent |

**Prerequisites**

none

## M

**7.104 Module: Holistic Approach of Managing Power Plant Operation under Uncertainty and Volatility [M-MACH-107097]****Responsible:** Dr. Marcus Seidl**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-112238 | <a href="#">Holistic Approach of Managing Power Plant Operation under Uncertainty and Volatility</a> | 4 CR | Seidl |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

Students understand the many aspects of power plant operation: the structure of the energy and commodity markets, the regulatory boundary conditions, the energy trading instruments, the principles of fleet management and the requirements of power plant maintenance.

Furthermore, students can develop on their own a suitable strategy for the management of a power plant fleet.

**Content**

The structure of electricity markets

Requirements from network operators

The basics of commodity markets

The impact of regulation on power plant operation

The role of behavioral economics in power plant decision making

Integration of renewable energy sources into the electricity market

Calibration of power plant operation and maintenance to market requirements

Asset management for power plant fleets

Applying financial engineering to optimize asset utilization

Day-to-day decision making for power plant operation

The lecture provides an overview of the many practical aspects of power plant operation. For this purpose, the knowledge of the energy and commodity markets, the regulatory boundary conditions, the energy trading instruments, the principles of fleet management and the requirements of power plant maintenance are required.

For the purpose of an efficient management of a power plant fleet it is explained how a variety of statistical models can be used to determine the optimal combination of resource purchases, outage management, load availability and ask prices.

**Module grade calculation**

The grade corresponds to the grade of the oral examination.

**Workload**

120 hours, of which 30 hours attendance and 90 hours self-study

**Learning type**

Lecture

## M

**7.105 Module: Hot Research Topics in AI for Engineering Applications [M-MACH-107089]****Responsible:** Prof. Dr.-Ing. Anne Meyer**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-113669 | <a href="#">Hot Research Topics in AI for Engineering Applications</a> | 4 CR | Meyer |

**Competence Certificate**

See individual course

**Prerequisites**

None

**Competence Goal**

After the event, participants will be able to:

- Identify the technical and algorithmic foundations behind the relevant research topics and explain their functionalities
- Identify application possibilities of current research findings and related technologies in an industrial context, as well as the challenges that arise in the process
- Implement solutions proposed in recent publications using existing frameworks and codebases as prototypes
- Structure and execute programming projects in a team
- Clearly present the results of practical projects tailored to the audience

**Content**

In " Hot Research Topics in AI for Engineering Applications", we explore the applicability of cutting-edge research findings in the fields of Machine Learning and Artificial Intelligence (e.g., LLM agents, Reinforcement Learning) to applications in engineering (e.g., optimization in production and logistics, creation of CAD models). Each year, we offer a different methodological focus (more on the IMI-homepage).

First, we provide the theoretical foundations and then move into a group work phase where students implement and analyze an application prototype. The event is aimed at students with prior knowledge in machine learning and programming.

- Theoretical foundations of the technologies considered in the course (e.g., Deep Learning, Transformers, LLM)
- Application possibilities of modern technologies in an industrial context
- Challenges in making current research findings usable for solving specific engineering problems and productive use
- Implementation of solutions to apply modern technologies to specified engineering problems (usually Python-based, using current frameworks)
- Independent execution of an implementation project with current, thematically relevant content (e.g., LLM agents for interaction with external systems such as robots, for algorithm construction, or for creating 3D CAD models, etc.)
- Technologies and applications are announced at the beginning of each semester

**Annotation**

Limited number of participants

**Workload**

120 h

(for details see individual course)

**Recommendation**

Basic knowledge of artificial intelligence and machine learning, Programming experience, preferably in Python, English proficiency

**M****7.106 Module: Human Brain and Central Nervous System: Anatomy, Information Transfer, Signal Processing, Neurophysiology and Therapy (24139 / 24678) [M-INFO-100725]****Responsible:** Prof. Dr.-Ing. Tamim Asfour**Organisation:** KIT Department of Informatics**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |                  |
|---------------|---|------|------------------|
| T-INFO-101262 | <a href="#">Human Brain and Central Nervous System: Anatomy, Information Transfer, Signal Processing, Neurophysiology and Therapy</a> | 3 CR | Asfour, Spetzger |



**M****7.107 Module: Human-Machine-Interaction in Anthropomatics: Basics (24100) [M-INFO-100824]****Responsible:** Prof. Dr.-Ing. Jürgen Beyerer**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |                      |
|---------------|---|------|----------------------|
| T-INFO-101361 | <a href="#">Human-Machine-Interaction in Anthropomatics: Basics</a> | 3 CR | Beyerer, van de Camp |

## M

## 7.108 Module: Humanoid Robots - Seminar [M-INFO-107152]

**Responsible:** Prof. Dr.-Ing. Tamim Asfour

**Organisation:** KIT Department of Informatics

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |                           |      |        |
|---------------|---------------------------|------|--------|
| T-INFO-114170 | Humanoid Robots - Seminar | 3 CR | Asfour |

### Competence Certificate

See partial Achievements (Teilleistung)

### Prerequisites

See partial Achievements (Teilleistung)

### Competence Goal

The students choose a topic from the field of humanoid robotics, e.g. robot design, motion generation, perception or learning. They conduct a literature research on this topic under the guidance of a scientific supervisor. At the end of the semester, they present the results and write a term paper in English in the form of a scientific publication.

Students are familiar with the DFG Code of Conduct "Guidelines for Safeguarding Good Scientific Practice" and successfully apply these guidelines in the preparation of their scientific work.

### Content

The student gained experience with literature research on a current research topic. He/she explored, understood and compared different approaches to a selected scientific problem. The student is able to write a summary of their literature research in the form of a scientific publication in English and to give a scientific talk on it.

### Workload

Seminar with 2 SWS, 3 LP

3 LP corresponds to 90 hours, including

45 hours literature research

25 hours manuscript preparation

10 hours preparation of the presentation

10 hours attendance time

### Recommendation

Attending the lectures Robotics I – Introduction to Robotics, Robotics II: Humanoid Robotics, Robotics III – Sensors and Perception in Robotics, Mechano-Informatics and Robotics and Wearable Robotic Technologies is recommended.

**M****7.109 Module: Hydrogen and reFuels - Energy Conversion in Combustion Engines [M-MACH-107158]****Responsible:** Prof. Dr. Thomas Koch**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-111585 | <a href="#">Hydrogen and reFuels - Energy Conversion in Combustion Engines</a> | 4 CR | Kubach |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

Students can name and describe the individual phases of the engine process and explain and thermodynamically analyze the overall process. They can name and explain special aspects of alternative fuels.

**Content**

Introduction

Fundamentals of engine processes

Thermodynamics of the combustion engine

Gas exchange

Flow field

Wall heat losses

Fundamentals and analysis of gasoline engine energy conversion

Fundamentals and analysis of diesel engine energy conversion

Mixture formation, ignition, combustion of hydrogen

Mixture formation, ignition, combustion of reFuels: HVO, methanol, NH<sub>3</sub>, eFuels, ethanol

Waste heat recovery

**Module grade calculation**

see individual course

**Workload**

120h

(for details see individual course)

## M

## 7.110 Module: Industrial Circuitry [M-ETIT-100399]

**Responsible:** Dr.-Ing. Andreas Liske

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |                                      |      |       |
|---------------|--------------------------------------|------|-------|
| T-ETIT-100716 | <a href="#">Industrial Circuitry</a> | 3 CR | Liske |

#### Prerequisites

none

#### Module grade calculation

Die Modulnote ist die Note der mündlichen Prüfung.

## M

**7.111 Module: Industrial Mobile Robotics Lab [M-MACH-106830]**

**Responsible:** Prof. Dr.-Ing. Kai Furmans  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale | Recurrence | Duration | Language | Level | Version |
|---------|---------------|------------|----------|----------|-------|---------|
| 4       | pass/fail     | Each term  | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-MACH-113701 | <a href="#">Industrial Mobile Robotics Lab</a> | 4 CR | Furmans |

**Competence Certificate**

Certificate through colloquium with presentation, documentation of the work results and fulfilment of the attendance requirement.

**Prerequisites**

None

**Competence Goal**

Students can:

- Identify and explain the basics of intralogistics systems
- Describe the application of mobile robots in industry
- Explain the basic idea of the VDA 5050 communication standard
- Understand the concept of multi-robot task assignment in intralogistics
- Develop solutions to control mobile robots
- Apply the learned theory to a practical problem
- Evaluate the developed solutions through group discussions and presentations

**Content**

Hard skills

- Introduction to the basics of intralogistic systems
- Implement the communication in a multi-robot system using uniform JSON messages defined in the VDA 5050 via MQTT
- Design and implement a fleet management system to coordinate a fleet of mobile robots using Python
- Design and implement a robot control to accomplish assigned tasks using Python
- Transfer the solutions from the simulation to real industrial mobile robots

Soft skills

- Presentation of the work results
- Software development in teamwork (including tools such as git, Scrum, ...)

**Annotation**

- The number of participants is limited to 15 students.
- The selection procedure is based on a letter of motivation in which the following questions should be answered:
  - Why do you want to attend the course?
  - What skills and previous knowledge do you have?

**Workload**

- Compulsory attendance: approx. 20 hours
- Self study with video lectures: 10 hours
- Group work project: 90 hours

**Recommendation**

Basic knowledge of Python programming and basic knowledge of technical logistics of advantage.

**Learning type**

Laboratory

**Literature**

None

## M

## 7.112 Module: Information Fusion [M-ETIT-103264]

**Responsible:** Prof. Dr.-Ing. Michael Heizmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Additive Electives )  
 Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |                    |      |          |
|---------------|--------------------|------|----------|
| T-ETIT-106499 | Information Fusion | 4 CR | Heizmann |

**Prerequisites**  
 none

## M

**7.113 Module: Information Processing in Sensor Networks [M-INFO-100895]****Responsible:** Prof. Dr.-Ing. Uwe Hanebeck**Organisation:** KIT Department of Informatics

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German/English | 4     | 1       |

| Mandatory     |   |      |          |
|---------------|---|------|----------|
| T-INFO-101466 | <a href="#">Information Processing in Sensor Networks</a> | 6 CR | Hanebeck |



**M****7.114 Module: Information Systems and Supply Chain Management [M-MACH-105281]****Responsible:** Prof. Dr.-Ing. Kai Furmans**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-102128 | <a href="#">Information Systems and Supply Chain Management</a> | 3 CR | Kilger |

**Competence Certificate**

The assessment consists of an oral exam according to §4 (2), 2 of the examination regulation. It may be a written exam (according to §4 (2), 1 of the examination regulation) in the case of large number of participants.

**Prerequisites**

none

**Competence Goal**

Students are able to:

- Describe requirements of logistical processes regarding IT systems,
- Choose information systems to support logistical processes and use them according to the requirements of a supply chain.

**Content**

- 1) Overview of logistics systems and processes
- 2) Basic concepts of information systems and information technology
- 3) Introduction to IS in logistics: Overview and applications
- 4) Detailed discussion of selected SAP modules for logistics support

**Workload**

regular attendance: 21 hours

self-study: 69 hours

**Learning type**

Lectures

**Literature**

Stadtler, Kilger: Supply Chain Management and Advanced Planning, Springer, 4th edition 2008

**M****7.115 Module: Information Technology in Industrial Automation Systems [M-ETIT-100367]****Responsible:** Dr.-Ing. Peter-Axel Bort**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |      |
|---------------|---|------|------|
| T-ETIT-100698 | <a href="#">Information Technology in Industrial Automation Systems</a> | 3 CR | Bort |

**Prerequisites**

none

**M****7.116 Module: Innovation and Project Management in Rail Vehicle Engineering [M-MACH-106514]**

**Responsible:** Prof. Dr.-Ing. Martin Cichon  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 2       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-113068 | <a href="#">Innovation and Project Management in Rail Vehicle Engineering</a> | 4 CR | Cichon |

**Competence Certificate**

Graded examination:

2/3 of the examination: 20-minute oral examination on the content of the lecture

1/3 of the examination performance of another type: unit accompanying the lecture as part of a 10-minute presentation and a practical application from innovation and project management

**Prerequisites**

none

**Competence Goal**

In this course, students will learn the basics of innovation and project management in the context of rail vehicle development. Creativity techniques are applied to the challenges of the rail system in a practical way, such as aspects of sustainability. Students will also learn about the various organizational, systemic, economic and technological challenges of a project and project management.

**Content**

- Fundamentals of innovation management
  - Challenges and aspects of sustainability in the rail system
  - Independent testing of various creativity techniques
  - Moderation of creativity workshops
  - Techniques for generating and evaluating ideas
- Fundamentals and methods of project management
  - Practical challenges in project management
  - Creation of tools for project management (work breakdown structure, project controlling, organizational charts)
  - Project team organization and role allocation

**Annotation**

A bibliography is available for students to download from the Ilias platform.

**Workload**

Attendance time: 21 hours

Preparation / wrap-up: 21 hours

Exam and exam preparation: 78 hours

Total time: 120 hours = 4 LP

**Learning type**

Lecture

## M

**7.117 Module: Innovation2Business – Innovation Strategy in the Industrial Corporate Practice [M-MACH-107188]****Responsible:** Prof. Dr.-Ing. Albert Albers**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-112882 | <a href="#">Innovation2Business – Innovation Strategy in the Industrial Corporate Practice</a> | 4 CR | Albers |

**Competence Certificate**

See partial performance

**Prerequisites**

None

**Competence Goal**

Learn....

- ... the challenges in product development using the example of a corporate group
- ... what influence (mega) trends have on the product development of a global player
- ... know and apply selected methods and tools for trend analysis / portfolio strategy / business case evaluation
- ... what role compliance plays in product development

**Content**

In this lecture series, learn from the example of Schaeffler how global companies are continuously transforming themselves in order to grow sustainably and maintain a leading position in the global market in the long term through business-oriented innovation.

Together we will go through the most important elements of the innovation and development process and learn about the successes and lessons learned using illustrative examples from practice.

Take part in the fireside evenings with the speakers to discuss the lecture content and beyond in a relaxed atmosphere.

**Module grade calculation**

The module grade corresponds to the grade from the partial performance.

**Annotation**

None

**Workload**

Attendance: 30h

Self-study: 90h

**Recommendation**

None

**Learning type**

Lecture

**Literature**

None

**Base for**

None

**M****7.118 Module: Innovative Concepts for Programming Industrial Robots (24179)  
[M-INFO-100791]****Responsible:** Prof. Dr.-Ing. Björn Hein**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |      |
|---------------|---|------|------|
| T-INFO-101328 | <a href="#">Innovative Concepts for Programming Industrial Robots</a> | 4 CR | Hein |

## M

**7.119 Module: Innovative Nuclear Systems [M-MACH-107119]**

**Responsible:** Dr. Aurelian Florin Badea  
Prof. Dr.-Ing. Xu Cheng

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-105404 | <a href="#">Innovative Nuclear Systems</a> | 4 CR | Cheng |

**Competence Certificate**

A performance assessment will consist of an oral examination of approx. 20 minutes.

**Prerequisites**

none

**Competence Goal**

The objective of the module is the explanation of state-of-the-art development of nuclear systems. Nuclear systems, that are from today's point of view promising will be presented and explained. The main characteristics of such systems and the associated challenges are also part of the lecture.

**Content**

1. state of the art and development tendencies in nuclear systems
2. advanced concepts in light water cooled systems
3. new developments in fast reactors
4. development tendencies in gas-cooled plants
5. transmutation systems for waste management
6. fusion systems

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

(for details see individual course)

## M

## 7.120 Module: Integrated Intelligent Sensors [M-ETIT-100457]

**Responsible:** Prof. Dr. Wilhelm Stork

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-100961 | <a href="#">Integrated Intelligent Sensors</a> | 3 CR | Stork |

#### Competence Certificate

Achievement will be examined in an oral examination (approx. 20 minutes).

#### Prerequisites

none

## M

**7.121 Module: Integrated Product Development [M-MACH-107141]****Responsible:** Prof. Dr.-Ing. Albert Albers**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 18      | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |       |               |
|---------------|--|-------|---------------|
| T-MACH-105401 | <a href="#">Integrated Product Development</a> | 18 CR | Albers, Düser |

**Competence Certificate**

See partial performance

**Prerequisites**

None

**Competence Goal**

The Students are able to ...

- analyze and evaluate product development processes based on examples and their own experiences.
- plan, control and evaluate the working process systematically.
- choose and use suitable methods of product development, system analysis and innovation management under consideration of the particular situation.
- prove their results.
- develop complex technical solutions in a team and to present them to qualified persons as well as non-qualified persons
- to design overall product development processes under consideration of market-, customer- and company- aspects

**Content**

organizational integration: integrated product engineering model, core team management and simultaneous engineering

informational integration: innovation management, cost management, quality management and knowledge management

personal integration: team coaching and leadership management

invited lectures

**Module grade calculation**

The module grade corresponds to the grade from the partial performance

**Annotation**

Registration takes place in the previous summer semester. The lecture starts at the beginning of October.

For organizational reasons, the number of participants for the product development project is limited to 42 people. A selection process will therefore take place. Registration for the selection process takes place via a registration form, which is made available on the IPEK homepage from April to July each year. Subsequently, the selection itself is made in personal selection interviews with Prof. Albers.

**Workload**

540h:

Attendance: 120h

Self-study/project work: 420h

**Recommendation**

None

**Learning type**

Lecture, Workshops, project work

**Literature**

Klaus Ehrlenspiel - Integrierte Produktentwicklung. Denkabläufe, Methodeneinsatz, Zusammenarbeit, Hanser Verlag, 2009



**Base for**  
None

## M

**7.122 Module: Integrated Systems and Circuits [M-ETIT-100474]****Responsible:** Prof. Dr. Sebastian Kempf**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-100972 | <a href="#">Integrated Systems and Circuits</a> | 4 CR | Kempf |

**Prerequisites**

none

## M

## 7.123 Module: Interdisciplinary Qualifications [M-ETIT-107193]

**Responsible:** Prof. Dr. Martin Doppelbauer  
Prof. Dr.-Ing. Marcus Geimer

**Organisation:** KIT Department of Electrical Engineering and Information Technology  
KIT Department of Mechanical Engineering

**Part of:** [Interdisciplinary Qualifications](#)

| Credits | Grading scale | Recurrence | Duration | Language       | Level | Version |
|---------|---------------|------------|----------|----------------|-------|---------|
| 8       | pass/fail     | Each term  | 1 term   | German/English | 4     | 1       |

**Election notes**

The module "Interdisciplinary Qualifications" consists of three parts:

- Compulsory: T-MACH-113883 - Introduction to Philosophy of Technology (2 CP)  
Recommended basis for:
- Compulsory-elective "Engineering Ethics" (2 CP: one of the following components)
  - T-MACH-113884 - Technology Assessment and its Normative Basis
  - T-MACH-113903 - Ethics of Technology
- Compulsory-elective "Further Interdisciplinary Qualifications" (4 CP)

In "Further Interdisciplinary Qualifications" for self assignment of taken interdisciplinary qualifications of HoC, FORUM, or SPZ the courses ('Teilleistungen') with the title 'Self Assignment-...' have to be selected according to the grading scale, graded or ungraded. Title and credits of the achievement are adopted. Students can access the module via the menu item "Exam Registration and Unregistration" at the Study Portal.

-----  
All courses are listed with English titles, regardless of the course language.

**To see English courses with English titles and German courses with German titles visit the [German website](#).**

Courses given in English (alphabetically ordered) are listed above the "Self Assignments", the ones in German (alphabetically ordered) below.

| Mandatory   |   |      |                     |
|---|---|------|---------------------|
| T-MACH-113883   | <a href="#">Introduction to Philosophy of Technology</a>                            | 2 CR | Hillerbrand         |
| Engineering Ethics (Election: at least 2 credits)                       |   |      |                     |
| T-MACH-113884   | <a href="#">Technology Assessment and its Normative Basis</a>                       | 2 CR | Hillerbrand         |
| T-MACH-113903   | <a href="#">Ethics of Technology</a>  | 2 CR | Hillerbrand         |
| Further Interdisciplinary Qualifications (Election: at least 4 credits) |   |      |                     |
| T-ETIT-111317   | <a href="#">Introduction to the Scientific Method (Seminar, Englisch)</a>           | 1 CR | Nahm                |
| T-ETIT-100814   | <a href="#">Seminar Project Management for Engineers</a>                            | 3 CR | Noe                 |
| T-ETIT-111688   | <a href="#">Self Assignment-HOC-SPZ-FORUM-graded</a>                                | 2 CR |                     |
| T-ETIT-111689   | <a href="#">Self Assignment-HOC-SPZ-FORUM-graded</a>                                | 2 CR |                     |
| T-ETIT-112898   | <a href="#">Self Assignment-HOC-SPZ-FORUM-ungraded</a>                              | 2 CR |                     |
| T-ETIT-112899   | <a href="#">Self Assignment-HOC-SPZ-FORUM-ungraded</a>                              | 2 CR |                     |
| T-ETIT-100797   | <a href="#">Educational Development for Student Teachers - Basic Level</a>          | 2 CR |                     |
| T-MACH-105721   | <a href="#">Engineer's Field of Work</a>  | 2 CR | Doppelbauer, Geimer |
| T-WIWI-100796   | <a href="#">Industrial Business Administration</a>                                  | 3 CR | Fichtner            |
| T-MACH-105442   | <a href="#">Intellectual Property Rights and Strategies in Industrial Companies</a> | 4 CR | Zacharias           |
| T-ETIT-111316   | <a href="#">Introduction to the Scientific Method (Seminar, German)</a>             | 1 CR | Nahm                |
| T-MACH-106460   | <a href="#">Leadership in Interdisciplinary Teams</a>                               | 4 CR | Matthiesen          |
| T-MACH-106738   | <a href="#">ProVIL - Product Development in a Virtual Idea Laboratory</a>           | 4 CR | Albers, Düser       |
| T-ETIT-100754   | <a href="#">Seminar Creating a Patent Specification</a>                             | 3 CR | Stork               |
| T-ETIT-108820   | <a href="#">Seminar Project Management for Engineers</a>                            | 3 CR | Day, Noe            |
| T-ETIT-111369   | <a href="#">Strategy Derivation for Engineers</a>                                   | 3 CR | Arndt               |

**Competence Certificate**

Depending on the selected offer

**Prerequisites**

None

**Content**

Depending on the selected offer

**Module grade calculation**

ungraded

**Workload**

Depending on the selected offer

## M

**7.124 Module: International Production Engineering [M-MACH-105109]****Responsible:** Prof. Dr.-Ing. Jürgen Fleischer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 8       | Grade to a tenth | Each term  | 2 terms  | German   | 4     | 1       |

| Mandatory     |  |      |           |
|---------------|--|------|-----------|
| T-MACH-110334 | <a href="#">International Production Engineering A</a> | 4 CR | Fleischer |
| T-MACH-110335 | <a href="#">International Production Engineering B</a> | 4 CR | Fleischer |

**Competence Certificate**

Alternative test achievement (graded):

- Result of the project work and final presentation with weighting 65%
- Oral exam (ca. 15 min) with weighting 35%

**Competence Goal**

The students ...

- can develop ideas for technical solutions in the environment of production plants in a team and evaluate their feasibility according to technical and economic criteria,
- are capable of selecting the essential components and modules of a production plant and carrying out the necessary calculations,
- can use FEM simulations to predict and evaluate the static and dynamic behavior of an assembly,
- are able to present, plan and assess their own work and decision-making processes,
- are able to apply basic methods of project management in an international environment.

**Content**

The module "International Production Engineering" offers a practical insight into the development of production plants in an international environment. A student team works on a current and concrete problem in the field of production engineering, which is introduced into the project by an industrial partner who is operating as well in Germany as in China.

As part of the course "International Production Engineering A", the problem will initially be transferred into work packages. According to the elaborated project plan, ideas and concepts for a solution of the problem will be generated and developed. Based on the concepts, the selected solution approach is elaborated and validated, e.g. through simulation, programming and/or design, but always in the context of production technology. The practical implementation of the developed solution is part of the course "International Production Engineering B" during an eight-week research stay in China.

The project will be carried out by the students under the guidance of scientific staff and in cooperation with the industrial partner. The results of the project will be presented and discussed with the project partner in a final presentation (respectively IPE A and B).

More details about the course are discussed in an information event (always in January/February, the exact date is published on the homepage: [www.wbk.kit.edu](http://www.wbk.kit.edu)).

The project offers students ...

- the unique opportunity to put the contents of the accompanying lecture into practice in an interdisciplinary and creative context,
- to gain insights into a wide range of development activities relevant for their future careers,
- cooperation with an attractive industrial partner,
- work in a team with other students with competent support from scientific staff,
- first practical experience in project management
- international practical experience.

**Workload****IPE A**

1. Presence time lecture:  $15 * 2 \text{ h} = 30 \text{ h}$
  2. Pre- and post-processing time lecture:  $15 * 5 \text{ h} = 75 \text{ h}$
  3. Exam preparation and presence in the same: 15 h
- In total: 120 h = 4 LP

**IPE B**

1. Presence time lecture:  $15 * 2 \text{ h} = 30 \text{ h}$
  2. Pre- and post-processing time lecture:  $15 * 5 \text{ h} = 75 \text{ h}$
  3. Exam preparation and presence in the same: 15 h
- In total: 120 h = 4 LP

## M

## 7.125 Module: Introduction into Energy Economics [M-WIWI-100498]

**Responsible:** Prof. Dr. Wolf Fichtner  
**Organisation:** KIT Department of Economics and Management  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 5       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-WIWI-102746 | <a href="#">Introduction to Energy Economics</a> | 5 CR | Fichtner |

**Competence Certificate**

The assessment consists of a written exam according to Section 4(2), 1 of the examination regulation.

**Prerequisites**

None

**Competence Goal**

The student is able to

- characterize and judge the different energy carriers and their peculiarities,
- understand contexts related to energy economics.

**Content**

1. Introduction: terms, units, conversions
2. The energy carrier gas (reserves, resources, technologies)
3. The energy carrier oil (reserves, resources, technologies)
4. The energy carrier hard coal (reserves, resources, technologies)
5. The energy carrier lignite (reserves, resources, technologies)
6. The energy carrier uranium (reserves, resources, technologies)
7. The final carrier source electricity
8. The final carrier source heat
9. Other final energy carriers (cooling energy, hydrogen, compressed air)

**Workload**

The total workload for this course is approximately 165.0 hours. For further information see German version.

**M****7.126 Module: Introduction to Automotive and Industrial Lidar Technology [M-ETIT-105461]****Responsible:** Prof. Dr. Wilhelm Stork**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-111011 | <a href="#">Introduction to Automotive and Industrial Lidar Technology</a> | 3 CR | Stork |

**Competence Certificate**

The examination consists of an oral exam and a short oral presentation. The overall impression is rated.

**Competence Goal**

- The students are able to explain the basic principles of a lidar sensor
- The students can explain all relevant components of a lidar sensor and put them in context
- The students can explain different forms of execution and make a meaningful choice depending on the requirements
- The students can describe lidar sensors theoretically using the lidar equations and explain the interactions based on this theory
- The students are able to assess the eye safety of a system
- The students are able to suggest possible sensor concepts for different applications or to evaluate existing concepts

**Content**

In this course the functionality of a lidar sensor is explained and then put into context with relevant use cases. Typical criteria for the evaluation of the performance are then presented. In the following the concept of the sensor is presented in detail and all relevant components are introduced individually. Afterwards they are qualitatively related to each other and the whole system is quantitatively examined by means of the lidar equation. Finally, the interaction of the components is further considered to present meaningful combinations and design solutions. The eye safety of lidar sensors is always explicitly considered. The course concludes with a colloquium in which the students will give short presentations on what they have learned. This repetition is intended to repeat and deepen what has been learned and to lead to a discussion of open question

**Module grade calculation**

The module grade results of the assessment of the oral exam and the short oral presentation. Details will be given during the lecture.

**Workload**

1. participation in the lectures 12h - 8 dates á 1,5h
2. preparation and postprocessing 14 h ( 2h for VL dates 1-7 )
3. preparation of the short lecture (16h)
4. preparation and participation in the oral exam : 48h

**Recommendation**

Basics of optics / optical technologies are helpful (e.g. optical engineering, optoelectronic, technical optics)



## M

## 7.127 Module: Introduction to Bionics [M-MACH-106525]

**Responsible:** apl. Prof. Dr. Hendrik Hölscher

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |          |
|---------------|---|------|----------|
| T-MACH-111807 | <a href="#">Introduction to Bionics</a> | 4 CR | Hölscher |

### Competence Certificate

The successful attendance of the lecture is controlled by a written examination.

### Prerequisites

Basic knowledge in physics and chemistry

### Competence Goal

The students should be able analyze, judge, plan and develop biomimetic strategies and products.

### Content

Bionics focuses on the design of technical products following the example of nature. For this purpose we have to learn from nature and to understand its basic design rules. Therefore, the lecture focuses on the analysis of the fascinating effects used by many plants and animals. Possible implementations into technical products are discussed in the end.

### Module grade calculation

The module grade corresponds to the grade of the partial performance.

### Workload

30 h attendance time

90 h self-study.

### Learning type

Lecture

### Literature

Slides and literature are provided by ILIAS.

## M

**7.128 Module: Introduction to Microsystem Technology I [M-MACH-102691]**

**Responsible:** Prof. Dr. Jan Gerrit Korvink  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |                   |
|---------------|--|------|-------------------|
| T-MACH-114100 | <a href="#">Introduction to Microsystem Technology I</a> | 4 CR | Badilita, Korvink |

**Competence Certificate**

Written exam: 60 min

**Prerequisites**

None

**Competence Goal**

The lecture gives an introduction into the basics of microsystems technology. In analogy to processes employed in fabrication of microelectronics circuits the core technologies as well as materials for producing microstructures and components are presented. Finally, various techniques for Silicon micromachining are explained and illustrated with examples for micro-components and micro-systems.

**Content**

- Introduction in Nano- and Microtechnologies
- Silicon and processes for fabricating microelectronics circuits
- Basic physics background and crystal structure
- Materials for micromachining
- Processing technologies for microfabrication
- Silicon micromachining
- Examples

**Workload**

Time of attendance: 15 \* 1,5 h = 22,5 h  
 Preparation and follow up: 15 \* 5,5 h = 82,5 h  
 Exam Preparation and Exam: 15 h  
 Total: 120 h = 4 LP

**Literature**

M. Madou  
 Fundamentals of Microfabrication  
 Taylor & Francis Ltd.; Auflage: 3. Auflage. 2011

## M

**7.129 Module: Introduction to Microsystem Technology II [M-MACH-102706]**

**Responsible:** Prof. Dr. Jan Gerrit Korvink  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |                   |
|---------------|---|------|-------------------|
| T-MACH-105183 | <a href="#">Introduction to Microsystem Technology II</a> | 4 CR | Badilita, Korvink |

**Competence Certificate**

Written exam: 60 min

**Prerequisites**

none

**Competence Goal**

The lecture gives an introduction into the basics of microsystems technology. In the first part, methods for lithographic pattern transfer are summarized. Then specific techniques such as the LIGA process, micro-machining, and laser-patterning are explained and examples are given. Finally assembly and packaging methods are presented leading into a discussion of entire microsystems.

**Content**

- Introduction in Nano- and Microtechnologies
- Lithography
- LIGA-technique
- Mechanical microfabrication
- Patterning with lasers
- Assembly and packaging
- Microsystems

**Workload**

Time of attendance: 15 \* 1,5 h = 22,5 h  
 Preparation and follow up: 15 \* 5,5 h = 82,5 h  
 Exam Preparation and Exam: 15 h  
 Total: 120 h = 4 LP

**Literature**

M. Madou  
 Fundamentals of Microfabrication  
 Taylor & Francis Ltd.; Auflage: 3. Auflage. 2011

## M

## 7.130 Module: Introduction to Nanotechnology [M-MACH-107207]

**Responsible:** apl. Prof. Dr. Hendrik Hölscher

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-MACH-111814 | <a href="#">Introduction to Nanotechnology</a> | 4 CR | Hölscher |

### Competence Certificate

see individual course

### Prerequisites

none

### Content

Nanotechnology deals with the fabrication and analysis of nanostructures. The topics of the lecture include

- the most common measurement principles of nanotechnology especially scanning probe methods
- the analysis of physical and chemical properties of surfaces
- interatomic forces and their influence on nanostructures
- methods of micro- and nanofabrication and lithography
- basic models of contact mechanics and nanotribology
- important functional characteristics of nanodevices

Basic knowledge in mathematics and physics is assumed

### Module grade calculation

see individual course

### Annotation

Course T-MACH-111814 may not be started

### Workload

120 h

(for details see individual course)

### Literature

Slides and literature will be made available in ILIAS.

## M

**7.131 Module: Introduction to Nuclear Energy [M-MACH-107122]**

**Responsible:** Dr. Aurelian Florin Badea  
Prof. Dr.-Ing. Xu Cheng

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-105525 | <a href="#">Introduction to Nuclear Energy</a> | 4 CR | Cheng |

**Competence Certificate**

A performance assessment will consist of an oral examination of approx. 20 minutes.

**Prerequisites**

none

**Competence Goal**

The objective of the module is the fundamental knowledge of nuclear energy and nuclear reactors. After the lecture the students understand the principle of the usage of nuclear energy, the structure and operation of nuclear power plants and nuclear safety measures. Furthermore, the students are capable of giving technical assessment of the usage of nuclear energy with respect to its safety and sustainability.

**Content**

1. Nuclear energy generation
2. Basics of reactor physics
3. Reactor types and structure
4. Reactor safety and heat dissipation
5. Nuclear materials
6. Fuel cycle and waste treatment
7. Radiation protection
8. Economic efficiency
9. Exercises with nuclear power plant simulation

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

(for details see individual course)

## M

## 7.132 Module: IT/OT-Security Seminar [M-ETIT-106789]

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Mike Barth   |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |                        |      |       |
|---------------|------------------------|------|-------|
| T-ETIT-113648 | IT/OT-Security Seminar | 4 CR | Barth |

**Competence Certificate**

The examination takes place in the form of an oral examination.

**Prerequisites**

none

**Competence Goal**

The students:

- know the definitions of terms and use-cases in the IT/OT-Security Domain
- know security requirements of both: the industrial information technology perspective as well as the production related operational technology domain
- can apply basic cryptographic mechanisms with focus on industrial IT networks
- know protection goals of IT/OT-security
- know various aspects of system security (buffer overflow, return-oriented programming, ...)
- can differentiate between classic information technology (IT) and operational technology (OT) in an industrial environment
- are familiar with attacks on industrial automation and control systems (Industrial Control Systems - ICS)
- are familiar with various concepts (defense-in-depth, security by design, ...) and specific security mechanisms (Public-Key-Infrastructure, network segmentation, ...) of OT security
- are familiar with current international security standards for ICS, in particular IEC 62443
- know the different roles involved and their challenges in the life cycle of ICS
- know and understand the concept of a risk analysis for security
- can evaluate the quality of security mechanisms and architectures for industrial systems
- know typical industrial communication protocols and can analyze and evaluate their security mechanisms

**Content**

- Industrial control and automation systems (ICS) are widely used in numerous domains and industries. They play a crucial role in areas such as industrial production, the process industry, critical infrastructures such as energy and water management, building automation and medical devices.
- In recent years, the frequency of vulnerabilities and attacks on these systems has increased, especially since the emergence of Stuxnet in 2014. As a result, the protection of ICS has become increasingly important.
- Compared to conventional IT systems, ICS have different boundary conditions and requirements. In particular, the focus is on availability and maintaining functional safety. Therefore, classic approaches to information security cannot be applied to industrial control systems without adaptation.
- This module first provides basic knowledge of security. Building on this, concepts, mechanisms and standards for the specific domain of ICS are introduced. This includes, for example:
  - o Defense-in-Depth concepts
  - o Risk-based approaches
  - o IEC 62443
  - o Structure and operation of cyber security management systems
  - o Security engineering
  - o Use of security information and event management systems in the industrial environment
  - o Secure use of Industry 4.0 technologies such as OPC UA

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

The workload includes:

1. attendance in seminar lectures and exercises:  $12 \cdot 2 \text{ h} = 24 \text{ h}$
2. preparation / follow-up of seminar lectures:  $12 \cdot 3 \text{ h} = 36 \text{ h}$
3. implementation of challenges and exercises:  $12 \cdot 3 \text{ h} = 36 \text{ h}$
4. preparation of exam: 24 h.

A total of 120 h = 4 CR

**Recommendation**

Enjoy working with networked software systems in the production and industrial IT environment. Curiosity in the interplay between attackers and defenders as well as a general affinity to software related topics.

## M

## 7.133 Module: IT-Fundamentals of Logistics: Opportunities for Digital Transformation [M-MACH-105282]

**Responsible:** Prof. Dr.-Ing. Kai Furmans  
Prof. Dr.-Ing. Frank Thomas

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-105187 | <a href="#">IT-Fundamentals of Logistics</a> | 4 CR | Thomas |

### Competence Certificate

The assessment consists of an oral exam (30 min.) or an written exam (60min.) taking place in the recess period according to § 4 paragraph 2 Nr. 1/2 of the examination regulation.

### Prerequisites

none

### Competence Goal

The students ...

- can describe the business process models from goods-inbound to goods-outbound based on sound basic knowledge, and derive the corresponding analysis models.
- will learn through the modularisation of the business process elements to think in reusable, adaptive IT components.
- will accomplish excellent work as a highly-motivated employee together in interdisciplinary teams (responses from the industry).



**Content**

The rapid development of information technology influences business processes drastically.

A strategic IT-orientation for an enterprise without a critical appreciation of worldwide IT-development (where the half-life value of IT for logistic systems knowledge is less than 3 years) is dangerous. The pressure of costs is always in focus. For this purpose the contents of this course, as well as the detailed script will be continuously revised, and the influences on business processes will be shown in practical examples.

**Focuses:****System architecture in Material Flow Control Systems (MFCS)**

A guiding principle for a new system architecture for MFC systems is the consideration of making new standardized, functional groups available for re-usability.

**Design and application of innovative Material Flow Control Systems (MFCS)**

The most important task of the MFCS is the commissioning of conveying systems with driving commands in a way that optimally utilizes the facility and serves the logistics processes on schedule.

**Identification of goods – Application in Logistics**

Along with business processes, coded information is the link between the flow of information and the flow of materials, and contributes to error prevention in the communication between people and machines.

**Data communication in Intra-logistics**

Information describes the content of a message that is of value to the recipient.  
The recipient can be both a human and a machine.

**Business processes for Intra-logistics – Software follows function!**

If the business processes from Goods Incoming to Goods Outgoing are adapted with reusable building blocks then capabilities become visible. Against this background the consideration becomes apparent, how, through an innovative software architecture, a reusable building-block based framework can be made.

Therefore applies: Software follows function. And only if all project requirements are documented in the planing phase, and supported together in an inter-disciplinary team - consisting of logistics planners, the customers (users) and the implementation leader (IL).

**Software development in accordance with industrial standards**

Today's development of object-oriented software, and the increasing penetration of industrial software production with this technology, makes it possible to create system designs that already offer these opportunities in their facility - both for a high degree of reuse and for easier adaptability.

In software development, object-oriented methods are used to improve the productivity, maintainability and software quality. An important aspect of object-orientation is: the objects used are primarily intended to depict the real world.

**Workload**

regular attendance: 21 hours

self-study: 69 hours

**Learning type**

Lectures

## M

**7.134 Module: Lab Computer-Aided Methods for Measurement and Control [M-MACH-105291]**

**Responsible:** Dr. Martin Lauer  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:**

**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale | Recurrence       | Duration | Language | Level | Version |
|---------|---------------|------------------|----------|----------|-------|---------|
| 4       | pass/fail     | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |                  |
|---------------|--|------|------------------|
| T-MACH-105341 | <a href="#">Lab Computer-Aided Methods for Measurement and Control</a> | 4 CR | Merkert, Stiller |

**Competence Certificate**

Successful passed Colloquia

**Prerequisites**

none

**Competence Goal**

Powerful and cheap computation resources have led to major changes in the domain of measurement and control. Engineers in various fields are nowadays confronted with the application of computer-aided methods. This lab tries to give an insight into the modern domain of measurement and control by means of practically oriented and flexible experiments. Based on experiments

on measurement instrumentation and digital signal processing, elementary knowledge in the domain of visual inspection and image processing will be taught. Thereby, commonly used software like MATLAB/Simulink will be used in both simulation and realization of control loops. The lab closes with selected applications, like control of a robot or supersonic computer tomography.

**Content**

1. Digital technology
  2. Digital storage oscilloscope and digital spectrum analyzer
  3. Supersonic computer tomography
  4. Lighting and image acquisition
  5. Digital image processing
  6. Image interpretation
  7. Control synthesis and simulation
  8. Robot: Sensors
  - 9 Robot: Actuating elements and path planning
- The lab comprises 9 experiments.

**Workload**

120 hours

**Recommendation**

Basic studies and preliminary examination; basic lectures in automatic control

**Learning type**

Tutorial

**Literature**

Instructions to the experiments are available on the institute's website

## M

## 7.135 Module: Lab Course on Nanoelectronics [M-ETIT-100468]

**Responsible:** Prof. Dr. Sebastian Kempf  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language       | Level | Version |
|---------|------------------|------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | German/English | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-100757 | <a href="#">Lab Course on Nanoelectronics</a> | 6 CR | Kempf |

**Competence Certificate**

The control of success takes place in form of the evaluation of a written report (approx. 10-20 pages) which introduces the topic, discusses the execution of the lab course and the scientific results puts the results into the overall context.

**Prerequisites**

none

**Competence Goal**

After successful completion of the module, students will be familiar with elementary processes of microsystems and thin-film technology and will be able to optimize the fabrication of thin-film structures independently and without external guidance. In addition, they will be able analyze and critically evaluate their results using adequate measuring tools. By working on the practical course in small groups, students also acquire or improve their teamwork skills.

**Content**

The students learn the basic procedures and processes for the fabrication of integrated circuits as they are also used in industry. After an introduction, they work on specified tasks in the clean room and technology laboratory of the Institute for Micro- and Nanoelectronic Systems and work independently on a set of tasks agreed upon in advance with the supervisor. In detail, the students learn the following methods or processes:

- Fabrication of thin films and multilayer systems by sputtering and thermal vapor deposition.
- Fotolithography
- Characterization of the manufactured devices at room temperature and low temperatures.
- Independent analyses, measurements and evaluations of characteristic quantities of the fabricated structures such as critical temperature, residual resistance ratio, current-voltage characteristics, etc.

The results are subsequently summarized by the students in a final report, put into context and critically discussed.

**Module grade calculation**

The module grade is the grade of the written report.

**Annotation**

Two weeks block course in lecture-free time

**Workload**

A workload of approx. 180h is required for the successful completion of the module. This is composed as follows:

- Preparation of the lab course: 20h
- Discussion and lab course planning with supervisor: 10h
- Attendance time in the lab course: 70h
- Preparation of the written report: 80h

**Recommendation**

Successful completion of the module M-ETIT-103451 - Thin Films: technology, physics and application I or M-ETIT-105608 - Physics, Technology and Applications of Thin Films is recommended.

## M

**7.136 Module: Laboratory Exercise in Energy Technology [M-MACH-107206]**

**Responsible:** Prof. Dr.-Ing. Hans-Jörg Bauer  
Prof. Dr. Ulrich Maas

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale | Recurrence | Duration | Language       | Level | Version |
|---------|---------------|------------|----------|----------------|-------|---------|
| 4       | pass/fail     | Each term  | 1 term   | German/English | 4     | 1       |

| Mandatory     |  |      |                      |
|---------------|--|------|----------------------|
| T-MACH-105331 | <a href="#">Laboratory Exercise in Energy Technology</a> | 4 CR | Bauer, Maas, Wirbser |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

Learning Objectives:

By participating in the course, students should:

- be able to work on experimental and constructive as well as theoretical tasks within a scientific framework
- correctly evaluate the data obtained
- document results and present them in a scientific context

**Content**

Information on the institute's website; registration is online.

Registration within the first two weeks of the lecture period on the institute's website: <http://www.its.kit.edu>

Course content:

- Model gas turbine
- Various measuring sections for investigating heat transfer on components subject to high thermal loads.
- Optimization of components of the internal air and oil system
- Spray jet characterization of atomizer nozzles
- Investigation of pollutant emissions, noise emissions, reliability and material damage in combustion chambers
- Exhaust gas aftertreatment
- Exhaust gas turbocharger
- Cooling tower
- Heat pump
- Vegetable oil cooker
- Heat capacity
- Wood combustion

**Module grade calculation**

The module is passed with successful assessment of the coursework.

**Workload**

120 h

(for details see individual course)

**M****7.137 Module: Laboratory FPGA Based Circuit Design [M-ETIT-100470]****Responsible:** Prof. Dr. Sebastian Kempf**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-100759 | <a href="#">Laboratory FPGA Based Circuit Design</a> | 6 CR | Kempf |

**Prerequisites**

none

**M****7.138 Module: Laboratory in Software Engineering [M-ETIT-100460]****Responsible:** Prof. Dr.-Ing. Eric Sax**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Internship/Lab Course \)](#)[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |     |
|---------------|--|------|-----|
| T-ETIT-100681 | <a href="#">Laboratory in Software Engineering</a> | 6 CR | Sax |

**Prerequisites**

none

## M

**7.139 Module: Laboratory Information Systems in Power Engineering [M-ETIT-107159]****Responsible:** Prof. Dr.-Ing. Thomas Leibfried**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German/English | 4     | 1       |

| Mandatory     |   |      |           |
|---------------|---|------|-----------|
| T-ETIT-114183 | <a href="#">Laboratory Information Systems in Power Engineering</a> | 6 CR | Leibfried |

**Competence Certificate**

Success control takes place in the form of other types of examination and is assessed in form of 3 experiments.

**Prerequisites**

none

**Competence Goal**

Students have a basic understanding of how to use common calculation programs in the fields of network calculation, field calculation and automation and control. They are able to carry out basic calculations in the respective sub-areas and are familiar with the underlying theory.

**Content**

The focus of the lecture is to impart sound knowledge in the field of field calculation using the finite element method, load flow and short flow calculation, as well as the implementation of control programs for PLC systems. The theoretical basics of the sub-areas are taught and the practical application is practiced using common programs based on case studies.

**Module grade calculation**

The module grade results of the assessment of the 3 experiments.

- 20 points are awarded for each experiment (max. 10 for preparation and max. 10 for performance).
- This results in a total of 60 points.
- At least 27 points must be achieved in order to pass the module.

**Workload**

The workload is 180 hours and is made up as follows:

- Attendance time 40 h
- Self-study time 140 h

**Recommendation**

Basic knowledge on high-voltage technology, calculation of electrical networks and energy transmission and network control, computer skills

## M

**7.140 Module: Laboratory Mechatronic Measurement Systems [M-ETIT-103448]****Responsible:** Prof. Dr.-Ing. Michael Heizmann**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German/English | 4     | 1       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-ETIT-106854 | <a href="#">Laboratory Mechatronic Measurement Systems</a> | 6 CR | Heizmann |

**Competence Certificate**

The success control is carried out in the form of a written test of 120 minutes. If there are fewer than 20 candidates, an oral exam of around 20 minutes can alternatively take place. The module grade is the grade of the written or oral exam.

**Prerequisites**

none

**Competence Goal**

- Students have in-depth knowledge of different methods for measuring objects, especially surfaces.
- Students master different procedures for the metrological recording of objects and know the relevant requirements, procedures and results.
- Students are able to implement procedures for evaluating sensor data from (surface) measuring devices and to evaluate the quality of the measurement result.

**Content**

A large number of different measuring methods and systems can be used for the quality inspection of technically manufactured objects and their surfaces. Examples are white light interferometry, confocal microscopy and systems based on focus variation. The measurement methods and systems naturally differ in terms of the physical measurement principle used, but also in terms of the evaluation of the raw sensor data recorded.

In this internship, different systems for the metrological recording of (technical) surfaces are presented and their properties are characterized. In the test dates, the students themselves create procedures and algorithms for processing the sensor data in order to obtain information about the desired geometric and / or optical properties of the examined surface. The algorithms obtained are evaluated on the basis of sensor data from exemplary objects and characterized in terms of the quality of the measurement statements achieved.

**Module grade calculation**

The module grade is the grade of the written or oral exam.

**Annotation**

The submission of the protocols of all experiments is required for admission to the examination. The quality of the protocols is assessed; for the admission to the exam, the quality must be acceptable. Attendance of all laboratory dates including the introductory event is required. Already in the event of a single unexcused absence, admission to the examination will not be granted.

**Workload**

Total: approx. 160 hours, of which

1. Attendance time in introductory session: 1.5 hours
2. Preparation of the test dates: 32 h
3. Attendance time in test appointments (8 appointments of 4 hours each): 32 hours
4. Follow-up of the test dates, Creation of the minutes: 32 h
5. Exam preparation and attendance in the same: 60 h

**Recommendation**

Knowledge from the lectures "Metrology" or "Metrology in Mechatronics" and "Manufacturing Metrology" as well as basic knowledge of programming (e.g. in Matlab, C / C++) are helpful.



## M

**7.141 Module: Laboratory Mechatronics [M-MACH-102699]**

**Responsible:** Prof. Dr. Veit Hagenmeyer  
Prof. Dr.-Ing. Wolfgang Seemann  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale | Recurrence       | Duration | Language | Level | Version |
|---------|---------------|------------------|----------|----------|-------|---------|
| 4       | pass/fail     | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |   |      |                     |
|---------------|---|------|---------------------|
| T-MACH-105370 | <a href="#">Laboratory Mechatronics</a> | 4 CR | Hagenmeyer, Stiller |

**Competence Certificate**

The laboratory course is offered exclusively as ungraded course work. The assessment consists of a group colloquium at the beginning of the individual specialization phases (Part 1). In addition, a robot control system for a pick-and-place task must be successfully implemented in the group phase (Part 2).

**Prerequisites**

None

**Competence Goal**

The students are able to put the knowledge from the specialization in mechatronics and microsystems technology into practice on an exemplary mechatronic system, a handling system. The students can create an automated object recognition, calculate kinematic systems and realize a communication between different systems (PC, CAN, USB).

Furthermore, the students can integrate the individual parts of a manipulator in teamwork to a functioning overall system.

**Content****Part I**

Control, programming and simulation of robots  
CAN-Bus communication  
Image processing / machine vision  
Dynamic simulation of robots in ADAMS

**Part II**

In a group work, a kinematic system has to be programmed so that it is able to recognize and grip objects fully automatically.

**Module grade calculation**

The module is not graded. Passing the module is 100% tied to the performance assessment of the partial performance.

**Workload**

1. Attendance time Lecture:  $15 * 2 \text{ h} = 30\text{h}$
2. self-study:  $15 * 6 \text{ h} = 90\text{h}$

Total:  $120\text{h} = 4 \text{ LP}$

**Learning type**

Seminar

## M

**7.142 Module: Laboratory Nanotechnology [M-ETIT-100478]**

|                      |  |
|----------------------|--|
| <b>Responsible:</b>  | Prof. Dr. Ulrich Lemmer<br>Dr.-Ing. Klaus Trampert   |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology  |
| <b>Part of:</b>      | <a href="#">Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Internship/Lab Course )</a><br><a href="#">Elective Area in Mechatronics and Information Technology (Internship/Lab Course )</a> |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 6              | Grade to a tenth     | Each term         | 1 term          | German/English  | 4            | 1              |

|                  |   |      |        |
|------------------|---|------|--------|
| <b>Mandatory</b> |   |      |        |
| T-ETIT-100765    | <a href="#">Laboratory Nanotechnology</a> | 6 CR | Lemmer |

**Competence Certificate**

Success control takes place in the form of a total of four tests. The overall impression is rated.

**Prerequisites**

none

**Competence Goal**

The students have practical experience in the use of measuring devices and manufacturing processes in nanotechnology and the methods for determining the physical and optical properties of optoelectronic components with functional nanotechnology components.

They can evaluate measurement results with regard to their plausibility and assess the influence of the measurement method on the uncertainty of the result.

You will also be able to reproduce the results in written form and interpret the knowledge gained from the measurements scientifically and explain the physical properties and the influence of the nanotechnology components.

**Content**

This module is designed to teach students the theoretical and practical aspects of laboratory work in the field of nanotechnology by means of independently conducted practical experiments. In the four experiments, students practise working with real measurement technology using the scientific equipment of the institute. The module also teaches students how to write a scientific report and the rules for the meaningful visualization of data sets.

The working titles of the experiments are

1. Production and characterization of an OLED
2. Optical mask lithography
3. Fabrication and characterization of an electrochromic device
4. Nanoimprint lithography and scanning electron microscopy

**Module grade calculation**

Oral examinations and the assessment of written assignments are included in the module grade. Further details will be provided at the beginning of the course.

**Workload**

Due to the self-administration of the small groups:

1 x 5 h are required for organizational tasks. This includes attending the information event, attending 2 safety briefings (laser and clean room) and making individual appointments between the experiment supervisor and the small group.

The workload for the 4 experiments in the module is calculated as follows:

4 x 5 h familiarization with the topic and literature study on the basics including preparation for the admission test.

4 x 8 h attendance at the institute

4 x 10 h data preparation and visualization

4 x 16 h Writing an individual report on the basis of the measurement data and the research question for the experiment.

4 x 1 h final discussion on the experiment with feedback on the report

4 x 4 h Improvement of the report based on the feedback on the report

Total hours required = 181 h = 6 CR

**Recommendation**

Knowledge of the theoretical principles of the individual experiments is helpful. It is advisable to attend the module after attending the subject-relevant courses, as knowledge of the theoretical basics is helpful but not mandatory. If the basics from the corresponding modules are not available, this means a longer preparation time for the respective experiment.

Helpful modules: Solid state electronics

## M

**7.143 Module: Laboratory Optoelectronics [M-ETIT-100477]**

**Responsible:** Dr.-Ing. Klaus Trampert  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language       | Level | Version |
|---------|------------------|------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | German/English | 4     | 1       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-ETIT-100764 | <a href="#">Laboratory Optoelectronics</a> | 6 CR | Trampert |

**Competence Certificate**

Success control takes place in the form of a total of four tests. The overall impression is rated.

**Prerequisites**

none

**Competence Goal**

Students have practical experience in using optoelectronic measuring devices and methods for determining the photometric and electrical properties of light sources and their operating devices.

They will be able to assess the plausibility of measurement results and estimate the influence of the measurement method on the uncertainty of the results.

You will also be able to reproduce the results in written form and interpret the knowledge gained from the measurements scientifically and use this to explain the physical properties of the light sources or the control gear.

**Content**

This module is designed to teach students the theoretical and practical aspects of laboratory work in the field of optoelectronics by means of independently conducted practical experiments. In the four experiments, students practise using real measurement technology on the scientific equipment of the institute. The module also teaches students how to write a scientific report and the rules for the meaningful visualization of data sets.

The working titles of the experiments are

1. Operating behavior of fluorescent lamps
2. Spectrophotometer | spectral transmission and reflection
3. Characterization of organic lasers
4. Spectroscopy & photosensor technology.

**Module grade calculation**

Oral examinations and the assessment of written assignments are included in the module grade. Further details will be provided at the beginning of the course.

**Workload**

Due to the self-administration of the small groups:

1 x 5 h are required for organizational tasks. This includes attending the information event, attending 2 safety briefings (laser and clean room) and making individual appointments between the experiment supervisor and the small group.

The workload for the 4 experiments in the module is calculated as follows:

4 x 5 h familiarization with the topic and literature study on the basics including preparation for the admission test.

4 x 8 h attendance at the institute

4 x 10 h data preparation and visualization

4 x 16 h Writing an individual report on the basis of the measurement data and the research question for the experiment.

4 x 1 h final discussion on the experiment with feedback on the report

4 x 4 h Improvement of the report based on the feedback on the report

Total hours required = 181 h = 6 CR

**Recommendation**

Knowledge of the theoretical principles of the individual experiments is helpful. It is advisable to attend the module after attending the subject-relevant courses, as knowledge of the theoretical basics is helpful but not mandatory. If the basics from the corresponding modules are not available, this means a longer preparation time for the respective experiment.

Helpful modules: Solid-state electronics, optoelectronic measurement technology, plasma radiation sources

## M

**7.144 Module: Laboratory Solar Energy [M-ETIT-102350]**

**Responsible:** Prof. Dr. Ulrich Wilhelm Paetzold  
Prof. Dr. Bryce Sydney Richards

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language       | Level | Version |
|---------|------------------|------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | German/English | 4     | 1       |

| Mandatory     |                         |      |          |
|---------------|-------------------------|------|----------|
| T-ETIT-104686 | Laboratory Solar Energy | 6 CR | Trampert |

**Competence Certificate**

Success is assessed on the basis of a total of four experiments. The overall impression is graded.

**Prerequisites**

none

**Competence Goal**

Students have practical experience in using photometric measurement equipment and methods for determining the photometric and electrical properties of lamps and luminaires. They also have basic experience in the simulation of luminaires with CAE tools.

They will be able to assess the plausibility of measurement results and estimate the influence of the measurement method on the uncertainty of the result.

They also have the competence to summarise the results in written form and to interpret the knowledge gained from the measurements scientifically and to explain the physical and photometric properties of lamps and luminaires.

**Content**

This module is designed to teach students the theoretical and practical aspects of laboratory work in the field of solar technology, particularly in the field of photovoltaics, by means of independently conducted practical experiments. In the four experiments, the handling of real measurement technology is trained on the institute's scientific equipment. The module also teaches the skills required to write a scientific report and the rules for the appropriate visualisation of data sets.

The working titles of the experiments are:

1. Light Beam Induced Current (LBIC) measurement in solar cells
2. Optical and electrical modelling of thin-film solar cells
3. Quantum efficiency measurements on solar cells
4. Outdoor measurements of PV modules

**Module grade calculation**

Oral examinations and the assessment of written reports are included in the module grade. Further details will be provided at the beginning of the course.

**Workload**

Due to the self-administration of the small groups:

1 x 5 h are required for organizational tasks. This includes attending the information event, attending 2 safety briefings (laser and clean room) and making individual appointments between the experiment supervisor and the small group.

The workload for the 4 experiments in the module is calculated as follows:

4 x 5 h familiarization with the topic and literature study on the basics including preparation for the admission test.

4 x 8 h attendance at the institute

4 x 10 h data preparation and visualization

4 x 16 h Writing an individual report on the basis of the measurement data and the research question for the experiment.

4 x 1 h final discussion on the experiment with feedback on the report

4 x 4 h Improvement of the report based on the feedback on the report

Total hours required = 181 h = 6 CR

**Recommendation**

Knowledge of the theoretical background of each experiment is recommended. It is strongly recommended that you attend this module after attending the relevant lectures, as knowledge of the theoretical background is important but not strictly necessary.

## M

## 7.145 Module: Leadership in Interdisciplinary Teams [M-MACH-107142]

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Sven Matthiesen  |
| <b>Organisation:</b> | KIT Department of Mechanical Engineering  |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 4              | Grade to a tenth     | Each winter term  | 1 term          | German          | 4            | 1              |

| Mandatory     |                                       |      |            |
|---------------|---------------------------------------|------|------------|
| T-MACH-106460 | Leadership in Interdisciplinary Teams | 4 CR | Matthiesen |

**Competence Certificate**

See individual course

**Prerequisites**

None

**Competence Goal**

After attending the course, students will be able to ...

- Use communication techniques to lead meetings
- Use and apply constructive criticism and reaction in meetings and discussions
- Apply problem and conflict resolution methods to project work in a team
- Identify strengths and weaknesses in the team, take them into account and use the existing strengths in the project
- Explain and apply different leadership styles
- Critically reflect on their own behavior and actions

**Content**

Communication, communication models, conversation techniques, self-management, formulating goals, delegating tasks, dealing with challenging situations, conflict resolution strategies, constructive criticism/reaction, project management, leadership, leadership tasks, leadership styles, leadership theories, team processes, recommendations for action

**Module grade calculation**

The module grade corresponds to the grade from the individual course

**Annotation**

None

**Workload**

Attendance: 40h

Self-study: 80h

**Recommendation**

Attendance of the course "Mechatronic Systems and Products" is recommended.

**Learning type**

Seminar, Workshop

**Literature**

None

**Base for**

None

## M

**7.146 Module: Liberalised Power Markets [M-WIWI-105403]****Responsible:** Prof. Dr. Wolf Fichtner**Organisation:** KIT Department of Economics and Management**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 3       |

| Mandatory     |   |      |          |
|---------------|---|------|----------|
| T-WIWI-107043 | <a href="#">Liberalised Power Markets</a> | 6 CR | Fichtner |

**Competence Certificate**

Success is monitored in the form of a written examination.

**Prerequisites**

See course description.

**Competence Goal**

The student has extensive knowledge of the new requirements of liberalized energy markets.



**Content****1. Power markets in the past, now and in future****2. Designing liberalised power markets**

- 2.1. Unbundling Dimensions of liberalised power markets
- 2.2. Central dispatch versus markets without central dispatch
- 2.3. The short-term market model
- 2.4. The long-term market model
- 2.5. Market flaws and market failure
- 2.6. Regulation in liberalised markets

**3. The power (sub)markets**

- 3.1 Day-ahead market
- 3.2 Intraday market
- 3.3 (Long-term) Forwards and futures markets
- 3.4 Emission rights market
- 3.5 Market for ancillary services
- 3.6 The “market” for renewable energies
- 3.7 Future market segments

**4. Grid operation and congestion management**

- 4.1. Grid operation
- 4.2. Congestion management

**5. Market power**

- 5.1. Defining market power
- 5.2. Indicators of market power
- 5.3. Reducing market power

**6. Future market structures in the electricity value chain****1. Power markets in the past, now and in future****2. Designing liberalised power markets**

- 2.2. Unbundling Dimensions of liberalised power markets
- 2.3. Central dispatch versus markets without central dispatch
- 2.4. The short-term market model
- 2.5. The long-term market model
- 2.6. Market flaws and market failure
- 2.7. Regulation in liberalised markets

**3. The power (sub)markets**

- 3.1 Day-ahead market
- 3.2 Intraday market
- 3.3 (Long-term) Forwards and futures markets
- 3.4 Emission rights market
- 3.5 Market for ancillary services
- 3.6 The “market” for renewable energies
- 3.7 Future market segments

**4. Grid operation and congestion management**

- 4.1. Grid operation
- 4.2. Congestion management

**5. Market power**

- 5.1. Defining market power
- 5.2. Indicators of market power
- 5.3. Reducing market power

**6. Future market structures in the electricity value chain****Workload**

The total workload for this module is approximately 180 hours.

## M

**7.147 Module: Lighting Engineering [M-ETIT-100485]****Responsible:** Prof. Dr. Cornelius Neumann**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)**Credits**  
4**Grading scale**  
Grade to a tenth**Recurrence**  
Each winter term**Duration**  
1 term**Language**  
German**Level**  
4**Version**  
1**Mandatory**

|               |                                      |      |         |
|---------------|--------------------------------------|------|---------|
| T-ETIT-100772 | <a href="#">Lighting Engineering</a> | 4 CR | Neumann |
|---------------|--------------------------------------|------|---------|

**Prerequisites**

none

## M

## 7.148 Module: Lightweight Engineering Design [M-MACH-102696]

**Responsible:** Prof. Dr.-Ing. Albert Albers  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |            |
|---------------|--|------|------------|
| T-MACH-105221 | <a href="#">Lightweight Engineering Design</a> | 4 CR | Düser, Ott |

**Competence Certificate**

Written examination (90 min)

**Prerequisites**

none

**Competence Goal**

The students are able to ...

- evaluate the potential of central lightweight strategies and their application in design processes.
- apply different stiffening methods qualitatively and to evaluate their effectiveness.
- evaluate the potential of computer-aided engineering as well as the related limits and influences on manufacturing.
- reflect the basics of lightweight construction from a system view in the context of the product engineering process.

**Content**

General aspects of lightweight design, lightweight strategies, construction methods, design principles, lightweight construction, stiffening techniques, lightweight materials, virtual product engineering, bionics, joining techniques, validation, recycling

Additionally, guest speakers from industry will present lightweight design from an practical point of view.

**Workload**

1. Time of presence lecture: 15 \* 2 h = 30 h
  2. Prepare/follow-up lecture: 15 \* 2 h = 30 h
  3. Exam preparation and time of presence: 60 h
- Total: 120 h = 4 LP

**Literature**

Klein, B.: Leichtbau-Konstruktion. Vieweg & Sohn Verlag, 2007

Wiedemann, J.: Leichtbau: Elemente und Konstruktion, Springer Verlag, 2006

Harzheim, L.: Strukturoptimierung. Grundlagen und Anwendungen. Verlag Harri Deutsch, 2008

## M

**7.149 Module: Localization of Mobile Agents (24613) [M-INFO-100840]****Responsible:** Prof. Dr.-Ing. Uwe Hanebeck**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-INFO-101377 | <a href="#">Localization of Mobile Agents</a>      | 6 CR | Hanebeck |
| T-INFO-114169 | <a href="#">Localization of Mobile Agents Pass</a> | 0 CR | Hanebeck |

## M

**7.150 Module: Logistics and Supply Chain Management [M-MACH-105298]**

**Responsible:** Prof. Dr.-Ing. Kai Furmans  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives\)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 9       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 2       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-MACH-110771 | <a href="#">Logistics and Supply Chain Management</a> | 9 CR | Furmans |

**Competence Certificate**

The assessment consists of a 120 minutes written examination (according to §4(2), 1 of the examination regulation).

**Prerequisites**

None

**Competence Goal**

The student

- has comprehensive and well-founded knowledge of the central challenges in logistics and supply chain management, an overview of various practical issues and the decision-making requirements and models in supply chains,
- can model supply chains and logistics systems using simple models with sufficient accuracy,
- identifies cause-effect relationships in supply chains,
- is able to evaluate supply chains and logistics systems based on the methods they have mastered.

**Content**

Logistics and Supply Chain Management provides comprehensive and well-founded fundamentals for the crucial issues in logistics and supply chain management. Within the scope of the lectures, the interaction of different design elements of supply chains is emphasized. For this purpose, qualitative and quantitative description models are used. Methods for mapping and evaluating logistics systems and supply chains are also covered. The lecture contents are enriched by exercises and case studies and partially the comprehension of the contents is provided by case studies. The interacting of the elements will be shown, among other things, in the supply chain of the automotive industry.

**Module grade calculation**

grade of the module is grades of the exam

**Workload**

contact hours (1 HpW = 1 h x 15 weeks):

- lecture: 60 h

independent study:

- preparation and follow-up lectures: 90 h
- preparation of case studies: 60 h
- examination preparation: 60 h

total: 270 h

**Recommendation**

none

**Learning type**

Lectures, tutorials, case studies.

**Literature**

Knut Alicke: Planung und Betrieb von Logistiknetzwerken: Unternehmensübergreifendes Supply Chain Management, 2003

Dieter Arnold et. al.: Handbuch Logistik, 2008

Marc Goetschalkx: Supply Chain Engineering, 2011

## M

**7.151 Module: Machine Dynamics [M-MACH-102694]****Responsible:** Prof. Dr.-Ing. Carsten Proppe**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |                                  |      |        |
|---------------|----------------------------------|------|--------|
| T-MACH-105210 | <a href="#">Machine Dynamics</a> | 5 CR | Proppe |

**Competence Certificate**

Written examination

**Prerequisites**

none

**Competence Goal**

Students are able to apply engineering-oriented calculation methods in order to model and to understand dynamic effects in rotating machinery. This includes the investigation of runup, stationary operation of rigid rotors including balancing, transient and stationary behavior of flexible rotors, critical speeds, dynamics of slider-crank mechanisms, torsional oscillations.

**Content**

1. Introduction
2. Machine as mechatronic system
3. Rigid rotors: equations of motion, transient and stationary motion, balancing
4. Flexible rotors: Laval rotor (equations of motion, transient and stationary behavior, critical speed, secondary effects), refined models)
5. Slider-crank mechanisms: kinematics, equations of motion, mass and power balancing

**Workload**

Lectures and exercises: 32 h

Studies: 118 h

**Learning type**

Lecture, tutorial

## M

**7.152 Module: Machine Learning - Basic Methods [M-INFO-105252]****Responsible:** Prof. Dr. Gerhard Neumann**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 4       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-INFO-110630 | <a href="#">Machine Learning - Basic Methods</a> | 5 CR | Neumann |

## M

**7.153 Module: Machine Learning - Foundations and Algorithms [M-INFO-107169]****Responsible:** Prof. Dr. Gerhard Neumann**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives\)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-INFO-111558 | <a href="#">Machine Learning - Foundations and Algorithms</a> | 6 CR | Neumann |

**Competence Certificate**

See partial achievements (Teilleistung)

**Prerequisites**

See partial achievements (Teilleistung)

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The module [M-INFO-105252 - Machine Learning - Basic Methods](#) must not have been started.

**Competence Goal**

- Students acquire knowledge of the basic methods of Machine Learning
- Students acquire the mathematical knowledge to understand the theoretical foundations of Machine Learning
- Students can categorize, formally describe and evaluate methods of Machine Learning
- Students can apply their knowledge to select appropriate models and methods for selected problems in the field of Machine Learning.

**Content**

The field of Machine Learning has made enormous progress in recent years and good knowledge of Machine Learning is becoming increasingly in demand on the job market. Machine Learning describes the acquisition of knowledge by an artificial system based on experience or data. Rules or certain calculations no longer have to be manually coded but can be extracted from data by intelligent systems.

This lecture provides an overview of essential and current methods of Machine Learning. After reviewing the necessary mathematical background, the lecture primarily deals with algorithms for classification, regression, and density estimation, with a focus on the mathematical understanding of probabilistic methods and neural networks.

Examples of topics include:

- Basics in Linear Algebra, Probability Theory, Optimization and Constraint Optimization
- Linear Regression
- Linear Classification
- Model Selection, Overfitting, and Regularization
- Support Vector Machines
- Kernel Methods
- Bayesian Learning and Gaussian Processes
- Neural Networks
- Dimensionality Reduction
- Density estimation
- Clustering
- Expectation Maximization
- Graphical Models

**Workload**

180h, divided into:

- ca 45h lecture attendance
- approx. 15h attending exercises
- approx. 90h post-processing and working on the exercise sheets
- ca 30h exam preparation



## M

**7.154 Module: Machine Learning 1 [M-WIWI-105003]****Responsible:** Prof. Dr.-Ing. Johann Marius Zöllner**Organisation:** KIT Department of Economics and Management**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-WIWI-106340 | <a href="#">Machine Learning 1 - Basic Methods</a> | 5 CR | Zöllner |

**Competence Certificate**

The assessment of this course is a written examination (60 min) according to §4(2), 1 of the examination regulation or an oral exam (20 min) following §4, Abs. 2, 2 of the examination regulation.

The exam takes place every semester and can be repeated at every regular examination date.

**Prerequisites**

None

**Competence Goal**

- Students gain knowledge of the basic methods in the field of machine learning.
- Students understand advanced concepts of machine learning and their application.
- Students can classify, formally describe and evaluate methods of machine learning.
- Students can use their knowledge to select suitable models and methods for selected problems in the field of machine learning.

**Content**

The course prepares students for the rapidly evolving field of machine learning by providing a solid foundation, covering core concepts and techniques to get started in the field. Students delve into different methods in supervised, unsupervised, and reinforcement learning, as well as various model types, ranging from basic linear classifiers to more complex methods, such as deep neural networks. Topics include general learning theory, support vector machines, decision trees, neural network fundamentals, convolutional neural networks, recurrent neural networks, unsupervised learning, reinforcement learning, and Bayesian learning.

The course is accompanied by a corresponding exercise, where students gain hands-on experience by implementing and experimenting with different machine learning algorithms, helping them to apply machine learning algorithms on real world problems.

By the end of the course, students will have acquired a solid foundation in machine learning, enabling them to apply state-of-the-art algorithms to solve complex problems, contribute to research efforts, and explore advanced topics in the field.

**Workload**

The total workload for this module is approximately 150 hours.

**Literature****Further reading**

- Machine Learning - Tom Mitchell
- Deep Learning - Ian Goodfellow, Yoshua Bengio, Aaron Courville
- Pattern Recognition and Machine Learning - Christopher M. Bishop
- Artificial Intelligence: A Modern Approach - Peter Norvig and Stuart J. Russell
- Reinforcement Learning: An Introduction - Richard S. Sutton and Andrew G. Barto

**Further (specific) literature on individual topics will be given in the lecture.**

## M

**7.155 Module: Machine Learning 2 [M-WIWI-105006]****Responsible:** Prof. Dr.-Ing. Johann Marius Zöllner**Organisation:** KIT Department of Economics and Management**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-WIWI-106341 | <a href="#">Machine Learning 2 – Advanced Methods</a> | 5 CR | Zöllner |

**Competence Certificate**

The assessment of this course is a written examination (60 min) according to §4(2), 1 of the examination regulation or an oral exam (20 min) following §4, Abs. 2, 2 of the examination regulation.

The exam takes place every semester and can be repeated at every regular examination date.

**Prerequisites**

None

**Competence Goal**

- Students gain knowledge of the basic methods in the field of machine learning.
- Students understand advanced concepts of machine learning and their application.
- Students can classify, formally describe and evaluate methods of machine learning.
- Students can use their knowledge to select suitable models and methods for selected problems in the field of machine learning.

**Content**

The subject area of machine intelligence and, in particular, machine learning, taking into account real challenges of complex application domains, is a rapidly expanding field of knowledge and the subject of numerous research and development projects.

The lecture "Machine Learning 2" deals with modern advanced methods of machine learning such as semi-supervised and active learning, deep neural networks (deep learning, CNNs, GANs, diffusion models, transformer, adversarial attacks) and hierarchical approaches, e.g. reinforcement learning. Another focus is the embedding and application of machine learning methods in real systems.

The lecture introduces the latest basic principles as well as extended basic structures and elucidates previously developed algorithms. The structure and the mode of operation of the methods and methods are presented and explained by means of some application scenarios, especially in the field of technical (sub) autonomous systems (vehicles, robotics, neurorobotics, image processing, etc.).

**Workload**

The total workload for this module is approximately 150 hours.

**Literature**

- Deep Learning - Ian Goodfellow
- Artificial Intelligence: A Modern Approach - Peter Norvig and Stuart J. Russell
- Machine Learning - Tom Mitchell
- Pattern Recognition and Machine Learning - Christopher M. Bishop
- Reinforcement Learning: An Introduction - Richard S. Sutton and Andrew G. Barto
- Deep Learning - Ian Goodfellow, Yoshua Bengio, Aaron Courville

**M****7.156 Module: Machine Learning and Optimization in Energy Systems [M-WIWI-106604]****Responsible:** Prof. Dr. Wolf Fichtner**Organisation:** KIT Department of Economics and Management**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |          |
|---------------|---|------|----------|
| T-WIWI-113073 | <a href="#">Machine Learning and Optimization in Energy Systems</a> | 4 CR | Fichtner |

**Competence Certificate**

The assessment of this module is a written examination (60 min) or an oral exam (30 min) depending on the number of participants.

**Prerequisites**

None.

**Competence Goal**

Participants know about the most common optimization and machine learning approaches for the application in energy systems. They understand the basic principles of the methods and are able to apply them for solving important problems of future energy systems with high shares of renewable energy sources.

**Content**

In the beginning, the essential transition of the energy system into a smart grid and the need for methods from the field of optimization and machine learning are explained. The course can be subdivided into an optimization part and a larger machine learning part. In the optimization part, the basics of optimization approaches that are used in energy systems are shown. Further, heuristic methods and approaches from the field of multiobjective optimization are introduced. In the machine learning part, the most important methods from the field of unsupervised learning, supervised learning and reinforcement learning are introduced and their application in future energy systems are investigated.

Amongst the considered applications are power plant dispatch, intelligent heating with heat pumps, charging strategies for electric vehicles, clustering of energy data for energy system models and electricity demand and renewable generation forecasting.

We also offer a voluntary computer exercise that deepens the understanding of the methods and applications covered in the lecture. The students will have the opportunity to solve problems from the energy domain by using optimization and machine learning approaches implemented in the programming language Python.

The course's general focus is on the application of the methods in the energy field and not on the mathematical details of the different approaches.

**Module grade calculation**

The module grade is the grade of the written or oral exam.

**Workload**

The total workload for this module is approximately 120 hours:

- Attendance: 30 hours
- Self-study: 45 hours
- Exam preparation: 55 hours

## M

**7.157 Module: Machine Learning for Robotic Systems 1 [M-MACH-106457]**

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Jun.-Prof. Dr. Rania Rayyes   |
| <b>Organisation:</b> | KIT Department of Mechanical Engineering  |
| <b>Part of:</b>      | <a href="#">Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – Methodical )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – General)</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – General)</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )</a><br><a href="#">Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)</a> |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 5              | Grade to a tenth     | Each winter term  | 1 term          | English         | 4            | 1              |

|                  |  |      |        |
|------------------|--|------|--------|
| <b>Mandatory</b> |  |      |        |
| T-MACH-113064    | <a href="#">Machine Learning for Robotic Systems 1</a> | 5 CR | Rayyes |

**Competence Certificate**

The assessment of this course is a written examination (90 min) according to §4(2), 1 of the examination regulation or an oral exam (20 min) following §4, Abs. 2, 2 of the examination regulation.

**Prerequisites**

None

**Competence Goal**

- Students acquire knowledge of the basic methods and concepts of Machine Learning
- Students can select suitable models and methods for learning problem in robotic systems
- Students can evaluate, compare and judge different machine learning models
- Student can implement and apply Machine Learning methods for Robotic Applications

**Content**

This lecture provides an overview of essential and current methods and concepts of Machine Learning for different robotic applications. It covers also their underlying mathematical and statistical methods. Important fundamental terminology, concepts and methods are presented for various topics including:

- Model selection, machine learning bias vs. parameter optimization
- Training, test, validation, generalization, overfitting, regularization
- Supervised vs unsupervised learning
- Regression
- Classifications
- Neural Networks
- Gaussian mixtures, Gaussian mixture regression

And other interesting topics

**Annotation**

None

**Workload**

150h

- approx 25h lecture attendance
- approx 25h attendance of exercises
- approx 70h studying and completing of the exercise sheets
- approx 30h exam preparation

**Recommendation**

None

**Learning type**

Lecture, exercise

**Literature**

None

## M

**7.158 Module: Machine Learning for Robotic Systems 2 [M-MACH-106652]**

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Jun.-Prof. Dr. Rania Rayyes   |
| <b>Organisation:</b> | KIT Department of Mechanical Engineering  |
| <b>Part of:</b>      | <a href="#">Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – General)</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )</a><br><a href="#">Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )</a><br><a href="#">Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)</a> |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 5              | Grade to a tenth     | Each summer term  | 1 term          | English         | 4            | 1              |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-113403 | <a href="#">Machine Learning for Robotic Systems 2</a> | 5 CR | Rayyes |

**Competence Certificate**

The assessment of this course is a written examination (90 min) according to §4(2), 1 of the examination regulation or an oral exam (20 min) following §4, Abs. 2, 2 of the examination regulation.

**Prerequisites**

None

**Competence Goal**

- Students acquire knowledge of the basic methods and concepts of Machine Learning
- Students can select suitable models and methods for learning problems in robotic systems
- Students can evaluate, compare, and judge different machine learning models
- Students can implement and apply Machine Learning methods for Robotic Applications

**Content**

This lecture provides an overview of current advanced machine learning for different robotic applications. Important fundamental terminology, concepts, and methods are presented for various topics including:

- Active Learning
- Transformers
- Adversarial learning, GANs
- Deep Reinforcement Learning
- Goal-Directed Exploration
- Recurrent Neural Network

And other interesting topics

The course also includes hands-on sessions for programming and implementing the methods.

## M

**7.159 Module: Machine Tools and Industrial Handling [M-MACH-105107]**

**Responsible:** Prof. Dr.-Ing. Jürgen Fleischer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 8       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |           |
|---------------|--|------|-----------|
| T-MACH-110962 | <a href="#">Machine Tools and High-Precision Manufacturing Systems</a> | 8 CR | Fleischer |

**Competence Certificate**

Oral exam (40 minutes)

**Competence Goal**

The students

- are able to assess the use and application of machine tools and high-precision manufacturing systems and to differentiate between them in terms of their characteristics and design.
- can describe and discuss the essential elements of machine tools and high-precision manufacturing systems (frame, main spindle, feed axes, peripheral equipment, control unit).
- are able to select and dimension the essential components of machine tools and high-precision manufacturing systems.
- are capable of selecting and evaluating machine tools and high-precision manufacturing systems according to technical and economic criteria.

**Content**

The module gives an overview of the construction, use and application of machine tools and high-precision manufacturing systems. In the course of the module a well-founded and practice-oriented knowledge for the selection, design and evaluation of machine tools and high-precision manufacturing systems is conveyed. First, the main components of the systems are systematically explained and their design principles as well as the integral system design are discussed. Subsequently, the use and application of machine tools and high-precision manufacturing systems will be demonstrated using typical machine examples. Based on examples from current research and industrial applications, the latest developments are discussed, especially concerning the implementation of Industry 4.0 and artificial intelligence.

Guest lectures from industry round off the module with insights into practice.

The individual topics are:

- Structural components of dynamic manufacturing Systems
- Feed axes: High-precision positioning
- Spindles of cutting machine Tools
- Peripheral Equipment
- Machine control unit
- Metrological Evaluation
- Maintenance strategies and condition Monitoring
- Process Monitoring
- Development process for machine tools and high-precision manufacturing Systems
- Machine examples

**Workload**

1. Presence time lecture/exercise: 15 \* 6 h = 90 h
  2. Pre- and post-processing time lecture/exercise: 15 \* 9 h = 135 h
  3. Exam preparation and presence in the same: 15 h
- In total: 240 h = 8 LP

**Learning type**

Lecture, exercise, field trip

## M

**7.160 Module: Machine Vision (Sp-MV) [M-MACH-101923]**

**Responsible:** Dr. Martin Lauer  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 8       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |                                |      |                |
|---------------|--------------------------------|------|----------------|
| T-MACH-105223 | <a href="#">Machine Vision</a> | 8 CR | Lauer, Stiller |

**Competence Certificate**

Type of Examination: written exam  
Duration of Examination: 60 minutes

**Prerequisites**

None

**Competence Goal**

After having participated in the lecture the participants have gained knowledge on modern techniques of machine vision and pattern recognition which can be used to evaluate camera images. This especially includes techniques in the areas of gray level image analysis, analysis of color images, segmentation of images, describing the geometrical relationship between the image and the 3-dimensional world, and pattern recognition with various classification techniques. The participants have learned to analyze the algorithms mathematically, to implement them in software, and to apply them to tasks in video analysis. The participants are able to analyze real-world problems and to develop appropriate solutions.



**Content**

The lecture on machine vision covers basic techniques of machine vision. It focuses on the following topics:

image preprocessing  
 edge and corner detection  
 curve and parameter fitting  
 color processing  
 image segmentation  
 camera optics  
 pattern recognition  
 deep learning

Image preprocessing:

The chapter on image processing discusses techniques and algorithms to filter and enhance the image quality. Starting from an analysis of the typical phenomena of digital camera based image capturing the lecture introduces the Fourier transform and the Shannon-Nyquist sampling theorem. Furthermore, it introduces gray level histogram based techniques including high dynamic range imaging. The discussion of image convolution and typical filters for image enhancement concludes the chapter.

Edge and corner detection:

Gray level edges and gray level corners play an important role in machine vision since gray level edges often reveal valuable information about the boundaries and shape of objects. Gray level corners can be used as feature points since they can be identified easily in other images. This chapter introduces filters and algorithms to reveal gray level edges and gray level corners like the Canny edge detector and the Harris corner detector.

Curve and parameter fitting:

In order to describe an image by means of geometric primitives (e.g. lines, circles, ellipses) instead of just pixels robust curve and parameter fitting algorithms are necessary. The lecture introduces and discusses the Hough transform, total least sum of squares parameter fitting as well as robust alternatives (M-estimators, least trimmed sum of squares, RANSAC)

Color processing:

The short chapter on color processing discusses the role of color information in machine vision and introduces various models for color understanding and color representation. It concludes with the topic of color consistency.

Image Segmentation:

Image segmentation belongs to the core techniques of machine vision. The goal of image segmentation is to subdivide the image into several areas. Each area shares common properties, i.e. similar color, similar hatching, or similar semantic interpretation. Various ideas for image segmentation exist which can be used to create more or less complex algorithms. The lecture introduces the most important approaches ranging from the simpler algorithms like region growing, connected components labeling, and morphological operations up to highly flexible and powerful methods like level set approaches and random fields.

Camera optics:

The content of an image is related by the optics of the camera to the 3-dimensional world. In this chapter the lecture introduces optical models that describe the relationship between the world and the image including the pinhole camera model, the thin lens model, telecentric cameras, and catadioptric sensors. Furthermore, the lecture introduces camera calibration methods that can be used to determine the optical mapping of a real camera.

Pattern recognition:

Pattern recognition aims at recognizing semantic information in an image, i.e. not just analyzing gray values or colors of pixels but revealing which kind of object is shown by the pixels. This task goes beyond classical measurement theory and enters the large field of artificial intelligence. Rather than just being developed and optimized by a programmer, the algorithms are adapting themselves to their specific task using training algorithms that are based on large collections of sample images.

The chapter of pattern recognition introduces standard techniques of pattern recognition in the context of image understanding like the support vector machine (SVM), decision trees, ensemble and boosting techniques. It combines those classifiers with powerful feature representation techniques like the histogram of oriented gradients (HOG) features, locally binary patterns (LBP), and Haar features.

Deep learning:

Throughout recent years standard pattern recognition techniques have more and more been outperformed by deep learning techniques. Deep learning is based on artificial neural networks, a very generic and powerful form of a classifier. The lecture introduces multi layer perceptrons as the most relevant form of artificial neural networks, discusses training algorithms and strategies to achieve powerful classifiers based on deep learning including deep auto encoders, convolutional networks, and multi task learning, among others.

**Workload**

240 hours, composed out of

hours of lecture:  $15 \cdot 4 \text{ h} = 60 \text{ h}$

preparation time prior to and after lecture:  $15 \cdot 6 \text{ h} = 90 \text{ h}$

exam preparation and exam: 90 h

**Learning type**

Lecture

**Literature**

Main results are summarized in the slides that are made available as pdf-files. Further recommendations will be presented in the lecture.

## M

## 7.161 Module: Magnet Technology of Fusion Reactors [M-MACH-107223]

**Responsible:** Dr. Klaus-Peter Weiss  
Dr. Michael Wolf

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German/English | 4     | 1       |

| Mandatory     |  |      |             |
|---------------|--|------|-------------|
| T-MACH-105434 | <a href="#">Magnet Technology of Fusion Reactors</a> | 4 CR | Weiss, Wolf |

### Competence Certificate

see individual course

### Prerequisites

none

### Competence Goal

The goal of the lecture is to impart the fundamentals of construction of superconducting magnets. Magnet technology is inherently of multidisciplinary character e.g. material properties at low temperature, high voltage and high current technique. The use of superconductors is mandatory to reach highest magnetic fields with comparable small losses. Examples of magnets from power application, basic research and fusion reactor construction are discussed.

Educational objective: The students know:

- Magnetic plasma confinement principles in connection with fusion machine
- Examples and basic properties of different superconductors
- Basics of formation of superconducting cables and magnet construction
- Generation of low temperature, cryostat construction
- Basics of magnet design and magnet safety
- Material testing and material properties at low temperatures
- High-temperature superconductor use in magnet construction and power application

### Content

The lecture will show basic principles for design and construction of such magnets and includes:

- Introduction with examples to nuclear fusion and to magnetic plasma confinement
- Basics of low temperature and high temperature properties and cryotechnique
- Material testing and critical material properties at low temperatures
- Principles of magnet design, construction and safe magnet operation
- Present status and magnet examples from fusion projects ITER, W7-X and JT-60SA
- Application of high temperature superconductors on fusion and power engineering

### Lecture Content:

- Basics of nuclear fusion and design aspects of fusion magnets
- Superconductors - basics and stability
- Low temperature cryogenic aspects
- Low temperature and high temperature superconductors
- Cryogenic material testing and properties of fusion materials at low temperatures
- Quench and high voltage aspects for magnets
- Status and magnets of fusion machines ITER, W7-X, JT-60SA & future DEMO
- Impact of high temperature superconductors on fusion and power engineering

### Module grade calculation

The module grade is the grade of the oral exam.

### Workload

120h

(for details see individual course)

## M

## 7.162 Module: Master's Thesis [M-ETIT-107192]

**Responsible:** Prof. Dr. Martin Doppelbauer  
Prof. Dr.-Ing. Marcus Geimer

**Organisation:** KIT Department of Electrical Engineering and Information Technology  
KIT Department of Mechanical Engineering

**Part of:** [Master's Thesis](#)

| Credits | Grading scale    | Recurrence | Duration | Language       | Level | Version |
|---------|------------------|------------|----------|----------------|-------|---------|
| 30      | Grade to a tenth | Each term  | 1 term   | German/English | 4     | 1       |

| Mandatory     |                                 |       |                     |
|---------------|---------------------------------|-------|---------------------|
| T-ETIT-114214 | <a href="#">Master's Thesis</a> | 30 CR | Doppelbauer, Geimer |

**Competence Certificate**

The Master's Thesis module has 30 credits. It consists of the Master's Thesis and a presentation. The presentation must be carried out within the processing time in accordance with SPO Section §14(4).

**Prerequisites**

According to SPO Section §14(1) the prerequisite for admission to the Master's Thesis module is that the student has successfully completed module examinations totaling 75 credits.

**Modeled Conditions**

The following conditions have to be fulfilled:

- You need to have earned at least 75 credits in the following fields:
  - Elective Area in Mechatronics and Information Technology
  - Field of Specialization in Mechatronics and Information Technology
  - Interdisciplinary Qualifications

**Competence Goal**

After successful completion of the module, students are able to work independently on a challenging task in the field of mechatronics or information technology within a given period of time using scientific methods and in compliance with the rules of good scientific practice under guidance and by applying the theoretical and methodological knowledge acquired in the Master's program. Students are able to do research, analyze and abstract the information and to compile and recognize basic principles and laws from less structured information. Students are able to get an overview of a problem, select complex scientific methods and procedures and use them to find solutions or show further potentials. In principle, this also takes into account social and/or ethical aspects.

The students are able to interpret and evaluate their results. They are also able to document their results in a clearly structured, written elaboration using the appropriate technical terminology. Furthermore, students are able to present and defend their results in front of a scientific audience. They have also deepened their problem-solving skills and their competence in transferring the theoretical and methodological knowledge of mechatronics and information technology into concrete applications.

In addition to the subject-related qualification goals, the students also gain knowledge and experience in the areas of project management as well as self and time management. This also includes knowledge and methods of various presentation techniques.

**Content**

The students work independently and with scientific methods on a research topic agreed with the subject examiner, which deals with a problem from the area of the Master's program in Mechatronics and Information Technology.

**Module grade calculation**

The Master's Thesis is examined by at least one university professor of the KIT Department of Electrical Engineering and Information Technology or the KIT Department of Mechanical Engineering or a habilitated member of the two KIT Departments and another examiner (SPO Section §14(7)). As a rule, one of the examiners is Person who has awarded the work in accordance with SPO Section §14(2). If the assessment of these two people does not match, the examination board determines the grade of the Master's Thesis in the context of the assessment of these two persons; additionally it can order another reviewer. The assessment must be completed within eight weeks of the submission of the Master's Thesis respectively. SPO Section §14 regulates further details.

The module grade consists of the Master's Thesis and a presentation (SPO §14(1a)).

## M

**7.163 Module: Material Flow in Logistic Systems [M-MACH-104984]**

**Responsible:** Prof. Dr.-Ing. Kai Furmans  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 9       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-MACH-102151 | <a href="#">Material Flow in Logistic Systems</a> | 9 CR | Furmans |

**Competence Certificate**

The assessment (Prüfungleistung anderer Art) consists of the following assignments:

- 40% assessment of the final case study as individual performance,
- 60% semester evaluation which includes working on 5 case studies and defending those (For both assessment types, the best 4 of 5 tries count for the final grade.):
  - 40% assessment of the result of the case studies as group work,
  - 20% assessment of the oral examination during the case study colloquiums as individual performance.

A detailed description of the learning control can be found under Annotations.

**Prerequisites**

none

**Competence Goal**

The student

- acquires comprehensive and well-founded knowledge on the main topics of logistics, an overview of different logistic questions in practice and knows the functionality of material handling systems,
- is able to illustrate logistic systems with adequate accuracy by using simple models,
- is able to realize coherences within logistic systems,
- is able to evaluate logistic systems by using the learnt methods.

**Content**

The module *Material Flow in Logistic Systems* provides comprehensive and well-founded basics for the main topics of logistics. Within the lectures, the interaction between several components of logistic systems will be shown. The module focuses on technical characteristics of material handling systems as well as on methods for illustrating and evaluating logistics systems. To gain a deeper understanding, the course is accompanied by exercises and case studies.

**Annotation**

Students are divided into groups for this course. Five case studies are carried out in these groups. The results of the group work during the lecture period are presented and evaluated in writing. In the oral examination during the case study colloquiums, the understanding of the result of the group work and the models dealt with in the course is tested. The participation in the oral defenses is compulsory and will be controlled. For the written submission the group receives a common grade, in the oral defense each group member is evaluated individually.

After the lecture period, there is the final case study. This case study contains the curriculum of the whole semester. The students work individually on this case study which takes place at a predefined place and time (duration: 4h).

**Recommendation**

Recommended elective subject: Probability Theory and Statistics

**Learning type**

Lecture, tutorial

## M

**7.164 Module: Materials for Lightweight Construction [M-MACH-102727]****Responsible:** Dr.-Ing. Wilfried Liebig**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-105211 | <a href="#">Materials of Lightweight Construction</a> | 4 CR | Liebig |

**Competence Certificate**

Oral exam, about 25 minutes

**Prerequisites**

none

**Competence Goal**

The students are capable to name different lightweight materials and can describe their composition, properties and fields of application. They can describe the hardening mechanisms of lightweight materials and can transfer this knowledge to applied problems.

The students can apply basic mechanical models of composites and can depict differences in the mechanical properties depending on composition and structure. The students can describe the basic principle of hybrid material concepts and can judge their advantages in comparison to bulk materials. The students can name special materials for lightweight design and depict differences to conventional materials. The students have the ability to present applications for different lightweight materials and can balance reasons for their use.

**Content**

Introduction

Constructive, production-oriented and material aspects of lightweight construction

Aluminium-based alloys  
Aluminium wrought alloys  
Aluminium cast alloys

Magnesium-based alloys  
Magnesium wrought alloys  
Magnesium cast alloys

Titanium-based alloys  
Titanium wrought alloys  
Titanium cast alloys

High-strength steels  
High-strength structural steels  
Heat-treatable and hardenable steels

Composites - mainly PMC  
Matrices  
Reinforcements

**Workload**

The workload for the lecture "Design with Plastics" is 120 h per semester and consists of the presence during the lectures (21 h), preparation and rework time at home (50 h) and preparation time for the oral exam (49 h).

## M

**7.165 Module: Materials Recycling and Sustainability [M-MACH-107043]****Responsible:** Dr.-Ing. Wilfried Liebig**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-110937 | <a href="#">Materials Recycling and Sustainability</a> | 4 CR | Liebig |

**Competence Certificate**

oral exam (about 25 min.)

**Prerequisites**

none

**Competence Goal**

Students are able to reproduce the history of sustainability, classify the limits of recycling, understand the relevance of manufacturing responsibility, enumerate and apply the basic principles of recycling optimised design, define, classify and critically question the concept of obsolescence and examine the interaction between recycling and sustainability. In addition, students will be able to define the basic concepts of recycling, work out the differences between recycling, downcycling and upcycling, mass and waste flows and their origins, name the work processes involved in recycling and apply them to different material classes as well as explain the specific challenges for the respective material class.

**Content**

The lecture series is organised in two main topics: On the one hand, fundamentals of sustainability are explained and it is shown how to tread more sustainable paths in materials science and mechanical engineering. On the other hand, separation and recycling processes for all common classes of materials are presented and discussed. It is shown how recycling fosters a holistic and sustainable perspective on material processing and use.

1. legal bases and historical background
2. climate change, ecology and material flows
3. sustainability in general
4. product responsibility, recyclable design and planned obsolescence
5. general and legal bases of recycling
6. material separation, sorting and processing
7. recycling of metals
8. recycling of polymers and composites
9. recycling of everyday materials
10. alternative materials and alternative design concepts
11. materials for renewable energy sources

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

The workload for the lecture "Materials Recycling and Sustainability" is 120 h per semester:

It consists of the presence during the lectures (21 h), preparation and rework time at home (50 h) and preparation time for the oral exam (49 h).

## M

**7.166 Module: Mathematical Methods in Continuum Mechanics [M-MACH-106210]****Responsible:** Prof. Dr.-Ing. Thomas Böhlke**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 3       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-110375 | <a href="#">Mathematical Methods in Continuum Mechanics</a>          | 4 CR | Böhlke |
| T-MACH-110376 | <a href="#">Tutorial Mathematical Methods in Continuum Mechanics</a> | 2 CR | Böhlke |

**Prerequisites**

M-MACH-106764 must not be started.



## M

**7.167 Module: Mathematical Methods in Fluid Mechanics [M-MACH-107032]****Responsible:** Prof. Dr.-Ing. Bettina Frohnäpfel**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language       | Level | Version |
|---------|------------------|------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | German/English | 4     | 1       |

| Mathematical Methods in Fluid Mechanics (Election: at most 6 credits) |   |      |                   |
|---|---|------|-------------------|
| T-MACH-113955   | <a href="#">Mathematical Methods in Fluid Mechanics</a> | 6 CR | Frohnäpfel, Gatti |
| T-MACH-113956   | <a href="#">Mathematical Methods in Fluid Mechanics</a> | 6 CR | Frohnäpfel, Gatti |

**Competence Certificate**

written exam - 90 minutes

**Competence Goal**

Students deepen and explain mathematical methods for solving the Navier-Stokes equations. They transfer these to technical problems. They are able to select suitable methods and discuss their application critically.

**Content**

The students can simplify the Navier-Stokes equations for specific flow problems. They are able to employ mathematical methods in fluid mechanics effectively in order to solve the resulting governing equations analytically, if possible, or to enable simpler numerical solution of the problem. The students can describe the limits of applicability of the assumptions made to model the flow behavior.

The lecture will cover a selection of the following topics:

- Creeping flows (Stokes flow)
- Lubrication theory
- Potential flow theory
- Boundary-layer theory
- Laminar-turbulent transition (linear stability theory)
- Turbulent flows

**Module grade calculation**

result of exam

**Workload**

see individual courses

**Learning type**

Lecture, Tutorial

**Literature**

Kundu, P.K., Cohen, K.M.: Fluid Mechanics, Elsevier, 4th Edition, 2008

Kuhlmann, H.: Strömungsmechanik, Pearson, 2007

Spurk, J. H.: Strömungslehre, Springer, 2006

Zierep, J., Bühler, K.: Strömungsmechanik, Springer, 1991

Schlichting H., Gersten K., Grenzschichttheorie, Springer, 2006

Kundu, P.K., Cohen, K.M.: Fluid Mechanics, Elsevier, 4th Edition, 2008

Batchelor, G.K.: An Introduction to Fluid Dynamics, Cambridge Mathematical Library, 2000

Pope, S. B.: Turbulent Flows, Cambridge University Press, 2000

Ferziger, H., Peric, M.: Computational Methods for Fluid Dynamics, Springer, 2008

## M

**7.168 Module: Mathematical Methods in Hydraulics [M-MACH-107210]****Responsible:** Prof. Dr.-Ing. Marcus Geimer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-113912 | <a href="#">Mathematical Methods in Hydraulics</a>          | 4 CR | Geimer |
| T-MACH-113913 | <a href="#">Tutorial Mathematical Methods in Hydraulics</a> | 2 CR | Geimer |

**Competence Certificate**

Oral examination, duration approx. 30 minutes

Successful completion of Ilias tests. Details will be announced in the first lecture.

**Prerequisites**

none

**Competence Goal**

Students are able to mathematically model hydraulic systems and set up differential equations, e.g. in the form of pressure build-up equations. They recognize and understand the analogies between hydraulic, electrical, mechanical and thermal systems.

In addition, students are able to select and apply suitable mathematical methods for solving hydraulic problems. This includes both analytical and numerical methods for solving the pressure curve over time.

Students are able to describe the dynamic behavior of hydraulic systems and differentiate between various simulation approaches for calculating these systems.

Students are able to apply the mathematical methods they have learned to real hydraulic problems and to critically question and evaluate the results obtained.

**Content**

- Fundamentals of hydraulics,
- Description of components for converting mechanical energy into hydraulic energy and vice versa (pumps and motors),
- Presentation of components for controlling pressure and volume flow (pressure and flow valves),
- Presentation and description of hydraulic systems,
- Solution methods for the pressure curve over time
- Simulation approaches for hydraulic networks

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

The workload includes:

1. attendance time in lectures, exercises (4 SWS):  $15 \cdot 4 \text{ h} = 60 \text{ h}$
2. preparation/follow-up of the same:  $15 \cdot 4 \text{ h} = 60 \text{ h}$
3. exam preparation and attendance: 60 h

Total: 180 h = 6 LP

**M****7.169 Module: Mechanical Properties of Nanomaterials and Microsystems [M-MACH-107185]**

**Responsible:** Dr. Patric Gruber  
Prof. Dr. Christoph Kirchlechner  
Dr. Daniel Weygand

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |                               |
|---------------|---|------|-------------------------------|
| T-MACH-114018 | <a href="#">Mechanical Properties of Nanomaterials and Microsystems</a> | 4 CR | Gruber, Kirchlechner, Weygand |

**Competence Certificate**

oral exam ca. 30 minutes

**Prerequisites**

none

**Competence Goal**

The students know and understand size and scaling effects in micro- and nanosystems based on the fundamental microstructure mechanisms at play. They can describe the mechanical behavior of nano- and microstructured materials and analyze and explain the origin for the differences compared to classical material behavior. They are able to explain suitable processing routes, experimental characterization techniques and adequate modelling schemes for nano- and microstructured materials. They also understand the relevance of mechanical phenomena in small dimensions and can judge how they determine material processing as well the performance and the design of microsensors and microactuators.

**Content**

1. Introduction: Application and properties of micro- and nanosystems; Overview on size effects
2. Fundamentals: Dislocation plasticity (definition of a dislocation; dislocation density, mobility, dislocation sources, statistical aspects incl. SSDs and GNDs).
3. Single crystal plasticity: mechanical and microstructure characterization, mechanisms and their size dependence.
4. Interface plasticity: Compatibility, slip transfer mechanisms, expected size effects.
5. Modelling of mechanisms causing size effects in crystals and at grain boundaries, e.g. dislocation dynamics.
6. Thin film materials: synthesis, characterization and mechanical properties.
7. Nanocrystalline materials: Synthesis, outstanding mechanical properties
8. Elektro-mechanical conversion: piezo-resistive, piezo-elektric, elektrostatic, ...
9. Actuation: inverse piezoelectric effect, shape-memory, electromagnetic, ...

**Module grade calculation**

see individual course

**Workload**

120h

regular attendance: 22,5 hours

self-study: 97,5 hours

**Learning type**

Lecture

## M

**7.170 Module: Medical Image Processing for Guidance and Navigation [M-ETIT-106672]****Responsible:** Prof. Dr.-Ing. Maria Francesca Spadea**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 9       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 2       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-ETIT-113425 | <a href="#">Medical Image Processing for Guidance and Navigation</a> | 9 CR | Spadea |

**Competence Certificate**

The examination takes place within the framework of an oral overall examination of approx. 30 minutes about the lecture including a presentation and discussion of the project developed during the course. The overall impression is rated.

**Prerequisites**

none

**Competence Goal**

- The students will be able to analyze, structure and formally describe problems in the field of image guided surgery and therapy.
- The students can apply the methods from medical image processing, surgical navigation, augmented reality for surgery and therapy, medical data science.
- The student will be able to communicate in English technical language.
- The students are able to perform calculations and use the necessary tools for this in a methodologically appropriate way.
- The students are able to critically evaluate them

## Content

- This module is designed to provide students with the theoretical and practical aspects of image guidance for minimally invasive surgery and therapy
- This module gives an overview about current status of technology in operation rooms (OR) and advanced radiotherapy bunkers
- Furthermore, this module gives knowledge about image process for quantitative information extraction
- Table of contents
  - Introduction to the course: minimally invasive surgery and medical data science
  - Git introduction
  - Image characteristics
  - Basic point, histogram and masked based operations
  - Similarity metrics, projections
  - Planning imaging, Dicom format, pre processing pipeline
  - Case study: planning in radiotherapy
  - Path planning
  - Pixel based image segmentation: manual segmentation, threshold, region growing
  - Convolution based segmentation: edge detection, morphological filters
  - Case study: neurosurgery and tractography
  - Image registration
  - Atlas based segmentation: SABS, MABS, atlas selection
  - Rendering and computer graphics
  - In room imaging technology
  - Reference system, notation and transformation
  - Localizing systems, tracking and calibration
  - Case study: patient monitoring in radiotherapy, adaptive treatments
  - Lab demonstration
  - Point based registration
  - Surface registration
  - Image features and descriptors (example with SIFT SURF)
  - Radiomics Features
  - Deep Learning in image processing
  - The role of deep learning in radiotherapy
  - Augmented reality

### Module grade calculation

The module grade is the grade of the oral exam.

A bonus can be earned for submitting homework that will be provided during the lecture time.

The exact criteria for awarding a bonus will be announced at the beginning of the lecture period. If the grade in the oral exam is between 4.0 and 1.3, the bonus improves the grade by 0.3 or 0.4.

Bonus points do not expire and are retained for any examinations taken at a later date.

### Annotation

The course is limited to a number of 30 participants due to capacity reasons. If necessary, a selection procedure will be carried out. Places will be allocated taking into account the students' study program (students of "Biomedical Engineering" specialization will be preferred, students from Computer Science Program and interest in medical applications will be preferred) and academic progress. Details will be announced on the lecture website.

**Workload**

The workload includes:

1. attendance in lectures and exercises:  $15 \cdot 6 \text{ h} = 90 \text{ h}$
2. preparation / follow-up:  $15 \cdot 8 \text{ h} = 120 \text{ h}$
3. preparation of and attendance in examination: 60 h

A total of 270 h = 9 CR

**Recommendation**

- Basic knowledge in the field of medical imaging;
- Knowledge of basic programming concept;
- Familiarity with Linux environment;
- Basic knowledge of linear algebra (transformations);
- Attitude towards teamwork and code management in Git;
- It is recommended to have access to a personal computer or desktop

**Learning type**

Lectures in “Medical Image Processing” (3 SWS), Seminars in “In room imaging modalities” (1 SWS), Tutorials/ Demonstrations in Medical image processing and navigation (2 SWS)

## M

**7.171 Module: Micro System Simulation [M-MACH-105486]**

**Responsible:** Prof. Dr. Jan Gerrit Korvink  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-MACH-108383 | <a href="#">Microsystem Simulation</a> | 4 CR | Korvink |

**Competence Certificate**

Written exam (120 min)

**Competence Goal**

Students are able to formulate the finite element method such as needed for mechanics, heat transfer, or transport processes. They are familiar with approximation using functions, and the relation between a finite element CAD model, and the underlying mechanism to solve the equations, an essential basis for modern engineering design.

**Content**

Microsystems are multiphysical devices. For example, in order to measure infrared radiation, a microsystem might use the Seebeck (thermoelectric) effect, which couples heat to electrical currents – thus radiation, heat flow, and charge transport are coupled in a multiphysical manner.

Because microsystem components are very small (in the micrometre range), often the operational modalities will be described better by statistical mechanics or even quantum mechanics, so that we have to take caution to use the right models.

In many cases, commercial tools are unavailable, so that engineers are forced to build their own simulation programs to be able to make intelligent designs.

In this lecture you will learn the fundamentals needed to build such a computer program. Because we want to be very efficient in learning, and not re-invent all the wheels or confront computer science issues such as compilation and libraries, you will learn to build your program in the higher level programming environment Mathematica®.

**Annotation**

The lecture is aimed at students who wish to learn the basis of numerical modelling and simulation programs, so as to understand the functioning of these most important engineering design tools. Practical examples are taken from microsystems engineering to illustrate the concepts.

**Workload**

Literature: 20 h

Lessons: 21 h

Preparation and Review: 50 h

Exam preparation: 30 h

**Recommendation**

There are no requirements for background, however, I recommend that you have at least the following: Basic knowledge in engineering, physics, and mathematics.

Regular attendance is definitely recommended, as well as doing all the exercises.

**Literature**

The following references are used by the lecturers to prepare the lecture. Students are not required to access most of these, but of course it does not hurt! Hints for efficient further reading, depending on interest, will be provided during the lecture.

- E. Buckingham, On physically similar systems: illustrations on the use of dimensional equations, Phys. Rev. 4, 345–376 (1914)
- E. Buckingham, Model Experiments and the Forms of Empirical Equations, ASME 263–296 (1915)
- K. Eriksson, D. Estep, P. Hansbo, C. Johnson, Computational Differential Equations, Cambridge University Press, Cambridge (1996)
- Bengt Fornberg, Calculation of Weights in Finite Difference Formulas, SIAM Rev. 40(3) 1998
- Gene H. Golub, Charles F. van Loan, Matrix Computations, John Hopkins University Press 1996
- H. Hanche-Olsen, Buckingham's pi-theorem, Internet (2004)
- Arieh Iserles, A First Course in the Numerical Analysis of Differential Equations, Cambridge University Press, Cambridge (1996)
- Mathematica Help Documentation
- N. Metropolis, A.W. Rosenbluth, M.N. Rosenbluth, A.H. Teller and E. Teller, "Equation of State Calculations by Fast Computing Machines, J. Chem. Phys. 21 (1953) 1087-1092.
- Rick Beatson and Leslie Greengard, A short course on fast multipole methods



## M

**7.172 Module: Microactuators [M-MACH-100487]**

**Responsible:** Prof. Dr. Manfred Kohl  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |                                |      |      |
|---------------|--------------------------------|------|------|
| T-MACH-101910 | <a href="#">Microactuators</a> | 4 CR | Kohl |

**Competence Certificate**

Written exam: 60 min

**Prerequisites**

none

**Competence Goal**

- Knowledge of the actuation principles including pros and cons
- Knowledge of important fabrication technologies
- Explanation of layout and function of the microactuators
- Calculation of important properties (time constants, forces, displacements, etc.)
- Development of a layout based on specifications

**Content**

- Basic knowledge in the material science of the actuation principles
- Layout and design optimization
- Fabrication technologies
- Selected developments
- Applications

The lecture includes amongst others the following topics:

- Microelectromechanical systems: linear actuators, microrelais, micromotors
- Medical technology and life sciences: Microvalves, micropumps, microfluidic systems
- Microrobotics: Microgrippers, polymer actuators (smart muscle)
- Information technology: Optical switches, mirror systems, read/write heads

**Workload**

Time of attendance: 15 \* 1,5 h = 22,5 h  
 Preparation and follow up: 15 \* 5,5 h = 82,5 h  
 Exam Preparation and Exam: 15 h  
 Total: 120 h = 4 LP

**Literature**

- Lecture notes
- D. Jendritza, Technischer Einsatz Neuer Aktoren: Grundlagen, Werkstoffe, Designregeln und Anwendungsbeispiele, Expert-Verlag, 3. Auflage, 2008
- M. Kohl, Shape Memory Microactuators, M. Kohl, Springer-Verlag Berlin, 2004
- N.TR. Nguyen, S.T. Wereley, Fundamentals and applications of Microfluidics, Artech House, Inc. 2002
- H. Zappe, Fundamentals of Micro-Optics, Cambridge University Press 2010

## M

**7.173 Module: Microenergy Technologies [M-MACH-102714]**

**Responsible:** Prof. Dr. Manfred Kohl  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 2       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-MACH-105557 | <a href="#">Microenergy Technologies</a> | 4 CR | Kohl, Xu |

**Competence Certificate**

Oral exam: 45 min

**Prerequisites**

none

**Competence Goal**

The students can:

- describe the energy conversion principles and exemplify them
- explain the underlying concepts of thermodynamics and materials science
- illustrate the layout, fabrication and function of the treated devices
- calculate important properties (time constants, power output, efficiency, etc.)
- develop a layout based on specifications

**Content**

- Basic physical principles of energy conversion optimization Technologies devices

- Layout and design  
- Selected Applications

The lecture includes amongst others the following topics:

- Micro energy harvesting of vibrations using different conversion principles (piezo, electrostatic, electromagnetic, etc.)
- Thermoelectric energy generation
- Novel thermal energy conversion principles (thermomagnetic, pyroelectric)
- Miniature scale solar devices
- RF energy harvesting
- Miniature scale heat pumping
- Solid-state cooling technologies (magneto-, electro-, mechanocalorics)
- Power management
- Energy storage technologies (microbatteries, supercapacitors, fuel cells)

**Module grade calculation**

Module grade calculation

The module grade is the grade of the written exam.

**Workload**

Time of attendance: 15 \* 1,5 h = 22,5 h

Preparation and follow up: 15 \* 5,5 h = 82,5 h

Exam Preparation and Exam: 15 h

Total: 120 h = 4 LP

**Literature**

- Lecture notes (overhead transparencies) „Micro Energy Technologies“
- Stephen Beeby, Neil White, Energy Harvesting for Autonomous Systems, Artech House, 2010
- Shashank Priya, Daniel J. Inman, Energy Harvesting Technologies, Springer, 2009

**M****7.174 Module: Microsystem Product Design for Young Entrepreneurs [M-MACH-107195]****Responsible:** Dr.-Ing. Dario Mager**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |                |
|---------------|--|------|----------------|
| T-MACH-105814 | <a href="#">Microsystem Product Design for Young Entrepreneurs</a> | 4 CR | Korvink, Mager |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

- Assessing one's own (technical) strengths and weaknesses, also in direct comparison with team members
- The ability to correctly assess the amount of work involved in solving a problem
- Looking at products not only in terms of their technical benefits, but also considering other aspects such as cost-effectiveness and feasibility.

**Content**

This event is all about developing your own product as a team and perhaps even founding your own company. Many successful products are manageable in their complexity and can therefore also be developed by small start-ups without a large development department. What is more important is that they hit the nerve of the times and make customers' lives better. Examples of this are products such as the fascia roll (very expensive construction foam) or the stitch healer Heat-it (a clever heater). The latter was developed as part of this course.

The aim of the course is for you to come together as a team and jointly design a product that suits the team. In the course of the semester, the first prototypes are then built and possible market opportunities evaluated. Starting a company is difficult to plan and it always helps to get external feedback, which is why many teams then take part in the VDE's Cosima student competition ([cosima-mems.de](http://cosima-mems.de)), where they can measure their product against that of other teams.

You can come to the event as a ready-made team or find yourself here, but since teams (3-5 people) are always needed, it would be great if you could send me a non-binding e-mail ([dario.mager@kit.edu](mailto:dario.mager@kit.edu)) up to one week before the start of the lecture to let me know that you are interested in the event.

**Module grade calculation**

see individual course

**Workload**

120h

(for details see individual course)

## M

**7.175 Module: Microsystem Technology [M-ETIT-100454]****Responsible:** Prof. Dr. Wilhelm Stork**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-100752 | <a href="#">Microsystem Technology</a> | 3 CR | Stork |

**Competence Certificate**

Achievement will be examined in an oral examination (approx. 20 minutes).

**Prerequisites**

none

## M

**7.176 Module: Microwave Engineering [M-ETIT-100535]**

**Responsible:** Prof. Dr.-Ing. Thomas Zwick  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language       | Level | Version |
|---------|------------------|------------|----------|----------------|-------|---------|
| 5       | Grade to a tenth | Each term  | 1 term   | German/English | 4     | 1       |

| Mandatory     |                                       |      |       |
|---------------|---------------------------------------|------|-------|
| T-ETIT-100802 | <a href="#">Microwave Engineering</a> | 5 CR | Zwick |

**Competence Certificate**

Success control is carried out as part of a written overall examination (120 minutes) of the selected courses, which in total meet the minimum requirement for LP.

**Prerequisites**

none

**Competence Goal**

The students have a deep understanding of microwave technology with a focus on passive components of microwave circuit technology. This includes the functioning of the most important microwave components such as waveguides, filters, resonators, couplers, power dividers up to directional lines and circulators. Students are able to understand and describe how these components work. You can transfer this knowledge to other areas of high-frequency technology and use it to analyze and solve high-frequency problems. You are able to apply what you have learned in a practical way.

**Content**

In-depth lecture on high-frequency technology: The focus of the lecture is the teaching of the functioning of the most important passive microwave components, starting with waveguides, through filters, resonators, power dividers and couplers to directional lines and circulators.

Accompanying the lecture, exercises are given on the lecture material. These are discussed in a large hall exercise and the associated solutions are presented in detail.

**Module grade calculation**

The module grade is the grade of the written exam.

**Annotation**

WS: German

SS: English

The exam is in each semester and for every student bilingual.

**Workload**

The workload includes: Attendance study time lecture / exercise: 45 h Self-study time including exam preparation: 105 h A total of 150 h = 5 LP

**Recommendation**

Knowledge of the basics of high frequency technology is helpful.

## M

**7.177 Module: Microwave Engineering Lab [M-ETIT-106973]**

**Responsible:** Prof. Dr.-Ing. Thomas Zwick  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-113938 | <a href="#">Microwave Engineering Lab</a> | 6 CR | Zwick |

**Competence Certificate**

In preparation for the laboratory experiments, each laboratory group must work together on a number of tasks as homework before the experiment and submit a single copy to the supervisor immediately before the start of the experiment. The tasks for the experiment itself are completed and recorded during the experiment. The protocol should be handed in to the supervisor immediately after the experiment. Before each experiment is carried out, there is a written or oral examination (approx. 20 minutes, no aids) on the content of the experiment.

**Prerequisites**

none

**Competence Goal**

Students will have in-depth knowledge of high-frequency components and systems as well as the functionality of the most important high-frequency measuring devices (network analyzer, spectrum analyzer, noise measurement, power measurement, oscilloscope, antenna measurement). They are also familiar with the use of high-frequency measuring devices and components. They are able to independently select and operate measuring devices based on specific applications and interpret the measurement results. Furthermore, they are able to work together in a self-organized team.

**Content**

Under the motto: "Practical relevance through state-of-the-art equipment and current problems", students are offered a modern and technically sophisticated high-frequency laboratory at Master's level. The aim of the experiments is to deepen the theory taught in the lectures in a practical way and to train the handling of high-frequency measuring devices and HF components. In groups of 2-4 students, various experiments are carried out and recorded over 8 afternoons. The order and topics of the experiments may vary.

**Module grade calculation**

The grade for the experiments is made up of the preparation, the protocol and the written or oral assessment of the learning objectives for each experiment. The final grade for the entire laboratory results from the overall impression of the performance. Students who appear unprepared for the respective experiment may not take part in the experiment. The experiment must be repeated at another time.

**Workload**

The workload includes:

- attendance study time laboratory: 45 h
- test preparation protocols, test preparation: 135 h

A total of 180 h = 6 LP

**Recommendation**

Knowledge of microwave measurement technology and RF components and systems is helpful.

## M

**7.178 Module: Microwaves Measurement Techniques [M-ETIT-100424]**

**Responsible:** Dr.-Ing. Mario Pauli  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology) (Usage until 3/31/2026)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 4       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-100733 | <a href="#">Microwaves Measurement Techniques</a> | 4 CR | Zwick |

**Competence Certificate**

The success control is carried out as part of an oral overall examination (approx. 20 minutes) of the selected courses, which in total meet the minimum requirement for LP.

**Prerequisites**

none

**Competence Goal**

The students have an in-depth knowledge of the structure and functioning of microwave measuring devices (signal generator, power measurement, frequency measurement, spectral analyzer, network analyzer). They understand the special features of measuring powers, frequencies and scattering parameters in the microwave range. You can apply the knowledge you have learned in practice and interpret the measurement results. You can analyze and assess possible sources of error in the measurement. You are able to design measurement setups with given measurement values and to carry out the measurements correctly.

**Content**

This lecture contains all basic areas of today's high-frequency measurement techniques, such as power measurement, frequency measurement, spectral analysis and network analysis. Particular attention is paid to the description of those measurement systems and methods that are used in modern applications.

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

The workload includes:

Attendance study time lecture / exercise: 45 h

Self-study time including exam preparation: 75 h

A total of 120 h = 4 LP

**Recommendation**

Knowledge of the basics of high frequency technology is helpful.



## M

**7.179 Module: Microwaves Measurement Techniques [M-ETIT-107007]****Responsible:** Dr.-Ing. Mario Pauli**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology) (Usage from 4/1/2026)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-114046 | <a href="#">Microwaves Measurement Techniques</a> | 4 CR | Zwick |

**Competence Certificate**

Success control takes place in the form of an oral examination (approx. 20 minutes).

**Prerequisites**

none

**Competence Goal**

The students have an in-depth knowledge of the structure and functioning of microwave measuring devices (signal generator, power measurement, frequency measurement, spectral analyzer, network analyzer). They understand the special features of measuring power, frequency and scattering parameters in the microwave range. They can apply the knowledge they have learned in practice and interpret the measurement results. They can analyze and assess possible sources of error in the measurement. They are able to design measurement setups and to carry out measurements correctly.

**Content**

This lecture contains all basic areas of today's high-frequency measurement techniques, such as power measurement, frequency measurement, spectral analysis and network analysis. Particular attention is paid to the description of those measurement systems and methods that are used in modern applications.

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

The workload includes:

Attendance study time lecture / exercise: 45 h

Self-study time including exam preparation: 75 h

A total of 120 h = 4 CR

**Recommendation**

Knowledge of the basics of high frequency technology is helpful.

## M

## 7.180 Module: Miniaturized Heat Transfer [M-MACH-107063]

**Responsible:** Prof. Dr.-Ing. Jürgen Brandner

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-MACH-108613 | <a href="#">Miniaturized Heat Exchangers</a> | 4 CR | Brandner |

### Competence Certificate

See course

### Competence Goal

After completing this module, students will be able to calculate, design and define miniaturized heat exchangers and solve basic problems in microfluidics

### Content

Advantages and disadvantages of miniaturization, basics of microfluidics; basics of heat transfer, design principles for microstructure heat exchangers, types of heat exchangers, materials and manufacturing methods, sensors and measurement technology, applications

### Module grade calculation

The module grade corresponds to the grade of the oral examination

### Workload

120h

### Learning type

Lecture

### Literature

V. Hessel, A. Renken, J.C. Schouten, J. Yoshida: Micro Process Engineering: A comprehensive handbook; Wiley-VCH  
 H.-O. Demski (ed.): Kompakt-Wärmeübertrager; Publico Publications  
 W. Wagner: Wärmeübertragung; Vogel Fachbuch - Kamprath-Reihe  
 W. Wagner: Heat exchangers; Vogel Fachbuch - Kamprath series

## M

## 7.181 Module: MMIC Design Laboratory [M-ETIT-105464]

**Responsible:** Prof. Dr.-Ing. Ahmet Cagri Ulusoy  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-ETIT-111006 | <a href="#">MMIC Design Laboratory</a> | 6 CR | Ulusoy |

**Competence Certificate**

The written report and the oral presentation are used to mark the course. The overall impression is assessed.

**Prerequisites**

none

**Competence Goal**

The students have a comprehensive understanding on the design of monolithic microwave integrated circuits.

The students are able to deduce specifications of individual building blocks in a microwave system and are able to connect these with system level considerations.

They are familiar with various IC fabrication technologies, and are able to identify pros and cons of the various state of the art technologies that are available today.

The students are able to perform the design of a complete microwave sub-system from conception to schematic level design and layout design, and are able to apply high-level design verification methods.

The students can apply their theoretical knowledge on RF engineering using modern design tools.

**Content**

In this laboratory course, the students will be assigned an RF system and will propose a hardware solution that will meet the requirements of the assigned RF system. The students will then perform schematic level design and system-level simulations of the proposed hardware. The laboratory course will be finalized with a layout implementation and verification of the proposed hardware. The students will learn to use state of the art CAD tools for system level simulations, schematic design, electromagnetic simulations, and layout design and verification in modern IC process technologies. Each RF sub-system will be developed by a group of 3-4 students.

**Module grade calculation**

The written report and the oral presentation are used to mark the course. The overall impression is assessed.

**Workload**

Each credit point corresponds approximately to 30h of the student's workload. Here, the average student is expected to reach an average performance. This contains:

1. Attendance to the laboratory tutorials ( $10 \times (3) = 30h$ )
2. Preparation to the laboratory tutorials ( $10 \times (2) = 20h$ )
3. Implementation of assigned design tasks after each tutorial ( $10 \times (8) = 80h$ )
4. Preparation of report and oral presentation (20h)

Total: 150h

**Recommendation**

Radio-Frequency Integrated Circuits and Systems, Modern Radio Systems Engineering, Microwave Engineering, Electromagnetics and Numerical Calculation of Fields

## M

## 7.182 Module: Mobile Machines [M-MACH-107041]

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Marcus Geimer  |
| <b>Organisation:</b> | KIT Department of Mechanical Engineering  |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 8       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |                 |      |        |
|---------------|-----------------|------|--------|
| T-MACH-105168 | Mobile Machines | 8 CR | Geimer |

**Competence Certificate**

The assessment consists of an oral exam (45 min) taking place in the recess period. The exam takes place in every semester. Re-examinations are offered at every ordinary examination date.

**Prerequisites**

none

**Competence Goal**

The student

- knows and understands the basic structure of the machines,
- masters the basic skills required to develop selected machines.

**Content**

- Introduction of the required components and machines
- Basics of the structure of the whole system
- Practical insight in the development techniques

Knowledge in Fluid Power is required.

**Module grade calculation**

see individual course

**Annotation**

It is recommended to attend the course *Fluid Power Systems* [2114093] beforehand.

**Workload**

- Attendance time: 42 hours
- Self-study: 198 hours

**Recommendation**

Knowledge in Fluid Power Systems is required. It is recommended to attend the course *Fluid Power Systems* [2114093] beforehand.

## M

## 7.183 Module: Modern Control Concepts I [M-MACH-105308]

**Responsible:** apl. Prof. Dr. Lutz Groell  
apl. Prof. Dr. Jörg Matthes

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |                 |
|---------------|---|------|-----------------|
| T-MACH-105539 | <a href="#">Modern Control Concepts I</a> | 4 CR | Groell, Matthes |

### Competence Certificate

A performance assessment is held in form of a written examination of 60 minutes.

### Prerequisites

None

### Competence Goal

After attending the lecture, the students are able to

- Analyze linear systems with respect to various properties,
- Identify linear dynamic models,
- Design linear controllers with feedforward control in the time domain and incorporate actuator limits,
- Use Matlab for the realization of the considered concepts and
- Implement controllers in software.

### Content

1. Introduction (system classes, nomenclature)
2. Equilibria
3. Linearization (software based, Hartman-Grobman-Theorem)
4. Parameter identification of linear dynamic models (SISO+MIMO)
5. PID-controller (realization, design-hints, Anti-Windup-mechanisms)
6. Concept of 2DOF-Controllers (structure, reference signal design)
7. State space (geometric view)
8. Controller with state feedback and integrator expansion (LQ-design, Eigenvalue placement, decoupling design)
9. Observer (LQG-design, disturbance observer, reduced observer)

### Workload

1. Attendance time Lecture:  $15 * 1.5h = 22.5h$
2. Pre- and postprocessing time Lecture:  $15 * 3.5h = 52.5h$
3. Exam preparation and attendance exam: 45h

Total: 120h = 4 LP

### Recommendation

The attendance of the following lecture is recommended:

- Grundlagen der Mess- und Regelungstechnik

Alternativly: comparable lectures at „Fakultät für Elektrotechnik und Informationstechnik“

### Learning type

Lecture

## M

## 7.184 Module: Modern Control Concepts II [M-MACH-105313]

**Responsible:** apl. Prof. Dr. Lutz Groell

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-106691 | <a href="#">Modern Control Concepts II</a> | 4 CR | Groell |

### Competence Certificate

A performance assessment is held in form of an oral examination of 30 minutes.

### Prerequisites

None

### Competence Goal

After attending the lectures, the students are able to

- analyze and control multivariable systems,
- analyze and control DAE systems,
- analyze and control time delay systems,
- use Matlab for simulation, analysis and synthesis of the discussed concepts,
- solve linear control problems with more routine.

### Content

1. Discrete time systems
2. The role of zeros (different kinds of zeros, zero dynamics, internal model principle, repetitive control, 2Dof structures, controller design via Diophantine equations)
3. Limitations of control systems (existency question, limitations w.r.t. time and frequency domain)
4. Linear multivariable systems (state space with structural invariants, canonical forms in frequency domain, polynomial matrices, matrix fractions)
5. Multivariable control for LTI systems (coprime factorization, relative gain array analysis, decentral and cooperative controls, decoupling controls, tracking controls)
6. Internal model control (internal stability, Youla parametrization, predictive structures, different 2DoF structures)
7. Advanced control loop structures (serial and parallel cascades, multiple controller structures, inferential control, split range control, extremal controls)
8. Differential-algebraic systems of equations
9. Time delay systems
10. Open topic (based on learning progress and interests, the aforementioned topics are deepened or other topics, such as time-varying systems, model order reduction, alternative stability concepts, etc. are discussed.)

### Workload

1. Attendance time Lecture:  $15 * 1.5h = 22.5h$
2. Pre- and postprocessing time Lecture:  $15 * 3.5h = 52.5h$
3. Exam preparation and attendance exam: 45h

Total: 120h = 4 LP

### Recommendation

The attendance of the following lecture is recommended:

- Grundlagen der Mess- und Regelungstechnik
- Moderne Regelungskonzepte I

Alternativly: comparable lectures at „Fakultät für Elektrotechnik und Informationstechnik“

**Learning type**

Lecture

**Literature**

- Aström, K.-J., Murray, R.M.: Feedback Systems, 2012
- Skogestad, S., Postlethwaite, I.: Multivariable Feedback Control, 2001

## M

## 7.185 Module: Modern Control Concepts III [M-MACH-105314]

**Responsible:** apl. Prof. Dr. Lutz Groell

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-106692 | <a href="#">Modern Control Concepts III</a> | 4 CR | Groell |

### Competence Certificate

A performance assessment is held in form of an oral examination of 30 minutes.

### Prerequisites

None

### Competence Goal

After attending the lectures, the students are able to

- analyze nonlinear systems and their solutions w.r.t. stability,
- design nonlinear controls with feedforward using different methods.

### Content

1. Qualitative theory of ODEs (advanced solution term in ODEs, bifurcation, Poincaré index, equilibria in infinity)
2. Lyapunov stability (definitions, theorems, topological properties of domains of attraction, Barbashin-Krasovskii-LaSalle's theorem, Barbalat's lemma)
3. Feedback linearization
4. Modifications of feedback linearization (zero dynamics, advanced linearization)
5. Flatness-based controller design
6. Lyapunov-based controller design (backstepping desing, nonlinear damping, tracking control)
7. Passivity-based controller design
8. Sliding mode control
9. Alternative linearization concepts
10. Open topic (based on learning progress and interests, the aforementioned topics are deepened or other topics, such as alternative stability concepts, observer design for nonlinear systems, basics in differential geometry, analysis and synthesis of underactuated systems, hybrid systems, Luré-type control or adaptive control.)

### Workload

1. Attendance time Lecture:  $15 * 1.5h = 22.5h$
2. Pre- and postprocessing time Lecture:  $15 * 3.5h = 52.5h$
3. Exam preparation and attendance exam: 45h

Total: 120h = 4 LP

### Recommendation

The attendance of the following lecture is recommended:

- Grundlagen der Mess- und Regelungstechnik
- Moderne Regelungskonzepte I und II

Alternativty: comparable lectures at „Fakultät für Elektrotechnik und Informationstechnik“

### Learning type

Lecture



**Literature**

- Khalil, H.: Nonlinear Systems, 1991.
- Krstic, M.; Kanellakopoulos, I.; Kokotovic, P.: Nonlinear and Adaptive Control Design, 1995.

## M

**7.186 Module: Modern Radio Systems Engineering [M-ETIT-100427]****Responsible:** Prof. Dr.-Ing. Thomas Zwick**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | English  | 4     | 2       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-100735 | <a href="#">Modern Radio Systems Engineering</a> | 6 CR | Zwick |

**Competence Certificate**

The success control takes place in the form of an oral examination of approx. 20 minutes.

**Prerequisites**

none

**Competence Goal**

After attending this course, students will be able to design an analog front end for a radio transmission system at the block diagram level. In particular, the non-idealities of typical components of high-frequency technology and their effects on the overall system performance are part of the knowledge imparted. The students also have an in-depth understanding of wave propagation.

**Content**

The course gives a general overview of radio transmission systems and their components including the radio channel and wave propagation. A brief repetition of microwave basics is also included. The focus is on the system components realized in analog technology and their non-idealities. Based on the physical functioning of the various system components, parameters are derived that allow an examination of their influence on the overall system performance.

The exercise is closely linked to the lecture and mainly consists of computer-based exercises that allow a visualization of the influences of various non-idealities on the overall system performance and demonstrate the practical system design of modern radio transmission systems.

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

The workload includes:

- Attendance study time lecture: 45 h
- Attendance study time computer exercise SystemVue ESL Design Software / MATLAB: 15 h
- Self-study time including exam preparation: 120 h

A total of 180 h

**Recommendation**

Knowledge of the basics of radio frequency technology and communications technology is recommended.

## M

**7.187 Module: Modern VLSI Technologies [M-ETIT-106921]****Responsible:** Prof. Dr. Jasmin Aghassi-Hagmann**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |                 |
|---------------|--|------|-----------------|
| T-ETIT-113864 | <a href="#">Modern VLSI Technologies</a> | 6 CR | Aghassi-Hagmann |

**Competence Certificate**

Success control takes place in form of an oral examination with a duration of approx. 20 minutes. Exercises have to be successfully completed before the exam is taken. Further details will be provided at the beginning of the course.

**Prerequisites**

none

**Competence Goal**

- The students will gain distinct knowledge in the field of modern CMOS technologies (FinFETs, High-k Gate-Stacks, Below 20nm nodes, Nanosheets).
- They will gain a good understanding of device physics and how to apply the most important design rules to design physical layouts of components and simple circuits.
- The students will be able to compare the functionality (current, performance, noise) of electrically characterized components with simulated devices, while assessing advantages and disadvantages.
- Students will learn to compare different technologies and to perform technology assessments based on benchmark circuit analyses. Understanding of critical paths in circuits for power-performance assessments.

**Content**

The lecture introduces CMOS technology with the latest technological innovations (high-k materials, gate-last processes, stress engineering, FinFETs, Gate all around FETs, nanosheets, etc.). A detailed understanding of interactions between novel materials, device architectures, and the functionality of basic components will be studied. In addition to physical and circuit properties (variations, self-heating, noise, performance), so-called layout effects, which play a crucial role in advanced CMOS are introduced. Special emphasis is put on the representation of technologies in design systems (electronic design automation) as well as SPICE simulations according to the BSIM (Berkeley Simulation Transistor Models) and PSP (Advanced Surface-Potential-Based MOSFET Model) standards. In addition, the use of industrial software (PDKs) for electrical simulation and circuit design will be introduced and practiced in the Exercises. Finally, highly integrated low power systems and their special requirements, wiring concepts and variation modeling are explained.

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

The workload includes:

1. Attendance time in laboratory (15h\*2=30h)
2. Attendance time in lectures (15h\*2=30h)
3. Preparation/follow-up, lecture and exercises (15h\*(2+2)=60h)
4. Preparation, written exercises and oral exam (60h)

Total: 180h

**Recommendation**

Previous knowledge from the lectures "Festkörperelektronik und Bauelemente" and "Elektronische Schaltungen" is recommended.

## M

**7.188 Module: Modules in English Language: [M-ETIT-107301]****Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Internship/Lab Course )  
 Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Internship/Lab Course )  
 Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Internship/Lab Course )  
 Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Internship/Lab Course )  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Internship/Lab Course )  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Internship/Lab Course )  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Internship/Lab Course )  
 Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Additive Electives )  
 Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)  
 Elective Area in Mechatronics and Information Technology (Internship/Lab Course )

| Credits | Grading scale | Recurrence      | Duration | Language | Level | Version |
|---------|---------------|-----------------|----------|----------|-------|---------|
| 0       | pass/fail     | see Annotations | 1 term   | English  | 4     | 1       |

**Annotation**

serves as a marker, not selectable

## M

**7.189 Module: Modules in German Language: [M-ETIT-107300]**

|                      |   |
|----------------------|---|
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Internship/Lab Course )<br>Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Internship/Lab Course )<br>Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Internship/Lab Course )<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Energy Technology (Internship/Lab Course )<br>Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Internship/Lab Course )<br>Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Internship/Lab Course )<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Internship/Lab Course )<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)<br>Elective Area in Mechatronics and Information Technology (Internship/Lab Course ) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 0              | pass/fail            | see Annotations   | 1 term          | German          | 4            | 1              |

**Annotation**

serves as a marker, not selectable

## M

**7.190 Module: Motion in Human and Machine - Seminar [M-INFO-102555]****Responsible:** Prof. Dr.-Ing. Tamim Asfour**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 3       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-INFO-105140 | <a href="#">Motion in Human and Machine - Seminar</a> | 3 CR | Asfour |

**Competence Certificate**

See partial achievements (Teilleistung)

**Prerequisites**

See partial achievements (Teilleistung)

**Competence Goal**

The student knows procedures for modelling human motion, as well as possibilities for its processing and analysis. He/she knows methods for learning motion primitives and mapping human motion to robots that have different kinematics and dynamics and can apply them in new contexts.

Students are familiar with the DFG Code of Conduct "Guidelines for Safeguarding Good Scientific Practice" and successfully apply these guidelines in the preparation of their scientific work.

**Content**

This interdisciplinary block seminar deals with methods of modelling, generating and controlling movements in humans and robot systems. Students get an insight into this interdisciplinary field and learn the basics of biological motion, biomechanical simulation, robotics, and machine learning. In the introduction, motion generation as effect of muscle contraction is discussed. It will be shown how movement patterns can be identified and categorized based on the observation of human movements and how these patterns can be reproduced on a humanoid robot. Finally, methods for the learning of movement primitives from human demonstration will be presented and their application for the generation of motion for humanoid robots will be explained.

**Annotation**

The block internship is an interdisciplinary event in co-operation with the University of Stuttgart and the University of Heidelberg.

**Workload**

Seminar with 3 SWS, 3 LP

3 LP corresponds to 90 hours, including

30 hours attendance time

15 hours group work

20 hours literature research

20 hours manuscript preparation

5 hours video creation

**Recommendation**

Programming experience in C++, Python or Matlab is recommended.

Attending the lectures Robotics I – Introduction to Robotics, Robotics II: Humanoid Robotics, Robotics III - Sensors and Perception in Robotics, Mechano-Informatics and Robotics and Wearable Robotic Technologies is recommended.

## M

**7.191 Module: Motor Vehicle Laboratory [M-MACH-102695]**

**Responsible:** Dr.-Ing. Michael Frey  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |      |
|---------------|--|------|------|
| T-ETIT-114320 | <a href="#">Motor Vehicle Labor (graded)</a> | 4 CR | Frey |

**Competence Certificate**

After completion of the experiments: written examination

Duration: 90 minutes

Auxiliary means: none

**Prerequisites**

None

**Competence Goal**

The students have deepened their knowledge on motor vehicles acquired in lectures and can apply it practically. They have an overview of the applied measuring technique and can execute and analyse measurements for the handling of given problem definitions. They are ready to analyze and to judge measurement results.

**Content**

1. Determination of the driving resistances of a passenger vehicle on a roller dynamometer; measurement of the engine performance of the test vehicle
2. Investigation of a twin-tube and a single-tube shock absorber
3. Behavior of car tyres under longitudinal forces and lateral forces
4. Behavior of car tires on wet road surface
5. Rolling resistance, energy dissipation and high-speed strength of car tires
6. Investigation of the moment transient characteristic of a Visco clutch

**Module grade calculation**

The module grade is the grade of the written examination.

**Annotation**

The admission is limited to 12 persons per group.

**Workload**

regular attendance: 31,5 hours

self-study: 103,5 hours

**Literature**

1. Matschinsky, W: Radführungen der Straßenfahrzeuge, Verlag TÜV Rheinland, 1998
2. Reimpell, J.: Fahrwerktechnik: Fahrzeugmechanik, Vogel Verlag, 1992
3. Gnadler, R.: Documents to the Motor Vehicle Laboratory



## M

## 7.192 Module: Nano- and Quantum Electronics [M-ETIT-105604]

**Responsible:** Prof. Dr. Sebastian Kempf

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-111232 | <a href="#">Nano- and Quantum Electronics</a> | 6 CR | Kempf |

### Competence Certificate

The assessment of success takes place in the form of a written examination lasting 120min. The grade corresponds to the result of the written examination.

### Prerequisites

none

### Competence Goal

Students will understand the physical limits of CMOS scaling and will be able to analyze the function of conventional nanoelectronic devices. Students will also understand the operation of novel nanoelectronic and quantum electronic devices and will be able to design this kind of devices that are based on quantum mechanical effects. They develop the ability to design nanoelectronic sensors and devices and can understand and analyze the fabrication methods for nano- and quantum electronic devices.

### Content

Nanoelectronics deals with integrated circuits whose typical length scale is well below 100nm. In this regime, physical effects, in particular of quantum mechanical origin, occur and strongly influence the scaling of classical microelectronic devices. This ultimately leads to a new form of electronic components as well as novel operation principles. A special form of nanoelectronics is quantum electronics in which quantum mechanical effects are exploited on purpose to build an entirely new class of devices whose performance reaches far beyond any other microelectronics devices. Well-known examples are superconducting digital electronics which enables to build, for example, microprocessors with clock rates exceeding several 100GHz, or the quantum computer, which will lead to a change of paradigms in the field of information processing.

Within this context, the module "Nano- and quantum electronics" intends to give students an overview of the theoretical and practical aspects of nano- and quantum electronics. In particular, it discusses the following topics:

- Limitations of conventional CMOS technology
- Quantum mechanical effects in the field of nano- and quantum electronics (quantized conductance, Coulomb blockade, tunnel effect, etc.)
- Hot-electron effect
- Nano- and quantum-technological manufacturing and analysis methods
- Nanostructure field-effect transistors
- Quantum dots
- Carbon nanotube field-effect transistor
- Resonant tunnel diodes
- Unipolar resonant tunnel transistor
- Single Electron Transistor (SET)
- Josephson junction based analog and digital electronics
- Quantum bits, quantum computers and quantum computing

The tutorial is closely linked to the lecture and deals with special aspects concerning the development of nano- and quantum electronics. In particular, the development and system integration of such devices for various applications is discussed by means of exercises.

### Module grade calculation

The module grade is the grade of the written examination.

**Workload**

A workload of approx. 175h is required for the successful completion of the module. This is composed as follows:

- Attendance time in lectures and exercises:  $18 \cdot 1.5h + 6 \cdot 1.5h = 36h$
- Preparation and follow-up of lectures:  $21 \cdot 3h = 54h$
- Preparation and follow-up of tutorials:  $7 \cdot 5h = 35h$
- Preparation for the exam: 50h

**Recommendation**

Successful completion of the modules "Superconductivity for Engineers" and „Einführung in die Quantentheorie für Elektrotechniker“ is recommended.

## M

**7.193 Module: NMR Micro Probe Hardware Conception and Construction [M-MACH-107196]**

**Responsible:** Prof. Dr. Jan Gerrit Korvink  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-MACH-108407 | <a href="#">NMR Micro Probe Hardware Conception and Construction</a> | 4 CR | Korvink |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

The aim of this practical block course is to familiarize the students with magnetic resonance imaging as a substantial non-invasive non-destructive imaging technique that is widely used for medical diagnosis.

It is also to give them hands-on experience on how to build the MRI probe from A to Z including

- Mechanical design
- High frequency electrical circuitry
- Testing on a commercial MRI scanner.

The course includes a concise introduction to the theory of MRI and the hardware of the MRI scanner. This will be followed by a number of work-packages through which the participants will construct and test their own functioning MRI probehead, with which it will be possible to record a proton-MRI image of a sample containing sufficient water. The probehead will be operated inside a Bruker MRI machine at the end of the one week course.

**Content**

In order to prepare attendees, the following chapters will be offered, spread over the week as lecture units, and accompanying the practical work:

- Theory of magnetic resonance imaging
- The MRI probe and the principle of reciprocity
- RF resonators
- Coaxial cables and cable traps
- Tuning and matching the MRI probe
- Effects of material susceptibility
- The mechanical support of the MRI probe
- Introduction to ParaVision, the MRI imaging software.

**Module grade calculation**

see individual course

**Workload**

120 h

(for details see individual course)

## M

**7.194 Module: Nonlinear Control Systems [M-ETIT-100371]****Responsible:** Prof. Dr.-Ing. Sören Hohmann**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-100980 | <a href="#">Nonlinear Control Systems</a> | 3 CR | Kluwe |

**Prerequisites**

none

## M

**7.195 Module: Nonlinear Optics [M-ETIT-100430]**

**Responsible:** Prof. Dr.-Ing. Christian Koos  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 2       |

| Mandatory     |                                  |      |      |
|---------------|----------------------------------|------|------|
| T-ETIT-101906 | <a href="#">Nonlinear Optics</a> | 6 CR | Koos |

**Competence Certificate**

The oral exam is offered continuously upon individual appointment.

**Prerequisites**

none

**Competence Goal**

The students

- understand and can mathematically describe the effect of basic nonlinear-optical phenomena using optical susceptibility tensors,
- understand and can mathematically describe wave propagation in nonlinear anisotropic materials,
- have an overview and can quantitatively describe common second-order nonlinear effects comprising the electro-optic effect, second-harmonic generation, sum- and difference frequency generation, parametric amplification and optical rectification,
- have an overview and can quantitatively describe the Kerr effect and other common third-order nonlinear effects, comprising self- and cross-phase modulation, four-wave mixing, self-focussing, and third-harmonic generation,
- have an overview and can describe nonlinear-optical interaction in active devices such as semiconductor optical amplifiers
- conceive the basic principles of various phase-matching techniques and can apply them to practical design problems,
- conceive the basic principles electro-optic modulators, can apply them to practical design problems, and have an overview on state-of-the art devices,
- conceive the basic principles third-order nonlinear signal processing and can apply them to practical design problems.

**Content**

1. The nonlinear optical susceptibility: Maxwell's equations and constitutive relations, relation between electric field and polarization, formal definition and properties of the nonlinear optical susceptibility tensor,
2. Wave propagation in nonlinear anisotropic materials
3. Second-order nonlinear effects and devices: Linear electro-optic effect / Pockels effect, second-harmonic generation, sum- and difference-frequency generation, phase matching, parametric amplification, optical rectification
4. Third-order nonlinear effects and devices: Nonlinear refractive index and Kerr effect, self- and cross-phase modulation, four-wave mixing, self-focussing, third-harmonic generation
5. Nonlinear effects in active optical devices

**Module grade calculation**

The module grade is the grade of the oral exam.

There is a bonus system based on the problem sets that are solved during the tutorials: During the term, 3 problem sets will be collected in the tutorial and graded without prior announcement. If for each of these sets more than 70% of the problems have been solved correctly, a bonus of 0.3 grades will be granted on the final mark of the oral exam.

**Workload**

Approx. 180 h – 30 h lectures, 30 h exercises, 120 h homework and self-studies

**Literature**

R. Boyd. Nonlinear Optics. Academic Press, New York, 1992.  
 E.H. Li S. Chiang Y. Guo, C.K. Kao. Nonlinear Photonics. Springer Verlag, 2002  
 G. Agrawal, Nonlinear Fiber Optics, Academic Press, San Diego, 1995.

## M

**7.196 Module: Novel Actuators and Sensors [M-MACH-105292]**

**Responsible:** Prof. Dr. Manfred Kohl  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |              |
|---------------|---|------|--------------|
| T-MACH-102152 | <a href="#">Novel Actuators and Sensors</a> | 4 CR | Kohl, Sommer |

**Competence Certificate**

Written exam, 60 min

**Prerequisites**

None

**Competence Goal**

- Knowledge of the actuation and sensing principles including pros and cons
- Knowledge of important fabrication technologies
- Explanation of layout and function of the actuators and sensors
- Calculation of important properties (time constants, forces, displacements, sensitivity etc.)
- Development of a layout based on specifications

**Content**

The content of the lecture is among others:

- Piezo actuators
- Magnetostruktive actuators
- Shape memory actuators
- Electro-/Magnetorheological actuators
- Sensors: Concepts, materials, fabrication
- Micromechanical sensors: Pressure, force, inertial sensors
- Temperature sensors
- Sensors for bioanalytics
- Mechano-magnetic sensors

**Workload**

lecture time 18 h

self preparation: 102 h

**Learning type**

Lecture

**Literature**

- Vorlesungsskript "Neue Aktoren" und Folienskript "Sensoren"
- Micro Mechatronics, K. Uchino, 2nd ed., CRC Press, Taylor & Francis Group, 2019.
- Donald J. Leo, Engineering Analysis of Smart Material Systems, John Wiley & Sons, Inc., 2007
- "Sensors Update", Edited by H.Baltes, W. Göpel, J. Hesse, VCH, 1996, ISBN: 3-527-29432-5
- "Multivariate Datenanalyse – Methodik und Anwendungen in der Chemie", R. Henrion, G. Henrion, Springer 1994, ISBN 3-540-58188-X

## M

**7.197 Module: Nuclear Power and Reactor Technology [M-MACH-107042]****Responsible:** Dr. Aurelian Florin Badea**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-110332 | <a href="#">Nuclear Power and Reactor Technology</a> | 4 CR | Badea |

**Competence Certificate**

A performance assessment will consist of an oral examination of 30 minutes.

**Competence Goal**

The objective of the module is the understanding of reactor technology and of the major physical processes in converting nuclear power into electrical energy. The students acquire comprehensive knowledge on the physics of nuclear fission reactors: neutron flux, cross sections, fission, breeding processes, chain reaction, critical size of a nuclear system, moderation, reactor dynamics, transport-and diffusion-equation for the neutron flux distribution, power density distributions in reactor, one-group, two-group and multi-group theories for the neutron spectrum. Students are able to analyze and understand the obtained results. The students are capable of understanding the advantages and disadvantages of different reactor technologies - LWR, heavy water reactors, nuclear power systems of generation IV - by using the delivered knowledge on reactor physics, thermal-hydraulics, reactor design, control, safety and requirements of the front-end and back-end of the fuel cycle. The students are qualified for further training in nuclear energy and safety field and for (also research-related) professional activity in the nuclear industry.

**Content**

- nuclear fission & fusion,
- radioactive decay, neutron excess, fission, fast and thermal neutrons, fissile and fertile nuclei, enrichment, neutron flux, cross section, reaction rate, mean freepath,
- chain reaction, critical size, moderation,
- reactor dynamics,
- transport- and diffusion-equation for the neutron flux distribution,
- power distributions in reactor,
- one-group and two-group theories,
- light-water reactors,
- reactor safety,
- design of nuclear reactors,
- breeding processes,
- nuclear power systems of generation IV

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

## M

**7.198 Module: Nuclear Power Plant Technology [M-MACH-107121]**

**Responsible:** Dr. Aurelian Florin Badea  
Prof. Dr.-Ing. Xu Cheng

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |              |
|---------------|--|------|--------------|
| T-MACH-105402 | <a href="#">Nuclear Power Plant Technology</a> | 4 CR | Badea, Cheng |

**Competence Certificate**

A performance assessment will consist of an oral examination of approx. 30 minutes.

**Prerequisites**

none

**Competence Goal**

The objective of the module is the qualification for a research-related professional activity in nuclear power plant engineering. The participants can describe the most important components of nuclear power plants and their function. You can design or modify nuclear power plants independently and creatively. They have acquired a broad knowledge of this power plant technology, including specific knowledge of core design, design of primary and secondary systems, and of nuclear safety technologies. Based on the acquired knowledge in thermodynamics and neutron physics, they can describe and analyze the specific behavior of the nuclear power plant components and assess risks. Participants of the lecture have a trained analytical thinking and judgment in the design of nuclear power plants.

**Content****Power plants with pressurized water reactors:***Design of the pressurized water reactor*

Fuel assemblies  
Control rods and drives  
Core instrumentation  
Reactor pressure vessel and its internals

*Components of the primary system*

Primary coolant pumps  
Pressurizer  
Steam generator  
Water make-up system

*Secondary system*

Turbines  
Reheater  
Feedwater system  
Cooling systems

*Containment*

Containment design  
Components of safety systems  
Components of residual heat removal systems

*Control of a nuclear power plant with PWR***Power plants with boiling water reactors:***Design of the boiling water reactor*

Fuel assemblies  
Control elements and drives  
Reactor pressure vessel and its internals  
Containment and components of safety systems

*Control of a nuclear power plant with boiling water reactors*



**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

(for details see individual course)

## M

## 7.199 Module: Numerical Fluid Mechanics [M-MACH-107036]

**Responsible:** Prof. Dr.-Ing. Bettina Frohnäpfel  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |                   |
|---------------|---|------|-------------------|
| T-MACH-105338 | <a href="#">Numerical Fluid Mechanics</a> | 4 CR | Frohnäpfel, Gatti |

**Competence Certificate**

oral exam - 30 minutes

**Prerequisites**

none

**Competence Goal**

The students deepen their understanding of the building blocks of numerical solutions for fluid mechanics problems. They can classify the fundamental equations of fluid mechanics based on their mathematical characteristics and recognize the implications for designing a numerical method. They can mathematically describe discretization approaches using finite differences and finite volumes and apply them to the incompressible Navier-Stokes equations. They can critically evaluate numerical methods in terms of their stability, accuracy, and efficiency.

**Content**

The course covers the following topics:

1. basic equations of computational fluid dynamics
2. main discretization methods for fluid mechanics problems, with focus on finite differences and finite volumes
3. boundary and initial conditions
4. mesh generation and mesh treatment
6. solution algorithms for linear and nonlinear systems of equations
7. solution strategies for the incompressible Navier-Stokes equations
8. introduction to the solution of the compressible Navier-Stokes equations
9. examples of numerical simulation in practice

**Module grade calculation**

result of exam

**Workload**

The work load is about 120 hours, corresponding to 4 credit points.

**Learning type**

Lectures + tutorials

**Literature**

Ferziger, Peric: Computational Methods for Fluid Dynamics. Springer-Verlag, 1999.

Hirsch: Numerical Computation of Internal and External Flows. John Wiley & Sons Inc., 1997.

Versteeg, Malalasekera: An introduction to computational fluid dynamics. The finite volume method. John Wiley & Sons Inc., 1995

## M

## 7.200 Module: Numerical Methods [M-MATH-105831]

**Responsible:** Prof. Dr. Wolfgang Reichel

**Organisation:** KIT Department of Mathematics

**Part of:** Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )  
 Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |                          |      |                          |
|---------------|--------------------------|------|--------------------------|
| T-MATH-111700 | Numerical Methods - Exam | 5 CR | Kunstmann, Liao, Reichel |

### Competence Certificate

Success control takes the form of a written examination (120 minutes).

### Prerequisites

none

### Competence Goal

Students who pass the module are familiar with basic concepts and ways of thinking on the topic of numerical mathematics. They know different procedures for solving linear and nonlinear problems in numerical mathematics. They are furthermore able to use numerical methods for solving problems from applications in an independent, critical, and needs-based way.

### Content

In the lecture basic ideas and numerical methods for the following topics will be presented:

- systems of linear equations, Gauss-algorithm, LR-decomposition, Cholesky decomposition
- eigenvalue problems, von-Mises iteration
- linear optimization (also called linear programming)
- error analysis
- Newton's method
- quadrature, Newton-Cotes formulas
- numerical solution of initial value problems, Runge-Kutta methods
- finite difference method for solving boundary value problems
- finite elements

### Module grade calculation

The module grade is the grade of the written exam.

**Workload**

Approximately 150h workload. The workload includes:

45h - attendance in lectures, exercises and examination

105h – self studies:

- follow-up and deepening of the course content
- solving problem sheets
- literature study and internet research on the course content
- preparation for the module examination

## M

**7.201 Module: Numerical Methods with Programming Practice [M-MATH-106972]****Responsible:** Prof. Dr. Wolfgang Reichel**Organisation:** KIT Department of Mathematics

**Part of:** Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )  
 Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |                          |
|---------------|---|------|--------------------------|
| T-MATH-111700 | Numerical Methods - Exam  | 5 CR | Kunstmann, Liao, Reichel |
| T-MATH-113937 | Numerical Methods - Workshop<br><i>This item will not influence the grade calculation of this parent.</i> | 1 CR | Kunstmann, Liao, Reichel |

**Competence Certificate**

Success control takes the form of a written examination (120 minutes) and mandatory participation in the programming workshop. Successful participation in the workshop is confirmed by signing the attendance sheet provided at each practice session.

**Prerequisites**

none

**Competence Goal**

Students who pass the module are familiar with basic concepts and ways of thinking on the topic of numerical mathematics. They know different procedures for solving linear and nonlinear problems in numerical mathematics. They are furthermore able to use numerical methods for solving problems from applications in an independent, critical, and needs-based way. The students are capable to implement the numerical procedures they have learned in programming workshop.

**Content**

In the lecture basic ideas and numerical methods for the following topics will be presented:

- systems of linear equations, Gauss-algorithm, LR-decomposition, Cholesky decomposition
- eigenvalue problems, von-Mises iteration
- linear optimization (also called linear programming)
- error analysis
- Newton's method
- quadrature, Newton-Cotes formulas
- numerical solution of initial value problems, Runge-Kutta methods
- finite difference method for solving boundary value problems
- finite elements

**Module grade calculation**

The module grade is the grade of the written exam.

**Annotation**

The workshop is held twice during the semester, offering students the opportunity to earn an additional credit point (+1) upon successful participation. Students are expected to work on the programming exercises on their own laptops prior to the workshop. During the workshop, solutions to the programming exercises are discussed with the students.

**Workload**

Approximately 180h workload. The workload includes:

45h - attendance in lectures, exercises and examination

4h - attendance in workshop

131h – self studies:

- follow-up and deepening of the course content
- solving problem sheets
- literature study and internet research on the course content
- preparation for the module examination
- preparation of workshop

## M

## 7.202 Module: Optical Design Lab [M-ETIT-100464]

**Responsible:** Prof. Dr. Wilhelm Stork  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 2       |

| Mandatory     |                                    |      |       |
|---------------|------------------------------------|------|-------|
| T-ETIT-100756 | <a href="#">Optical Design Lab</a> | 6 CR | Stork |

**Competence Certificate**

The examination consists of an oral exam (20 min).

**Prerequisites**

none

**Competence Goal**

The students can apply previous theoretical knowledge in optics to design optical systems based on ray tracing, using a typical optics design software.

The students can apply typical analysis methods to evaluate the imaging performance of optical systems.

The students can recognize aberrations in optical systems and apply methods to compensate them.

**Content**

The students participating in this lab are given the opportunity to gain practical experience in the use of software tools commonly used in industry for the design of optical elements and systems. Thus improving their knowledge in optical engineering.

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

Approximately 162 h workload of the student.

The workload includes:

- attendance in lectures and exercises: 36 h
  - 9 exercises of 4 h
- preparation / follow-up: 51 h
  - preparation 9x3 h
  - writing lab reports: 8x3 h
- preparation of and attendance in examination: 75h

**Recommendation**

Basic knowledge in optics. The participation in the course Optical Engineering is strongly advised.

## M

## 7.203 Module: Optical Engineering and Machine Vision [M-ETIT-106974]

**Responsible:** Prof. Dr.-Ing. Michael Heizmann

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-ETIT-113941 | <a href="#">Optical Engineering and Machine Vision</a> | 6 CR | Heizmann |

### Competence Certificate

The examination takes place in form of a written examination lasting 90 minutes.

### Prerequisites

none

### Competence Goal

- Students have a sound knowledge of the fundamentals (physical basics of optics, optical imaging, image sensors) and procedures of optical engineering and machine vision.
- Students are proficient in diverse methods for optical imaging, image acquisition, pre-processing and image evaluation and can characterize them based on their prerequisites, model assumptions and results.
- Students are able to analyze and structure optical engineering and machine vision tasks, synthesize possible solutions from optics principles and image processing methods and assess their suitability.



### Content

Optical engineering and machine vision are collective terms for using optical signals to solve tasks of information retrieval for technical and other application. They comprise the propagation of light in optical systems, the acquisition of image signals using optical imaging and cameras, the processing of the recorded image signals using (digital) image processing and the evaluation of the image data to obtain useful information from the recorded images.

The module teaches the basics, procedures and exemplary applications of optical engineering and image processing.

The module include in detail:

- Optical Imaging
  - Imaging with a pinhole camera, central projection
  - Imaging using a (single) lens
- Color
  - Photometry
  - Color perception and color spaces
  - Filters
- Sensors for Image Acquisition
  - CCD, CMOS sensors
  - Color sensors and color cameras
  - Quality criteria for image sensors
- Methods of Image Acquisition
  - Measuring optical properties
  - 3D shape capturing
- Image Signals
  - Mathematical model of image signals
  - Systems theory
  - Two-dimensional Fourier transform
  - Noise of digital imaging sensors (EMVA 1288)
- Preprocessing and Image Enhancement
  - Simple image enhancement methods
  - Reduction of systematic errors
  - Attenuation of random disturbances
- Segmentation
  - Region-based segmentation
  - Edge-oriented methods
- Morphological Image Processing
- Binary morphology
  - Gray-scale morphology
- Texture analysis
  - Types of textures
  - Model-based texture analysis
  - Feature-based texture analysis
- Detection
  - Detection of known objects by linear filters
  - Detection of unknown objects (defects)
  - Detection of straight lines (Radon and Hough transform)

### Module grade calculation

The module grade is the grade of the written examination.

### Workload

The workload includes:

1. attendance in lectures and exercises:  $15 \cdot 4 \text{ h} = 60 \text{ h}$
2. preparation / follow-up:  $15 \cdot 4 \text{ h} = 60 \text{ h}$
3. preparation of and attendance in examination: 60 h

A total of 180 h = 6 CR

### Recommendation

Basic knowledge of systems theory and signal processing (e.g. from the module "Signals and Systems") as well as optics is helpful.

### Learning type

lecture (3 SWS) and exercise (1 SWS)

## M

## 7.204 Module: Optical Transmitters and Receivers [M-ETIT-100436]

**Responsible:** Prof. Dr. Wolfgang Freude

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 2       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-ETIT-100639 | <a href="#">Optical Transmitters and Receivers</a> | 6 CR | Freude |

### Competence Certificate

Oral examination (approx. 20 minutes). The individual dates for the oral examination are offered regularly.

### Prerequisites

none

### Competence Goal

The students

- understand the peculiarities of optical communications, and how optical signals are generated, transmitted and received,
- know about sampling, quantization and coding,
- learn the basics about noise on reception,
- understand the properties of a linear and a nonlinear optical fibre channel, grasp the idea of channel capacity and spectral efficiency,
- know about various forms of modulation,
- acquire knowledge of optical transmitter elements,
- understand the function of optical amplifiers,
- have a basic understanding of optical receivers,
- know the sensitivity limits of optical systems, and
- understand how these limits are measured.

### Content

The course concentrates on basic optical communication concepts and connects them with the properties of physical components. The following topics are discussed:

- Advantages and limitations of optical communication systems
- Optical transmitters comprising lasers and modulators
- Optical receivers comprising direct and heterodyne reception
- Characterization of signal quality

### Module grade calculation

The module grade is the grade of the oral exam.

### Workload

Approx. 120 hours workload for the student. The amount of work is included:

- 30 h - Attendance times in lectures
- 15 h - Exercises
- 75 h - Preparation / revision phase

### Recommendation

Knowledge of the physics of the pn-junction

### Literature

Detailed textbook-style lecture notes can be downloaded from the IPQ lecture pages.

Grau, G.; Freude, W.: *Optische Nachrichtentechnik*, 3. Ed. Berlin: Springer-Verlag 1991. In German. Since 1997 out of print. Electronic version available via [w.freude@kit.edu](mailto:w.freude@kit.edu).

Kaminow, I. P.; Li, Tingye; Willner, A. E. (Eds.): *Optical Fiber Telecommunications VI A: Components and Subsystems +VI B: Systems and Networks*, 6th Ed. Elsevier (Imprint: Academic Press), Amsterdam 2013

## M

## 7.205 Module: Optical Waveguides and Fibers [M-ETIT-100506]

**Responsible:** Prof. Dr.-Ing. Christian Koos

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |      |
|---------------|---|------|------|
| T-ETIT-101945 | <a href="#">Optical Waveguides and Fibers</a> | 4 CR | Koos |

### Competence Certificate

Type of Examination: Oral exam

Duration of Examination: approx. 20 minutes

Modality of Exam: The written exam is offered continuously upon individual appointment.

### Prerequisites

None

### Competence Goal

The students

- conceive the basic principles of light-matter-interaction and wave propagation in dielectric media and can explain the origin and the implications of the Lorentz model and of Kramers-Kronig relation,
- are able to quantitatively analyze the dispersive properties of optical media using Sellmeier relations and scientific databases,
- can explain and mathematically describe the working principle of an optical slab waveguide and the formation of guided modes,
- are able to program a mode solver for a slab waveguide in Matlab,
- are familiar with the basic principle of surface plasmon polariton propagation,
- know basic structures of planar integrated waveguides and are able to model special cases with semi-analytical approximations such as the Marcatili method or the effective-index method,
- are familiar with the basic concepts of numerical mode solvers and the associated limitations,
- are familiar with state-of-the-art waveguide technologies in integrated optics and the associated fabrication methods,
- know basic concepts of step-index fibers, graded-index fibers and microstructured fibers,
- are able to derive and solve basic relations for step-index fibers from Maxwell's equations,
- are familiar with the concept of hybrid and linearly polarized fiber modes,
- can mathematically describe signal propagation in single-mode fibers design dispersion-compensated transmission links,
- conceive the physical origin of fiber attenuation effects,
- are familiar with state-of-the-art fiber technologies and the associated fabrication methods,
- can derive models for dielectric waveguide structures using the mode expansion method,
- conceive the principles of directional couplers, multi-mode interference couplers, and waveguide gratings,
- can mathematically describe active waveguides and waveguide bends.

### Content

1. Introduction: Optical communications
2. Fundamentals of wave propagation in optics: Maxwell's equations in optical media, wave equation and plane waves, material dispersion, Kramers-Kronig relation and Sellmeier equations, Lorentz and Drude model of refractive index, signal propagation in dispersive media.
3. Slab waveguides: Reflection from a plane dielectric boundary, slab waveguide eigenmodes, radiation modes, inter- and intramodal dispersion, metal-dielectric structures and surface plasmon polariton propagation.
4. Planar integrated waveguides: Basic structures of integrated optical waveguides, guided modes of rectangular waveguides (Marcatili method and effective-index method), basics of numerical methods for mode calculations (finite difference- and finite-element methods), waveguide technologies in integrated optics and associated fabrication methods
5. Optical fibers: Optical fiber basics, step-index fibers (hybrid modes and LP-modes), graded-index fibers (infinitely extended parabolic profile), microstructured fibers and photonic-crystal fibers, fiber technologies and fabrication methods, signal propagation in single-mode fibers, fiber attenuation, dispersion and dispersion compensation
6. Waveguide-based devices: Modeling of dielectric waveguide structures using mode expansion and orthogonality relations, multimode interference couplers and directional couplers, waveguide gratings, material gain and absorption in optical waveguides, bent waveguides

**Module grade calculation**

The module grade is the grade of the oral exam.

There is, however, a bonus system based on the problem sets that are solved during the tutorials: During the term, 3 problem sets will be collected in the tutorial and graded without prior announcement. If for each of these sets more than 70% of the problems have been solved correctly, a bonus of 0.3 grades will be granted on the final mark of the oral exam.

**Workload**

Total 120 h, hereof 45 h contact hours (30 h lecture, 15 h tutorial) and 75 h homework and self-studies.

**Recommendation**

Solid mathematical and physical background, basic knowledge of electrodynamics

**Literature**

B.E.A. Saleh, M.C. Teich: Fundamentals of Photonics

G.P. Agrawal: Fiber-optic communication systems

C.-L. Chen: Foundations for guided-wave optics

Katsunari Okamoto: Fundamentals of Optical Waveguides

K. Iizuka: Elements of Photonics

## M

## 7.206 Module: Optimal Control and Estimation [M-ETIT-102310]

**Responsible:** Prof. Dr.-Ing. Sören Hohmann

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-ETIT-104594 | <a href="#">Optimal Control and Estimation</a> | 3 CR | Hohmann |

**Prerequisites**

none

## M

## 7.207 Module: Optimization of Dynamic Systems [M-ETIT-100531]

**Responsible:** Prof. Dr.-Ing. Sören Hohmann

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |                                 |      |         |
|---------------|---------------------------------|------|---------|
| T-ETIT-100685 | Optimization of Dynamic Systems | 5 CR | Hohmann |

### Competence Certificate

The assessment consists of a written exam (120 min) taking place in the recess period.

### Prerequisites

none

### Competence Goal

- The students know as well the mathematical basics as the fundamental methods and algorithms to solve constraint and unconstraint nonlinear static optimization problems.
- They can solve constraint and unconstraint dynamic optimization by using the calculus of variations approach and the Dynamic Programming method.
- Also they are able to transfer dynamic optimization problem to static problems.
- The students know the mathematic relations, the pros and cons and the limits of the particular optimization methods.
- They can transfer problems from other fields of their studies in a convenient optimization problem formulation and they are able to select and implement suitable optimization algorithms for them by using common software tools.

### Content

The module teaches the mathematical basics that are required to solve optimization problems. The first part of the lecture treats methods for solving static optimization problems. The second part of the lecture focuses on solving dynamic optimization problems by using the method of Euler-Lagrange and the Hamilton method as well as the dynamic programming approach.

### Module grade calculation

The module grade is the grade of the written exam.

### Annotation

Will be changed to 6 CR in winter term 25/26.

**Workload**

Each credit point stands for an amount of work of 30h of the student. The amount of work includes

1. presence in lecture/exercises/tutorial(optional) (2+1 SWS: 45h1.5 LP)
2. preparation/postprocessing of lecture/exercises (90h3 LP)
3. preparation/presence in the written exam (15h0.5 LP)

## M

## 7.208 Module: Optoelectronic Measurement Engineering [M-ETIT-100484]

**Responsible:** Dr.-Ing. Klaus Trampert

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-ETIT-100771 | <a href="#">Optoelectronic Measurement Engineering</a> | 3 CR | Trampert |

**Prerequisites**

none

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

Based on 15 courses per semester, each with 1.5 h presence in the lecture, 2.5 h each Before and after, as well as approx. 2 hours of literature reading and self-exercises, the total workload is 90 hours



## M

## 7.209 Module: Organ Support Systems [M-MACH-102702]

**Responsible:** apl. Prof. Dr. Christian Pylatiuk  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |                                       |      |          |
|---------------|---------------------------------------|------|----------|
| T-MACH-105228 | <a href="#">Organ Support Systems</a> | 4 CR | Pylatiuk |

**Competence Certificate**

A performance assessment is held in form of a written examination of 60 minutes.

**Prerequisites**

none

**Competence Goal**

Students have comprehensive knowledge of the functioning of support systems and their components (e.g. sensors, actuators) for different human organs (e.g. heart, kidney, liver, eye, ear, locomotor system). They know the physical basics, the technical solutions and the essential aspects of these medical technology systems and their current limitations. Furthermore, they know bioreactors and other methods of using the body's own cells to support organs (tissue engineering). Furthermore, they have comprehensive knowledge of organ transplantation and its limitations.

**Content**

Hemodialysis, liver dialysis, heart-lung machine, artificial hearts, biomaterials, definition and classification of organ support and organ replacement, hearing prostheses, visual prostheses, exoskeletons, neuroprostheses, endoprostheses, tissue engineering.

**Module grade calculation**

The module grade is the grade of the written exam.

**Workload**

1. Attendance time Lecture:  $15 * 2h = 30h$
2. Pre- and postprocessing time Lecture:  $15 * 3h = 45h$
3. Exam preparation and attendance exam: 45h

Total: 120h = 4 LP

**Recommendation**

The content of module MMACH-105235 complements this lecture.

**Literature**

- Jürgen Werner: Kooperative und autonome Systeme der Medizintechnik: Funktionswiederherstellung und Organersatz. Oldenbourg Verlag.
- Rüdiger Kramme: Medizintechnik: Verfahren - Systeme – Informationsverarbeitung. Springer Verlag.
- E. Wintermantel, Suk-Woo Ha: Medizintechnik. Springer Verlag.

## M

## 7.210 Module: Pattern Recognition (24675) [M-INFO-100825]

**Responsible:** Prof. Dr.-Ing. Jürgen Beyerer

**Organisation:** KIT Department of Informatics

**Part of:** Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )  
 Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |                     |      |                 |
|---------------|---------------------|------|-----------------|
| T-INFO-101362 | Pattern Recognition | 6 CR | Beyerer, Zander |

## M

**7.211 Module: Photonics and Communications Lab [M-ETIT-104485]**

**Responsible:** Prof. Dr.-Ing. Christian Koos  
Prof. Dr.-Ing. Sebastian Randel

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |              |
|---------------|--|------|--------------|
| T-ETIT-109173 | <a href="#">Photonics and Communications Lab</a> | 6 CR | Koos, Randel |

**Prerequisites**

none

## M

## 7.212 Module: Photovoltaics [M-ETIT-100513]

**Responsible:** Prof. Dr.-Ing. Michael Powalla

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |                               |      |         |
|---------------|-------------------------------|------|---------|
| T-ETIT-101939 | <a href="#">Photovoltaics</a> | 6 CR | Powalla |

### Prerequisites

Module "M-ETIT-100524 - Solar Energy" must not have started.

### Modeled Conditions

The following conditions have to be fulfilled:

1. The module [M-ETIT-100524 - Solar Energy](#) must not have been started.

## M

## 7.213 Module: Physical Basics of Laser Technology [M-MACH-107064]

**Responsible:** Dr.-Ing. Johannes Schneider  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |           |
|---------------|---|------|-----------|
| T-MACH-102102 | <a href="#">Physical Basics of Laser Technology</a> | 5 CR | Schneider |

**Competence Certificate**

The assessment consists of an oral exam (ca. 30 min).

**Prerequisites**

none

**Competence Goal**

The student

- can explain the principles of light generation, the conditions for light amplification as well as the basic structure and function of different laser sources.
- can describe the influence of laser, material and process parameters for the most important methods of laser-based materials processing and choose laser sources suitable for specific applications.
- can illustrate the possible applications of laser sources in measurement and medicine technology
- can explain the requirements for safe handling of laser radiation and for the design of safe laser systems.

**Content**

Based on the description of the physical basics about the formation and the properties of laser light the lecture goes through the different types of laser beam sources used in industry these days. The lecture focuses on the usage of lasers especially in materials engineering. Other areas like measurement technology or medical applications are also mentioned.

- physical basics of laser technology
- laser beam sources (solid state, diode, gas, liquid and other lasers)
- beam properties, guiding and shaping
- lasers in materials processing
- lasers in measurement technology
- lasers for medical applications
- safety aspects

The lecture is complemented by a tutorial.

**Module grade calculation**

see individual course

**Workload**

Regular attendance: 33,5 hours

Self-study: 116,5 hours

**Recommendation**

Basic knowledge of physics, chemistry and material science is assumed.

**Learning type**

Lecture + Tutorial

**Literature**

J. Eichler, H.-J. Eichler: Lasers - Basics, Advances and Applications, 2018, Springer

W. T. Silfvast: Laser Fundamentals, 2008, Cambridge University Press

W. M. Steen: Laser Material Processing, 2010, Springer

R. Poprawe, et al.: Tailored Light 1 - High Power Lasers for Production, 2018, Springer

R. Poprawe, et al.: Tailored Light 2 - Laser Applications, 2024, Springer

## M

**7.214 Module: Plasma Sources [M-ETIT-100481]****Responsible:** Dr.-Ing. Rainer Kling**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)**Credits**  
4**Grading scale**  
Grade to a tenth**Recurrence**  
Each winter term**Duration**  
1 term**Language**  
German**Level**  
4**Version**  
1

| Mandatory     |                                |      |                |
|---------------|--------------------------------|------|----------------|
| T-ETIT-100768 | <a href="#">Plasma Sources</a> | 4 CR | Heering, Kling |

**Prerequisites**

none

## M

**7.215 Module: Polymers in MEMS A: Chemistry, Synthesis and Applications [M-MACH-107183]**

**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German/English | 4     | 1       |

**Election notes**

First part of the lecture series Polymers in MEMS with focus on chemical fundamentals. Lecture forms a good basis for Polymers in MEMS-C, Biopolymers

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-MACH-102192 | <a href="#">Polymers in MEMS A: Chemistry, Synthesis and Applications</a> | 4 CR | Worgull |

**Competence Certificate**

Oral examination by arrangement, duration approx. 30 min

**Prerequisites**

none

**Competence Goal**

The aim of the lecture is providing mechanical or chemical engineers, as well as interested students from the life or material sciences the basic knowledge required for understanding what polymers are and how they are made, highlighting their importance for modern MEMS systems with a wide view to applications in everyday life.

After attending the lecture the students will be able:

- ... to understand the physico/chemical basics of organic chemistry in polymer synthesis.
- ... to state the most important polymers and polymer classes and to develop application examples for these.
- ... to state the most important polymers in MEMS.
- ... to understand the most important techniques for rapid prototyping.
- ... to state and to understand the most important resists in MEMS.
- ... to understand the chemical synthesis of polymers.
- ... to correctly estimate the application scope of the individual classes of polymers.



**Content**

We all come in contact with numerous polymeric products in everyday life. From water bottles to packaging to the cover of the iPad, many things are made of polymers. Polymers are also important materials for modern microelectromechanical systems (MEMS) allowing cost effective mass market compatible products, e.g., in the life sciences or diagnostics. But polymers are not just cost-effective replacements for more expensive classical materials in MEMS (such as, e.g., silicon) – some polymers have intrinsic properties that make them ideal materials for sensors, actuators or templates for biology and chemistry in MEMS.

This lecture will introduce the basics of organic chemistry required for understanding what polymers are, how they are manufactured and which mechanisms are responsible for their unique properties. The lecture will highlight (in the context of MEMS but also in a wider scope) where and why polymers are applied with a strong focus on their chemical and physical properties (and on their synthesis).

Some of the topics covered are:

- What is the basic chemistry of polymers? What are monomers, what are macromolecules and how are they formed?
- How are polymers produced on industrial scale – but also on the laboratory scale? Numerous examples of how to make (commonly and lesser known) polymers will be discussed including materials such as Plexiglas.
- Why are polymers so important for biochemistry and tissue engineering?
- How do photoresists work and why do some polymers contract when exposed to light?
- What are high-performance polymers and why do they have such a wide application range, e.g., in implants?
- What polymers fuel the household 3D printing community and what materials do 3D printers such as, e.g., the RepRap work with?
- How does 3D printing and rapid prototyping work and which polymers can be employed for which techniques?
- Why does silicone always smell like vinegar and why is this material so important for modern day microfluidics? How do you build fluid-logic devices using silicone?
- How do shape memory polymers remember their shape?
- What are polymer foams and why are they not only important for heat insulation but also for organic chemistry?
- How do glues work? Why are there two-component glues, what is superglue and how can you make glue from potatoes?

**Module grade calculation**

according to the performance in the oral examination

**Annotation**

Basic knowledge of organic chemistry is an advantage. A basic understanding of microsystems technology and microsystems technology processes is helpful but not necessary.

**Workload**

120h

- lecture: 15 \* 1.5 h (22 h)
- lecture preparation (before and after lecture): 15 \* 2 h (30 h)
- preparation of final exam: approx. 68 h

**Recommendation**

Basic knowledge of organic chemistry and microsystems technology is advantageous, the effort may be somewhat higher

**Learning type**

Online lecture, presentations are available as downloads. Individual additional meetings as required

**Literature**

Literature will be named accordingly in the lecture

**Base for**

Basis for module "Polymers in MEMS-C", Biopolymers

## M

**7.216 Module: Polymers in MEMS B: Physics, Microstructuring and Applications (MIT-Export) [M-MACH-107035]****Responsible:** Dr.-Ing. Matthias Worgull**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology](#)

(Mandatory Electives – General)

[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

**Election notes**

Part of the lecture series Polymers in MEMS. Focus of part B: physical properties of polymers, polymer characterization and polymer processing can be taken independently of the other modules

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-MACH-102191 | <a href="#">Polymers in MEMS B: Physics, Microstructuring and Applications</a> | 4 CR | Worgull |

**Competence Certificate**

Oral examination (approx. 30min)

**Prerequisites**

none

**Competence Goal**

After attending the lecture the students will be able:

- to understand the properties of polymers as a consequence of their morphology.
- to describe the most important structuring techniques and technologies for polymers in MEMS.
- to understand the mathematical basis of the most important physical models for polymers.
- to correctly judge polymer properties and the applicability of the polymers for their industrial processability.
- to understand the basics of process simulation in polymer structuring.
- to state the most important technical thermoplasts in MEMS and to understand their properties.
- to correctly classify the various types of polymers, blends, composite materials.

**Content**

This lecture will introduce the basics of physics and material science required for the understanding of the mechanical behavior seen from the engineers view. Micro and nanostructuring of polymers allows the fabrication of micro parts fulfilling their tasks in mostly invisible different applications. But also the fabrication of polymer parts with functional surfaces inspired from Bionics will be presented in this lesson. The lesson will give further an overview over the polymer based structuring processes and will underline the importance by a number of applications e.g. photonic structures or Lotus-like structures.

**Module grade calculation**

The module grade corresponds to the grade of the examination.

**Annotation**

The language will depend on the participants present. If interested, an optional laboratory tour on polymer processing can also be offered.

**Workload**

120 hours

**Recommendation**

Basics of chemistry and microsystem technology (MST) are beneficial but not required

**Learning type**

The screen presentations are available for download in English and German after registration

**Literature**

Bibliography available on request in the lecture

**Base for**

M-MACH-107034 – Practical Course Polymers in MEMS

## M

**7.217 Module: Polymers in MEMS C: Biopolymers and Bioplastics [M-MACH-107085]****Responsible:** Dr.-Ing. Matthias Worgull**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German/English | 4     | 1       |

**Election notes**

Recommendation: Basic knowledge of polymers

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-MACH-102200 | <a href="#">Polymers in MEMS C: Biopolymers and Bioplastics</a> | 4 CR | Worgull |

**Competence Certificate**

Oral exam: approx. 30min

**Prerequisites**

none

**Competence Goal**

Students are given an overview of so-called bioplastics - their resources, production, degradability and applications.

The aim of the lecture is to provide expertise in the field of so-called bioplastics, the use of raw materials, the specific sustainability and the substitution potential compared to conventional plastics. To this end, the individual plastics are presented in detail, from synthesis and processing to application. A further focus is on natural biopolymers from DNA, which can also be used as building blocks. A consideration of bioplastics also includes an analysis of the environmental impact of plastics and the contribution of bioplastics to this scenario.

**Content**

This lecture describes the most important categories of these so-called biopolymers. A distinction is made between polymers that produce chemically analogous raw materials by natural means (e.g. by fermentation), how these starting materials are chemically processed and polymerized and how the polymers obtained from them are technologically processed. Numerous examples from microtechnology as well as from everyday life are highlighted.

Some of the questions addressed are:

- How can bioplastics influence the environmental balance of plastics
- Are bioplastics sustainable?
- What does biodegradable mean?
- What are biopolyurethanes and how can they be made from castor oil?
- What exactly are "natural adhesives" and how do they differ from chemical adhesives?
- How are car tires made from natural rubber?
- What are the two most important polymers for life on earth?
- Can you make polymers from potatoes?
- Can wood be injection molded?
- How do you make buttons from milk?
- Can you listen to music with biopolymers?
- Where and how can biopolymers be used for tissue engineering, for example?  
How do LEGO bricks made from DNA work?

**Module grade calculation**

corresponds to the examination grade

**Annotation**

The lecture is intended to demonstrate the potential and limitations of bioplastics. However, this requires an understanding of organic chemistry and the structure of polymers. The basic knowledge is taught in Polymers in MEMS A or B

**Workload**

120h

**Recommendation**

Attendance of the lectures “Polymers in MEMS A” or “Polymers in MEMS B”, but not a prerequisite

**Learning type**

The presentations are made available to the students via download. Exhibits will be shown where possible.

The lecture will be held in German or English, depending on the participants. The presentation is held in English.

**Literature**

Links to literature are given in the lessons

## M

## 7.218 Module: Power Electronic Systems in Energy Technology [M-ETIT-106067]

**Responsible:** Prof. Dr.-Ing. Marc Hiller

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-ETIT-112286 | <a href="#">Power Electronic Systems in Energy Technology</a> | 6 CR | Hiller |

**Prerequisites**

none

## M

**7.219 Module: Power Electronics [M-ETIT-104567]**

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Marc Hiller  |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Energy Technology (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 6              | Grade to a tenth     | Each summer term  | 1 term          | English         | 4            | 6              |

|                  |                   |      |        |
|------------------|-------------------|------|--------|
| <b>Mandatory</b> |                   |      |        |
| T-ETIT-109360    | Power Electronics | 6 CR | Hiller |

**Competence Certificate**

The examination takes place in form of a written examination lasting 120 minutes.

**Prerequisites**

None

**Competence Goal**

Students will be familiar with state-of-the-art power semiconductors including their application related features. Furthermore students will be familiar with the circuit topologies for DC/DC and DC/AC power conversion. They know the associated modulation and control methods and characteristics. They are able to analyze the circuit topologies with regard to harmonics and power losses. This also includes the thermal design of power electronic circuits. In addition, they are able to select and combine suitable circuits for given electrical energy conversion requirements.

**Content**

In the lecture, power electronic circuits for DC/DC and DC/AC power conversion using IGBTs and MOSFETs are presented and analyzed. First, the basic properties of self-commutated circuits under idealized conditions are elaborated using the DC/DC converter as an example. Then, self-commutated power converters for three-phase applications are presented and analyzed with respect to modulation and their AC and DC terminal behavior. Based on the real power semiconductor behavior in on- and off-state the device losses are calculated. Furthermore the thermal design of power converters is explained using thermal equivalent circuits of power devices and cooling equipment. The voltage and current stress on the power semiconductors in switching operation is explained as well as protective snubber circuits allowing a reliable operation within the safe operating area of the devices.

In detail, the following topics are treated:

- Power Semiconductors
- Commutation principles
- DC/DC converters
- Self-commutated 1ph and 3ph DC/AC inverters
- Modulation methods (Fundamental frequency modulation, Pulse width modulation with 3rd harmonic injection, Space vector modulation)
- Multilevel inverters
- Switching behavior in hard and soft switching applications
- Loss calculation
- Thermal equivalent circuits, thermal design
- Snubber circuits.

The lecturer reserves the right to adapt the contents of the lecture to current needs without prior notice.

**Module grade calculation**

The module grade is the grade of the written exam.

**Workload**

14x lecture and 14x exercise à 2 h = 56 h  
14x wrap-up of the lecture à 1 h = 14 h  
14x preparation of the exercise à 2 h = 28 h  
Preparation for the exam = 75 h  
Examination time = 2 h  
Total = approx. 175 h (corresponds to 6 LP)



## M

**7.220 Module: Power Electronics for Photovoltaics and Wind Energy [M-ETIT-102261]****Responsible:** Prof. Dr.-Ing. Marc Hiller**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#) (Usage until 9/30/2025)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#) (Usage until 9/30/2025)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German/English | 4     | 2       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-ETIT-104569 | <a href="#">Power Electronics for Photovoltaics and Wind Energy</a> | 3 CR | Hiller |

**Competence Certificate**

Success control takes place in the form of an overall oral examination (20 minutes) on the selected courses, which together fulfill the minimum LP requirement.

**Prerequisites**

none

**Competence Goal**

Students will be familiar with the main renewable energy generation systems. They will be able to assess typical inverter circuits and consider their application aspects including grid connections in design, construction and operation. They will be able to estimate the essential system properties in rough calculations.

**Content**

The lecture explains all the possibilities of regenerative energy generation that are currently being used on a large scale. These include

- wind power
- hydropower
- solar thermal energy
- geothermal energy
- photovoltaics

It also looks at how these systems can be integrated into existing grids and how stand-alone grids can be set up. An overview of energy storage systems is also provided.

This is followed by a detailed look at photovoltaic energy generation.

This topic includes

- PV DC voltage systems
- charge controllers
- MPP trackers
- PV grid couplings
- Inverter circuits
- Grid power control / reactive power control
- Characteristic curves of solar cells
- System efficiencies

are covered and explained in detail.

The lecturer reserves the right to deviate from the content of the current lecture without deviate from the content given here without special notice.

**Module grade calculation**

The module grade is the grade of the oral examination.

**Annotation**

English videos are available for English-speaking students.

- Last offer in SoSe25 -

**Workload**

7x V à 3 h = 21 h

Exam preparation = 60 h

Total approx. 81 h (corresponds to 3 LP)

**Recommendation**

Module Power Electronics

## M

## 7.221 Module: Power System Protection and Automation [M-ETIT-106506]

**Responsible:** Prof. Dr.-Ing. Thomas Leibfried

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |           |
|---------------|--|------|-----------|
| T-ETIT-113164 | <a href="#">Power System Protection and Automation</a> | 3 CR | Leibfried |

**Prerequisites**

none

**M****7.222 Module: Power Systems and Economy [M-ETIT-100413]****Responsible:** Dr.-Ing. Bernd Hoferer**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-ETIT-100725 | <a href="#">Power Systems and Economy</a> | 3 CR | Hoferer |

**Prerequisites**

none

## M

**7.223 Module: Power Tool Design [M-MACH-107144]****Responsible:** Prof. Dr.-Ing. Sven Matthiesen**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |            |
|---------------|---|------|------------|
| T-MACH-105229 | <a href="#">Appliance and Power Tool Design</a> | 4 CR | Matthiesen |

**Competence Certificate**

See individual course

**Prerequisites**

The participation in "Power tool design" requires the concurrent project work.

Due to organizational reasons, the number of participants is limited. At the beginning of august, a registration form will be available at the IPEK website. In the case of too many applicants, a selection process will be taking place. An early application is advantageous.

**Competence Goal**

The students...

- are able to analyze complex and sometimes contradictory problems in the interaction between user, device and application and develop innovative solutions based on this with a clear focus on customer benefits.
- are able to name, identify and explain strategies and methodical procedures for the development of mechatronic devices and apply them to new challenges.
- are able to recognize and evaluate the effects of specific boundary conditions on the development task and to interpret and assess their consequences even in unfamiliar contexts.
- are able to understand and reflect on key success factors of product development in interdisciplinary development teams and apply this knowledge to practical examples and new problems in the areas of customer, company and market.

**Content**

The lecture "Device Design" offers a practice-oriented insight into the development of technical devices using real industrial examples. The focus is on the product development process of mechatronic systems, starting with the analysis of existing products and the identification of potential. Students learn to generate innovative ideas and implement them in prototypes. Particular attention is paid to hand-held devices, which serve as interdisciplinary examples and illustrate engineering work. The lecture comprises theoretical principles, practical exercises and a compulsory project in which the interaction of analysis and synthesis is deepened in small groups.

**Module grade calculation**

The module grade corresponds to the grade from the individual course

**Annotation**

None

**Workload**

Attendance: 30h

Self-study: 90h

**Recommendation**

None

**Learning type**

Lecture

**Literature**

None

**Base for**

None

## M

## 7.224 Module: Power Tool Design Project Work [M-MACH-107145]

**Responsible:** Prof. Dr.-Ing. Sven Matthiesen  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale | Recurrence       | Duration | Language | Level | Version |
|---------|---------------|------------------|----------|----------|-------|---------|
| 8       | pass/fail     | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |            |
|---------------|--|------|------------|
| T-MACH-110767 | <a href="#">Appliance and Power Tool Design Project Work</a> | 8 CR | Matthiesen |

**Competence Certificate**

See partial performance

**Prerequisites**

The participation in the project work requires the participation in "Appliance and power tool design". Due to organizational reasons, the number of participants is limited. At the beginning of august, a registration form will be available at the IPEK website. In the case of too many applicants, a selection process will be taking place. An early application is advantageous

**Competence Goal**

The students...

- are able to analyze complex and sometimes contradictory problems in the interaction between user, device and application and develop innovative solutions based on this with a clear focus on customer benefits.
- are able to name, identify and explain strategies and methodical procedures for the development of mechatronic devices and apply them to new challenges.
- are able to recognize and evaluate the effects of specific boundary conditions on the development task and to interpret and assess their consequences even in unfamiliar contexts.
- are able to understand and reflect on key success factors of product development in interdisciplinary development teams and apply this knowledge to practical examples and new problems in the areas of customer, company and market.

**Content**

The "Power Tool Design" project enables students to apply the knowledge and skills they have acquired in practice as part of a real product development project. Working in small groups, students put the knowledge they have acquired in the lecture into practice by analyzing and further developing various hand-held devices. The project work goes through typical phases of the product development process, starting with the analysis of existing devices and the identification of potential improvements. Based on this, innovative ideas are generated and implemented in prototypes. The focus is on the interplay between analysis and synthesis, which gives students a practical insight into the challenges of device design.

**Module grade calculation**

The module grade corresponds to the grade from the partial performance

**Annotation**

None

**Workload**

Attendance: 60h

Self-study: 180h

**Recommendation**

None

**Learning type**

Project work

**Literature**

None

**Base for**

None

## M

**7.225 Module: Practical Aspects of Electrical Drives [M-ETIT-100394]**

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr. Martin Doppelbauer  |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Energy Technology (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 4              | Grade to a tenth     | Each winter term  | 1 term          | German          | 4            | 2              |

| Mandatory     |  |      |             |
|---------------|--|------|-------------|
| T-ETIT-100711 | Practical Aspects of Electrical Drives | 4 CR | Doppelbauer |

**Competence Certificate**

Success is assessed in a written examination lasting 120 minutes.

**Prerequisites**

none

**Competence Goal**

Students understand the function of all components of modern electrical drive systems. They have detailed knowledge of the basic electrical machine types and know the function and physical behavior of loads and other drive components. Students will be able to design electrical drive systems for an application-specific use, taking into account all boundary conditions, and calculate their mechanical and electrical behavior.

**Content**

The lecture is divided into the following areas

- Drive systems
- electric motors
- Transmission elements
- Drive and load
- Starting, braking, positioning
- Thermal and protection
- Variable speed drives
- Electromagnetic compatibility
- Small drives
- Noise
- Drives with limited movement

**Module grade calculation**

The module grade is the grade of the written examination.

**Annotation**

**Shift from SoSe to WiSe, does not take place in WiSe24/25 and SoSe25.**

**Workload**

14x lecture + 7x exercises of 1.5 h each = 31.5 h

14x post-processing of lectures à 1 h = 14 h

6x preparation of exercises à 2 h = 12 h

Preparation for the exam = 50 h

Total = 107.5 h (corresponds to 4 CP)



**Recommendation**

To understand the module, basic knowledge in the field of electrical machines is recommended (acquired, for example, by attending the modules "Electrical Machines and Power Electronics")

## M

## 7.226 Module: Practical Course Polymers in MEMS [M-MACH-107034]

**Responsible:** Dr.-Ing. Matthias Worgull  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale | Recurrence       | Duration | Language       | Level | Version |
|---------|---------------|------------------|----------|----------------|-------|---------|
| 2       | pass/fail     | Each summer term | 1 term   | German/English | 4     | 2       |

**Election notes**

The practical course focuses on polymer processing, therefore it is necessary to attend the module "Polymers in MEMS B".

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-MACH-105556 | <a href="#">Practical Course Polymers in MEMS</a> | 2 CR | Worgull |

**Competence Certificate**

The practical course will close with an oral examination. There will be only passed and failed results, no grades.

**Prerequisites**

MACH-107035 must be started

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The module [M-MACH-107035 - Polymers in MEMS B: Physics, Microstructuring and Applications](#) must have been started.

**Competence Goal**

Students gain in-depth insights into plastics processing with a focus on microstructures and microstructured surfaces. The aims of the practical course are

- carrying out a necessary design analysis and selecting a suitable processing method
- the selection of suitable process parameters based on the desired polymer material
- setting up a molding machine (hot embossing)
- the analysis and measurement of a molded component

**Content**

The practical course provides detailed insights into the molding of plastic components with details in the micro range. To this end, students will carry out practical experiments on nanoimprint systems. In addition, the topic of micro injection molding will be demonstrated and explained in detail.

**Module grade calculation**

ungraded

**Annotation**

The practical course will only be held if there is a sufficient number of registrations.

**Workload**

60 hours

**Learning type**

Practical course

**Literature**

Literature on polymers in MEMS-B

## M

**7.227 Module: Practical Course: Autonomous Driving [M-MACH-107052]**

**Responsible:** Dr.-Ing. Martin Gießler  
Kevin Simon

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale | Recurrence       | Duration | Language | Level | Version |
|---------|---------------|------------------|----------|----------|-------|---------|
| 6       | pass/fail     | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |               |
|---------------|--|------|---------------|
| T-MACH-113713 | <a href="#">Practical Course: Autonomous Driving</a> | 6 CR | Frey, Gießler |

**Competence Certificate**

To pass the course it is necessary to successfully complete the colloquia, the homework and the final demonstration of the driving task.

**Prerequisites**

none

**Competence Goal**

The main objective of the event is the practical implementation of the pipeline required for automated/autonomous driving functions with a real test vehicle. This includes recording the environment using various sensors, processing the recorded sensor data (perception), planning driving manoeuvres and the final execution of the manoeuvre by the actuators.

**Content**

- Sensor data acquisition: Setup and data recording of the sensors on the test vehicle
- Perception: data annotation, segmentation of sensor data, object recognition
- Manoeuvre planning: path and trajectory planning, behaviour generation, etc.
- Manoeuvre execution: vehicle control, implementation of the driving manoeuvre in the real test vehicle using actuators

**Module grade calculation**

see individual course

**Annotation**

Limited number of participants with selection procedure, in German language. Please send the application at the end of the previous semester

**Workload**

120h

(for details see individual course)

**M****7.228 Module: Practical Course: Machine Learning and Intelligent Systems [M-INFO-105958]****Responsible:** Prof. Dr.-Ing. Uwe Hanebeck**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Internship/Lab Course \)](#)[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Internship/Lab Course \)](#)[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 8       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |                  |
|---------------|--|------|------------------|
| T-INFO-112104 | <a href="#">Practical Course: Machine Learning and Intelligent Systems</a> | 8 CR | Fennel, Hanebeck |

## M

## 7.229 Module: Practical Course: Smart Energy System [M-INFO-105955]

**Responsible:** Prof. Dr. Veit Hagenmeyer

**Organisation:** KIT Department of Informatics

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |           |
|---------------|---|------|-----------|
| T-INFO-112030 | <a href="#">Practical Course: Smart Energy System</a> | 6 CR | Waczowicz |

### Competence Certificate

See partial achievements (Teilleistung)

### Prerequisites

See partial achievements (Teilleistung)

### Competence Goal

After successfully completing the course, students will be able to

- be able to explain the structure and objectives of a smart grid using the Energy Lab 2.0 and the Smart Energy System Simulation and Control Centre (SEnSSiCC),
- be able to name and categorise current research issues in the field of innovative, application-oriented information, automation and system technology for sustainable energy systems,
- analyse a problem from the current research questions of SEnSSiCC as part of a project and develop a strategy for a solution together in a team and
- be able to check, analyse and evaluate the feasibility of results in a laboratory.

### Content

As part of the preparation for the internship, project topics are derived from the current research questions of the Smart Energy System Simulation and Control Centre of the Energy Lab 2.0 (<https://www.iai.kit.edu/RPE.php>). The topics are made available to the participating students in advance of the internship as a list, on the basis of which the students can express their preferences for the respective topics. Based on their stated preferences, the students are assigned to the respective project topics.

The two-week internship begins with a joint kick-off event, which includes an introduction and tour of the Energy Lab 2.0 and the SEnSSiCC as well as a brief presentation of all project topics. Students are provided with current scientific papers on their research topic. During the two-week internship, the groups of students work on their project topics under the supervision of the respective scientists. The students use a laboratory set-up to test their concepts and solutions. Particularly promising approaches can be tested on the real system under the supervision of the scientists. The block course ends with a joint final event at which the students present their solutions and work results.

After the internship, the students follow up the project work by preparing a report on the project topic they have worked on, categorising the work results and reflecting on the work process.

Working in a team is another important aspect of all project topics.

The work placement consists of the following sections:

- Familiarisation with the topic
- Selection of a suitable project topic in consultation with the supervising scientists
- Practical realisation of the project topic
- Presentation of the results (colloquium, research report)

### Workload

6 credit points corresponds to approx. 180 working hours, of which

- Attendance time / meetings in large and small groups: 10h
- Select and carry out project work: 140h
- Writing a research report and preparing a presentation: 30 hours

### Recommendation

- Knowledge of the fundamentals of energy informatics is a prerequisite.
- Knowledge of the fundamentals of electrical engineering and energy technology is required.
- Knowledge of the basics of mechatronics, data analysis and signal processing is helpful.
- Knowledge of power systems or power electronics is helpful.

**M****7.230 Module: Practical Course: Software Development and Application of  
Mobile, Bio-Inspired Robots [M-MACH-106904]****Responsible:** Prof. Dr.-Ing. Arne Rönnau**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Internship/Lab Course \)](#)[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Internship/Lab Course \)](#)[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-113854 | <a href="#">Practical Course: Software Development and Application of Mobile, Bio-Inspired Robots</a> | 6 CR | Rönnau |

**Competence Certificate**

See partial achievement

**Prerequisites**

None

**Competence Goal**

Students are able to understand biologically inspired mobile robots and extend their software.

**Content**

This module teaches students how to work with and expand biologically inspired mobile robotics. The topics covered include control engineering, computer vision, 3D mapping, navigation and human-machine interaction.

Students work in groups and produce a joint final report and presentation.

**Workload**

180h

- 30h weekly regular meeting

- 120h preparation and follow-up time

- 30h Presentation and report preparation

**Recommendation**

See partial achievement

## M

## 7.231 Module: Practical Machine Learning [M-ETIT-106673]

**Responsible:** Prof. Dr.-Ing. Michael Heizmann

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-ETIT-113426 | <a href="#">Practical Machine Learning</a> | 6 CR | Heizmann |

#### Competence Certificate

Success is assessed by the submission of the scientific essay and the presentation of the team project lasting approx. 30 minutes.

#### Prerequisites

none

#### Competence Goal

- After completing the module, students have in-depth knowledge in the field of machine learning.
- They have in-depth knowledge and an overview of various algorithms and methods in the field of machine learning.
- Students are able to describe different concepts and methods of machine learning and recognize connections between different algorithms.
- They are able to communicate with specialists in related disciplines in the field of machine learning and artificial intelligence and to formulate and evaluate solution approaches for tasks in this area.
- Students will gain practical experience in the field of machine learning through the semester-long team project. In particular, students will benefit from mutual feedback on their theoretical work at the end of the semester.

### Content

Remarkable progress has been made in the field of artificial intelligence (AI) in recent years. Machine learning (ML) is a sub-discipline of AI that attempts to develop techniques that enable computers to learn from data. The goal of ML methods is to reliably abstract the underlying model for specific tasks.

This lecture covers the theoretical foundations as well as the basic concepts and techniques of machine learning, with a focus on problem solving and practical application. The course offers the opportunity to explore various ML algorithms and their applications in different areas, including computer vision, natural language processing and data mining.

During the course, you will have the opportunity to work on various application tasks and a group project in which you will apply the concepts you have learned to real-world data sets. You will learn how to use common libraries and tools for ML such as Scikit-Learn, TensorFlow and Keras and apply them to real-world datasets. You will also learn how to evaluate the performance of your models and interpret their results.

The lecture style will be a mix of theory and practical applications, with an emphasis on problem solving and hands-on experimentation. The theoretical part of the lecture will be offered as a block course at the beginning of the semester (early/mid April). Students then have the opportunity to work on a problem from the field of

ML alone or in small groups during the semester and present their results in the form of a scientific essay.

The quality assurance of the essay is carried out through a mutual peer review process in which students benefit from mutual feedback both from a technical point of view and with regard to the presentation of content.

The module covers the fundamentals and concepts of machine learning. Topics covered include the following:

- Introduction to machine learning and its applications.
- Data pre-processing and feature engineering techniques.
- Supervised and unsupervised learning algorithms.
- Deep learning techniques such as Convolutional Neural Networks and Recurrent Neural Networks.
- Transfer learning and Tiny ML.
- Probabilistic ML.
- Evaluation metrics for ML models.
- Hyperparameter tuning and model selection techniques.
- Interpreting the results of ML models.
- ... other interesting topics.

### Module grade calculation

The module grade results from the team project accompanying the semester and the presentation of the team project. The overall impression is assessed. Further details will be provided at the beginning of the course.

### Workload

- Attendance of the lectures: approx. 21 hours
- Preparation and follow-up of the lecture: approx. 42 hours
- Team project during the semester: approx. 60 hours
- Peer review of the scientific essays  
and presentation of the team project: approx. 47 hours

Total: approx. 170 hours (6 CP)

### Recommendation

Basic knowledge of mathematics and linear algebra (matrices, vectors, etc.) as well as basic knowledge of Python.

### Learning type

Block lecture (2 SWS) and practical part (by arrangement within the framework of 2 SWS)



**M****7.232 Module: Practical Project Robotics and Automation I (Software) [M-INFO-102224]**

**Responsible:** Prof. Dr.-Ing. Björn Hein  
Prof. Dr.-Ing. Thomas Längle

**Organisation:** KIT Department of Informatics

**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |              |
|---------------|--|------|--------------|
| T-INFO-104545 | <a href="#">Practical Project Robotics and Automation I (Software)</a> | 6 CR | Hein, Längle |

**M****7.233 Module: Practical Project Robotics and Automation II (Hardware) [M-INFO-102230]**

**Responsible:** Prof. Dr.-Ing. Björn Hein  
Prof. Dr.-Ing. Thomas Längle

**Organisation:** KIT Department of Informatics

**Part of:** [Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |              |
|---------------|---|------|--------------|
| T-INFO-104552 | <a href="#">Practical Project Robotics and Automation II (Hardware)</a> | 6 CR | Hein, Längle |

## M

## 7.234 Module: Practical Tools for Control Engineers [M-ETIT-106780]

**Responsible:** Dr.-Ing. Balint Varga  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives\)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-113628 | <a href="#">Practical Tools for Control Engineers</a> | 4 CR | Varga |

**Competence Certificate**

The examination takes place in form of other types of examination. It consists of an oral overall examination in the amount of 25 minutes and a homework programming task. The examination includes questions from the lecture slides and the presentation of the homework assignment. The homework must be submitted two weeks before of the oral exam. The overall impression is evaluated.

**Prerequisites**

none

**Competence Goal**

- The students will be able to analyze, structure and formally describe problems in the field of practical control engineering.
- The students are able to use the necessary tools for software projects with control engineering focus.
- The students can apply the methods
  - Modular software development for control engineering problems
  - Model Predictive Controller for practical engineering problems
  - Inevitable software engineering tools to able to develop control system

**Content**

- Practical examples from the control engineering problems and modelling tool
  - Robotics examples
  - Human-machine interaction
  - Automotive
- Control solution concepts for these practical problems
- Software development tool

**Module grade calculation**

The module grade results of the assessment of the oral exam and of the homework programming task. Details will be given during the lecture.

**Workload**

The workload includes 2 SWS:

- attendance in lectures and exercises: 15\*2 h = 30 h
- preparation / follow-up: 15\*2,5 h = 37,5 h
- preparation of the homework assignment: 22,5 h
- preparation of and attendance in examination: 30 h

**Sum: 120 h = 4 CR**

**Recommendation**

The contents of the modules "Optimization of Dynamic Systems (ODS)" and "Regelung linearer Mehrgrößensysteme (RLM)" are helpful for the lecture.

## M

**7.235 Module: Practical Training in Basics of Microsystem Technology [M-MACH-105479]****Responsible:** Dr. Arndt Last**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |      |
|---------------|--|------|------|
| T-MACH-102164 | <a href="#">Practical Training in Basics of Microsystem Technology</a> | 4 CR | Last |

**Competence Certificate**

Written exam, 60 min.

**Prerequisites**

None

**Competence Goal**

Insight into the real, practical work at the Institute of Microstructure Technology.

**Content**

In the practical training includes nine experiments:

1. Hot embossing of plastics micro structures
2. Micro electroforming
3. X-ray optics
4. UV-lithography
5. Fluidic polymer components by example of a microfluidic mixer
6. Additive prototyping of microstructures
7. Introduction to SAW biosensors
8. Light diffraction at photomasks
9. Atomic force microscopy
10. Centrifugal microfluidics

Each student takes part in only five experiments.

The experiments are carried out at real workstations at the IMT and coached by IMT-staff.

**Annotation**

The internship takes place in the laboratories of the IMT at the CN. Meeting place: Building 307, room 322.

Participation requests to Mrs. Novotny, [marie.nowotny@kit.edu](mailto:marie.nowotny@kit.edu)**Workload**

regular attendance: 20 hours

self-study: 100 hours, Preparation of the five experiments

**Recommendation**

Attend at least one of the lectures Micro System Technology I or II.

Read the practical course documents provided as pdf-file!

**Learning type**

Lab, Self-study of the internship documents and guided experiments during the course.

**Literature**Madou, M. (2003). *Fundamentals of Microfabrication*. CRC. ISBN 978-0849308260.

Practical course documents provided as pdf-file.

## M

## 7.236 Module: Principles of Whole Vehicle Engineering I [M-MACH-105289]

**Responsible:** Prof.Dipl.-Ing. Rolf Frech  
Dr.-Ing. Martin Gießler  
Dr.-Ing. Hans-Joachim Unrau

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 2       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-105162 | <a href="#">Fundamentals of Automobile Development I</a> | 2 CR | Harrer |

### Competence Certificate

Written exam, duration approximately 90 minutes.

Auxiliary means: none

### Competence Goal

The students have an overview of the entire development process of a passenger car. In addition to the chronological sequence of passenger car development, they also know the national and international legal requirements. They have knowledge of the conflict of objectives between aerodynamics, thermal management and design. They will be able to assess conflicting goals in the area of passenger car development and work out possible solutions.

### Content

1. Process of automobile development
2. Conceptual dimensioning and design of an automobile
3. Laws and regulations – National and international boundary conditions
4. Aero dynamical dimensioning and design of an automobile I
5. Aero dynamical dimensioning and design of an automobile II
6. Thermo-management in the conflict of objectives between styling, aerodynamic and packaging guidelines I
7. Thermo-management in the conflict of objectives between styling, aerodynamic and packaging guidelines

### Workload

The total work load for this module is about 60 Hours (2 Credits). The partition of the work load is carried out according to the credit points of the courses of the module. The work load for courses with 2 credit points is about 60 hours.

### Learning type

Lecture

## M

## 7.237 Module: Principles of Whole Vehicle Engineering II [M-MACH-105290]

**Responsible:** Prof.Dipl.-Ing. Rolf Frech  
Dr.-Ing. Hans-Joachim Unrau

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 2       | Grade to a tenth | Each summer term | 1 term   | German/English | 4     | 2       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-105163 | <a href="#">Fundamentals of Automobile Development II</a> | 2 CR | Harrer |

### Competence Certificate

Written exam, duration: approximately 90 minutes.

Auxiliary means: none

### Competence Goal

Students are familiar with the selection of suitable materials and with various manufacturing techniques. They have an overview of the acoustics of the vehicle. They are familiar with both the aspects of acoustics in the interior of the vehicle and the aspects of exterior noise. They are familiar with testing the vehicle and assessing the overall vehicle characteristics. They are able to participate competently in the development process of the entire vehicle.

### Content

1. Application-oriented material and production technology I
2. Application-oriented material and production technology II
3. Overall vehicle acoustics in the automobile development
4. Drive train acoustics in the automobile development
5. Testing of the complete vehicle
6. Properties of the complete automobile

### Workload

The total work load for this module is about 60 Hours (2 Credits). The partition of the work load is carried out according to the credit points of the courses of the module. The work load for courses with 2 credit points is about 60 hours.

### Learning type

Lecture

## M

## 7.238 Module: Probabilistic Measurement and Estimation [M-MACH-107087]

**Responsible:** Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )  
 Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-MACH-113873 | Probabilistic Measurement and Estimation | 4 CR | Stiller |

### Competence Certificate

written exam

60 min.

### Prerequisites

none

### Competence Goal

The capabilities of modern sensor technology pave the way for novel applications in engineering. Especially digital measurement techniques may be used even in very complex environments and this has a strong impact on technological progress. Stochastic models of measurement processes form the basis for meaningful information processing and provide a valuable tool for engineering. This interdisciplinary lecture addresses students in mechanical engineering and related subjects. The lecture gives an overview of digital technology and stochastics. These areas form the basics of estimation methods that can be embedded elegantly in the theory of state observers. Applications in signal processing for modern environmental perception (video, Lidar, Radar) illustrate the discussed subjects.

### Content

1. Amplifiers
2. Digital technology
3. Stochastic modeling for measurement applications
4. Estimation
5. Kalman Filter
6. Environmental perception

### Workload

In total 120h:

Attendance time: 20 h

Self-study: 100 h

## M

**7.239 Module: Product- and Production-Concepts for modern Automobiles [M-MACH-105346]**

**Responsible:** Dr. Stefan Kienzle  
Dr. Dieter Steegmüller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |                      |
|---------------|---|------|----------------------|
| T-MACH-110318 | <a href="#">Product- and Production-Concepts for Modern Automobiles</a> | 4 CR | Kienzle, Steegmüller |

**Competence Certificate**

Oral Exam (20 min)

**Prerequisites**

None

**Competence Goal**

The students ...

- are able to name the presented general conditions of vehicle development and are able to discuss their influences on the final product using practical examples.
- are able to name the various lightweight approaches and identify possible areas of application.
- are able to identify the different production processes for manufacturing lightweight structures and explain their functions.
- are able to perform a process selection based on the methods and their characteristics.

**Content**

The module illuminates the practical challenges of modern automotive engineering. As former leaders of the automotive industry, the lecturers refer to current aspects of automotive product development and production.

The aim is to provide students with an overview of technological trends in the automotive industry. In this context, the course also focuses on changes in requirements due to new vehicle concepts, which may be caused by increased demands for individualisation, digitisation and sustainability. The challenges that arise in this context will be examined from both a production technology and product development perspective and will be illustrated with practical examples thanks to the many years of industrial experience of both lecturers.

The topics covered are:

- General conditions for vehicle and body development
- Integration of new drive technologies
- Functional requirements (crash safety etc.), also for electric vehicles
- Development Process at the Interface Product & Production, CAE/Simulation
- Energy storage and supply infrastructure
- Aluminium and lightweight steel construction
- FRP and hybrid parts
- Battery, fuel cell and electric motor production
- Joining technology in modern car bodies
- Modern factories and production processes, Industry 4.0.

**Workload**

regular attendance: 25 hours

self-study: 95 hours

**Learning type**

Lecture



## M

**7.240 Module: Product Development – Methods of Product Engineering [M-MACH-102718]**

**Responsible:** Prof. Dr.-Ing. Albert Albers  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Mandatory Electives – Methodical )  
 Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems (Additive Electives )  
 Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language       | Level | Version |
|---------|------------------|------------------|----------|----------------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German/English | 4     | 3       |

| Mandatory     |   |      |                              |
|---------------|---|------|------------------------------|
| T-MACH-109192 | Methods and Processes of PGE - Product Generation Engineering | 6 CR | Albers, Burkardt, Matthiesen |

**Competence Certificate**  
 See course ("Teilleistung")

**Prerequisites**  
 None

**Competence Goal**  
 The students are able to ...

- classify product development in companies and differentiate between different types of product development.
- name the relevant influencing factors of a market for product development.
- name, compare and use the central methods and process models of product development within moderate complex technical systems.
- explain problem solving techniques and associated development methods.
- explain product profiles and to differentiate and choose suitable creative techniques of solution/idea generation finding on this basis.
- use design guidelines to create simple technical systems and to explain these guidelines.
- name and compare quality assurance methods; to choose and use suitable methods for particular applications.
- explain the different methods of design of experiment.
- explain the costs in development process.

**Content**

Basics of Product Development: Basic Terms, Classification of the Product

Development into the industrial environment, generation of costs / responsibility for costs

Concept Development: List of demands / Abstraction of the Problem Definition / Creativity Techniques / Evaluation and selection of solutions

Drafting : Prevailing basic rules of Design / Design Principles as a problem oriented accessory

Rationalization within the Product Development: Basics of Development

Management/ Simultaneous Engineering and Integrated Product Development/Development of Product Lines and Modular Construction Systems

Quality Assurance in early Development Phases : Methods of Quality Assurance in an overview/QFD/FMEA

**Workload**

1. Time of presence lecture:  $15 * 3h = 45 h$

2. Prepare/follow-up lecture:  $15 * 4,5 h = 67,5 h$

3. Time of presence exercise:  $4 * 1,5h = 6 h$

4. Prepare/follow-up exercise:  $4 * 3 h = 12 h$

5. Exam preparation and time of presence: 49,5 h

Total: 180 h = 6 LP

**Learning type**

Lecture

Tutorial

**Literature**

Lecture documents

Pahl, Beitz: Konstruktionslehre, Springer-Verlag 1997

Hering, Triemel, Blank: Qualitätssicherung für Ingenieure; VDI-Verlag, 1993

## M

## 7.241 Module: Production Techniques Laboratory [M-MACH-102711]

**Responsible:** Prof. Dr.-Ing. Barbara Deml  
 Prof. Dr.-Ing. Kai Furmans  
 Prof. Dr.-Ing. Jivka Ovtcharova  
 Prof. Dr.-Ing. Volker Schulze

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale | Recurrence       | Duration | Language | Level | Version |
|---------|---------------|------------------|----------|----------|-------|---------|
| 4       | pass/fail     | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |                                      |
|---------------|--|------|--------------------------------------|
| T-MACH-105346 | <a href="#">Production Techniques Laboratory</a> | 4 CR | Deml, Fleischer, Furmans, Ovtcharova |

#### Competence Certificate

A performance assessment (non-graded) is obligatory and can be oral, a written exam, or of another kind.

#### Prerequisites

None

#### Competence Goal

The students acquire in the lab profound knowledge about the scientific theories, principles and methods of Production Engineering. Afterwards they are able to evaluate and design complex production systems according to problems of manufacturing and process technologies, materials handling, handling techniques, information engineering as well as production organisation and management.

After completion this lab, the students are able

- to analyse and solve planning and layout problems of the discussed fields,
- to evaluate and configure the quality and efficiency of production, processes and products,
- to plan, control and evaluate the production of a production enterprise,
- to configure and evaluate the IT architecture of a production enterprise,
- to design and evaluate appropriate techniques for conveying, handling and picking within a production system,
- to design and evaluate the part production and the assembly by considering the work processes and the work places.

#### Content

The production technique laboratory (PTL) is a collaboration of the institutes wbk, IFL, IMI and ifab.

1. Computer Aided Product Development (IMI)
2. Computer communication in factory (IMI)
3. Production of parts with CNC turning machines (wbk)
4. Controlling of production systems using PLCs (wbk)
5. Automated assembly systems (wbk)
6. Optical identification in production and logistics (IFL)
7. RFID identification systems (IFL)
8. Storage and order-picking systems (IFL)
9. Design of workstations (ifab)
10. Time study (ifab)
11. Accomplishment of workplace design (ifab)

#### Workload

Present time: 20 h

Self study: 100 h

#### Learning type

Seminar

**Literature**

Handout and literature online ILIAS.

**M****7.242 Module: Project Management in the Development of Products for Safety-Critical Applications [M-ETIT-104475]**

**Responsible:** Dr.-Ing. Manfred Nolle  
Prof. Dr.-Ing. Eric Sax

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-109148 | <a href="#">Project Management in the Development of Products for Safety-Critical Applications</a> | 4 CR | Nolle |

## M

**7.243 Module: Project Workshop: Automotive Engineering [M-MACH-107074]****Responsible:** Dr.-Ing. Martin Gießler**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |               |
|---------------|--|------|---------------|
| T-MACH-102156 | <a href="#">Project Workshop: Automotive Engineering</a> | 6 CR | Frey, Gießler |

**Competence Certificate**

oral examination, duration approx. 30-40 minutes

**Prerequisites**

none

**Competence Goal**

The students are familiar with typical industrial development processes and working style. They are able to apply knowledge gained at the university to a practical task. They are able to analyze and to judge complex relations. They are ready to work self-dependently, to apply different development methods and to work on approaches to solve a problem, to develop practice-oriented products or processes.

**Content**

During the Project Workshop Automotive Engineering a team of six persons will work on a task given by an German industrial partner using the instruments of project management. The task is relevant for the actual business and the results are intended to be industrialized after the completion of the project workshop.

The team will generate approaches in its own responsibility and will develop solutions for practical application. Coaching will be supplied by both, company and institute.

At the beginning in a start-up meeting goals and structure of the project will be specified. During the project workshop there will be weekly team meetings. Also a milestone meeting will be held together with persons from the industrial company. In a final presentation the project results will be presented to the company management and to institute representatives.

**Module grade calculation**

see individual course

**Workload**

120h

(for details see individual course)

**Learning type**

Steinle, Claus; Bruch, Heike; Lawa, Dieter (Hrsg.), Projektmanagement, Instrument moderner Innovation, FAZ Verlag, Frankfurt a. M., 2001, ISBN 978-3929368277

**M****7.244 Module: ProVIL - Product Development in a Virtual Idea Laboratory [M-MACH-105418]****Responsible:** Prof. Dr.-Ing. Albert Albers**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |               |
|---------------|---|------|---------------|
| T-MACH-106738 | <a href="#">ProVIL - Product Development in a Virtual Idea Laboratory</a> | 4 CR | Albers, Düser |

**Competence Certificate**

Coursework: Final report

**Prerequisites**

none

**Competence Goal**

The student

- can model problems of product development including their partial aspects (market, technology, product).
- can systematically design and conduct experiments for the validation of product models and interpret the results in a targeted manner.
- can select development methods specific to the situation and adapt them to realistic tasks.

**Content**

The course ProVIL is carried out as an innovation project with 4 phases and a realistic task definition. Students develop their own product concepts in a team using the latest hardware and software and execute the following activities:

- Analysis of the existing market and the environment of a product area
- Implementation and application of creativity methods and problem solving techniques
- Modelling of customer and user benefits as product profiles
- Validation of product profiles for target customer markets
- Generation of solution ideas for the technical implementation of the product profiles
- Visualization of user stories based on product videos
- Implementation of the selected ideas in functional prototypes and mock-ups
- Evaluation of the functional prototypes by planning, execution, evaluation and interpretation of suitable tests
- Presentation of the prototypes in a final event

**Annotation**

none

**Workload**

1. Time of presence kick-offs, workshops: 18 h
  2. Time of presence Pre-Milestones, Milestones: 18 h
  3. Project work: 84 h
- Total: 120 h = 4 LP

**Recommendation**

none

**Learning type**

- Transfer of knowledge in lectures and workshops as block courses
- Project work in small teams
- Presentation of the prototypes in a final event

**Literature**

none



## M

**7.245 Module: Python Algorithms for Automotive Engineering [M-MACH-107072]**

**Responsible:** Dr.-Ing. Martin Gießler  
Dr.-Ing. Stephan Rhode

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-110796 | <a href="#">Python Algorithms for Vehicle Technology</a> | 4 CR | Rhode |

**Competence Certificate**

written examination

**Competence Goal**

The students have an overview of the programming language Python and important Python libraries to solve automotive engineering problems with computer programs. The students know current tools around Python to create algorithms, to apply them and to interpret and visualize their results. Furthermore, the students know basics in the creation of software to be used in later programming projects in order to develop high-quality software solutions in teamwork. Through practical programming projects (road sign recognition, vehicle state estimation, calibration, data-based modelling), the students can perform future complex tasks from the area of driver assistance systems.

**Content**

- Introduction to Python and useful tools and libraries for creating algorithms, graphical representation, optimization, symbolic arithmetic and machine learning
  - [Anaconda](#), [Pycharm](#), [Jupyter](#)
  - [NumPy](#), [Matplotlib](#), [SymPy](#), [Scikit-Learn](#)
- Methods and tools for creating software
  - Version management [GitHub](#), [git](#)
  - Testing software [pytest](#), [Pylint](#)
  - Documentation [Sphinx](#)
  - Continuous Integration (CI) [Travis CI](#)
  - Workflows in Open Source and Inner Source, Kanban, Scrum
- Practical programming projects to:
  - Road sign recognition
  - Vehicle state estimation
  - Calibration of vehicle models by mathematical optimization
  - Data-based modelling of the powertrain of an electric vehicle

**Module grade calculation**

see individual course

**Annotation**

Lecture language is German, scripts are written in English

**Workload**

120h

(for details see individual course)

**Literature**

- A Whirlwind Tour of Python, Jake VanderPlas, Publisher: O'Reilly Media, Inc. Release Date: August 2016, ISBN: 9781492037859 [link](#)
- Scientific Computing with Python 3, Olivier Verdier, Jan Erik Solem, Claus Führer, Publisher: Packt Publishing, Release Date: December 2016, ISBN: 9781786463517 [link](#)
- Introduction to Machine Learning with Python, Sarah Guido, Andreas C. Müller, Publisher: O'Reilly Media, Inc., Release Date: October 2016, ISBN: 9781449369880, [link](#)
- Clean Code, Robert C. Martin, Publisher: Prentice Hall, Release Date: August 2008, ISBN: 9780136083238, [link](#)

## M

**7.246 Module: Quality Management [M-MACH-105332]**

**Responsible:** Prof. Dr.-Ing. Gisela Lanza  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |                                    |      |       |
|---------------|------------------------------------|------|-------|
| T-MACH-102107 | <a href="#">Quality Management</a> | 4 CR | Lanza |

**Competence Certificate**

Written Exam (60 min)

**Prerequisites**

None

**Competence Goal**

The students ...

- are capable to comment on the content covered by the module.
- are capable of substantially quality philosophies.
- are able to apply the QM tools and methods they have learned about in the module to new problems from the context of the module.
- are able to analyze and evaluate the suitability of the methods, procedures and techniques they have learned about in the module for a specific problem.

**Content**

Based on the quality philosophies Total Quality Management (TQM) and Six-Sigma, the module will specifically address the needs of a modern quality management. The process orientation in a modern company and the process-specific fields of quality assurance are presented in detail. Preventive as well as non-preventive quality management methods, which are state of the art in operational practice today, are content of the module. The use of suitable measurement techniques in production engineering (production measurement technology) as well as their potential levels of integration in the production system are discussed. The use of suitable statistical methods for data analysis and their modern extension by methods of artificial intelligence are be discussed. The contents are complemented by legal aspects in the field of quality management.

Main topics of the module:

- The term "Quality"
- Total Quality Management (TQM)
- Six-Sigma and universal methods and tools within the DMAIC cycle
- QM in early product stages – Determination and realization of customer requirements
- QM in product development
- Production measurement Technology
- QM in production - statistical Methods
- Artificial intelligence and machine learning in quality Management
- Operating behaviour and reliability
- Legal aspects in QM

**Workload**

1. Presence time lecture: 15 \* 2 h = 30 h
  2. Pre- and post-processing time lecture: 15 \* 3 h = 45 h
  3. Exam preparation and presence in the same: 45 h
- In total: 120 h = 4 LP

**Learning type**

Lecture

## M

## 7.247 Module: Quantum Detectors and Sensors [M-ETIT-105606]

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | Prof. Dr. Sebastian Kempf   |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 6              | Grade to a tenth     | Each winter term  | 1 term          | English         | 4            | 1              |

| Mandatory     |                               |      |       |
|---------------|-------------------------------|------|-------|
| T-ETIT-111234 | Quantum Detectors and Sensors | 6 CR | Kempf |

**Competence Certificate**

The assessment of success takes place in the form of a written examination lasting 120min. The grade corresponds to the result of the written examination.

**Prerequisites**

None

**Competence Goal**

Students know the basics and fundamentals of quantum detectors and sensors and understand how quantum technology can be used to design and realize devices whose performance reaches far beyond the limits of any classical sensor or detector. They know the basic components of quantum sensors and detectors, in particular in the field of superconducting quantum technology, and are able to analyze the operation of such detectors and sensors on the basis of circuit diagrams. Students are able to develop quantum sensors and detectors for given applications and know how to consider special requirements in a concrete component.

**Content**

This module provides a comprehensive overview of the basics and physical principles of quantum detectors and sensors and discusses in detail how quantum technology can be used to design and realize detectors and sensors with performance that reaches far beyond the limits of any classical sensor or detector. The discussion includes particularly an introduction to the basic components of quantum sensors and detectors, especially in the field of superconducting quantum technology, and their fabrication. Using simplified circuit diagrams, the functionality and operation of quantum detectors and sensors such as superconducting quantum interference devices, low-temperature detectors, noise thermometers or superconducting radiation detectors is analyzed. Furthermore, methods and simple models are developed allowing to realize quantum sensors and detectors that are matched to given applications. Within this context, typical applications of quantum detectors and sensors are also discussed.

The tutorial is closely related to the lecture and deals with special aspects concerning the development of quantum detectors and sensors. In particular, the development and system integration of quantum detectors and sensors for applications in precision metrology, particle detection or applied sciences is discussed by means of exercises.

**Module grade calculation**

The module grade is the grade of the written examination.

**Workload**

A workload of approx. 180h is required for the successful completion of the module. This is composed as follows:

- Attendance time in lectures and exercises:  $21 \cdot 1.5h + 7 \cdot 1.5h = 42h$
- Preparation and follow-up of lectures:  $21 \cdot 3h = 63h$
- Preparation and follow-up of tutorials:  $7 \cdot 5h = 35h$
- Preparation for the exam: 40h

**Recommendation**

Successful completion of the module "Superconductivity for Engineers" is recommended.

## M

## 7.248 Module: Quantum Machines I [M-MACH-107164]

**Responsible:** Prof. Dr. Marcel Utz  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |                                    |      |     |
|---------------|------------------------------------|------|-----|
| T-MACH-113827 | <a href="#">Quantum Machines I</a> | 4 CR | Utz |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

- be able to explain and apply the fundamental principles and mathematical structure of quantum mechanics
- be able to apply these to concrete engineered systems where quantum effects are an integral part of the operating principles

**Content**

Quantum Machines I and II are designed to immerse students in the fascinating intersection of quantum mechanics and cutting-edge engineering applications. Aimed at advanced undergraduate and graduate students in mechanical engineering, these courses provide a comprehensive exploration of quantum principles through practical technology examples. In Quantum Machines I, students will build a solid foundation in quantum mechanics, including fundamental concepts such as quantum states, operators, and the uncertainty principle. The course then connects these concepts to real-world engineering systems like MEMS devices, scanning probes, and quantum sensors, making abstract theories tangible and relevant.

**Module grade calculation**

see individual course

**Workload**

120h

(for details see individual course)

## M

## 7.249 Module: Quantum Machines II [M-MACH-107165]

**Responsible:** Prof. Dr. Marcel Utz  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |                                     |      |     |
|---------------|-------------------------------------|------|-----|
| T-MACH-113826 | <a href="#">Quantum Machines II</a> | 4 CR | Utz |

**Competence Certificate**

see individual course

**Competence Goal**

- be able to explain and apply the principles and mathematical structure of advanced quantum mechanical concepts, in particular symmetry, group theory, and angular momentum
- be able to apply these to the design of engineered systems where quantum effects play a major part; in particular in sensing and measurement, imaging systems and in spectroscopy.

**Content**

Quantum Machines II delves deeper into advanced topics such as angular momentum, quantum electrodynamics, and quantum information processing. Students will explore sophisticated applications including nuclear magnetic resonance spectroscopy, quantum dots, and atomic clocks. A particular focus is the theory and technology of nuclear magnetic resonance (NMR) and magnetic resonance imaging (MRI). The teaching concept integrates theoretical rigor with hands-on examples from modern technology, enabling students to see how quantum effects drive innovation in various fields. Through this approach, complex theoretical concepts are made accessible and engaging, bridging the gap between theory and practice. Registering for both courses will equip students with the knowledge and skills to understand and contribute to the forefront of quantum engineering and technology.

**Module grade calculation**

see individual course

**Workload**

120h

(see individual course)

## M

**7.250 Module: Radio-Frequency Electronics [M-ETIT-106955]****Responsible:** Prof. Dr.-Ing. Ahmet Cagri Ulusoy**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-ETIT-113910 | <a href="#">Radio-Frequency Electronics</a> | 6 CR | Ulusoy |

**Competence Certificate**

The examination takes place in form of a written examination lasting 120 minutes.

**Prerequisites**

none

**Competence Goal**

- The students have a comprehensive understanding of the theory and the basic design methodology of RF and microwave circuits up to 300 GHz.
- They understand the limitations of active and passive circuit elements at high frequencies and their impact on the applications.
- They understand the limitations and how linear network theory is applied at higher frequencies.
- The students can apply the acquired theoretical knowledge to modern RF design problems.

**Content**

In this lecture, the theory and design methodology of RF electronic circuits will be studied in detail. The focus of the lecture is on the fundamentals of active and passive linear circuits. The important topics are:

- Phasor analysis and resonance,
- Electromagnetic theory, transmission lines and waveguides,
- Impedance matching networks,
- Two-port parameters of RF components and microwave network analysis,
- Feedback and stability analysis,
- High-frequency behavior of basic amplifier circuits, RF amplifiers design techniques,
- Microwave power dividers, couplers and filters

**Module grade calculation**

The module grade is the grade of the written examination.

**Workload**

The total effort for this lecture is estimated as following:

1. Attendance to the lectures ( $15 \cdot 3 = 45$ h)
2. Attendance to the exercises ( $15 \cdot 1 = 15$ h)
3. Preparation to the lectures and exercises ( $17 \cdot (3+1) = 68$ h)
4. Preparation to the exam (52h)

A total of 180h

**Recommendation**

Basic knowledge of linear electrical networks and electronic circuits is recommended (e.g. M-ETIT-106417 – Lineare Elektrische Netze; M-ETIT-104465 – Elektronische Schaltungen).

## M

**7.251 Module: Rail System Technology [M-MACH-103232]**

**Responsible:** Prof. Dr.-Ing. Martin Cichon  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 3       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-106424 | <a href="#">Rail System Technology</a> | 4 CR | Cichon |

**Competence Certificate**

written examination in German language

Duration: 60 minutes

No tools or reference materials may be used during the exam except calculator and dictionary

**Prerequisites**

none

**Competence Goal**

- The students understand relations and interdependencies between rail vehicles, infrastructure and operation in a rail system.
- Based on operating requirements and legal framework they derive the requirements concerning a capable infrastructure and suitable concepts of rail vehicles.
- They recognize the impact of alignment, understand the important function of the wheel-rail-contact and estimate the impact of driving dynamics on the operating program.
- They evaluate the impact of operating concepts on safety and capacity of a rail system.
- They know the infrastructure to provide power supply to rail vehicles with different drive systems.

**Content**

1. Railway System: railway as system, subsystems and interdependencies, definitions, laws, rules, railway and environment, economic impact
2. Operation: Transportation, public transport, regional transport, long-distance transport, freight service, scheduling
3. Infrastructure: rail facilities, track alignment, railway stations, clearance diagram
4. Wheel-rail-contact: carrying of vehicle mass, adhesion, wheel guidance, current return
5. Vehicle dynamics: tractive and brake effort, driving resistance, inertial force, load cycles
6. Signaling and Control: operating procedure, succession of trains, European Train Control System, blocking period, automatic train control
7. Traction power supply: power supply of rail vehicles, comparison electric traction and diesel traction, dc and ac networks, system pantograph and contact wire, filling stations

**Annotation**

A bibliography is available for download (Ilias-platform).

**Workload**

Regular attendance: 21 hours

Self-study: 21 hours

Exam and preparation: 78 hours

total: 120 hours = 4 ECTS

**Learning type**

Lecture



## M

## 7.252 Module: Rail Vehicle Technology [M-MACH-102683]

**Responsible:** Prof. Dr.-Ing. Martin Cichon  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 3       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-105353 | <a href="#">Rail Vehicle Technology</a> | 4 CR | Cichon |

**Competence Certificate**

written examination in German language

Duration: 60 minutes

No tools or reference materials may be used during the exam except calculator and dictionary

**Prerequisites**

none

**Competence Goal**

- The students learn the role of rail vehicles and understand their classification. They understand the basic structure and know the functions of the main systems. They understand the overall tasks of vehicle system technology.
- They learn functions and requirements of car bodies and judge advantages and disadvantages of design principles. They know the functions of the car body's interfaces.
- They know about the basics of running dynamics and bogies.
- The students learn about advantages and disadvantages of different types of traction drives and judge, which one fits best for each application.
- They understand brakes from a vehicular and an operational point of view. They assess the fitness of different brake systems.
- They know the basic setup of train control management system and understand the most important functions.
- They specify and define suitable vehicle concepts based on requirements for modern rail vehicles.

**Content**

1. Vehicle system technology: structure and main systems of rail vehicles
2. Car body: functions, requirements, design principles, crash elements, coupling, doors and windows
3. Bogies: forces, running gears, bogies, Jakobs-bogies, active components, connection to car body, wheel arrangement
4. Drives: principles, electric drives (main components, asynchronous traction motor, inverter, with DC supply, with AC supply, without line supply, multisystem vehicles, dual mode vehicles, hybrid vehicles), non-electric drives
5. Brakes: basics, principles (wheel brakes, rail brakes, blending), brake control (requirements and operation modes, pneumatic brake, electropneumatic brake, emergency brake, parking brake)
6. Train control management system: definition of TCMS, bus systems, components, network architectures, examples, future trends
7. Vehicle concepts: trams, metros, regional trains, intercity trains, high speed trains, double deck vehicles, locomotives, freight wagons

**Annotation**

A bibliography is available for download (Ilias-platform).

**Workload**

Regular attendance: 21 hours

Self-study: 21 hours

Exam and preparation: 78 hours

total: 120 hours = 4 ECTS

**Learning type**

Lecture

## M

**7.253 Module: Railway System Digitalisation [M-MACH-106513]**

**Responsible:** Prof. Dr.-Ing. Martin Cichon  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-113016 | <a href="#">Digitization in the Railway System</a> | 4 CR | Cichon |

**Competence Certificate**

Examination performance oral  
 Duration approx. 20 minutes  
 Auxiliary means: none

**Prerequisites**

none

**Competence Goal**

The students have a basic understanding of train control and its technical implementation in Germany, the functioning of the European Train Control System (ETCS) and its planning, Automated Train Operation. They are able to explain the knowledge they have acquired (terms, interrelationships) in context and apply it to issues in practice. Furthermore, the students can classify the operational and technical advantages and disadvantages in the context of the digitalization of the rail network in Germany and take future challenges into account.

The students can discuss the technical aspects and areas of application of ETCS in the different levels and reproduce the main features of balise planning for ETCS Level 2. Digital planning approaches such as PlanPro as well as measurement and test runs are known and can be classified.

**Content**

1. introduction and motivation: organizational aspects; current developments in Germany, Europe
2. Basics of the railroad system: terminology; interaction of rolling stock, infrastructure and operations
3. Securing train movements: overview of possibilities and areas of application; operational and technical aspects with a focus on Germany
4. Basics of interlockings, control and safety elements: Train protection in Germany with PZB, LZB
5. Safety and security: EN5012x, CENELEC, RAMS
6. European Train Control System (ETCS): specification; system components, braking curves; ETCS level and modes, train integrity; interface between vehicle and infrastructure, data exchange; infrastructure-side ETCS balise planning using the example of ETCS level 2; track surveying, commissioning; digitization of the planning process using the example of PlanPro
7. Automatic Train Operation (ATO), Communication-Based Train Control (CBTC): system architecture, Grade of Automation (GoA); advantages and challenges ATO; differences CTBC to ETCS
8. Future Developments: Future Railway Mobile Communication System (FRMCS) as successor to GSM-R.

**Annotation**

A bibliography is available for students to download from the Ilias platform.

**Workload**

Attendance time: 21 hours  
 Preparation / wrap-up: 21 hours  
 Exam and exam preparation: 78 hours  
 Total effort: 120 hours = 4 LP

**Learning type**

Lecture

**Literature**

- ETCS for Engineers, Stanley, 2011, ISBN 978-3-96245-034-2
- European Train Control System (ETCS), Schnieder, ISBN 978-3-662-66054-6
- Communications-Based Train Control (CBTC), Schnieder, ISBN 978-3-662-61012-1

## M

**7.254 Module: Railways in the Transportation Market [M-MACH-107044]****Responsible:** Prof. Dr.-Ing. Martin Cichon**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-105540 | <a href="#">Railways in the Transportation Market</a> | 4 CR | Cichon |

**Competence Certificate**

Oral examination

Duration: ca. 20 minutes

No tools or reference materials may be used during the exam.

**Prerequisites**

none

**Competence Goal**

- To capture the entrepreneurial perspective on transport companies
- To appraise the intra- and intermodal competition
- To understand the regulative determinant
- To reflect trends in transportation market
- To comprehend strategic challenges, chances and fields of actions of transport companies
- To apply intermodal perspective
- To take important key figures of railways and transportation market
- To realize the relevance of sustainability and digitalization

**Content**

The lecture gives an overview about perspective, challenges and chances of rail systems in the national and European market. Following items will be discussed:

- Introduction and basics
- Rail reform in Germany
- Overview of Deutsche Bahn
- Regulation of railways
- Financing and development of rail infrastructure
- Group strategy "Strong Rail" and their building blocks:  
(climate, environment, digitalization, "Strong Rail" in Baden-Württemberg)
- Trends in the transportation market
- Field of actions in transport policy
- Intra- and intermodal competition
- Summary

**Workload**

Regular attendance: 21 hours

Self-study: 21 hours

Exam and preparation: 78 hours

total: 120 hours = 4 ECTS

**Learning type**

Lecture

**Literature**

A bibliography is available for download (Ilias-platform).

## M

## 7.255 Module: Re:Invent - Revolutionary Business Models as the Basis for Product Innovations [M-MACH-106662]

**Responsible:** Prof. Dr.-Ing. Tobias Düser  
Dr.-Ing. Thomas Schneider

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |           |
|---------------|--|------|-----------|
| T-MACH-111888 | <a href="#">Re:Invent - Revolutionary Business Models as the Basis for Product Innovations</a> | 4 CR | Schneider |

### Competence Certificate

see individual course

### Prerequisites

None

### Competence Goal

- Acquiring skills in innovative business model development: Students acquire the ability to integrate their knowledge of product development into the development of innovative business models.
- Understanding the connection between business models and global challenges: Students learn to understand and describe the connections between business models and current global challenges such as competitive pressure, decarbonisation and data sovereignty.
- Development of technical foundations for servitisation business models: Students develop the necessary technical requirements for the development and introduction of different servitisation business models.
- Ability to build industrial ecosystems: Students will learn to develop and present the fundamentals for building industrial ecosystems within business models.

### Content

- Integration of product-service systems: Focus on shaping the change to user-centred product-service systems in the coming decades.
- Case study of TRUMPF machine tools: Discussion and analysis of the first industrial pay-per-part business model.
- Teamwork and idea exploration: students work in teams to explore and develop further ideas.
- Practice-orientated workshop: Conclusion of the lecture with a workshop on product launch in European markets, allowing practical application of what has been learnt.

### Module grade calculation

The module grade is the grade of the oral examination.

### Annotation

None

### Workload

120 hours, including 30 hours attendance

### Recommendation

None

### Learning type

Lecture, workshop and excursion

**Literature**

None

**Base for**

None

## M

**7.256 Module: Reactor Physics [M-MACH-107071]****Responsible:** Dr. Aurelian Florin Badea**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-105550 | <a href="#">Energy Systems II: Reactor Physics</a> | 4 CR | Badea |

**Competence Certificate**

A performance assessment will consist of an oral examination of approx. 30 minutes.

**Prerequisites**

none

**Competence Goal**

The objective of the module is to train the students for the field of nuclear energy using fission reactors. The students acquire comprehensive knowledge on the physics of nuclear fission reactors: neutron flux, cross sections, fission, breeding processes, chain reaction, critical size of a nuclear system, moderation, reactor dynamics, transport- and diffusion-equation for the neutron flux distribution, power density distributions in reactor, one-group, two-group and multi-group theories for the neutron spectrum. Students are able to analyze and understand the obtained results. Based on the reactor physics knowledge, the students are able to understand, compare and evaluate the capabilities of different types of reactors -LWR, heavy water reactors, nuclear power systems of generation IV – as well as their fundamental nuclear safety concepts. The students are qualified for further training in nuclear energy and safety field and for (also research-related) professional activity in the nuclear industry.

**Content**

- nuclear fission & fusion,
- radioactive decay, neutron excess, fission, fast and thermal neutrons, fissile and fertile nuclei, neutron flux, cross section, reaction rate, mean free path,
- chain reaction, critical size, moderation,
- reactor dynamics,
- transport- and diffusion-equation for the neutron flux distribution,
- power distributions in reactor,
- one-group and two-group theories,
- light-water reactors,
- reactor safety,
- design of nuclear reactors,
- breeding processes,
- nuclear power systems of generation IV

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

(for details see individual course)



## M

**7.257 Module: Reactor Safety 1: Fundamentals [M-MACH-107116]****Responsible:** Dr. Victor Hugo Sanchez-Espinoza**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |                  |
|---------------|--|------|------------------|
| T-MACH-105405 | <a href="#">Reactor Safety I: Fundamentals</a> | 4 CR | Sanchez-Espinoza |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

The student can

- explain the structure and mode of operation of a nuclear power plant and the safety systems
- understand and classify the hazard potential of hypothetical accidents in a nuclear power plant
- explain the basic principles of reactor safety and understand the inherent safety characteristics of reactors
- understand and apply the methods of safety assessment
- explain the sequence of typical accident sequences in nuclear power plants
- get informed about typical numerical tools for safety assessment and can classify the importance of validation of tools
- obtain knowledge of the most important steps for modeling nuclear power plants for safety assessment

**Content**

The lecture discusses the fundamental principles and concepts of reactor safety including the methodologies for safety assessment and major accidents. It starts with the short description of the reactor systems and their safety functions. Then, the inherent safety features and key thermal hydraulic safety parameters are introduced. The composition of the fuel and amount of radioactive material in the core and it changes during operation are explained for understanding of the radiological risk. The main principles and concepts of reactor safety are discussed such as defense in depth, multi-barrier concept. The initiation and progression of incidents/accidents as well as the methods for the safety evaluation are also treated in the lecture. The approach to model the behavior of nuclear reactors under accidental conditions such as in case of severe accidents is developed including the radiological risk from hypothetical severe accident. Finally, the safety features of innovative reactors such as small modular reactors and liquid-metal fast reactors and molten salt reactors are presented.

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

120h

(for details see individual course)

## M

## 7.258 Module: Real Time Control of Electrical Drives [M-ETIT-105916]

**Responsible:** Dr.-Ing. Andreas Liske

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-111898 | <a href="#">Real Time Control of Electrical Drives</a> | 6 CR | Liske |

**Workload**

Jeder Leistungspunkt (Credit Point) entspricht ca. 25-30h Arbeitsaufwand (des Studierenden). Hierbei ist vom durchschnittlichen Studierenden auszugehen, der eine durchschnittliche Leistung erreicht.

56h = 22x V à 2h + 3x Ü à 4h

21h = 21x Nachbereitung von V à 1 h

12h = 3x Vorbereitung von Ü à 4 h

80h = Vorbereitung zur Prüfung

Summe = 169 h (entspricht 6 LP)

## M

**7.259 Module: Real-Time Systems (24576) [M-INFO-100803]****Responsible:** Prof. Dr.-Ing. Thomas Längle**Organisation:** KIT Department of Informatics

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |                                   |      |        |
|---------------|-----------------------------------|------|--------|
| T-INFO-101340 | <a href="#">Real-Time Systems</a> | 6 CR | Längle |

## M

## 7.260 Module: Reinforcement Learning [M-INFO-105623]

|                      |   |
|----------------------|---|
| <b>Responsible:</b>  | TT-Prof. Dr. Rudolf Lioutikov<br>Prof. Dr. Gerhard Neumann  |
| <b>Organisation:</b> | KIT Department of Informatics   |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 6              | Grade to a tenth     | Each winter term  | 1 term          | English         | 4            | 2              |

| Mandatory     |                        |      |                    |
|---------------|------------------------|------|--------------------|
| T-INFO-111255 | Reinforcement Learning | 6 CR | Lioutikov, Neumann |

**Competence Certificate**

See partial achievements (Teilleistung)

**Prerequisites**

See partial achievements (Teilleistung)

**Competence Goal**

- Students are able to understand the RL problem and challenges.
- Students can differentiate between different RL algorithm and understand their underlying theory
- Students will know the mathematical tools necessary to understand RL algorithms
- Students can implement RL algorithms for various tasks
- Students understand current research questions in RL

**Content**

Reinforcement Learning (RL) is a sub-field of machine learning in which an artificial agent has to interact with its environment and learn how to improve its behaviour by trial and error. For doing so, the agent is provided with an evaluative feedback signal, called reward, that he perceives for each action performed in its environment. RL is one of the hardest machine learning problems, as, in contrast to standard supervised learning, we do not know the targets (i.e. the optimal actions) for our inputs (i.e. the state of the environment) and we also need to consider the long-term effects of the agent's actions on the state of the environment. Due to recent successes, RL has gained a lot of popularity with applications in robotics, automation, health care, trading and finance, natural language processing, autonomous driving and computer games. This lecture will introduce the concepts and theory of RL and review current state of the art methods with a particular focus on RL applications in robotics. An exemplary list of topics is given below:

- Primer in Machine Learning and Deep Learning
- Supervised Learning of Behaviour
- Introduction in Reinforcement Learning
- Dynamic Programming
- Value Based Methods
- Policy Optimization and Trust Regions
- Episodic Reinforcement Learning and Skill Learning
- Bayesian Optimization
- Variational Inference, Max-Entropy RL and Versatility
- Model-based Reinforcement Learning
- Offline Reinforcement Learning
- Inverse Reinforcement Learning
- Hierarchical Reinforcement Learning
- Exploration and Artificial Curiosity
- Meta Reinforcement Learning

**Workload**

Approximately 180 hours, divided into:

- 45 hours of lecture attendance
- 15 hours of exercise attendance
- 90 hours of post-processing and working on exercise sheets
- 30 hours of exam preparation.

**Recommendation**

- Students should be familiar with the content of the "Foundations of Artificial Intelligence" lecture.
- Good Python knowledge is required.
- Good mathematical background knowledge is required.

## M

**7.261 Module: Reliability and Test Engineering [M-MACH-106050]**

**Responsible:** Dr.-Ing. Thomas Gwosch  
Prof. Dr.-Ing. Sven Matthiesen

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-111840 | <a href="#">Reliability and Test Engineering</a> | 5 CR | Gwosch |

**Competence Certificate**

The grade is composed of the evaluation of a final report following the practical part. The assessment criteria are as follows:

- Structure of the report
- Comprehensibility and comprehensibility
- Preparation of the tests
- Use of test and reliability methods
- Formulation and answering of test hypotheses
- Test evaluation, comprehensible results

Attendance and active participation in the lab is mandatory.

**Prerequisites**

keine

**Competence Goal**

The students:

- know the relevance of reliability and test engineering in engineering practice.
- know the methods of reliability and test engineering and the components and tools used.
- are able to carry out test planning, test execution and test interpretation for a given problem on a test bench by themselves.

**Content**

The students learn the methods of reliability and test engineering and the components used. Furthermore, they are able to independently carry out test planning, test execution and test interpretation for a given problem on a test bench.

The following contents are taught in the lecture:

- Relevance of reliability and test engineering in the industry.
- Overview of test equipment
- Test strategies and statistical test planning
- Testing with hypotheses
- Reliability models

The implementation of test planning, test execution and test interpretation on a demonstrator test bench is part of the practical session subsequent to the lecture (See also Event 2145351: Workshop for Reliability and Test Engineering).

**Module grade calculation**

The module grade is the grade of the examination performance of another type.

**Annotation**

In case of questions please contact [lrt@ipek.kit.edu](mailto:lrt@ipek.kit.edu)

The number of participants is limited, an application is necessary. For details please check the lab's web page <https://www.ipek.kit.edu/2976.php>

**Workload**

150 h

**Recommendation**

We strongly recommend the attendance of the MSuP lectures. Students who have not (yet) attended are recommended to learn the contents in advance.

**Learning type**

Materials/lecture notes are supplied via ILIAS.

**Literature**

O'Connor: Test Engineering

O'Connor: Practical Reliability Engineering

Birolini: Reliability Engineering

Bertsche: Zuverlässigkeit mechatronischer Systeme

VDI 4002: Zuverlässigkeitsingenieur

## M

**7.262 Module: Renewable Energy-Resources, Technologies and Economics [M-WIWI-100500]****Responsible:** Prof. Dr. Russell McKenna**Organisation:** KIT Department of Economics and Management**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 3       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-WIWI-100806 | <a href="#">Renewable Energy-Resources, Technologies and Economics</a> | 4 CR | Jochem |

**Competence Certificate**

The assessment consists of a written exam according to Section 4(2), 1 of the examination regulation.

**Prerequisites**

None

**Competence Goal**

The student:

- understands the motivation and the global context of renewable energy resources.
- gains detailed knowledge about the different renewable resources and technologies as well as their potentials.
- understands the systemic context and interactions resulting from the increased share of renewable power generation.
- understands the important economic aspects of renewable energies, including electricity generation costs, political promotion and marketing of renewable electricity.
- is able to characterize and where required calculate these technologies.

**Content**

1. General introduction: Motivation, Global situation
2. Basics of renewable energies: Energy balance of the earth, potential definition
3. Hydro
4. Wind
5. Solar
6. Biomass
7. Geothermal
8. Other renewable energies
9. Promotion of renewable energies
10. Interactions in systemic context
11. Excursion to the "Energieberg" in Mühlburg

**Workload**

The total workload for this course is approximately 105.0 hours. For further information see German version.

**Literature****Elective literature:**

- Kaltschmitt, M., 2006, Erneuerbare Energien : Systemtechnik, Wirtschaftlichkeit, Umweltaspekte, aktualisierte, korrigierte und ergänzte Auflage Berlin, Heidelberg : Springer-Verlag Berlin Heidelberg.
- Kaltschmitt, M., Streicher, W., Wiese, A. (eds.), 2007, Renewable Energy: Technology, Economics and Environment, Springer, Heidelberg.
- Quaschnig, V., 2010, Erneuerbare Energien und Klimaschutz : Hintergründe - Techniken - Anlagenplanung – Wirtschaftlichkeit München : Hanser, Ill.2., aktualis. Aufl.
- Harvey, D., 2010, Energy and the New Reality 2: Carbon-Free Energy Supply, Eathscan, London/Washington.
- Boyle, G. (ed.), 2004, Renewable Energy: Power for a Sustainable Future, 2ndEdition, Open University Press, Oxford.



## M

## 7.263 Module: Robotics - Practical Course [M-INFO-107155]

**Responsible:** Prof. Dr.-Ing. Tamim Asfour

**Organisation:** KIT Department of Informatics

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-INFO-114172 | <a href="#">Practical Course: Robotics</a> | 6 CR | Asfour |

### Competence Certificate

See partial Achievements (Teilleistung)

### Prerequisites

See partial Achievements (Teilleistung)

### Competence Goal

The student knows concrete solutions for different problems in robotics. He/she uses methods of inverse kinematics, grasp and motion planning, and visual perception. The student can implement solutions in the programming languages C++ and Python with the help of suitable software frameworks.

### Content

The practical course is offered as an accompanying course to the lectures Robotics I-III. Every week, a small team of students will work on solving a given robotics problem. The list of topics includes robot modeling and simulation, inverse kinematics, robot programming via state charts, collision-free motion planning, grasp planning, robot vision and robot learning.

### Workload

Practical course with 4 SWS, 6 LP  
 6 LP corresponds to 180 hours, including  
 2 hours introductory event  
 18 hours initial familiarization with the software framework  
 120 hours group work  
 40 hours attendance time

### Recommendation

Attending the lectures Robotics I – Introduction to Robotics, Robotics II: Humanoid Robotics, Robotics III - Sensors and Perception in Robotics and Mechano-Informatics and Robotics is recommended.

## M

## 7.264 Module: Robotics II - Humanoid Robotics [M-INFO-107123]

**Responsible:** Prof. Dr.-Ing. Tamim Asfour

**Organisation:** KIT Department of Informatics

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-INFO-114152 | <a href="#">Robotics II - Humanoid Robotics</a> | 3 CR | Asfour |

### Competence Certificate

See partial achievements (Teilleistung)

### Prerequisites

See partial achievements (Teilleistung)

### Competence Goal

The students have an overview of current research topics in autonomous learning robot systems using the example of humanoid robotics. They are able to classify and evaluate current developments in the field of cognitive humanoid robotics.

The students know the essential problems of humanoid robotics and are able to develop solutions on the basis of existing research.

### Content

The lecture presents current work in the field of humanoid robotics that deals with the implementation of complex sensorimotor and cognitive abilities. In the individual topics different methods and algorithms, their advantages and disadvantages, as well as the current state of research are discussed.

The topics addressed are: Applications and real world examples of humanoid robots; biomechanical models of the human body, biologically inspired and data-driven methods of grasping, imitation learning and programming by demonstration; semantic representations of sensorimotor experience as well as cognitive software architectures of humanoid robots.

### Workload

Lecture with 2 SWS, 3 CP.

3 LP corresponds to approx. 90 hours, thereof:

approx. 15 \* 2h = 30 Std. Attendance time

approx. 15 \* 2h = 30 Std. Self-study prior/after the lecture

approx. 30 Std. Preparation for the exam and exam itself

### Recommendation

Having visited the lectures on Robotics I - Introduction to Robotics and Mechano-Informatics and Robotics is recommended.

## M

**7.265 Module: Robotics III - Sensors and Perception in Robotics (24635) [M-INFO-107130]****Responsible:** Prof. Dr.-Ing. Tamim Asfour**Organisation:** KIT Department of Informatics

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-INFO-114155 | <a href="#">Robotics III - Sensors and Perception in Robotics</a> | 3 CR | Asfour |

**Competence Certificate**

See partial achievements (Teilleistung)

**Prerequisites**

See partial achievements (Teilleistung)

**Competence Goal**

Students can name the main sensor principles used in robotics.

Students can explain the data flow from physical measurement through digitization to the use of the recorded data for feature extraction, state estimation and semantic scene understanding.

Students are able to propose and justify suitable sensor concepts for common tasks in robotics.

**Content**

The lecture supplements the lecture Robotics I with a broad overview of sensors used in robotics. The lecture focuses on visual perception, object recognition, semantic scene interpretation, and (inter-)active perception. The lecture is divided into two parts:

In the first part a comprehensive overview of current sensor technologies is given. A basic distinction is made between sensors for the perception of the environment (exteroceptive) and sensors for the perception of the internal state (proprioceptive).

The second part of the lecture concentrates on the use of exteroceptive sensors in robotics. The topics covered include tactile exploration and visual data processing, including advanced topics such as feature extraction, object localization, semantic scene interpretation, and (inter-)active perception.

**Workload**

Lecture with 2 SWS, 3 LP

3 LP corresponds to 90 hours, including

15 \* 2 = 30 hours attendance time

15 \* 2 = 30 hours self-study

30 hours preparation for the exam

**Recommendation**

Attending the lecture Robotics I – Introduction to Robotics is recommended.

## M

## 7.266 Module: Seamless Engineering [M-MACH-105725]

**Responsible:** Prof. Dr.-Ing. Kai Furmans  
Prof. Dr.-Ing. Eric Sax

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 9       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |                                      |      |              |
|---------------|--------------------------------------|------|--------------|
| T-MACH-111401 | <a href="#">Seamless Engineering</a> | 9 CR | Furmans, Sax |

**Competence Certificate**

Examination of another type. The description of the form of examination can be found in the description of the partial performance.

**Prerequisites**

None

**Competence Goal**

After successful completion of the course, the students are able to model and parameterise the requirements and boundary conditions for typical mechatronic systems. In addition, students learn the ability to select the appropriate procedures, processes, methods and tools for the development of a mechatronic system.

Important core competences in the areas of communication, problem solving and self-organisation are further essential components of the workshop, which enable the students to do reflected work independently and in a team.

**Content**

This module is designed to teach students how to develop a heterogeneous integrated mechatronic system. In the lecture, students are introduced to a system-oriented, higher-level approach to the description, assessment and development of a mechatronic system.

Parallel to this, the contents taught are applied and deepened in the practical part on hardware that is close to industry. The students learn the systematic development in a simulative environment as well as the transition from simulation to real hardware.

To achieve this, important components of software development in the robotics environment are taught. This includes, among other things, the basics of programming (Python) as well as the handling of the framework "Robot Operating System (ROS)". In addition, students gain insights into the use of sensors and actuators, image processing, autonomous navigation of automated guided vehicles and robotic grasping.

**Module grade calculation**

The evaluation of the colloquia and a final examination are included in the module grade. Further details will be provided at the beginning of the course.

**Annotation**

None

**Workload**

1. attendance time lecture and exercise: 45 h
2. interdisciplinary qualification: 45 h
3. group work project: 130 h
4. colloquia and final event: 30 h
5. exam preparation and presence in the same: 20 h

In total: 270 = 9 LP

**Recommendation**

None

**Learning type**

Lecture, exercise, project.

**Literature**

None

## M

## 7.267 Module: Seminar Data-Mining in Production [M-MACH-105477]

**Responsible:** Prof. Dr.-Ing. Gisela Lanza

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 2       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-MACH-108737 | <a href="#">Seminar Data-Mining in Production</a> | 3 CR | Lanza |

### Competence Certificate

Alternative test achievement

### Prerequisites

None

### Competence Goal

The students ...

- can name, describe and distinguish between different methods, procedures and techniques of production data analysis.
- can perform basic data analyses with the data mining tool KNIME.
- can analyze and evaluate the results of data analyses in the production environment.
- are able to derive suitable recommendations for action.
- are able to explain and apply the CRISP-DM model.

### Content

In the age of Industry 4.0, large amounts of production data are generated by the global production networks and value chains. Their analysis enables valuable conclusions about production and lead to an increasing process efficiency. The aim of the modul is to get to know production data analysis as an important component of future industrial projects. The students get to know the data mining tool KNIME and use it for analyses. A specific industrial use case with real production data enables practical work and offers direct references to industrial applications. The participants learn selected methods of data mining and apply them to the production data. The work within the seminar takes place in small groups on the computer. Subsequently, presentations on specific data mining methods have to be prepared.

### Annotation

The number of students is limited to twelve. Dates and deadlines for the seminar will be announced at <https://www.wbk.kit.edu/studium-und-lehre.php>.

### Workload

regular attendance: 10 hours

self-study: 80 hours

### Learning type

Seminar

## M

**7.268 Module: Seminar Electrocatalysis [M-ETIT-105629]****Responsible:** Prof. Dr.-Ing. Ulrike Krewer**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-ETIT-111256 | <a href="#">Seminar Electrocatalysis</a> | 3 CR | Krewer |

**Prerequisites**

none

## M

## 7.269 Module: Seminar Embedded Systems [M-ETIT-100455]

**Responsible:** Prof. Dr.-Ing. Jürgen Becker  
Prof. Dr.-Ing. Eric Sax  
Prof. Dr. Wilhelm Stork

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 3       |

| Mandatory     |  |      |                    |
|---------------|--|------|--------------------|
| T-ETIT-100753 | <a href="#">Seminar Embedded Systems</a> | 4 CR | Becker, Sax, Stork |

**Competence Certificate**

Success is assessed in the form of a written paper, reviews and a presentation. The overall impression is assessed.

**Prerequisites**

none

**Competence Goal**

Seminar participants can independently familiarize themselves with a given technical topic, identify all relevant aspects and summarize the results. In this context, students can identify relevant literature in terms of the research question, assess the strengths and weaknesses of existing approaches and methods, and formally evaluate other works according to specified criteria. They can also suggest new aspects in line with the research question. They can present the results of their work concisely in the form of a short text (approx. 6-page paper, usually written in English) and an approx. 15-minute presentation in words and pictures (slides).

**Content**

In the "Embedded Systems" seminar, students work on a given topic from the field of information processing through literature and internet research under the guidance of research assistants and then present it to the other seminar participants in a short text (approx. 6-page paper, usually written in English) and a 15-minute presentation in words and pictures (slides). The students give each other feedback as part of a peer review and thus experience a part of the scientific publication process.

**Module grade calculation**

The grading is based on the elaboration, the mutual review and the presentation.

**Workload**

The workload includes:

1. Independent familiarization with a topic: 50h
2. Writing a scientific article: 40h
3. Preparing a peer review: 10h
4. Preparing and giving a presentation: 20h

Total: 120h = 4 LP



## M

**7.270 Module: Seminar for Rail System Technology [M-MACH-104197]**

**Responsible:** Prof. Dr.-Ing. Martin Cichon  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 2       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-108692 | <a href="#">Seminar for Rail System Technology</a> | 3 CR | Cichon |

**Competence Certificate**

Examination: Writing an essay (Seminararbeit), final presentation

**Prerequisites**

None

**Competence Goal**

- The students become aware of the fundamental relations and interdependencies between rail vehicles, infrastructure and operation in a rail system.
- They overview the technical components of a rail system, in particular rail vehicle technology.
- They are able to use the essential elements of scientific work and present their results in written form and verbal presentation.

**Content**

1. Railway System: railway as a system, subsystems and interdependencies, definitions, laws, rules, railway and environment, economic impact
2. Operation: Transportation, public transport, regional transport, long-distance transport, freight service, scheduling
3. System structure of railway vehicles: structure and major systems of rail vehicles
4. Scientific working: structuring and writing of scientific papers, literature research, scheduling (mile stones), self-management, presentation skills, using the software Citavi for literature and knowledge management, working with templates in Word, giving and taking feedback
5. The learnt knowledge regarding scientific writing is used to elaborate a Seminararbeit. To this the students create a presentation, train and reflect it and finally present it to an auditorium.

**Workload**

Regular attendance: 21 hours

Self-study (writing Seminararbeit): 65 hours

Final presentation (including preparation): 4 hours

total: 90 hours = 3 ECTS

**Learning type**

Essay

## M

**7.271 Module: Seminar Industrial Process and Plant Engineering [M-ETIT-106970]****Responsible:** Prof. Dr.-Ing. Mike Barth**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives\)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-ETIT-113932 | <a href="#">Seminar Industrial Process and Plant Engineering</a> | 4 CR | Barth |

**Competence Certificate**

The examination will be the seminar presentation at the end of the semester. The criteria are:

- Live presentation of the created CAD and simulation models
- Poster design and usage within the presentation
- Answering the questions from the examiners
- Structure of the talk

**Prerequisites**

none

**Competence Goal**

The students:

- are able to create (concept and virtual realization) mechatronic plants and production facilities (e.g. robot cells).
- understand the Engineering-Lifecycle of unique production plants, machines and modules.
- are familiar with modern CAX-Engineering Methods.
- know advanced (cloud-based) CAX-Tool-Chains.
- know about advanced computer-aided design principles, e.g. model- and equation-based 3D-Design.
- are familiar with design definitions, patterns and features for semi-automated engineering tasks, e.g. automatic generation of variants.
- know CAX-information models, e.g. asset administration shell (AAS) or Parasolid.
- can implement new software-based Engineering features and interfaces.
- are able to perform the virtual commissioning of complex systems using advanced CAX-features.

**Content**

- This module is designed to teach students the theoretical and practical aspects of advanced model-based and computer-aided design of unique systems, e.g.
  - Industrial plants,
  - Production cells (e.g. robot),
  - Production modules and machines.
- This includes every lifecycle phase of an engineering project starting from 3D-CAD Design to advanced system simulations and concluding in virtual commissioning and optimization during operations.
- Introduction to advanced cloud-based 3D-Plant-Engineering (e.g. OnShape).
- Principals of model-based system design (3D-Modeling, Drawings, Feature-based Rule Set) including advanced kinematics and simulation.
- Configuration and use of VR-, AR-Setups for virtual commissioning and operator training setups.
- Concept and implementation of software-based feature scripts (e.g. C++, python) for advanced engineering in the used tool chain.
- Concept and implementation of interfaces to external engineering data-sources (e.g. data tables, Asset Administration Shell via REST-API, ROS, MQTT or OPC UA).

**Module grade calculation**

The module grade is the grade of the final presentation including the aspects named above.

**Annotation**

The seminar is limited to a number of 20 participants due to capacity reasons. If necessary, a selection procedure will be carried out. Places will be allocated taking into account the students' academic progress. Details will be announced on the lecture website.

**Workload**

1. Attendance in Lecture Blocks for Engineering Theory:  $10 \cdot 2 \text{ h} = 20 \text{ h}$
2. Guided Seminar Work Block: 80 h
3. Preparation of exam: 20 h

A total of 120 h = 4 CR

**Recommendation**

Enjoyment and interest in industrial engineering and Computer-aided-X Technologies like e.g. 3D CAD, Robotics, Kinematic Simulations, VR, MR and AR-Technologies.

## M

**7.272 Module: Seminar Intelligent Industrial Robots [M-INFO-102212]****Responsible:** Prof. Dr.-Ing. Björn Hein**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |      |
|---------------|---|------|------|
| T-INFO-104526 | <a href="#">Seminar Intelligent Industrial Robots</a> | 3 CR | Hein |

**M****7.273 Module: Seminar New Components and Systems of Power Electronics [M-ETIT-100396]****Responsible:** Prof. Dr.-Ing. Marc Hiller**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 2       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-ETIT-100713 | <a href="#">Seminar New Components and Systems of Power Electronics</a> | 4 CR | Hiller |

**Prerequisites**

none

## M

**7.274 Module: Seminar Novel Concepts for Solar Energy Harvesting [M-ETIT-103447]****Responsible:** Prof. Dr. Bryce Sydney Richards**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 2       |

| Mandatory     |  |      |          |
|---------------|--|------|----------|
| T-ETIT-108344 | <a href="#">Seminar Novel Concepts for Solar Energy Harvesting</a> | 3 CR | Richards |

**Competence Certificate**

The examination consists of a written journal article and an oral presentation of the student's work, both given in English. The overall impression is rated.

**Prerequisites**

none

**Competence Goal**

After completion of the seminar, students are able to independently familiarize themselves with a new research topic, recapitulate the corresponding literature and present the topic in the form of a review journal article as well as an oral overview presentation. Besides the exposure to new scientific research topics, the students will develop their know-how in scientific presentations and scientific writing in English which are key competences for their future (e.g. MSc thesis projects and research).

**Content**

We are offering an advanced seminar on „Novel Concepts for Solar Energy Harvesting“ for students curious in latest research topics on devices, materials and physics of next generation solar energy harvesting. The students will get the opportunity to familiarize themselves with a state-of-the-art research topic of their choice under the guidance of a mentor and present the topic during the seminar. The students must attend the seminar regularly, present the research topic in a 30-min scientific talk and submit a short scientific paper (3-5 pages). The seminar addresses master students from electrical engineering, physics, mechanical engineering, material science, KSOP and related MSc programs.

**Module grade calculation**

The module grade results of the assessment of the written paper and the oral presentation. Details will be given during the lecture.

**Workload**

1. participation in the seminar lectures: 22,5 h
2. preparation of the seminar presentation: 50 h
3. preparation of the journal article: 47,5 h

**Recommendation**

Good knowledge of semiconductor components/optoelectronics is desirable.

## M

**7.275 Module: Seminar: Bionic Algorithms and Robot Technologies [M-MACH-106902]****Responsible:** Prof. Dr.-Ing. Arne Rönnau**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each term  | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-MACH-113842 | <a href="#">Seminar: Bionic Algorithms and Robot Technologies</a> | 3 CR | Rönnau |

**Competence Certificate**

See partial achievement

**Prerequisites**

None

**Competence Goal**

The aim is to work independently on a scientific topic in the field of biologically inspired algorithms and robot technologies.

Students are able to independently carry out a literature search on the state of research, summarize external work accurately, relate it to each other and evaluate it.

The results and content can be summarized in a seminar paper and an oral presentation.

Students are familiar with the DFG Code of Conduct "Guidelines for Safeguarding Good Scientific Practice" and apply these guidelines successfully in the preparation of their scientific work.

**Content**

Biologically inspired robots and their methods and technologies transfer concepts for problem solving from nature to mechanical design, sensor technology, navigation, control and interpretation, among other things. These solution approaches are approximated by technical systems. The spectrum of robotics inspired by biology ranges from multi-legged walking robots, distributed sensor concepts and lightweight construction to machine learning methods and neuromorphic hardware.

**Workload**

90h workload

- Literature research: 24h
- Elaboration of the seminar paper: 40h
- Preparation of the final presentation: 16h
- Attendance time: Kickoff, presentation and discussion as well as meeting with supervisors: 10h

**Recommendation**

The visit of the lecture "Biologically Inspired Robots" is helpful.

## M

## 7.276 Module: Sensors [M-ETIT-100378]

**Responsible:** Dr. Wolfgang Menesklou

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Mandatory Electives – General)  
 Field of Specialization in Mechatronics and Information Technology / Micro System Technology (Additive Electives )  
 Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 2       |

| Mandatory     |         |      |           |
|---------------|---------|------|-----------|
| T-ETIT-101911 | Sensors | 3 CR | Menesklou |



## M

**7.277 Module: Signal Processing Lab [M-ETIT-106633]****Responsible:** Prof. Dr.-Ing. Sander Wahls**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |                                       |      |       |
|---------------|---------------------------------------|------|-------|
| T-ETIT-113369 | <a href="#">Signal Processing Lab</a> | 6 CR | Wahls |

**Competence Certificate**

Success is assessed in the form of a written examination lasting 120 minutes.

**Prerequisites**

none

**Competence Goal**

After this module, students will have a sound basic knowledge of the main methods of signal processing as well as their areas of application, key parameters and the effects of parameter changes on the behavior of the methods. Students will be able to analyze given signal processing tasks in group work, develop solutions and document their results.

**Content**

The Digital Signal Processing practical course currently comprises eight experiments designed to familiarize students with the fundamentals of signal processing, in particular some selected measurement methods such as correlation measurement technology and modal analysis as well as Kalman filtering and the fundamentals of image processing. The focus of the experiments to be completed with various programs and devices is to teach students the practical aspects of modern signal processing.

Note: The lecturer reserves the right to include experiments other than those listed here in this practical course without prior notice.

**Module grade calculation**

The module grade is the grade of the written examination.

**Annotation**

A prerequisite for admission to the examination is the submission of protocols of all experiments. The quality of the protocols will be assessed; they must be acceptable for admission to the examination.

Attendance is compulsory during all practical sessions, including the introductory session. Admission to the examination will not be granted for even one unexcused absence.

**Workload**

The workload results from attending the introductory event (1.5 h), 8 experimental sessions of 4 h each. In addition, the preparation of the experiments is estimated at 8x4 h and the writing of the protocols as well as the follow-up work at 8x4 h. Preparing for the exam and attending it takes about 60 hours. This results in a total workload of approx. 160 hours.

**Recommendation**

Knowledge of the contents of the modules "Signals and Systems", "Measurement Technology" and "Methods of Signal Processing" is strongly recommended.

## M

## 7.278 Module: Signal Processing Methods [M-ETIT-106899]

|                      |  |
|----------------------|--|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Sander Wahls  |
| <b>Organisation:</b> | KIT Department of Electrical Engineering and Information Technology  |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics (Additive Electives )<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – Methodical )<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Mandatory Electives – General)<br>Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering (Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

|                |                      |                   |                 |                 |              |                |
|----------------|----------------------|-------------------|-----------------|-----------------|--------------|----------------|
| <b>Credits</b> | <b>Grading scale</b> | <b>Recurrence</b> | <b>Duration</b> | <b>Language</b> | <b>Level</b> | <b>Version</b> |
| 6              | Grade to a tenth     | Each winter term  | 1 term          | English         | 4            | 1              |

|                  |                           |      |       |
|------------------|---------------------------|------|-------|
| <b>Mandatory</b> |                           |      |       |
| T-ETIT-113837    | Signal Processing Methods | 6 CR | Wahls |

**Competence Certificate**

Written exam, approx. 120 minutes.

**Prerequisites**

none

**Competence Goal**

Students can

- choose appropriate estimation methods based on theoretical properties and practical considerations
- determine estimators for specific problems
- can weight the pros and cons of data decomposition methods; apply them to given problems; interpret the results
- understand the advantages and limitations of the considered time-frequency analysis methods
- interpret time-frequency representations
- choose appropriate analysis and synthesis windows/wavelets
- determine time-frequency transforms of given signals

**Content**

This module introduces students to advanced signal processing methods that are widely employed in engineering. The three main topic areas are

1. Parameter estimation
2. Decomposition of data into components and modes
3. Time-frequency analysis

The following topics are treated:

- Best linear unbiased estimator
- Maximum likelihood estimation
- General Bayesian estimators
- Linear Bayesian estimators
- Principal component analysis
- Independent component analysis
- Dynamic and empirical mode decomposition
- Hilbert spaces and frames
- Short-time Fourier transform
- Wavelets
- Analytic signals
- Wigner-Ville-Distribution
- Huang-Hilbert transform

Illustrating examples from diverse application areas are discussed.

**Module grade calculation**

The module grade is the grade of the written exam.

**Workload**

The workload includes:

1. attendance in lectures and tutorials:  $15 \cdot 4 \text{ h} = 60 \text{ h}$
2. preparation / follow-up:  $15 \cdot 4 \text{ h} = 60 \text{ h}$
3. preparation of and attendance in examination: 60 h

A total of 180 h = 6 CR

**Recommendation**

Familiarity with signals and systems (in particular, Fourier transforms) and probability theory at the Bachelor level is assumed.

## M

## 7.279 Module: Signal Processing with Nonlinear Fourier Transforms and Koopman Operators [M-ETIT-106675]

**Responsible:** Prof. Dr.-Ing. Sander Wahls

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-113428 | <a href="#">Signal Processing with Nonlinear Fourier Transforms and Koopman Operators</a> | 6 CR | Wahls |

### Competence Certificate

The examination in this module consists of programming assessments and a graded written examination of 120 minutes.

The programming assignments are either pass or fail. They must be passed during the lecture period for admission to the written examination.

### Prerequisites

none

### Competence Goal

Students

- understand the basic theory of linear operator on Hilbert spaces and can analyze simple operators analytically
- know the use cases for selected integrable partial differential equations (PDEs) and can apply them under non-ideal circumstances (small non-integrable terms)
- can determine the PDE corresponding to a given Lax-pair and check if the PDE is actually integrable (i.e. check if the Lax pair is “fake”)
- understand the theory of nonlinear Fourier analysis for selected PDEs and can compute nonlinear (inverse) Fourier transforms numerically and, in simple cases, analytically
- know and implement practical engineering applications of nonlinear Fourier transforms
- understand the theory of the Koopman operator including selected engineering applications
- compute Koopman spectra numerically using data-driven methods and use them in practical engineering applications

### Content

This module introduces students to signal processing methods that rely on nonlinear Fourier transforms and Koopman operators. These methods allow us to transform large classes of nonlinear systems such that they essentially behave like linear systems. They can also be used to decompose signals driven by such systems into physically meaningful nonlinear wave components (for example, solitons).

While these methods originated in mathematical physics, there has been a growing interest of exploiting their unique capabilities in engineering contexts. The goal of this module is to give engineering students a practical introduction to this area. It provides the necessary theoretical background, enables students to apply the methods in practice via computer assignments, and discusses recent research from the engineering literature.

The following topics will be discussed:

- Introduction to linear operators on Hilbert spaces
- Integrable model systems (Korteweg-de Vries equation, Nonlinear Schrödinger equation)
- Lax-integrable systems (representations of Lax pairs, fake Lax pairs, conserved quantities)
- Solution of integrable model systems using nonlinear Fourier transforms (inverse scattering method) and the unified transform method
- Physical interpretation of nonlinear Fourier spectra (in particular, solitons)
- Practical applications of nonlinear Fourier transforms
- Theoretical properties of Koopman operators
- Data-driven computation of Koopman operators (residual dynamic mode decomposition)
- Practical applications of Koopman operators

**Module grade calculation**

The module grade is the grade of the written exam.

**Annotation**

Some tutorial sessions will be classically devoted to solving pen and paper problems, but in others students will be working on their practical computer assignments. For the latter, students have to bring their own laptops with Matlab installed. The solutions of the computer assignments must be submitted by the provided deadlines, which are typically one week after the corresponding tutorial has taken place.

**Workload**

The workload includes:

1. attendance in lectures and tutorials:  $15 \cdot 4 \text{ h} = 60 \text{ h}$
2. preparation / follow-up:  $30 \cdot 3 \text{ h} = 60 \text{ h}$
3. finishing programming assignments: 30 h
4. preparation of and attendance in examination: 30 h

A total of 180 h = 6 CR

**Recommendation**

Familiarity with signals and systems at the Bachelor level (Fourier and Laplace transforms, linear systems, etc.) is assumed.

## M

**7.280 Module: Simulation and Optimization in Robotics and Biomechanics [M-INFO-106504]****Responsible:** Prof. Dr. Katja Mombaur**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives\)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-INFO-113123 | <a href="#">Simulation and Optimization in Robotics and Biomechanics</a> | 6 CR | Mombaur |

**Competence Certificate**

See partial achievements (Teilleistung)

**Prerequisites**

See partial achievements (Teilleistung)

**Competence Goal**

The students

- can explain advanced principles of modeling, optimization and control of dynamic processes, in particular mechanical systems and can apply them
  - can model, classify and analyze complex motions in robotics or biomechanics, and investigate specific properties such as stability.
  - can apply nonlinear optimization and optimal control methods and can compare and evaluate different mathematical approaches.
  - know how to use software tools based on C++ and Lua for modeling, simulation, optimization and visualization of humanoid and robotic systems
- are capable of solving optimal control problems numerically and to evaluate the quality of the solution.

**Content**

The goal of this course is to give a practical introduction into simulation and optimization of motions in robotics and biomechanics. Simulation and optimization play an important role in generating and controlling motions in complex robotics systems and in predicting and analyzing motions of humans. Theory and methods will be covered, but the focus is on the use software tools for modeling, simulation, optimization and visualization of multibody systems. Topics covered include:

- Dynamic process modeling
- Transforming real world problems into mathematical models
- Modeling of complex robotics and biomechanics systems (e.g. humanoids), based on previous modeling knowledge
- Common template models for bipedal walking and running in robotics and biomechanics
- Simulation of mechanical / robotics systems (Integrators and Initial value problems)
- Boundary value problems
- Nonlinear optimization problems
- Optimal control problems
- Direct and indirect methods for optimal control problems, focus on direct methods, especially direct multiple shooting
- Stability of dynamical systems, stability in biomechanics and robotics

**Annotation**

Limitation to 30 participants

**Workload**

Estimated effort for this module is 180 hours:

60h - Lecture and exercises (2+2 SWS)

80h - Independent work (repetition of lecture contents, preparation of assignments)

40h - Exam preparation

## M

**7.281 Module: Simulation with Lumped Parameters [M-MACH-107053]****Responsible:** Prof. Dr.-Ing. Marcus Geimer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Mandatory Electives – Methodical \)](#)[Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Mandatory Electives – General\)](#)[Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-113862 | <a href="#">Simulation with Lumped Parameters</a>          | 3 CR | Geimer |
| T-MACH-113863 | <a href="#">Tutorial Simulation with Lumped Parameters</a> | 1 CR | Geimer |

**Competence Certificate**

Success is assessed in the form of an oral examination (20 minutes) during the lecture-free period of the semester. The examination is offered every semester and can be repeated at any regular examination date.

Prior registration is required; details will be announced on the website of the *Institute of Vehicle Systems Engineering / Institute of Mobile Machinery*. If there are too many interested students, a selection will be made among all interested students according to qualification.

**Prerequisites**

see individual course

**Competence Goal**

After completing this part of the course, students will be able to evaluate how a simulation with concentrated parameters can be used sensibly and which simulation methods are suitable for a given problem. They can create a model for a problem and can explain and implement algorithms for solving a model. You will acquire in-depth knowledge of how a system can be modelled and parameterized with concentrated parameters. You will be able to carry out simulation studies, evaluate simulation results and recognize and avoid errors in the simulation.

**Content**

The basics of discrete-time modeling are taught using the example of simulation with concentrated parameters. For this purpose, modeling in the disciplines of mechanics, electrics and hydraulics is shown by way of example and analogies are drawn. Furthermore, possibilities for simulation coupling of the disciplines are shown. The students solve exemplary tasks with the help of simulation and briefly summarize the solutions in a report.

**Module grade calculation**

see individual course

**Annotation**

Basic knowledge of Matlab/Simulink and hydraulics.

Knowledge of the dynamics of mechanical systems and the fundamentals of electrical engineering is assumed.

**Workload**

- Attendance time: 21 hours
- Self-study: 99 hours

**Recommendation**

- Knowledge of ProE (ideally in the current version)
- Basic knowledge of Matlab/Simulink
- Basic knowledge of machine dynamics
- Basic knowledge of hydraulics

## M

## 7.282 Module: Software Engineering [M-ETIT-100450]

**Responsible:** Dr. Clemens Reichmann

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 4       |

| Mandatory     |                                      |      |           |
|---------------|--------------------------------------|------|-----------|
| T-ETIT-108347 | <a href="#">Software Engineering</a> | 3 CR | Reichmann |

**Prerequisites**

none



## M

**7.283 Module: Solar Energy [M-ETIT-100524]**

**Responsible:** Prof. Dr. Bryce Sydney Richards  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |                              |      |          |
|---------------|------------------------------|------|----------|
| T-ETIT-100774 | <a href="#">Solar Energy</a> | 6 CR | Richards |

**Competence Certificate**

Type of Examination: written exam

Duration of Examination: 120 Minutes

Modality of Exam: One written exam at the end of each semester.

**Prerequisites**

Students are not allowed to take „Photovoltaik“ (M-ETIT-100513) in addition to this one.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The module [M-ETIT-100513 - Photovoltaics](#) must not have been started.

**Competence Goal**

The students:

- understand the basic working principle of pn-junction solar cells,
- learn about the different kinds of solar cells (crystalline and amorphous silicon, CIGS, Cadmium telluride, organic, dye-sensitized solar cells, etc.),
- get an overview over upcoming third-generation photovoltaic concepts,
- receive information on photovoltaic modules and module fabrication,
- develop an understanding of solar cell integration and feeding the electrical power to the grid,
- get insight into solar concentration and tandem solar cells for highly efficient energy conversion,
- compare photovoltaic energy harvesting with solar thermal technologies
- understand the environmental impact of solar energy technologies.

Die Studentinnen und Studenten können in englischer Fachsprache sehr gut kommunizieren.

**Content****I. Introduction: The Sun****II. Semiconductor fundamentals****III. Solar cell working principle****IV. First Generation solar cells: silicon wafer based****V. Second Generation solar cells: thin films of amorphous silicon, copper indium gallium diselenide, cadmium telluride, organic photovoltaics and dye sensitized solar cells****V. Third Generation Photovoltaics: high-efficiency device concepts incl. tandem solar cells****VI. Modules and system integration****VII. Cell and module characterization techniques****VIII. Economics, energy pay-back time, environmental impact****IX. Other solar energy harvesting processes, incl. thermal and solar fuels****X. Excursion****Module grade calculation**

The module grade is the grade of the written exam.

**Workload**

Total 180 h, thereof 60h contact hours (45h lecture, 15h problems class), and 120h homework and self-studies

**Recommendation**

Knowledge of optoelectronics is a prerequisite, e.g. M-ETIT-100480 – Optoelektronik.

**Literature**

P. Würfel: Physics of Solar Cells

V. Quaschnig: Renewable Energy Systems

C. Honsberg and S. Bowden, PV Education CD-ROM and website, <http://www.pveducation.org/pvcdrom>

## M

**7.284 Module: Solar Thermal Energy Systems (Sp-STES) [M-MACH-101924]****Responsible:** apl. Prof. Dr. Ron Dagan**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 3       |

| Mandatory     |  |      |       |
|---------------|--|------|-------|
| T-MACH-106493 | <a href="#">Solar Thermal Energy Systems</a> | 4 CR | Dagan |

**Competence Certificate**

oral exam of about 30 minutes

**Prerequisites**

None

**Competence Goal**

The students

get familiar with the global energy demand and the role of renewable energies

learn about improved designs for using efficiently the potential of solar energy

gain basic understanding of the main thermal hydraulic phenomena which support the work on future innovative applications

will be able to evaluate quantitatively various aspects of the thermal solar systems

**Content**

I. Introduction to solar energy: Energy resources, consumption and costs

II. The sun as an energy resource:

Structure of the sun, Black body radiation, solar constant, solar spectral distribution

Sun-Earth geometrical relationship

III. Passive and active solar thermal applications.

IV. Fundamentals of thermodynamics and heat transfer

V. Solar thermal systems - solar collector-types, concentrating collectors, solar towers. Heat losses and efficiency

VII. Energy storage

The course deals with fundamental aspects of solar energy. Starting from a global energy panorama the course deals with the sun as a thermal energy source. In this context, basic issues such as the sun's structure, blackbody radiation and solar-earth geometrical relationship are discussed. In the next part, the lectures cover passive and active thermal applications and review various solar collector types including concentrating collectors and solar towers and the concept of solar tracking. Further, the collector design parameters determination is elaborated, leading to improved efficiency. This topic is augmented by a review of the main laws of thermodynamics and relevant heat transfer mechanisms.

The course ends with an overview on energy storage concepts which enhance practically the benefits of solar thermal energy systems.

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

Total 90 h, hereof 30 h contact hours and 60 h homework and self-studies

**Learning type**

Lecture, tutorial

**Literature**

Foster, Ghassemi, cota,; Solar Energy

Duffie and Beckman; Solar engineering of thermal processes

Holman.; Heat transfer

Heinzel; script to solar thermal energy (in German)

## M

**7.285 Module: Spaceborne Radar Remote Sensing [M-ETIT-103042]****Responsible:** Prof. Dr.-Ing. Thomas Zwick**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 2       |

| Mandatory     |  |      |                |
|---------------|--|------|----------------|
| T-ETIT-112857 | <a href="#">Spaceborne Radar Remote Sensing - Exam</a>     | 4 CR | Moreira, Prats |
| T-ETIT-112858 | <a href="#">Spaceborne Radar Remote Sensing - Workshop</a> | 2 CR | Younis         |

**Competence Certificate**

The assessment takes place in the form of a written examination lasting 120 min. and in the form of reports (other types of examination). Those reports have to be submitted as part of the SAR computer workshop (approx. a total of five workshops). Details will be given during the lecture.

**Prerequisites**

"M-ETIT-100426 - Spaceborne SAR Remote Sensing" is not allowed to be started or to be completed.

**Competence Goal**

The students obtain a sound knowledge on the fundamentals, theory and applications of spaceborne radar systems. They understand the principle and function of synthetic aperture radars (SAR). They are able to explain the theory, techniques, algorithms for data processing and system concepts as well as to report on several application examples.

**Content**

The lecture is interdisciplinary and well suited for students interested in learning different aspects of the entire end-to-end system chain of spaceborne radar systems. Today, Synthetic Aperture Radar (SAR) systems are generating images of the Earth's surface with a resolution better than 1 meter. Due to their ability to produce high-resolution radar images independent of sunlight illumination and weather conditions, SAR systems have demonstrated their outstanding capabilities for numerous applications, ranging from environmental and climate monitoring, generation of three-dimensional maps, hazard and disaster monitoring as well as reconnaissance and security related applications. We have entered a new era of spaceborne and airborne SAR systems. New satellite systems like TerraSAR-X and TanDEM-X provide radar images with a resolution cell of more than a hundred times better than the one of conventional SAR systems. The lecture will cover all aspects of spaceborne radar systems including an overview of new technologies, applications and future developments.

Supporting the main lecture, exercise assignments are distributed to the students. The exercise solutions are presented and discussed in detail during lecture hall exercises. Further dedicated topics are explained to deepen the understanding of the main lecture contents.

The aim of the computer-workshop is to gain practical experience on radar systems using data and parameter simulations which are based on the evaluation of simplified models.

**Module grade calculation**

The module grade results of the assessment of the exam (4 LP) and the reports (2 LP).

**Annotation**

Further information can be found at the internet page of the IHE (<https://s.kit.edu/ihe-srrs>).

**Workload**

Each credit point corresponds to approximately 25-30 hours of work (of the student). This is based on the average student who achieves an average performance. Workload (for a lecture)

Attendance time in lectures, exercises: 60 h

Present study time computer exercise: 40 h

Self-study time including exam preparation: 80 h

A total of 180 h = 6 LP

**Recommendation**

Signal processing and radar fundamentals.

**Literature**

Lecture viewgraphs, reading material, and literature references can be found on ILIAS at <https://s.kit.edu/srrs>.

**M****7.286 Module: Stochastic Information Processing (24113) [M-INFO-100829]**

**Responsible:** Prof. Dr.-Ing. Uwe Hanebeck  
**Organisation:** KIT Department of Informatics  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Additive Electives\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Additive Electives\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives\)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |          |
|---------------|---|------|----------|
| T-INFO-101366 | <a href="#">Stochastic Information Processing</a> | 6 CR | Hanebeck |

**M****7.287 Module: Strategic Product Development - Identification of Potentials of Innovative Products [M-MACH-107140]**

**Responsible:** Prof. Dr.-Ing. Andreas Siebe  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |                           |
|---------------|--|------|---------------------------|
| T-MACH-105696 | <a href="#">Strategic Product Development - Identification of Potentials of Innovative Products</a>              | 3 CR | Siebe                     |
| T-MACH-110396 | <a href="#">Strategic Product Development - Identification of Potentials of Innovative Products - Case Study</a> | 1 CR | Albers, Matthiesen, Siebe |

**Competence Certificate**

See individual course

**Prerequisites**

None

**Competence Goal**

After attending the lecture, the student will be able to ...

- discuss the importance and objectives of future management in product planning.
- analyze and evaluate different approaches to strategic product planning in context.
- explain the procedure of scenario-based strategic product planning.
- illustrate the scenario-based strategic product planning approach using examples.

**Content**

Introduction into future management, Development of scenarios, scenariobased strategy development, trendmanagement, strategic early detection, innovation- and technologymanagement, scenarios in product development, from profiles of requirements to new products, examples out of industrial praxis.

**Module grade calculation**

The module grade corresponds to the grade from the graded individual course

**Annotation**

None

**Workload**

Attendance: 20h

Self-study: 100h

**Recommendation**

None

**Learning type**

Lecture, Case Study

**Literature**

None

**Base for**

None

## M

**7.288 Module: Structural Materials [M-MACH-100291]****Responsible:** Dr.-Ing. Stefan Guth**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |                                      |      |      |
|---------------|--------------------------------------|------|------|
| T-MACH-100293 | <a href="#">Structural Materials</a> | 6 CR | Guth |

**Competence Certificate**

oral exam about 25 minutes



## M

## 7.289 Module: Student Innovation Lab [M-ETIT-105073]

**Responsible:** Prof. Dr.-Ing. Sören Hohmann  
 Prof. Dr. Werner Nahm  
 Prof. Dr.-Ing. Eric Sax  
 Prof. Dr. Wilhelm Stork  
 Prof. Dr. Orestis Terzidis  
 Prof. Dr.-Ing. Thomas Zwick

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Autonomous Systems and AI \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 15      | Grade to a tenth | Each term  | 2 terms  | English  | 4     | 2       |

| Mandatory     |  |      |                                  |
|---------------|--|------|----------------------------------|
| T-ETIT-110291 | <a href="#">Innovation Lab</a>               | 9 CR | Hohmann, Nahm, Sax, Stork, Zwick |
| T-WIWI-102864 | <a href="#">Entrepreneurship</a>             | 3 CR | Terzidis                         |
| T-WIWI-110166 | <a href="#">SIL Entrepreneurship Project</a> | 3 CR | Terzidis                         |

**Competence Certificate**

This module consists of an approx. 60-minute written exam on the contents of the Entrepreneurship lectures, as well as 5 other types of exams on the contents of the seminar Entrepreneurship and Innovation Lab in the form of term papers and presentations. All exams results are graded.

In addition, smaller, ungraded term papers are due during the course to monitor progress.

**Prerequisites**

none

**Competence Goal****Personal competence**

- Reflection faculty:  
The students are able to analyze, evaluate and develop an alternative for action for certain elements of action in social interaction
- Decision-making ability:  
The students are able to prepare a decision template in time and to provide the necessary arguments for alternative decisions and therefore are able to decide in time.
- Interdisciplinary teamwork  
Students are able to detect their limits of competence in one domain and to adjust to a the non-specialist domain. The students are able to detect a lack in competence and to compensate this lack via competences of other team members. The students are able to communicate their domain-specific knowledge and develop a basic understanding of other domains.
- Value-based action:  
The students are able to use selected psychological tools to determine their own values. They are able to match these values with team members and reflect if their offer fits these values.

**Social competence**

- Ability to cooperate:  
The students are able to analyze and judge their cooperative behavior in a group.
- Communication competence:  
The students are able to present their information in persuasive, focused and target group oriented way.
- Ability to deal with conflicts:  
The students are able to detect conflicts in advance, analyze them and name solution concepts.

**Innovation and entrepreneurship competence**

- Agile product development:  
The students are able to apply methods of agile product development e.g. Scrum.
- Methodical innovation retrieval:  
The students are able to conduct processes for user- and technology-centered innovation to develop sustainable value propositions for certain target groups (e.g. Design Thinking (DT), Technology Application Selection (TAS)- process).
- Orientation on management of new technology-based firms (NTBF):  
The students are able to name central concepts of intellectual property and legal structures. The students are able to name the most important tasks of entrepreneurial leadership. They are able to name the most common form of business modeling and to setup a business plan. The students know important approaches to establish an organization. The students are able to determine the ownership structure in an investment situation. The students are able to name marketing concepts and setup a business model.
- Generate investment readiness:  
The students are able to setup rudimentary revenue and cost plan. Furthermore, they are able to establish a project plan for a company in order to derive an investment plan. The students are able to present their business proposal to investors and develop empathy for the investors.
- Competence to develop a business model:  
The students are able to apply respective tools for business modeling e.g. Business Model Canvas. The students are able to develop and assess alternative business models.
- Risk handling:  
The students are able to name basic risks w.r.t. requirements, technical limitations and profitability. The students are able to apply methods of customer interaction for evaluation of requirements and willingness to pay. The students are able to setup a rudimentary competitors analyze. The students are able to name and identify risks and present potential reactions.

**Systemic technical competence**

- Problem solution competence:  
The students are able to analyze, assess and structurally solve a technical problem.
- Agile methodology of system development:  
The students are able to name and apply different system development processes.
- Validation in volatile environment:  
The students are able to conduct technical and economical validation under volatile constraints. For this, they are able to name the constraints and interpret the results of the validation.
- Functional decomposition:  
The students are able to identify, interpret and derive functional requirements from complex customer needs.
- Architecture development:  
The students are able to recognize coherences from the functional requirements and derive a suitable system architecture.

## Content

This module strives to combine technical, social and personal competences from the technical and entrepreneurial domain. The objective is to prepare students as best as possible for entrepreneurial activity within or outside of an established organization. Our teaching methods are research-based with a practical orientation.

The lecture Entrepreneurship as the essential component offers the theoretical basis and provides insight in important theoretical concepts and empirical evidence. Currently released case studies and practical experiences of successful founders support the theoretical and empirical content. In order to run a company for the long term additional knowledge is important. That's why the lecture also teaches basic principles for opportunity recognition, business modeling, an introduction to entrepreneurial marketing and leadership. Customer-based design methods from the lean startup approach as well as methods of technology-centered innovation are presented. Future founders have to be able to develop and handle resources such as financial and human capital, infrastructure and intellectual property. Further aspects tackle the establishment of an organization and funding of the own project.

The knowledge taught in the lecture Entrepreneurship will be applied in an application-oriented seminar and the labs. Hence we use an action learning approach to extend the taught knowledge by practical skills and reflection capabilities. In an team of five, the students will experience their way from the ideation process to the final pitch in front of investors.

The students are able to choose between the following options concerning the labs:

- The Automation Innovation Lab offers drones as an innovation platform for cooperative swarm solutions.
- The Industry 4.0 Innovation Lab enables innovation in the context of the next industrial revolution via mobile robot platforms.
- In the Interconnected Intelligent Systems Lab innovations in the context of Assisted Living and Smart Housing are enabled by providing a rich assembly set of mobile robots, actuators and sensors.
- The Computer Vision for Health Lab offers a selection of state-of-the-art imaging devices and powerful computing hardware for innovative image-based applications for medicine and healthcare.

The module also presents methods of agile system development (Scrum) along with associated validation methods as well as methods for functional prototyping. Gate plans are used within the module to determine the progress of the project. Methods for single person work and teamwork are presented and applied. Additionally group-specific knowledge of the different roles of team members, solutions to conflict situations and interdisciplinary teams are presented.

## Module grade calculation

The module grade consists of the written exam of the Lecture Entrepreneurship (40%), of the submissions and presentation of the Innovation Lab (40%) and of the submissions and presentation of the SIL Entrepreneurship Project (20%).

## Annotation

**An application is required to participate in this module. Information about the application:** [www.kit-student-innovation-lab.de](http://www.kit-student-innovation-lab.de).

## Workload

**Lecture Entrepreneurship:** 32h attendance time, 48h preparation and follow-up time, 10h preparation time for assessment

**Seminar Entrepreneurship:** 34h attendance time, 3h preparation and follow-up time, 53h preparation time for assessment.

**Innovation Lab:** 8h attendance time, 213h preparation and follow-up time, 49h preparation time for assessment.

This results in a total of 450 hours and a total of 15 LPs for both semesters ( $15 \cdot 30/2 = 225$ ).

## Recommendation

It is recommended to attend the lecture Entrepreneurship at the same time as the seminar Entrepreneurship Project and the Innovation Lab in the winter semester.

## Learning type

### Related courses:

Lecture Entrepreneurship

Seminar Entrepreneurship Project

Innovation Labs

Please note that the courses must be booked in parallel.

### Related exams:

Written exams covering the content of lecture Entrepreneurship

Presentation of the Value Profile (seminar Entrepreneurship)

Submission of the Business Plan (seminar Entrepreneurship)

Submission of a Technical Report with requirements list and system architecture (Innovation Lab)

Submission of the reflection of the Gate Plans (Innovation Lab)

Presentation of the High-fidelity (Innovation Lab)

## M

**7.290 Module: Superconducting Magnet Technology [M-ETIT-106684]****Responsible:** Prof. Dr. Tabea Arndt**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-ETIT-113440 | <a href="#">Superconducting Magnet Technology</a> | 4 CR | Arndt |

**Competence Certificate**

The examination takes place in form of an oral exam (abt. 30 minutes).

Two timeslots (weeks) for examination dates will be announced (usually near end of lecture period & end of semester)

**Prerequisites**

none

**Competence Goal**

- The students have a solid knowledge of architecture and design aspects of applications in magnets, windings and coils in power engineering.
- For the most important magnet applications the students can apply the state of the art, choose between options and can reflect the main benefits.
- The students have a clear understanding of opportunities, benefits and limitations of superconducting windings and magnets.
- The students are able to perform the required design calculations and to solve fundamental design questions independently.

**Content**

As the materials become increasingly mature and powerful, using superconductivity in a variety of applications of electrical engineering is of rising interest and benefit, too. This module is focuses on Superconducting Magnet Technology:

Windings, coils and magnets may be used as a device by itself (providing high magnetic fields e.g. in MRI, NMR, accelerators, industry magnets, etc.) or as components for Power Systems.

This section will cover the following aspects:

- Unique selling points of superconducting windings.
- Basic approaches and tools to design superconducting windings.
- Discussion of winding architectures
- Criteria to design the appropriate operating temperatures, materials, conductors, cooling technology for the electromagnetic purpose.
- Limits and opportunities when preparing and operating superconducting windings.
- Measures for safe operation of superconducting magnets.
- High-Field Magnets
- Magnets for Fusion Technology
- 3D topologies (e.g. in dipole magnets or motors/ generators)
- New options potentially offered by widespread use of hydrogen.
- New winding topologies

In the exercises, selected magnets will be designed and calculated analytically and with some computational tools (e.g. dipole magnets and compact, cryogen free HTS-magnets)

The lecturer may change the details of the content without further notice. Materials will be offered on ILIAS.

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

1. attendance in lectures and exercises:  $15 \cdot 3 \text{ h} = 45 \text{ h}$
2. preparation / follow-up:  $15 \cdot 3 \text{ h} = 45 \text{ h}$
3. preparation of and attendance in examination: 30 h

A total of 120 h = 4 CR

**Recommendation**

Having knowledge in "Superconducting Materials" is beneficial, but not mandatory.

## M

**7.291 Module: Superconducting Power Systems [M-ETIT-106683]****Responsible:** Prof. Dr.-Ing. Mathias Noe**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)**Credits**  
4**Grading scale**  
Grade to a tenth**Recurrence**  
Each winter term**Duration**  
1 term**Language**  
English**Level**  
4**Version**  
1

| Mandatory     |   |      |     |
|---------------|---|------|-----|
| T-ETIT-113439 | <a href="#">Superconducting Power Systems</a> | 4 CR | Noe |

**Competence Certificate**

The examination takes place in form of an oral exam (abt. 45 minutes).

**Prerequisites**

none

**Competence Goal**

- The students have a solid knowledge of architecture and design aspects of applications in windings and energy technology devices.
- For the most important power system applications the students can apply the state of the art and can reflect the main benefits.
- The students have a clear understanding of opportunities, benefits and limitations of superconducting components and devices.
- The students are able to perform the required design calculations and to solve fundamental design questions independently.

**Content**

As the materials become increasingly mature and powerful, using superconductivity in a variety of applications of electrical engineering is of rising interest and benefit, too. This module focuses on Superconducting Power Systems.

It will provide an overview of the state of the art, will give an insight into the basic setup, the design, the characteristic parameters and the specific operation behaviour of the following applications:

- Power Transmission Cables and Lines
- Motors and Generators
- Transformers
- Fault Current Limiters
- Magnetic Energy Storage
- Basics of Cryo Technology

For each application a design example is shown and the focus is given on the conceptual design of each application.

The lecturers may change the details of the content without further announcement.

Materials will be offered on ILIAS.

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

1. attendance in lectures and exercises: 15\*3 h = 45 h
2. preparation / follow-up: 15\*3 h = 45 h
3. preparation of and attendance in examination: 30 h

A total of 120 h = 4 CR

**Recommendation**

Having knowledge in „Superconducting Materials“ is beneficial.

Successful participation in „Superconductivity for Engineers“

## M

**7.292 Module: Sustainable Product Engineering: Sustainable Product Design -  
Long-term Business Success with Sustainably Developed Products [M-  
MACH-107189]****Responsible:** Dr.-Ing. Karl-Friedrich Ziegahn**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |         |
|---------------|---|------|---------|
| T-MACH-114033 | <a href="#">Sustainable Product Engineering</a> | 4 CR | Ziegahn |

**Competence Certificate**

See partial performance

**Prerequisites**

None

**Competence Goal**

Students are able to ...

- name and describe key points of sustainable product development in an economic, social and ecological context, as well as sustainability goals and their significance in product development, interactions between technical products and their environment, the holistic approach and the equal importance of economic, social and ecological aspects as well as environmental performance characteristics.
- discuss life cycle-related product design using the example of complex vehicle components such as airbag systems and other current products.
- understand practical product stresses caused by environmental conditions using the example of technology-intensive components; robustness and service life of products as the basis for sustainable product development; development of skills for the application of environmental simulation in the development process of technical products.
- To develop key qualifications such as teamwork / project planning / self-organization / presentation using realistic projects.

**Content**

Understanding of sustainability goals and their importance in product development, the interactions between technical products and their environment, the holistic approach and the equal importance of economic, social and ecological aspects as well as environmental performance characteristics

Teaching life cycle-related product design skills using the example of complex vehicle components such as airbag systems and other current products

Understanding of practical product stresses caused by environmental conditions using the example of technology-intensive components; robustness and service life of products as the basis for sustainable product development; development of skills for the application of environmental simulation in the development process of technical products

Promotion of the development of key qualifications such as teamwork / project planning / self-organization / presentation based on realistic projects

The aim of the course is to convey the key points of sustainable product development in an economic, social and ecological context.

**Module grade calculation**

The module grade corresponds to the grade from the partial performance.

**Annotation**

None

**Workload**

Attendance: 30h

Self-study: 90h

7 MODULES

Module: Sustainable Product Engineering: Sustainable Product Design -  
Long-term Business Success with Sustainably Developed Products [M-  
MACH-107189]

**Recommendation**

None

**Learning type**

Lecture

**Literature**

None

**Base for**

None



**M****7.293 Module: System Integration and Communication Structures in Industry 4.0 and IoT [M-ETIT-106026]****Responsible:** Prof. Dr.-Ing. Jürgen Becker**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |        |
|---------------|---|------|--------|
| T-ETIT-112212 | <a href="#">System Integration and Communication Structures in Industry 4.0 and IoT</a> | 3 CR | Becker |

**Prerequisites**

none

**M****7.294 Module: System Integration in Micro- and Nanotechnology [M-MACH-105315]****Responsible:** apl. Prof. Dr. Ulrich Gengenbach**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |            |
|---------------|---|------|------------|
| T-MACH-105555 | <a href="#">System Integration in Micro- and Nanotechnology</a> | 4 CR | Gengenbach |

**Competence Certificate**

A performance assessment is obligatory and can be oral, a written exam, or of another kind.

**Prerequisites**

None

**Competence Goal**

The students acquire basic knowledge of challenges and system integration technologies from mechanical engineering, precision engineering and electronics

**Content**

- Introduction to system integration (fundamentals)
- Brief introduction to MEMS processes
- Flexures
- Surfaces and plasma processes for surface treatment
- Adhesive bonding in engineering
- Mounting techniques in electronics
- Molded Interconnect devices (MID)
- Functional Printing
- Low temperature cofired ceramics in system integration
- 3D-Integration in semiconductor technology

**Workload**

The work load is about 120 hours, corresponding to 4 credit points.

**Learning type**

Lecture

**Literature**

- Risse, Fertigungsverfahren der Mechatronik, Feinwerk- und Präzisionsgerätetechnik, Vieweg+Teubner Verlag, Wiesbaden, 2012
- Madou, Fundamentals of microfabrication and nanotechnology, CRC Press Boca Raton, 2012
- Habenicht, Kleben Grundlagen, Technologien, Anwendungen, Springer-Verlag Berlin Heidelberg, 2009
- J. Franke, Räumliche elektronische Baugruppen (3D-MID), Carl Hanser-Verlag München, 2013

**M****7.295 Module: System Integration in Micro- and Nanotechnology 2 [M-MACH-105316]****Responsible:** apl. Prof. Dr. Ulrich Gengenbach**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |            |
|---------------|---|------|------------|
| T-MACH-110272 | <a href="#">System Integration in Micro- and Nanotechnology 2</a> | 4 CR | Gengenbach |

**Competence Certificate**

A performance assessment is obligatory and can be oral, a written exam, or of another kind.

**Prerequisites**

None

**Competence Goal**

The students acquire knowledge of novel system integration technologies and their application in microoptic and microfluidic systems.

**Content**

Introduction to system integration (novel processes and applications)

Assembly of hybrid microsystems

Packaging processes

Applications:

- Micro process engineering
- Lab-on-chip systems
- Microoptical systems
- Silicon Photonics

Novel integration processes:

- Direct Laser Writing
- Self Assembly

**Workload**

The work load is about 120 hours, corresponding to 4 credit points.

**Learning type**

Lecture

**Literature**

- N.-T. Nguyen, Fundamentals and Applications of Microfluidics, Artech House
- G. T. Reed, Silicon Photonics: An Introduction, Wiley

## M

**7.296 Module: System-on-Chip Laboratory [M-ETIT-100451]**

**Responsible:** Prof. Dr.-Ing. Jürgen Becker  
Prof. Dr. Ivan Peric

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Micro System Technology \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 6       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |               |
|---------------|---|------|---------------|
| T-ETIT-100798 | <a href="#">System-on-Chip Laboratory</a> | 6 CR | Becker, Peric |

**Competence Certificate**

Other types of examinations

**Prerequisites**

none

**Competence Goal**

Students can reproduce basic knowledge of digital and analog circuit design and hardware-related software programming. In practice, students are able to apply these methods in the following areas using a current system-on-chip architecture:

- Design of a system architecture for mixed-signal systems
- Simulation of the designed digital and analog circuits
- Debugging the implementations at the simulation and implementation level
- Verification of the overall system developed through test benches

In addition, they can apply the hardware / software code design approach and can evaluate implementation targets based on the given requirements (FPGA and ASIC).

**Content**

In the System-on-Chip Laboratory, a fully-fledged mixed-signal hardware architecture for audio playback based on a system-on-chip (SoC) is developed.

The system design includes the creation of necessary sub-components, their integration into an overall system, and the simulation and verification of the individual components and the overall system. A prototype is implemented and tested on an FPGA basis. The integration is then prepared for a possible ASIC production. Analog circuits are also considered and designed to build an audio amplifier.

**Module grade calculation**

The grade formation results from the combination of the processing of the exercise sheets, the evaluations during the internship and a final presentation including discussion of the results developed in the project.

**Workload**

1. Presence time in laboratory appointments:  $15 * 4 = 60$  hours
2. Preparation / post-processing:  $15 * 4 = 60$  hours
3. Demonstration and integration tests:  $3 * 3 = 9$  hours
4. Preparation of the final presentation: 15 hours

**Recommendation**

- Knowledge of Verilog Hardware Description Language, e.g. from Digital Circuit Design
- Knowledge in the design of analog circuits (amplifier circuits, stability considerations), e.g. from the Analog Circuit Design
- Knowledge of VHDL design, e.g. from Hardware Modeling and Simulation
- Knowledge of simulation of digital circuits, e.g. from Hardware Modeling and Simulation
- Knowledge of hardware design processes and algorithms, e.g. from Hardware Synthesis and Optimisation

## M

**7.297 Module: Systems and Software Engineering [M-ETIT-100537]****Responsible:** Prof. Dr.-Ing. Eric Sax**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Mandatory Electives – Methodical \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Mandatory Electives – General\)](#)  
[Field of Specialization in Mechatronics and Information Technology / Industrial Informatics and Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 2       |

| Mandatory     |  |      |     |
|---------------|--|------|-----|
| T-ETIT-100675 | <a href="#">Systems and Software Engineering</a> | 5 CR | Sax |

**Competence Certificate**

Written exam, approximately 90 minutes.

Students are given the opportunity to earn a grade bonus through separate task assignments. If the grade of the written exam is between 4.0 and 1.3, the bonus improves the grade by a maximum of one grade level (0.3 or 0.4). The exact criteria for awarding a bonus will be announced at the beginning of the lecture. Bonus points do not expire and remain valid for exams taken at a later date.

**Prerequisites**

none

**Competence Goal**

- Students are able to analyse and explain the functional principles and applications of embedded systems.
- Students are able to evaluate and apply maturity models as well as Software Development Life Cycle models including the waterfall model, V-model, prototyping model, agile models, and DevOps.
- Students are able to apply various creativity techniques to develop innovative solutions to problems. They will be able to derive and analyse requirements.
- Students are familiar with diagram formats software modelling languages; they can evaluate and create these based on problem descriptions of an application area. They will be able to create and evaluate functional, data-oriented, algorithmic, state-oriented, and object-oriented views.
- Students are able to understand and apply various aspects of the realization of embedded systems. They will be able to consider implementation alternatives: hardware, co-design and scheduling aspects.
- Students are familiar with the various testing phases in a project and can explain them. They can assess the reliability of a system and understand the concept of functional safety.

**Content**

The focus of the course is on processes and methods for the design of systems composed of electrical, electronic and electronically programmable systems that contain software, hardware and mechanical components. The desired competencies of the course include the knowledge and goal-oriented use of modeling techniques, design processes, description and representation tools as well as specification languages that correspond to the current state of the art.

**Module grade calculation**

The grade is determined by the written exam and the bonus points.

**Annotation**

Will be changed to 6 CR in winter term 25/26.

**Workload**

For each Credit Point (CP), 30h of work is scheduled. The resulting 150h are distributed as follows:

- 15 weeks of 1.5h attendance in lecture and 2h preparation and follow-up per week = 52.5h
- 15 weeks of 1.5h attendance in each exercise and at least 2h preparation (includes processing of exercise sheets and the processing of tasks for the acquisition of bonus points) per week = 52.5h
- Preparation for the exam = 45h

**Recommendation**

Knowledge in Digital Technology and Information and Automation Technology (e.g. module M-ETIT-102102 and M-ETIT-106336)

## M

**7.298 Module: Technical Design in Product Development [M-MACH-105318]****Responsible:** Prof. Dr.-Ing. Albert Albers**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)**Credits**  
4**Grading scale**  
Grade to a tenth**Recurrence**  
Each summer term**Duration**  
1 term**Language**  
German**Level**  
4**Version**  
1

| Mandatory     |   |      |                            |
|---------------|---|------|----------------------------|
| T-MACH-105361 | <a href="#">Technical Design in Product Development</a> | 4 CR | Albers, Matthiesen, Schmid |

**Competence Certificate**

Written examination; duration approx. 1h

**Prerequisites**

None

**Competence Goal**

The students:

- acquire and possess sound design skills for use at the interface between engineer and designer.
- master all relevant human-product requirements, such as demographic/geographic and psychographic characteristics, relevant modes of perception, typical recognition contents as well as ergonomic basics.
- have a command of the procedure for designing a product, product range or product system from the structure, through form, colour and graphic design within the phases of the design process.
- have a command of the functional and structural design as well as the important human-machine interface of interface design, have knowledge of the essential parameters of a good corporate design.

**Content**

Value relevant parameters of the technical design

Basics Interface Design

Macroergonomics: Planning and concept phase

Microergonomics: Concept and design phase

Microergonomics: development phase

Best practice

**Module grade calculation**

The module grade is composed of:

1. Grade of the written examination (100%)

**Annotation**

After attending the module, students will have the knowledge of the essential fundamentals of technically oriented design, as an integral part of methodical product development.

**Workload**

1. Time of presence lecture: 21 h

2. Prepare/follow-up lecture exam preparation: 99 h

Total: 120 h = 4 LP

**Learning type****Tutorial.****Media:**

- Beamer
- Models

**Literature**

Markus Schmid, Thomas Maier

Technisches Interface Design

Anforderungen, Bewertung, Gestaltung.

Springer Vieweg Verlag (<http://www.springer.com/de/book/9783662549476> )

Hardcover ISBN: 978-3-662-54947-6 / eBook ISBN: 978-3-662-54948-3

2017

Hartmut Seeger

Design technischer Produkte, Produktprogramme und -systeme

Industrial Design Engineering.

2., bearb. und erweiterte Auflage.

Springer-Verlag GmbH (<http://www.springer.com/de/book/9783540236535> )

ISBN: 3540236538

September 2005 - gebunden - 396 Seiten



**M****7.299 Module: Technical Optics [M-ETIT-100538]****Responsible:** Prof. Dr. Cornelius Neumann**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Elective Area in Mechatronics and Information Technology](#) (Elective Area in Mechatronics and Information Technology)**Credits**  
5**Grading scale**  
Grade to a tenth**Recurrence**  
Each winter term**Duration**  
1 term**Language**  
German**Level**  
4**Version**  
1

| Mandatory     |                                  |      |         |
|---------------|----------------------------------|------|---------|
| T-ETIT-100804 | <a href="#">Technical Optics</a> | 5 CR | Neumann |

**Prerequisites**

none

## M

**7.300 Module: Thermal Solar Energy [M-MACH-102388]****Responsible:** apl. Prof. Dr. Ron Dagan**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 2       |

| Mandatory     |                                      |      |       |
|---------------|--------------------------------------|------|-------|
| T-MACH-105225 | <a href="#">Thermal Solar Energy</a> | 4 CR | Dagan |

**Competence Certificate**

A performance assessment is obligatory; oral exam about 30 minutes

**Prerequisites**

none

**Competence Goal**

Based on the elaboration of the basic physics knowledge of the solar irradiation, heat radiation, optics and thermal-hydraulics, the student will be able to

- select solar thermal components such as mirrors, glasses, selective absorbers and insulation materials and their manufacturing processes and to calculate and assess their performance,
- identify different collector types and to indicate their potential field of application,
- characterize the entire solar thermal collector system with respect to its performance and derive from the collector characteristics its suitability for different types of use,
- embed collectors into a technical overall system for heat (household, process heat, heat storage networks) or electricity generation (power plant), to calculate the system efficiency and independently develop the basics of its optimization.
- identify adequate thermal storage types for the temporal separation of generation and consumption, to dimension them appropriately and to integrate them into a system concept,
- evaluate solar thermal systems in their entirety (capacity, estimation of system dynamics, response behavior, efficiency) and know options for integration into networks (heat, cold, electricity).

**Content**

Fundamentals of thermal solar energy from solar irradiation (influence of time and place, modifications in the atmosphere) and their implementation in a collector to integration into a technical overall system. In detail:

1. *introduction* to the energy demand and evaluation of the application potential of solar thermal energy.
2. *primary energy source SUN*: Sun, solar constant, solar radiation (scattering, absorption in the atmosphere, direct-diffuse radiation, angular influences, radiation balance).
3. *solar collectors*: basic design of a collector, basics of determining the efficiency, significance of concentration and its limitations, solar thermal collector types (designs, efficiency, system technology).
4. *passive mechanisms of solar thermal energy*: heat conduction in solids and gases, radiation heat transport in transparent and opaque bodies Design requirements and physical principles of solar thermal glasses, mirrors and selective absorbers. Goal oriented selection of materials and manufacturing processes.
5. *momentum and heat transport*: basic equations of single- and multi-phase transport, basic ideas of local and system engineering calculation methods, stability limits.

Optional

6. *solar thermal low-temperature systems*: collector variants, methods for system simulation, planning and dimensioning of systems, system-related system design and stagnation scenarios and their handling.
7. *solar thermal high-temperature systems*: solar thermal power plants (classification of system components, loss mechanisms, upwind power plants), coupling of collector with energy generation process.

At the end:

8. *Thermal energy storage*: Explanation of terms (energy contents, storage forms and materials, potentials ...), storage concepts (system structure, design ratio), system integration.
9. *Solar air conditioning*: Determination of cooling capacity, indoor climate, solar cooling methods and evaluation of air conditioning.

**Module grade calculation**

The module grade is the grade of the oral examination.

**Workload**

regular lecture attendance: 30 h

self-study: 60 h (incl. supplementary searches)

exam preparation 30 h

**Recommendation**

desirable are reliable knowledge in physics in optics and thermodynamics

Basics in heat and mass transfer, material science, energy technology and fluid mechanics

**Learning type**

Präsentation complemented by printouts

**Literature**

supply of lecture material in printed and electronic form

Stieglitz & Heinzl; Thermische Solarenergie -Grundlagen-Technologie- Anwendungen. Springer Vieweg Verlag. 711 Seiten. ISBN 978-3-642-29474-7

## M

**7.301 Module: Thermal Turbomachines I [M-MACH-107219]****Responsible:** Prof. Dr.-Ing. Hans-Jörg Bauer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 8       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-MACH-114052 | <a href="#">Thermal Turbomachines I</a> | 8 CR | Bauer |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

Students will be able to explain the structure and function of thermal turbomachinery in detail and assess the areas of application of these machines. They will be able to describe and analyze the tasks of the individual components and assemblies. Students are able to assess and evaluate the influence of physical, economic and ecological boundary conditions.

**Content**

- General principles of thermal turbomachinery
- Steam turbine system analysis
- Gas turbine system analysis
- Combined cycle power plants and combined heat and power plants
- Mode of operation of turbomachinery: General overview
- Working principle of turbines: Energy transfer in the stage
- Types and design examples of turbines
- Flat straight blade grids
- Spatial flow in the turbine and radial equilibrium
- Compressor stages and outlook
- Calculation principles and correlation approaches for turbine and compressor design, stage characteristics

**Module grade calculation**

The module grade is the grade of the oral exam.

**Workload**

240h

(for details see individual course)

**Recommendation**

Recommended in combination with the lecture 'Thermal Turbomachinery II'.

**Literature**

Lecture notes (available on the Internet)

Bohl, W.: Strömungsmaschinen, Bd. I, II; Vogel Verlag, 1990, 1991

Sigloch, H.: Strömungsmaschinen, Carl Hanser Verlag, 1993

Traupel, W.: Thermische Turbomaschinen Bd. I, II, Springer-Verlag, 1977, 1982

## M

**7.302 Module: Thermal-Fluid-Dynamics [M-MACH-107112]****Responsible:** Dr. Sebastian Ruck**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |      |
|---------------|--|------|------|
| T-MACH-106372 | <a href="#">Thermal-Fluid-Dynamics</a> | 4 CR | Ruck |

**Competence Certificate**

see individual course

**Prerequisites**

none

**Competence Goal**

The objectives of the lecture are the fundamentals of thermal-hydraulics for describing and modelling convective fluid flow as occurring in power engineering components. A major objective is the description of the convective heat transfer for external and internal flows. A key issue is the transfer of analytic models and empirical results into "state of the art" computational tools and their validation by advanced experimental methods. Within the scope of the course, the students learn (a) to develop differential equation for thermal-hydraulic problems and to describe the thermal flow field by means of dimensionless parameters, (b) to transfer a real problem to an experiment or computational model, (c) to develop analogies and correlations for heat transfer processes of forced convection, (d) to select adequate computational methods/models, (e) to evaluate and select experiments including measurement techniques with adequate instrumentation for thermal-hydraulic problems and (f) to know design option for an efficient and effective heat exchange.

**Content**

- Fundamentals of flows and heat transfer
- Dimensionless parameters of thermal fluid dynamics
- Velocity and temperature laws in boundary layers
- Convective heat transfer of external and internal flows
- Heat transfer analogies (Prandtl-, von Kármán, Martinelli,...)
- Methods for enhancing heat transfer
- Strategies and methods for investigation of thermal-hydraulics in R&D

The lecture provides an overview of momentum and energy transport as occurring in power engineering components and heat exchangers. On the basis of the conservation equations and the fundamentals of thermal-hydraulics, dimensionless parameters for forced and free convection are evolved. Flows close to walls play a crucial role for the convective heat transfer and for heat exchanger components. Thus, with scaling rules the laminar and turbulent thermal boundary layer equations are introduced. In the following, velocity and temperature laws of the wall as a basis for analogies and models of computational tools are discussed and the influence of roughness and surface design are shown. Concepts of state-of-the-art turbulence modelling and their applicability for different conditions or different heat transfer fluids (e.g. liquid metals, gas, oil) are described. Analogies and correlations for internal and external forced convection are developed by means of approximation concepts. Design options to enhance the efficiency and effectiveness of heat exchangers are discussed.

**Module grade calculation**

The grade corresponds to the grade of the oral examination.

**Workload**

120 hours, of which 30 hours attendance and 90 hours self-study

**M****7.303 Module: Tires and Wheel Development for Passenger Cars [M-MACH-107070]**

**Responsible:** Dr.-Ing. Martin Gießler  
Prof. Dr.-Ing. Günter Leister

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-MACH-102207 | <a href="#">Tires and Wheel Development for Passenger Cars</a> | 4 CR | Leister |

**Competence Certificate**

oral examination, duration: approximately 30 minutes

**Prerequisites**

none

**Competence Goal**

The students are informed about the interactions of tires, wheels and chassis. They have an overview of the processes regarding the tire and wheel development. They have knowledge of the physical relationships.

**Content**

1. The role of the tires and wheels in a vehicle
2. Geometrie of Wheel and tire, Package, load capacity and endurance, Book of requirement
3. Mobility strategy, Minispare, runflat systems and repair kit.
4. Project management: Costs, weight, planning, documentation
5. Tire testing and tire properties
6. Wheel technology including Design and manufacturing methods, Wheeltesting
7. Tire pressure: Indirect and direct measuring systems
8. Tire testing subjective and objective

**Module grade calculation**

The module grade corresponds to the grade of the examination in the course.

**Workload**

120h

## M

**7.304 Module: Tractors [M-MACH-107058]****Responsible:** Prof. Dr.-Ing. Marcus Geimer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |                          |      |                 |
|---------------|--------------------------|------|-----------------|
| T-MACH-105423 | <a href="#">Tractors</a> | 4 CR | Geimer, Kremmer |

**Competence Certificate**

The assessment consists of an written exam taking place in the recess period (90 min).

**Prerequisites**

none

**Content**

Tractors are one of the most underestimated vehicles in regard to performance und technics. Almost none vehicle is as multifunctional and fulfilled with high-tec as a tractor. Automatic guidance, special chassis suspension or special concepts of power trains are one of the topics where tractors are in leading position in technologies

During the lecture an overview about the design and construction and application area is given. A close look will be taken on the historical backround, legal requirements, ways of development, agricultural organizations and the proces of development itself.

In detail the following topics will be dealt with:

- agricultural organization / legal requirements
- history of tractors
- tractor engineering
- tractor mechanics
- chassis suspension
- combustion engine
- transmission
- interfaces
- hydraulics
- wheels and tyres
- cabin
- electrics and electronics

basic knowledge in mechanical engineering

**Module grade calculation**

see individual course

**Workload**

Attendance time: 28 hours

Self-study: 92 hours

**Literature**

- K.T. Renius: Traktoren - Technik und ihre Anwendung; DLG Verlag (Frankfurt), 1985
- E. Schilling: Landmaschinen - Lehr- und Handbuch für den Landmaschinenbau; Schilling-Verlag (Köln), 1960

## M

**7.305 Module: Ubiquitous Computing (24146) [M-INFO-107161]****Responsible:** Prof. Dr.-Ing. Michael Beigl**Organisation:** KIT Department of Informatics**Part of:** [Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 5       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |                                      |      |       |
|---------------|--------------------------------------|------|-------|
| T-INFO-114188 | <a href="#">Ubiquitous Computing</a> | 5 CR | Beigl |

**Competence Certificate**

See partial achievements (Teilleistung)

**Prerequisites**

See partial achievements (Teilleistung)

**Competence Goal**

The aim of the lecture is to impart knowledge of the fundamentals and advanced methods and techniques of ubiquitous computing. After completing the lecture, students will be able to

- reproduce and discuss what they have learnt about existing ubiquitous computing systems.
- evaluate the general knowledge of ubiquitous systems and transfer statements and laws to special cases.
- evaluate and assess different methods for design processes and user studies and select suitable methods for the development of new solutions.
- invent, plan, design and evaluate new ubiquitous systems for use in everyday or industrial process environments and assess the costs and technical implications.

**Content**

The lecture provides an overview of the history and teaches the concepts, theories and methods of ubiquitous information technology (ubiquitous computing). Based on the appliance concept, students then design their own appliances in the exercise, plan the construction and then develop them. The necessary technical and methodological basics such as hardware for ubiquitous systems, software for ubiquitous systems, principles of context recognition for ubiquitous systems, networking of ubiquitous systems and design of ubiquitous systems and in particular information appliances are discussed. Methods of design and testing for human-machine interaction and human-machine interfaces developed in ubiquitous computing are explained in detail. There is also an introduction to the economic aspects of a ubiquitous system.

In the practical part of the lecture, the understanding of ubiquitous systems is deepened through practical application of the knowledge base of the lecture. The students design and develop their own appliance and test it. The aim is to have gone through the steps towards a prototypical and possibly marketable appliance.



**Workload**

The total workload for this course unit is approximately 150 hours (5.0 credits).

**Activity****Workload****Attendance time: Attendance of the lecture**

15 x 90 min

22 h 30 min

**Attendance time: Attendance of the exercise**

15 x 45 min

11 h 15 min

**Preparation / follow-up of the lecture and exercise**

15 x 90 min

22 h 30 min

**Developing a self-developed concept for an information appliance**

33 h 45 min

**Go through set of slides 2x**

2 x 12 h

24 h 00 min

**Prepare exam**

36 h 00 min

**TOTAL**

**150 h 00 min**

Workload for the course unit "Ubiquitous Information Technologies

## M

**7.306 Module: Validation of Technical Systems [M-MACH-107143]**

**Responsible:** Prof. Dr.-Ing. Tobias Düser  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |       |
|---------------|---|------|-------|
| T-MACH-113982 | <a href="#">Validation of Technical Systems</a> | 4 CR | Düser |

**Competence Certificate**

See individual course

**Prerequisites**

None

**Competence Goal**

Learn ...

- How validation environments in complex cyber-physical system fields look like
- How to plan and operationalize the validation of complex cyber-physical systems
- How to conceptualize and design test benches on a mechanical and electrical level, using different sensors, actuators and models
- How to use simulations in combination with the real system on a test bench
- How to validate an automated driving system with a practical example

**Content**

- Discussion and analysis of various validation environments from technical areas such as automotive, medical technology, device technology (focus on automotive)
- Teaching methodological aspects of how validation of complex cyber-physical systems is planned and operationalized
- Learning content on power test benches with their mechanical and electrical design, as well as measurement and control technology, actuators and modeling
- Understanding the use of simulations, their scaling and connection to the real system
- Application of theoretical knowledge in the context of a leading example in the field of automated driving
- Outlook on the role of large language models and gamification in validation

**Module grade calculation**

The module grade corresponds to the grade from the individual course.

**Annotation**

None

**Workload**

Attendance: 30h

Self-study: 90h

**Recommendation**

None

**Learning type**

Lecture

**Literature**

None

**Base for**  
None

## M

**7.307 Module: Vehicle Drive Technology [M-MACH-107056]****Responsible:** Prof. Dr.-Ing. Marcus Geimer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-113997 | <a href="#">Vehicle Drive Technology</a> | 4 CR | Geimer |

**Competence Certificate**

Success is assessed in the form of an oral examination (20 minutes) during the lecture-free period of the semester. The examination is offered every semester and can be repeated at any regular examination date.

**Prerequisites**

none

**Competence Goal**

Students will be able to explain the structure and function of all the drive trains of mobile machinery discussed. They will be able to analyze complex gearbox schematics as well as calculate simple gearbox functions using rough calculations.

**Content**

This lecture presents and discusses the possible variations of the traction drive trains of mobile machinery. The focus of the lecture is as follows:

- Mechanical transmissions
- Hydrodynamic converters
- Hydrostatic drives
- Power-split transmissions
- Electric drives
- Hybrid drives
- axles
- Terra mechanics (wheel-ground effects)

**Module grade calculation**

see individual course

**Workload**

120h (attendance time: 21h, self-study: 99h)

## M

**7.308 Module: Vehicle Lightweight Design - Strategies, Concepts, Materials [M-MACH-102703]**

**Responsible:** Prof. Dr.-Ing. Frank Henning  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** Lightweight Design  
 Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering (Additive Electives )  
 Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |         |
|---------------|--|------|---------|
| T-MACH-105237 | Vehicle Lightweight Design - Strategies, Concepts, Materials | 4 CR | Henning |

**Competence Certificate**

Written exam; Duration approx. 90 min

**Prerequisites**

none

**Competence Goal**

Students learn that lightweight design is a process of realizing a demanded function by using the smallest possible mass. They understand lightweight construction as a complex optimization problem with multiple boundary conditions, involving competences from methods, materials and production.

Students learn the established lightweight strategies and ways of construction. They know the metallic materials used in lightweight construction and understand the relation between material and vehicle body.

**Content**Strategies in lightweight design

Shape optimization, light weight materials, multi-materials and concepts for lightweight design

Construction methods

Differential, integral, sandwich, modular, bionic

body construction

Shell, space-frame, monocoque

metallic materials

Steel, aluminium, magnesium, titan

**Workload**

- Attendance of lectures: 21 h
  - Preparation and attendance of examination: 99 h
- Total: 120 h = 4 LP

**Learning type**

Lecture

**Literature**

- [1] E. Moeller, *Handbuch Konstruktionswerkstoffe : Auswahl, Eigenschaften, Anwendung*. München: Hanser, 2008.
- [2] H.-J. Bargel, *et al.*, *Werkstoffkunde*, 10., bearb. Aufl. ed. Berlin: Springer, 2008.
- [3] C. Kammer, *Aluminium-Taschenbuch : Grundlagen und Werkstoffe*, 16. Aufl. ed. Düsseldorf: Aluminium-Verl., 2002.
- [4] K. U. Kainer, "Magnesium - Eigenschaften, Anwendungen, Potentiale ", Weinheim [u.a.], 2000, pp. VIII, 320 S.
- [5] A. Beck and H. Altwicker, *Magnesium und seine Legierungen*, 2. Aufl., Nachdr. d. Ausg. 1939 ed. Berlin: Springer, 2001.
- [6] M. Peters, *Titan und Titanlegierungen*, [3., völlig neu bearb. Aufl.] ed. Weinheim [u.a.]: Wiley-VCH, 2002.
- [7] H. Domininghaus and P. Elsner, *Kunststoffe : Eigenschaften und Anwendungen; 240 Tab*, 7., neu bearb. u. erw. Aufl. ed. Berlin: Springer, 2008.

## M

**7.309 Module: Vehicle Systems for Urban Mobility [M-MACH-106515]**

**Responsible:** Prof. Dr.-Ing. Martin Cichon  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Vehicle Systems Engineering \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each term  | 1 term   | German   | 4     | 1       |

| Mandatory     |  |      |        |
|---------------|--|------|--------|
| T-MACH-113069 | <a href="#">Vehicle Systems for Urban Mobility</a> | 4 CR | Cichon |

**Competence Certificate**

Oral exam  
Duration approx. 20 minutes  
Auxiliary means: none

**Prerequisites**

none

**Competence Goal**

Students will gain a basic understanding of the essential traffic, transport policy and technological contexts of urban mobility. On the basis of this basic understanding, different vehicle concepts of public transport in urban and regional environments will be analyzed, compared and the optimal range of applications will be discussed. In addition to the established public transport systems, special attention will be paid to innovative mobility solutions. In particular, an understanding of how sustainable, systemic mobility solutions should be designed depending on the individual use case is to be created

**Content**

- Definitions of urban mobility and public transport services
- Comparison and performance parameters of different vehicle concepts
- Rail-bound vehicle systems
- Bus systems and alternative propulsion systems
- Definition of an "innovative vehicle concept for public transport".
- Historical innovative urban vehicle concepts and analysis of why they did not succeed
- Future innovative urban vehicle concepts and discussion of their market opportunities
- Comparison of urban mobility solutions under the aspects of sustainability, resource conservation, resilience and economic efficiency
- Presentations by external experts

**Annotation**

A bibliography is available for students to download from the Ilias platform.

**Workload**

Attendance time: 21 hours  
Preparation / wrap-up: 21 hours  
Exam and exam preparation: 78 hours  
Total time: 120 hours = 4 LP

**Learning type**

Lecture

## M

**7.310 Module: Virtual Engineering 1 [M-MACH-105293]****Responsible:** Prof. Dr.-Ing. Jivka Ovtcharova**Organisation:****Part of:** [Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | English  | 4     | 1       |

| Mandatory     |                                       |      |            |
|---------------|---------------------------------------|------|------------|
| T-MACH-102123 | <a href="#">Virtual Engineering I</a> | 4 CR | Ovtcharova |

**Competence Certificate**

Written exam, graded, 90 min.

**Competence Goal**

After successful attendance of the course, students can:

- conceptualize complex systems with the methods of virtual engineering and continue the product development in different domains
- model the digital product with regard to planning, design, manufacturing, assembly and maintenance.
- use validation systems to validate product and production in an exemplary manner.
- Describe AI methods along the product creation process.

**Content**

- Conception of the product (system approaches, requirements, definitions, structure)
- Generation of domain-specific product data (CAD, ECAD, software, ...) and AI methods
- Validation of product properties and production processes through simulation
- Digital twin for optimization of products and processes using AI methods

**Module grade calculation**

Examination result "Virtual Engineering 1" 100%

**Workload**

120 h

**Recommendation**

None

**Learning type**

Lecture and exercises

**Literature**

Lecture slides

## M

**7.311 Module: Virtual Engineering A (WW4INGMB29) [M-MACH-101283]****Responsible:** Prof. Dr.-Ing. Jivka Ovtcharova**Organisation:** KIT Department of Mechanical Engineering**Part of:** Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology)

| Credits | Grading scale    | Recurrence | Duration | Language | Level | Version |
|---------|------------------|------------|----------|----------|-------|---------|
| 9       | Grade to a tenth | Each term  | 2 terms  | German   | 4     | 7       |

| Mandatory  |  |      |                   |
|--|--|------|-------------------|
| T-MACH-102123  | Virtual Engineering I                                  | 4 CR | Ovtcharova        |
| Virtual Engineering A (Election: at least 5 credits) |  |      |                   |
| T-MACH-113857  | CAD Engineering Project for Intelligent Systems        | 3 CR | Rönnau            |
| T-MACH-102185  | CATIA CAD Training Course                              | 2 CR | Ovtcharova        |
| T-MACH-105312  | CATIA Advanced   | 4 CR | Ovtcharova        |
| T-MACH-113669  | Hot Research Topics in AI for Engineering Applications | 4 CR | Meyer             |
| T-MACH-102209  | Information Engineering                                | 3 CR | Meyer, Ovtcharova |
| T-MACH-106743  | IoT Platform for Engineering                           | 4 CR | Ovtcharova        |
| T-MACH-113956  | Mathematical Methods in Fluid Mechanics                | 6 CR | Frohnapfel, Gatti |
| T-MACH-102181  | PLM for Product Development in Mechatronics            | 4 CR | Eigner            |
| T-MACH-106740  | Virtual Engineering Lab                                | 4 CR | Ovtcharova        |

**Competence Certificate**

The assessment is carried out as partial exams (according to Section 4 (2), 1-3 SPO) of the core course and further single courses of this module, whose sum of credits must meet the minimum requirement of credits of this module. The assessment procedures are described for each course of the module separately.

The overall grade of the module is the average of the grades for each course weighted by the credits and truncated after the first decimal.

**Prerequisites**

None

**Competence Goal**

The students should:

- have basic knowledge about the industrial application of Information Technology in product development,
- have understanding about current and future application of information systems in product development processes in the context of Product Lifecycle Management and Virtual Engineering,
- be able to operate current CAx- and PLM-systems in the product development process
- understands demands and relevance of interconnected IT-systems and respective methods for product development

**Content**

The Module Virtual Engineering A gives an overview about product development processes, beginning with requirement engineering, verification of manufacturing feasibility and virtual operation in the scope of Digital Factory. The guest-lectures contained in this module complete the content of the lecture with introducing current product development processes focusing.

**Workload**

- regular attendance: 140 hours
- Preparation and reworking: 20 hours
- Exam and exam revision/preparation: 110 hours

**Learning type**

Lecture, exercise



## M

**7.312 Module: Virtual Engineering Lab [M-MACH-105475]****Responsible:** Prof. Dr.-Ing. Jivka Ovtcharova**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [Field of Specialization in Mechatronics and Information Technology / Automation, Control, and Robotics \(Internship/Lab Course \)](#)  
[Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems \(Internship/Lab Course \)](#)  
[Elective Area in Mechatronics and Information Technology \(Internship/Lab Course \)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |   |      |            |
|---------------|---|------|------------|
| T-MACH-106740 | <a href="#">Virtual Engineering Lab</a> | 4 CR | Ovtcharova |

**Competence Certificate**

Alternative exam assessment.

**Prerequisites**

None

**Competence Goal**

Students are able to design and implement a complex task in teamwork using VR/MR/AR hardware and software.

**Content**

VR/AR/MR basics (hardware, software), tools and applications

**Module grade calculation**

Alternative exam assessment.

**Workload**

120 hours

**Learning type**

Project work in the team

## M

## 7.313 Module: Wearable Robotic Technologies [M-INFO-107113]

|                      |  |
|----------------------|--|
| <b>Responsible:</b>  | Prof. Dr.-Ing. Tamim Asfour<br>Prof. Dr.-Ing. Michael Beigl  |
| <b>Organisation:</b> | KIT Department of Informatics  |
| <b>Part of:</b>      | Field of Specialization in Mechatronics and Information Technology / Design of Mechatronic Systems<br>(Additive Electives )<br>Elective Area in Mechatronics and Information Technology (Elective Area in Mechatronics and Information Technology) |

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |   |      |               |
|---------------|---|------|---------------|
| T-INFO-114145 | <a href="#">Wearable Robotic Technologies</a> | 4 CR | Asfour, Beigl |

**Competence Certificate**

See partial achievements (Teilleistung)

**Prerequisites**

See partial achievements (Teilleistung)

**Competence Goal**

The student has received fundamental knowledge about wearable robotic technologies and understands the requirements for the design, the interface to the human body and the control of wearable robots. He/she is able to describe methods for modelling the human neuromusculoskeletal system, the mechatronic design, fabrication and composition of interfaces to the human body. The student understands the symbiotic human-machine interaction as a core topic of Anthropomatics and has knowledge of state-of-the-art examples of exoskeletons, orthoses and prostheses.

**Content**

The lecture provides an overview of wearable robot technologies (exoskeletons, prostheses and orthoses) and their potentials. It starts with the basics of wearable robotics and introduces different approaches to the design of wearable robots and their related actuator and sensor technology. The lecture focuses on modeling the neuromusculoskeletal system of the human body, the interfaces of wearable robots to the human body and the physical and cognitive human-robot interaction for tightly-coupled hybrid human-robot systems. Examples of current research and various applications of lower, upper and full body exoskeletons as well as prostheses are presented.

**Workload**

Lecture with 2 SWS, 4 LP  
4 LP corresponds to 120 hours, including  
15 \* 2 = 30 hours attendance time  
15 \* 3 = 45 self-study  
45 hours preparation for the exam

**Recommendation**

Attendance of the lecture Mechano-Informatics in Robotics is recommended.

## M

**7.314 Module: Windpower [M-MACH-105732]****Responsible:** Dr. Balazs Pritz**Organisation:** KIT Department of Mechanical Engineering  
Institute of Thermal Turbomachinery**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)  
[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 4       | Grade to a tenth | Each winter term | 1 term   | German   | 4     | 1       |

| Mandatory     |                           |      |        |
|---------------|---------------------------|------|--------|
| T-MACH-105234 | <a href="#">Windpower</a> | 4 CR | Lewald |

**Competence Certificate**

Written exam.

Duration: 80 min

**Prerequisites**

none

**Competence Goal**

The students are familiar with the elementary basics of using wind power.

The focus of the lecture is on the general principles of using wind power to generate electricity, supplemented by the historical development, general knowledge of wind and alternative, renewable energies.

**Content**

Due to the broad basic knowledge, the lecture is aimed at students from all faculties and all semesters.

Based on an overview of alternative, renewable energy technologies and general energy data, the entry into wind energy is made by means of an overview of the historical development of wind power.

Since wind provides the driving energy as indirect solar energy, a separate chapter is devoted to the global and local wind systems and their measurement and energy content.

Based on this, the aerodynamic basics and relationships of wind turbines and their profiles are explained.

Another focus is the electrical system of the wind turbines. Beginning with basic generator technology over the control and management of the energy output.

After the focus on aerodynamics and electrical system, the other components of wind turbines and their special features are explained in context.

Finally, the current economic, ecological and legislative boundary conditions for the operation of wind turbines are examined.

In addition to wind turbines for generating electricity, the lecture also briefly discusses alternative uses such as pump systems.

The conclusion is an overview of current developments such as supergrids or future visions of wind energy use.

**Module grade calculation**

The module grade is the grade of the written examination.

**Workload**

Attendance time: 28 hours

Self study: 60 hours

Exam preparation: 30 hours

**Learning type**

Lecture in presence, course material is provided via ILIAS.

## M

**7.315 Module: Workshop Finite Element Method in Electromagnetics [M-ETIT-107147]****Responsible:** Prof. Dr. Martin Doppelbauer**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [Field of Specialization in Mechatronics and Information Technology / Energy Technology \(Additive Electives \)](#)[Elective Area in Mechatronics and Information Technology \(Elective Area in Mechatronics and Information Technology\)](#)

| Credits | Grading scale    | Recurrence       | Duration | Language | Level | Version |
|---------|------------------|------------------|----------|----------|-------|---------|
| 3       | Grade to a tenth | Each summer term | 1 term   | English  | 4     | 1       |

| Mandatory     |  |      |             |
|---------------|--|------|-------------|
| T-ETIT-114166 | <a href="#">Workshop Finite Element Method in Electromagnetics</a> | 3 CR | Doppelbauer |

**Competence Certificate**

Success control takes place in the form of different types of examination consisting of a written assignment in the form of an written report.

**Prerequisites**

none

**Competence Goal**

In this course, students acquire basic knowledge about the application of the finite element method in electromagnetic analysis: mathematical principles, levels of abstraction, model creation and result analysis.

**Content**

- Introduction to the mathematical basics of the finite element method (FEM) of electromagnetics
- Presentation of the industry-standard software ANSYS Maxwell
- Construction of a model of a permanently excited synchronous machine
- Presentation and implementation of optimization strategies for the design of machines with regard to various parameters
- Introduction to results analysis

The module teaches students

- How to use industry-standard software from the field of electromagnetic FEM
- Solve basic practical tasks in the field of electromagnetic FEM
- Approaches to optimizing various parameters using the example of electrical machines
- Question and evaluate the results of a simulation or optimization

**Module grade calculation**

The module grade is the grade of the written paper.

**Workload**

1. Attendance time: 20h
2. Preparation and follow-up time: 10h
3. Project work: approx. 60h

Total approx. 90 h, corresponds to 3 CP

**Recommendation**

Knowledge from the modules "Elektrische Maschinen und Stromrichter" and "Entwurf elektrischer Maschinen" is desired.

## 8 Courses

**T**

### 8.1 Course: Actuators and Sensors in Nanotechnology [T-MACH-105238]

**Responsible:** Prof. Dr. Manfred Kohl

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102698 - Actuators and Sensors in Nanotechnology](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

#### Competence Certificate

oral exam

#### Prerequisites

none

## T


**8.2 Course: Adaptive Optics [T-ETIT-107644]**


**Responsible:** Dr. Szymon Gladysz  
Prof. Dr. Ulrich Lemmer

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-103802 - Adaptive Optics](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each winter term | 1       |

| Events   |         |                                 |       |   |         |
|----------|---------|---------------------------------|-------|---|---------|
| WT 24/25 | 2313724 | <a href="#">Adaptive Optics</a> | 2 SWS | Lecture /  | Gladysz |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Type of Examination: Oral examination

Duration of Examination: approx. 30 Minutes

Modality of Exam: The oral exam will be scheduled during the semester break.

The module grade is the grade of the oral exam.

**Prerequisites**

None.

**Recommendation**

Basic knowledge of statistics.

**Workload**

90 hours

T

## 8.3 Course: Advanced Artificial Intelligence [T-INFO-114220]

**Responsible:** Prof. Dr. Jan Niehues  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-107198 - Advanced Artificial Intelligence](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1       |

### Competence Certificate

The assessment is carried out as a written examination (§ 4 Abs. 2 No. 1 SPO) lasting 60 minutes.

### Prerequisites

None.

### Modeled Conditions

The following conditions have to be fulfilled:

1. The course [T-INFO-112768 - Advanced Artificial Intelligence](#) must not have been started.

T

**8.4 Course: Advanced Communications Engineering [T-ETIT-113676]**

**Responsible:** Dr.-Ing. Holger Jäkel  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106815 - Advanced Communications Engineering](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 1       |

**Competence Certificate**

The assessment takes place in the form of a written examination lasting 120 min.

The module grade is the grade of the written exam.

**Prerequisites**

none





T

**8.5 Course: Analog Circuit Design [T-ETIT-100973 ]**

**Responsible:** Prof. Dr. Ivan Peric  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100466 - Analog Circuit Design](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |  |       |
|----------|---------|--|-------|--|-------|
| WT 24/25 | 2312664 | <a href="#">Analog Circuit Design</a>                      | 2 SWS | Lecture /   | Peric |
| WT 24/25 | 2312666 | <a href="#">Tutorial for 2312664 Analog Circuit Design</a> | 1 SWS | Practice /  | Peric |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T


## 8.6 Course: Analysis Tools for Combustion Diagnostics [T-MACH-105167]





**Responsible:** Jürgen Pfeil

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107031 - Analysis Tools for Combustion Diagnostics](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |       |
|---------|---------|---|-------|---|-------|
| ST 2025 | 2134134 | <a href="#">Analysis tools for combustion diagnostics</a> | 2 SWS | Lecture /  | Pfeil |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

oral examination, Duration: 25 min., no auxiliary means

### Prerequisites

none

T

**8.7 Course: Antennas and Beamforming [T-ETIT-113920]**

**Responsible:** Prof. Dr.-Ing. Thomas Zwick  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106956 - Antennas and Beamforming](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1 terms   | 1       |

**Competence Certificate**

The examination takes place in form of a written examination lasting 120 minutes.  
 The module grade is the grade of the written exam.

**Prerequisites**

none

**Recommendation**

Knowledge of the basics of radio frequency technology and some basic knowledge on communication and radar systems is recommended.


## T

**8.8 Course: Appliance and Power Tool Design [T-MACH-105229]**

**Responsible:** Prof. Dr.-Ing. Sven Matthiesen  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107144 - Power Tool Design](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 4       |

| Events  |         |                                   |       |   |            |
|---------|---------|-----------------------------------|-------|---|------------|
| ST 2025 | 2145164 | <a href="#">Power Tool Design</a> | 2 SWS | Lecture /  | Matthiesen |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Approx. 30 min oral exam

The Appliance and Power Tool Design Project Work will be examined in conjunction with the concurrent lecture. To ensure that the impact on the overall grade is appropriate, the weighting of the exam is 12 credits, for MSc Mechanical Engineering 2025.

**Prerequisites**

T-MACH-110767 - Appliance and Power Tool Design Project Work must be started.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-MACH-110767 - Appliance and Power Tool Design Project Work](#) must have been started.

**Recommendation**

None

**Annotation**

The participation in the lecture requires the participation in Appliance and Power Tool Design Project Work.

Due to organizational reasons, the number of participants is limited. In the beginning of August, a registration form will be available at the IPEK website. The selection itself is made by the course's responsible in personal interviews. The criterion for selection is the verified progress of studies. In the event of equal progress, the decision is made by lot.

**Workload**

120 hours


## T

**8.9 Course: Appliance and Power Tool Design Project Work [T-MACH-110767]**

**Responsible:** Prof. Dr.-Ing. Sven Matthiesen  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-107145 - Power Tool Design Project Work](#)

| Type                 | Credits | Grading scale | Recurrence       | Expansion | Version |
|----------------------|---------|---------------|------------------|-----------|---------|
| Completed coursework | 8       | pass/fail     | Each summer term | 1 terms   | 3       |

| Events  |         |  |       |  |            |
|---------|---------|--|-------|--|------------|
| ST 2025 | 2145165 | <a href="#">Power Tool Design Project Work</a> | 4 SWS | Project (P /  | Matthiesen |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The Appliance and Power Tool Design Project Work will be examined in conjunction with the concurrent lecture.

**Prerequisites**

None

**Recommendation**

None

**Annotation**

The participation in the project work requires the participation in "Appliance and power tool design".

Due to organizational reasons, the number of participants is limited. In the beginning of August, a registration form will be available at the IPEK website. The selection itself is made by the course's responsible in personal interviews. The criterion for selection is the verified progress of studies. In the event of equal progress, the decision is made by lot.

**Workload**



240 hours

## T

## 8.10 Course: Applied Information Theory [T-ETIT-100748]

**Responsible:** Dr.-Ing. Holger Jäkel  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100444 - Applied Information Theory](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |  |       |
|----------|---------|---|-------|--|-------|
| WT 24/25 | 2310537 | <a href="#">Applied Information Theory</a>                      | 3 SWS | Lecture /   | Jäkel |
| WT 24/25 | 2310539 | <a href="#">Tutorial for 2310537 Applied Information Theory</a> | 1 SWS | Practice /  | Jäkel |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The success control takes place in the form of an oral examination lasting 25 minutes. Before the examination, there is a preparation phase of 15 minutes in which preparatory tasks are solved.

**Prerequisites**

none


T

**8.11 Course: Artificial Intelligence in Production [T-MACH-112115]**

**Responsible:** Prof. Dr.-Ing. Jürgen Fleischer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105968 - Artificial Intelligence in Production](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |   |           |
|----------|---------|---|-------|---|-----------|
| WT 24/25 | 2149921 | <a href="#">Artificial Intelligence in Production</a> | 2 SWS | Lecture /  | Fleischer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written Exam (90 min)

**Prerequisites**

none

**Workload**


120 hours

T

**8.12 Course: Automated Visual Inspection and Image Processing [T-INFO-101363]**

**Responsible:** Prof. Dr.-Ing. Jürgen Beyerer  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-100826 - Automated Visual Inspection and Image Processing](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 2       |

| Events   |         |  |       |   |                 |
|----------|---------|--|-------|---|-----------------|
| WT 24/25 | 2424169 | <a href="#">Automated Visual Inspection and Image Processing</a> | 4 SWS | Lecture /  | Beyerer, Zander |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled



## T

**8.13 Course: Automotive Engineering I [T-MACH-100092]****Responsible:** Dr.-Ing. Martin Gießler**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-100501 - Automotive Engineering I](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Language | Version |
|---------------------|---------|------------------|------------------|-----------|----------|---------|
| Written examination | 8       | Grade to a third | Each winter term | 1 terms   |          | 3       |

| Events   |         |  |       |              |         |
|----------|---------|--|-------|--------------|---------|
| WT 24/25 | 2113805 | <a href="#">Automotive Engineering I</a> | 4 SWS | Lecture / 🗣️ | Gießler |
| WT 24/25 | 2113809 | <a href="#">Automotive Engineering I</a> | 4 SWS | Lecture / 🗣️ | Gießler |

Legend: 📺 Online, 🔄 Blended (On-Site/Online), 🗣️ On-Site, ✖ Canceled

**Competence Certificate**

Written examination

Duration: 120 minutes

Auxiliary means: none

**Prerequisites**

The brick "T-MACH-102203 - Automotive Engineering I" is not started or finished. The bricks "T-MACH-100092 - Grundlagen der Fahrzeugtechnik I" and "T-MACH-102203 - Automotive Engineering I" can not be combined.

**Workload**

240 hours

T



## 8.14 Course: Automotive Engineering II [T-MACH-102117]





**Responsible:** Dr.-Ing. Martin Gießler

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-100502 - Automotive Engineering II](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |         |
|---------|---------|---|-------|---|---------|
| ST 2025 | 2114835 | <a href="#">Automotive Engineering II</a> | 2 SWS | Lecture /  | Gießler |
| ST 2025 | 2114855 | <a href="#">Automotive Engineering II</a> | 2 SWS | Lecture /  | Gießler |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Written Examination

Duration: 90 minutes

Auxiliary means: none

### Prerequisites

none

### Workload

120 hours

T


**8.15 Course: Automotive Vision [T-MACH-105218]**





**Responsible:** Dr. Martin Lauer  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102693 - Automotive Vision](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 3       |

| Events  |         |                                   |       |   |             |
|---------|---------|-----------------------------------|-------|---|-------------|
| ST 2025 | 2138340 | <a href="#">Automotive Vision</a> | 3 SWS | Lecture /  | Lauer, Bätz |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Type of Examination: written exam

Duration of Examination: 60 minutes

**Prerequisites**

none

**Workload**

180 hours

T


**8.16 Course: Automotive Vision [T-MACH-114149]**





**Responsible:** Dr. Martin Lauer  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107148 - Automotive Vision](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 2       |

| Events  |         |                                   |       |   |             |
|---------|---------|-----------------------------------|-------|---|-------------|
| ST 2025 | 2138340 | <a href="#">Automotive Vision</a> | 3 SWS | Lecture /  | Lauer, Bätz |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Type of Examination: written exam

Duration of Examination: 60 minutes

**Prerequisites**

none

**Workload**


180 hours





T

**8.17 Course: Basics of Converter Control [T-ETIT-100717]**

**Responsible:** Dr.-Ing. Andreas Liske  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100400 - Basics of Converter Control](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |       |
|---------|---------|---|-------|---|-------|
| ST 2025 | 2306330 | <a href="#">Basics of Converter Control</a> | 2 SWS | Lecture /  | Liske |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

**8.18 Course: Basics of Technical Logistics II [T-MACH-109920]**

**Responsible:** Prof. Dr.-Ing. Kai Furmans  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105302 - Basics of Technical Logistics II](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 2       |

| Events   |         |  |       |                        |            |
|----------|---------|--|-------|------------------------|------------|
| WT 24/25 | 2117098 | <a href="#">Basics of Technical Logistics II</a> | 3 SWS | Lecture / Practice ( / | Mittwollen |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

The assessment consists of a written exam (60 min.) according to § 4 paragraph 2 Nr. 1 of the examination regulation.

**Prerequisites**

none

**Recommendation**

Knowledge of the basics of technical mechanics and out of "Basic of Technical Logistics I" (T-MACH-109919) preconditioned.

**Workload**



150 hours

T

**8.19 Course: Batteries and Fuel Cells [T-ETIT-100983]**

**Responsible:** Prof. Dr.-Ing. Ulrike Krewer  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100532 - Batteries and Fuel Cells](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each winter term | 3       |

| Events   |         |  |       |  |                |
|----------|---------|--|-------|--|----------------|
| WT 24/25 | 2304207 | <a href="#">Batteries and Fuel Cells</a>                       | 2 SWS | Lecture /   | Krewer         |
| WT 24/25 | 2304213 | <a href="#">Batteries and Fuel Cells (Exercise to 2304207)</a> | 1 SWS | Practice /  | Krewer, Sonder |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled


**Prerequisites**





none

T

**8.20 Course: Batteries and Fuel Cells Laboratory [T-ETIT-100708]****Responsible:** Dr.-Ing. Andre Weber**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-100381 - Batteries and Fuel Cells Laboratory](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |  |       |
|----------|---------|---|-------|--|-------|
| WT 24/25 | 2304235 | <a href="#">Batteries and Fuel Cells Laboratory</a> | 4 SWS | Practical course /  | Weber |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled




T

## 8.21 Course: Battery and Fuel Cells Systems [T-ETIT-100704]

**Responsible:** Dr.-Ing. Andre Weber  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100377 - Battery and Fuel Cells Systems](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |       |
|---------|---------|---|-------|---|-------|
| ST 2025 | 2304214 | <a href="#">Batterie- und Brennstoffzellensysteme</a> | 2 SWS | Lecture /  | Weber |


Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled





T

**8.22 Course: Bioelectric Signals [T-ETIT-101956]**

**Responsible:** Dr.-Ing. Axel Loewe  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100549 - Bioelectric Signals](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 3       | Grade to a third | Each summer term | 2       |

| Events  |         |                                     |       |   |       |
|---------|---------|-------------------------------------|-------|---|-------|
| ST 2025 | 2305264 | <a href="#">Bioelectric Signals</a> | 2 SWS | Lecture /  | Loewe |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The examination is a written examination with a duration of 90 minutes.

**Prerequisites**

none





T

**8.23 Course: Biologically Inspired Robots [T-MACH-113856]**

**Responsible:** Prof. Dr.-Ing. Arne Rönnau  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-106903 - Biologically Inspired Robots](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 1 terms   | 1       |

| Events  |         |  |       |   |        |
|---------|---------|--|-------|---|--------|
| ST 2025 | 2122330 | <a href="#">Biologically Inspired Robots</a> | 2 SWS | Lecture /  | Rönnau |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Success is assessed in the form of an oral examination (approx. 15-20 minutes)

**Prerequisites**

none

**Recommendation**

It is recommended to listen to the course "Robotics I" beforehand .

**Annotation**

none

**Workload**

90 hours

T

**8.24 Course: BioMEMS - Microfluidic Chipsystems V [T-MACH-111069]**

**Responsible:** Prof. Dr. Andreas Guber  
Dr. Taleieh Rajabi

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105484 - BioMEMS - Microfluidic Chipsystems V](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1 terms   | 2       |

**Competence Certificate**

oral exam (appr. 20 Min.)

**Prerequisites**

none

**Workload**

120 hours

T


## 8.25 Course: BioMEMS - Microsystems Technologies for Life-Sciences and Medicine I [T-MACH-100966]





**Responsible:** Prof. Dr. Andreas Guber

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-100489 - BioMEMS - Microsystems Technologies for Life Sciences and Medicine I](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 2       |

| Events   |         |  |       |   |               |
|----------|---------|--|-------|---|---------------|
| WT 24/25 | 2141864 | <a href="#">BioMEMS - Microsystems Technologies for Life-Sciences and Medicine I</a> | 2 SWS | Lecture /  | Guber, Ahrens |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

written exam (75 Min.)

### Prerequisites

none

### Workload

120 hours

T


## 8.26 Course: BioMEMS - Microsystems Technologies for Life-Sciences and Medicine II [T-MACH-100967]





**Responsible:** Prof. Dr. Andreas Guber

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-100490 - BioMEMS - Microsystems Technologies for Life Sciences and Medicine II](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |   |               |
|---------|---------|---|-------|---|---------------|
| ST 2025 | 2142883 | <a href="#">BioMEMS - Microsystems Technologies for Life-Sciences and Medicine II</a> | 2 SWS | Lecture /  | Guber, Ahrens |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Written exam (75 Min.)

### Prerequisites

none

### Workload

120 hours

T


## 8.27 Course: BioMEMS - Microsystems Technologies for Life-Sciences and Medicine III [T-MACH-100968]





**Responsible:** Prof. Dr. Andreas Guber

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-100491 - BioMEMS - Microsystems Technologies for Life Sciences and Medicine III](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |   |               |
|---------|---------|--|-------|---|---------------|
| ST 2025 | 2142879 | <a href="#">BioMEMS - Microsystems Technologies for Life-Sciences and Medicine III</a> | 2 SWS | Lecture /  | Guber, Ahrens |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Written exam (75 Min.)

### Prerequisites

none

### Workload

120 hours

T



## 8.28 Course: BioMEMS - Microsystems Technologies for Life-Sciences and Medicine IV [T-MACH-106877]


**Responsible:** Dr. Ralf Ahrens  
Prof. Dr. Andreas Guber

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105483 - BioMEMS - Microsystemtechnology for Life-Science and Medicine IV](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |   |                            |
|----------|---------|---|-------|---|----------------------------|
| WT 24/25 | 2141102 | <a href="#">BioMEMS IV - Microsystems technology for Life Sciences and Medicine</a> | 2 SWS | Lecture /  | Guber, Ahrens, Länge       |
| ST 2025  | 2142893 | <a href="#">BioMEMS IV - Microsystems technology for Life Sciences and Medicine</a> | 2 SWS | /           | Guber, Ahrens, Länge, Doll |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Oral examination (45 Min.)

### Prerequisites

none

### Workload

120 hours



T

## 8.29 Course: CAD Engineering Project for Intelligent Systems [T-MACH-113857]

**Responsible:** Prof. Dr.-Ing. Arne Rönna  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-101283 - Virtual Engineering A](#)  
[M-MACH-106905 - CAD Engineering Project for Intelligent Systems](#)

| Type                        | Credits | Grading scale    | Recurrence | Expansion | Version |
|-----------------------------|---------|------------------|------------|-----------|---------|
| Examination of another type | 3       | Grade to a third | Each term  | 1 terms   | 1       |

| Events  |         |   |       |                 |       |
|---------|---------|---|-------|-----------------|-------|
| ST 2025 | 2122331 | <a href="#">CAD Engineering Project for Intelligent Systems</a> | 4 SWS | Project (P / ●) | Rönna |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

### Competence Certificate

Examination of a different kind. Design project as well as written elaboration in a team and a final presentation. Grading: Design project 3/5, written paper 1/5 and presentation 1/5.

### Prerequisites

none

### Workload

90 hours



T

**8.30 Course: CAE-Workshop [T-MACH-105212]**

**Responsible:** Prof. Dr.-Ing. Tobias Düser  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102684 - CAE-Workshop](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 4       | Grade to a third | Each term  | 2       |

| Events   |         |                              |       |   |       |
|----------|---------|------------------------------|-------|---|-------|
| WT 24/25 | 2147175 | <a href="#">CAE-Workshop</a> | 3 SWS | Block /  | Düser |
| ST 2025  | 2147175 | <a href="#">CAE-Workshop</a> | 3 SWS | Block /  | Düser |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written test (with practical part on the computer), duration 60 min.

**Prerequisites**

None

**Annotation**

Consistent attendance on the workshop days is required for successful participation in the exam. The number of participants is limited. Selection will be made by drawing lots after the end of the registration period.

**Workload**

120 hours


T


**8.31 Course: CATIA Advanced [T-MACH-105312]**

**Responsible:** Prof. Dr.-Ing. Jivka Ovtcharova  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-101283 - Virtual Engineering A](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 4       | Grade to a third | Each term  | 1       |

| Events   |         |                                |       |  |                     |
|----------|---------|--------------------------------|-------|--|---------------------|
| WT 24/25 | 2123380 | <a href="#">Advanced CATIA</a> | 3 SWS | Project (P /  ) | Rönnau, Mitarbeiter |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Assessment of another type. Design project and written documentation in team work and final presentation. Grading: Project work 3/5, documentation 1/5 and presentation 1/5.

**Prerequisites**

none

**Workload**

120 hours


T

**8.32 Course: CATIA CAD Training Course [T-MACH-102185]**

**Responsible:** Prof. Dr.-Ing. Jivka Ovtcharova  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-101283 - Virtual Engineering A](#)

| Type                             | Credits | Grading scale | Recurrence | Version |
|----------------------------------|---------|---------------|------------|---------|
| Completed coursework (practical) | 2       | pass/fail     | Each term  | 2       |

| Events   |         |   |       |  |                     |
|----------|---------|---|-------|--|---------------------|
| WT 24/25 | 2123358 | <a href="#">CATIA CAD training course</a> | 2 SWS | Practical course /  | Rönnau, Mitarbeiter |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Practical examination on CAD computer, duration: 60 min.

**Prerequisites**

None

**Recommendation**

Dealing with technical drawings is required.

**Annotation**

For the practical course attendance is compulsory.


**Workload**

60 hours

T

**8.33 Course: CFD for Power Engineering [T-MACH-114187]****Responsible:** Dr. Ivan Otic**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107157 - Computational Fluid Dynamics \(CFD\) for Energy Technologies](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |      |
|---------|---------|---|-------|---|------|
| ST 2025 | 2130910 | <a href="#">CFD for Power Engineering</a> | 2 SWS | Lecture /  | Otic |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Oral exam, approx. 30 min

**Prerequisites**

none

**Workload**

120 hours

T


## 8.34 Course: Channel Coding: Algebraic Methods for Communications and Storage [T-ETIT-111244]



**Responsible:** Prof. Dr.-Ing. Laurent Schmalen

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-105616 - Channel Coding: Algebraic Methods for Communications and Storage](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 1 terms   | 1       |

| Events  |         |  |       |   |          |
|---------|---------|--|-------|---|----------|
| ST 2025 | 2310546 | <a href="#">Channel Coding: Algebraic Methods for Communications and Storage</a> | 2 SWS | Lecture /  | Schmalen |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

The exam is held as an oral exam of 20 Min according to 4 Abs. 2 Nr. 1 SPO Bachelor/Master Elektrotechnik und Informationstechnik. Grade of the module corresponds to the grade of the oral exam.

### Prerequisites

none

### Recommendation





Previous attendance of the lectures "Communication Engineering I" and "Probability Theory" is recommended.

T

**8.35 Course: CO2-Neutral Combustion Engines and their Fuels I [T-MACH-111550]****Responsible:** Prof. Dr. Thomas Koch**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107060 - CO2-Neutral Combustion Engines and their Fuels I](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1 terms   | 2       |

| Events   |         |  |       |                          |      |
|----------|---------|--|-------|--------------------------|------|
| WT 24/25 | 2133113 | <a href="#">CO2-neutral combustion engines and their fuels I</a> | 3 SWS | Lecture / Practice ( / ) | Koch |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral examination, Duration: 25 min., no auxiliary means

**Prerequisites**

none

**Workload**

120 hours

T

## 8.36 Course: CO2-Neutral Combustion Engines and their Fuels II [T-MACH-111560]

**Responsible:** Prof. Dr. Thomas Koch  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-107180 - CO2-Neutral Combustion Engines and their Fuels II](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 5       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |                          |      |
|---------|---------|---|-------|--------------------------|------|
| ST 2025 | 2134151 | <a href="#">CO2-neutral combustion engines and their fuels II</a> | 3 SWS | Lecture / Practice ( / ) | Koch |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

### Competence Certificate

oral examination, duration: 25 minutes, no auxiliary means

### Prerequisites

none

### Recommendation

Fundamentals of Combustion Engines II helpful

### Workload

150 hours



T

**8.37 Course: Cognitive Automobiles - Laboratory [T-MACH-105378]**

**Responsible:** Dr. Martin Lauer  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106744 - Cognitive Automobiles - Laboratory](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |     |                          |
|---------|---------|--|-------|-----|--------------------------|
| ST 2025 | 2138341 | <a href="#">Cognitive Automobiles - Laboratory</a> | 3 SWS | / ● | Stiller, Lauer, Blumberg |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

oral exam  
30 minutes

**Prerequisites**

none

**Annotation**

The number of participants is limited. A registration is mandatory, the details are announced on the webpages of the institute of measurement and control systems (mrt). In case of too many interested students a subset will be selected (see website).

**Workload**

180 hours

T

**8.38 Course: Combined Cycle Power Plants [T-MACH-105444]**





**Responsible:** Prof. Dr.-Ing. Daniel Banuti  
Hon.-Prof. Dr. Thomas Schulenberg

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107062 - Combined Cycle Power Plants](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |                     |
|---------|---------|---|-------|---|---------------------|
| ST 2025 | 2170490 | <a href="#">Combined Cycle Power Plants</a> | 2 SWS | Lecture /  | Banuti, Schulenberg |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral exam ca. 30 min

**Prerequisites**

none

**Recommendation**

We recommend to combine the lecture with the Simulator Exercises for Combined Cycle Power Plants (T-MACH-105445).

**Workload**

120 hours

T



**8.39 Course: Communication Systems and Protocols [T-ETIT-101938]**





**Responsible:** Dr.-Ing. Jens Becker  
Prof. Dr.-Ing. Jürgen Becker

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-100539 - Communication Systems and Protocols](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |  |                |
|---------|---------|--|-------|--|----------------|
| ST 2025 | 2311616 | <a href="#">Communication Systems and Protocols</a>                      | 2 SWS | Lecture /   | Becker, Becker |
| ST 2025 | 2311618 | <a href="#">Tutorial for 2311616 Communication Systems and Protocols</a> | 1 SWS | Practice /  | Stammler       |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T



## 8.40 Course: Communications Engineering Laboratory [T-ETIT-114159]





**Responsible:** Dr.-Ing. Holger Jäkel

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-107136 - Communications Engineering Laboratory](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1       |

| Events   |         |   |       |  |                           |
|----------|---------|---|-------|--|---------------------------|
| WT 24/25 | 2310517 | <a href="#">Communication Engineering Laboratory</a>  | 4 SWS | Practical course /  | Schmalen, Jäkel, Edelmann |
| ST 2025  | 2310517 | <a href="#">Communications Engineering Laboratory</a> | 4 SWS | Practical course /  | Schmalen, Jäkel, Edelmann |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

The examination consists of the participation in the experiments and an oral examination. The overall impression is rated.

The module grade results of the participation in the experiments and an oral examination. Details will be given during the lecture.

### Prerequisites

none

### Recommendation

Previous attendance of the lectures "Signals and Systems" and "Communications Engineering I".





T

**8.41 Course: Components of Power Systems [T-ETIT-113445]**

**Responsible:** Prof. Dr.-Ing. Thomas Leibfried  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106689 - Components of Power Systems](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |              |
|---------|---------|---|-------|---|--------------|
| ST 2025 | 2307397 | <a href="#">Components of Power Systems</a> | 2 SWS | Lecture /  | Kaptue Kamga |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The examination takes place in form of an oral examination lasting approx. 20 minutes.  
 The module grade is the grade of the oral exam.

**Prerequisites**

none

T


**8.42 Course: Computational Intelligence [T-MACH-105314]**





**Responsible:** Stefan Meisenbacher  
apl. Prof. Dr. Ralf Mikut  
apl. Prof. Dr. Markus Reischl

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105296 - Computational Intelligence](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |   |                              |
|----------|---------|--|-------|---|------------------------------|
| WT 24/25 | 2105016 | <a href="#">Computational Intelligence</a> | 2 SWS | Lecture /  | Mikut, Reischl, Meisenbacher |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written exam (Duration: 1h)

**Prerequisites**

none

**Workload**

120 hours

## T


**8.43 Course: Continuum Mechanics of Solids and Fluids [T-MACH-110377]**





**Responsible:** Prof. Dr.-Ing. Thomas Böhlke  
Prof. Dr.-Ing. Bettina Frohnäpfel

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105180 - Continuum Mechanics](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1 terms   | 6       |

| Events   |         |  |       |   |                    |
|----------|---------|--|-------|---|--------------------|
| WT 24/25 | 2161252 | <a href="#">Continuum mechanics of solids and fluids</a> | 2 SWS | Lecture /  | Böhlke, Frohnäpfel |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written examination (90 min). Additives as announced

**Prerequisites**

Coursework in *Tutorial Continuum Mechanics of Solids and Fluids* (T-MACH-110333) must be passed

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-MACH-110333 - Tutorial Continuum Mechanics of Solids and Fluids](#) must have been passed.

**Annotation**

Due to capacity reasons it is possible that not all students of this course can be admitted to the computer tutorials. Students of the bachelor's degree program in mechanical engineering who have chosen the Major Field Continuum Mechanics (SP-Nr 13) and students of the bachelor's degree program in material science and material technology will be admitted to the computer tutorials in any case.

If additional places are available in the computer tutorials for this course, these will be allocated according to the BSc average grade.

**Workload**

90 hours

T

## 8.44 Course: Control of Linear Multivariable Systems [T-ETIT-100666]

**Responsible:** Dr.-Ing. Mathias Kluwe  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100374 - Control of Linear Multivariable Systems](#)



**Type**  
Written examination





**Credits**  
6

**Grading scale**  
Grade to a third

**Recurrence**  
Each winter term

**Version**  
1

| Events   |         |   |       |  |       |
|----------|---------|---|-------|--|-------|
| WT 24/25 | 2303177 | <a href="#">Control of Linear Multivariable Systems</a>                       | 3 SWS | Lecture /   | Kluwe |
| WT 24/25 | 2303179 | <a href="#">Control of Linear Multivariable Systems (Tutorial to 2303177)</a> | 1 SWS | Practice /  | Fehn  |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Success is checked as part of a written overall test (120 minutes) of the course.

### Prerequisites

none

### Recommendation

For a deeper understanding, basic knowledge of system dynamics and control technology is absolutely necessary, as taught in the ETIT Bachelor module "System Dynamics and Control Technology" M-ETIT-102181.



T

**8.45 Course: Control of Mobile Machines [T-MACH-111821]**

**Responsible:** Simon Becker  
Prof. Dr.-Ing. Marcus Geimer

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106468 - Control of Mobile Machines](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 3       |

**Competence Certificate**

The assessment consists of an oral exam (20 min) taking place in the recess period. The exam takes place in every semester. Re-examinations are offered at every ordinary examination date.

**Prerequisites**

A prerequisite for participation in the examination is the preparation of a semester report. T-MACH-111820 must be passed.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-MACH-111820 - Control of Mobile Machines – Prerequisites](#) must have been passed.

**Workload**

120 hours

T

**8.46 Course: Control of Mobile Machines – Prerequisites [T-MACH-111820]**

**Responsible:** Simon Becker  
Prof. Dr.-Ing. Marcus Geimer

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106468 - Control of Mobile Machines](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 0       | pass/fail     | Each summer term | 1       |

**Competence Certificate**

Preparation of a report on the completion of the semester task

**Prerequisites**



none





T

**8.47 Course: Control of Power-Electronic Systems [T-ETIT-111897]**

**Responsible:** Dr.-Ing. Andreas Liske  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-105915 - Control of Power-Electronic Systems](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |  |               |
|---------|---------|--|-------|--|---------------|
| ST 2025 | 2306337 | <a href="#">Control of Power-Electronic Systems</a>                      | 3 SWS | Lecture /   | Liske, Göhner |
| ST 2025 | 2306338 | <a href="#">Tutorial for 2306337 Control of Power-Electronic Systems</a> | 1 SWS | Practice /  | Liske, Göhner |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled


T

**8.48 Course: Control Technology [T-MACH-105185]**

**Responsible:** Hon.-Prof. Dr. Christoph Gönnheimer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105348 - Control Technology](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 2       |

| Events  |         |                                    |       |   |            |
|---------|---------|------------------------------------|-------|---|------------|
| ST 2025 | 2150683 | <a href="#">Control Technology</a> | 2 SWS | Lecture /  | Gönnheimer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written Exam (60 min)

**Prerequisites**

none

**Workload**

120 hours





T

**8.49 Course: Control Theory Laboratory [T-ETIT-111009]**

**Responsible:** Prof. Dr.-Ing. Sören Hohmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-105467 - Control Theory Laboratory](#)

| Type                        | Credits | Grading scale    | Recurrence | Expansion | Version |
|-----------------------------|---------|------------------|------------|-----------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1 terms   | 1       |

| Events   |         |   |       |  |                  |
|----------|---------|---|-------|--|------------------|
| WT 24/25 | 2303169 | <a href="#">Control Theory Laboratory</a> | 4 SWS | Block /             | Hohmann          |
| ST 2025  | 2303169 | <a href="#">Control Theory Laboratory</a> | 4 SWS | Practical course /  | Kluwe, Illerhaus |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none


T

**8.50 Course: Current Topics on BioMEMS [T-MACH-102176]**

**Responsible:** Prof. Dr. Andreas Guber  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105485 - Current Topics on BioMEMS](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 4       | Grade to a third | Each term  | 2       |

| Events   |         |  |       |   |               |
|----------|---------|--|-------|---|---------------|
| WT 24/25 | 2143873 | <a href="#">Actual topics of BioMEMS</a> | 2 SWS | Seminar /  | Guber, Ahrens |
| ST 2025  | 2143873 | <a href="#">Actual topics of BioMEMS</a> | 2 SWS | Seminar /  | Guber, Ahrens |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

active participation and own presentation (30 Min.)

**Prerequisites**

none

**Workload**

120 hours

## T

**8.51 Course: Cyber-Physical Modeling [T-ETIT-113908]**

**Responsible:** Prof. Dr.-Ing. Mike Barth  
Prof. Dr.-Ing. Sören Hohmann

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-106953 - Cyber-Physical Modeling](#)

| Type                | Credits | Grading scale    | Version |
|---------------------|---------|------------------|---------|
| Written examination | 6       | Grade to a third | 1       |

| Events  |         |   |       |              |                         |
|---------|---------|---|-------|--------------|-------------------------|
| ST 2025 | 2303310 | <a href="#">Cyber Physical Modeling</a>                     | 3 SWS | Lecture / 🗎  | Hohmann, Barth          |
| ST 2025 | 2303311 | <a href="#">Tutorial to 2303310 Cyber Physical Modeling</a> | 1 SWS | Practice / 🗎 | Hohmann, Barth, Thömmes |

Legend: 🗎 Online, 🔄 Blended (On-Site/Online), 🗎 On-Site, ✕ Cancelled

**Competence Certificate**

The examination takes place in the form of a written examination lasting 90 min.  
The module grade is the grade of the written exam.

**Prerequisites**

none

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-ETIT-112223 - Cyber Physical Production Systems](#) must not have been started.

T

**8.52 Course: Data Analytics for Engineers [T-MACH-105694]**





**Responsible:** Stefan Meisenbacher  
apl. Prof. Dr. Ralf Mikut  
apl. Prof. Dr. Markus Reischl

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105307 - Data Analytics for Engineers](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |   |                              |
|---------|---------|--|-------|---|------------------------------|
| ST 2025 | 2106014 | <a href="#">Data Analytics for Engineers</a> | 3 SWS | Lecture / Practice ( /  ) | Mikut, Reischl, Meisenbacher |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written exam (Duration: 1h)

**Prerequisites**

none

**Workload**


150 hours



T

**8.53 Course: Data-Driven Algorithms in Vehicle Technology [T-MACH-112126]****Responsible:** Dr. Stefan Scheubner**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107151 - Data-Driven Algorithms in Vehicle Technology](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1 terms   | 1       |

| Events   |         |  |       |   |           |
|----------|---------|--|-------|---|-----------|
| WT 24/25 | 2113840 | <a href="#">Data-Driven Algorithms in Vehicle Technology</a> | 2 SWS | Lecture /  | Scheubner |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Written Examination

Duration: 90 minutes

**Workload**

120 hours

T

## 8.54 Course: Decision-Making and Motion Planning for Automated Driving [T-MACH-113597]




**Responsible:** Dr.-Ing. Maximilian Naumann  
apl. Prof. Dr. Moritz Werling

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106926 - Decision-Making and Motion Planning for Automated Driving](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |   |                  |
|----------|---------|---|-------|---|------------------|
| WT 24/25 | 2137401 | <a href="#">Decision-Making and Motion Planning for Automated Driving</a> | 3 SWS | Lecture /  | Naumann, Werling |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

written examination, duration 60 min.

Simple calculators are allowed, programmable or graphical ones are prohibited.

### Prerequisites

none

### Annotation

Basic knowledge of control engineering and systems theory should be available from "Measurement and Control Systems" or from other lectures.

### Workload

180 hours

T

**8.55 Course: Deep Learning and Neural Networks [T-INFO-114219]**

**Responsible:** Prof. Dr. Jan Niehues  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-107197 - Deep Learning and Neural Networks](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1       |

**Competence Certificate**

The assessment is carried out as a written examination (§ 4 Abs. 2 No. 1 SPO) lasting 60 minutes.

**Prerequisites**

T-INFO-101383 - Neural networks must not be started.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-INFO-109124 - Deep Learning and Neural Networks](#) must not have been started.

**Recommendation**


Prior successful completion of the core module "Cognitive Systems" is recommended.

T

**8.56 Course: Deep Learning for Computer Vision I: Basics [T-INFO-111491]**

**Responsible:** Prof. Dr.-Ing. Rainer Stiefelhagen  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-105753 - Deep Learning for Computer Vision I: Basics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 3       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |   |                          |
|---------|---------|---|-------|---|--------------------------|
| ST 2025 | 2400007 | <a href="#">Deep Learning for Computer Vision I: Basics</a> | 2 SWS | Lecture /  | Stiefelhagen, Reiß, Peng |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment is carried out as a written examination (§ 4 Abs. 2 No. 1 SPO) lasting 120 minutes.

**Prerequisites**

None.

**Recommendation**

Basic knowledge of pattern recognition as taught in the module Cognitive Systems, is expected.

**Annotation**

The course is partially given in German and English.

T

## 8.57 Course: Deep Learning for Computer Vision II: Advanced Topics [T-INFO-111494]

**Responsible:** Prof. Dr.-Ing. Rainer Stiefelhagen

**Organisation:** KIT Department of Informatics

**Part of:** [M-INFO-105755 - Deep Learning for Computer Vision II: Advanced Topics](#)

**Type**  
Written examination

**Credits**  
3





**Grading scale**  
Grade to a third

**Recurrence**  
Each winter term

**Version**  
2

### Events



|          |         |   |       |   |                          |
|----------|---------|---|-------|---|--------------------------|
| WT 24/25 | 2400258 | <a href="#">Deep Learning for Computer Vision II: Advanced Topics</a> | 2 SWS | Lecture /  | Stiefelhagen, Reiß, Peng |
|----------|---------|---|-------|---|--------------------------|





Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T

**8.58 Course: Deep Learning for Engineers [T-MACH-113882]****Responsible:** Prof. Dr.-Ing. Christoph Stiller**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107088 - Deep Learning for Engineers](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1 terms   | 2       |

| Events  |         |  |       |  |                       |
|---------|---------|--|-------|--|-----------------------|
| ST 2025 | 2138335 | <a href="#">Deep Learning for Engineers</a>            | 2 SWS | Lecture /   | Stiller, Lauer, Pauls |
| ST 2025 | 2138337 | <a href="#">Deep Learning for Engineers (Tutorial)</a> | 1 SWS | Practice /  | Stiller, Lauer, Pauls |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

written exam

60 min

**Prerequisites**

none

**Workload**

180 hours

T





**8.59 Course: Design and Development of Mobile Machines [T-MACH-105311]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107055 - Design and Development of Mobile Machines](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |   |        |
|----------|---------|---|-------|---|--------|
| WT 24/25 | 2113079 | <a href="#">Design and Development of Mobile Machines</a> | 2 SWS | Lecture /  | Geimer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment consists of an oral exam (20 min) taking place in the recess period. The exam takes place in every semester. Re-examinations are offered at every ordinary examination date.

A registration is mandatory, the details will be announced on the webpages of the *Institute of Vehicle System Technology / Institute of Mobile Machines*. In case of too many applications, attendance will be granted based on pre-qualification.

The course will be replenished by interesting lectures of professionals from leading hydraulic companies.

**Prerequisites**

Required for the participation in the examination is the preparation of a report during the semester. T-MACH-108887 must have been passed.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-MACH-108887 - Design and Development of Mobile Machines - Advance](#) must have been passed.

**Recommendation**

Knowledge in Fluid Power Systems

**Annotation**

After completion of the lecture, students can:

- design working and travel drive train hydraulics of mobile machines and can derive characteristic key factors.
- choose and apply suitable state of the art designing methods successfully
- analyse a mobile machines and break its structure down from a complex system to subsystems with reduced complexity
- identify and describe interactions and links between subsystems of a mobile machine
- present and document solutions of a technical problem according to R&D standards

The number of participants is limited.

**Content:**

The working scenario of a mobile machine depends strongly on the machine itself. Highly specialised machines, e.g. pavers are also as common as universal machines with a wide range of applications, e.g. hydraulic excavators. In general, all mobile machines are required to do their intended work in an optimal way and satisfy various criteria at the same time. This makes designing mobile machines to a great and interesting challenge. Nevertheless, usually key factors can be derived for every mobile machine, which affect all other machine parameters. During this lecture, those key factors and designing mobile machines accordingly will be addressed. To do so, an exemplary mobile machine will be discussed and designed in the lecture as a semester project.

**Literature:**

See german recommendations

**Workload**

120 hours

T

**8.60 Course: Design and Development of Mobile Machines - Advance [T-MACH-108887]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
Jan Siebert

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107055 - Design and Development of Mobile Machines](#)

| Type                 | Credits | Grading scale | Recurrence | Version |
|----------------------|---------|---------------|------------|---------|
| Completed coursework | 0       | pass/fail     | Each term  | 1       |

**Competence Certificate**

Preparation of semester report

**Prerequisites**

none



T

## 8.61 Course: Design and Optimization of Conventional and Electrified Automotive Transmissions [T-MACH-110958]





**Responsible:** Dr.-Ing. Hartmut Faust

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107082 - Design and Optimization of Conventional and Electrified Automotive Transmissions](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |       |
|---------|---------|--|-------|---|-------|
| ST 2025 | 2146208 | <a href="#">Design and Optimization of Conventional and Electrified Automotive Transmissions</a> | 2 SWS | Lecture /  | Faust |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

oral exam (20 min)

### Prerequisites

none

### Workload



120 hours

T

## 8.62 Course: Design of Electrical Machines [T-ETIT-100785]

**Responsible:** Prof. Dr. Martin Doppelbauer  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100515 - Design of Electrical Machines](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each winter term | 2       |

| Events   |         |  |       |  |             |
|----------|---------|--|-------|--|-------------|
| WT 24/25 | 2306324 | <a href="#">Design of Electrical Machines</a>                      | 2 SWS | Lecture /   | Doppelbauer |
| WT 24/25 | 2306325 | <a href="#">Tutorial for 2306324 Design of Electrical Machines</a> | 1 SWS | Practice /  | Doppelbauer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Prerequisites

none

### Recommendation

Modul: Elektrische Maschinen und Stromrichter


T

**8.63 Course: Design with Plastics [T-MACH-105330]**

**Responsible:** Dipl.-Ing. Markus Liedel  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102712 - Design with Plastics](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |                                      |       |   |        |
|---------|---------|--------------------------------------|-------|---|--------|
| ST 2025 | 2174571 | <a href="#">Design with Plastics</a> | 2 SWS | Block /  | Liedel |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Oral exam, about 20 minutes

**Prerequisites**

none

**Recommendation**

Poly I

**Workload**

120 hours

T


## 8.64 Course: Development of Hybrid Drivetrains [T-MACH-110817]

**Responsible:** Prof. Dr. Thomas Koch

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107078 - Development of Hybrid Powertrains](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |                   |
|---------|---------|---|-------|---|-------------------|
| ST 2025 | 2134155 | <a href="#">Development of Hybrid Powertrains</a> | 2 SWS | Lecture /  | Koch, Doppelbauer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

written exam, 1 hour

### Prerequisites

None

### Workload

120 hours

T


**8.65 Course: Development of Oil-Hydraulic Powertrain Systems [T-MACH-105441]**





**Responsible:** Dr.-Ing. Gerhard Geerling  
Prof. Dr.-Ing. Marcus Geimer

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107059 - Development of Oil-Hydraulic Powertrain Systems](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |   |          |
|----------|---------|---|-------|---|----------|
| WT 24/25 | 2113072 | <a href="#">Development of Oil-Hydraulic Powertrain Systems</a> | 2 SWS | Block /  | Geerling |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral exam (approx. 20 min)

**Prerequisites**

none

**Workload**



120 hours





T

**8.66 Course: Digital Beam-Forming for Imaging Radar [T-ETIT-110940]**

**Responsible:** Prof. Dr.-Ing. Thomas Zwick  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-105415 - Digital Beam-Forming for Imaging Radar](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |  |        |
|----------|---------|---|-------|--|--------|
| WT 24/25 | 2308450 | <a href="#">Digital Beam-Forming for Imaging Radar</a>                      | 2 SWS | Lecture /   | Younis |
| WT 24/25 | 2308451 | <a href="#">Tutorial for 2308450 Digital Beam-Forming for Imaging Radar</a> | 1 SWS | Practice /  | Younis |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written Exam approx. 120 Min.

**Prerequisites**

*The basic principles will be repeated in the lecture. The following lectures are helpful for a comprehensive understanding: Radar System Engineering (engl.), Antennen und Mehrantennensysteme, Spaceborne Radar Remote Sensing (engl.), Modern Radio System Engineering (engl.)*

**Recommendation**

*Basics of signal processing and radar techniques are useful.*

T

**8.67 Course: Digital Circuit Design [T-ETIT-100974 ]**

**Responsible:** Prof. Dr. Ivan Peric  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100473 - Digital Circuit Design](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |              |       |
|---------|---------|--|-------|--------------|-------|
| ST 2025 | 2312683 | <a href="#">Digital Circuit Design</a>             | 2 SWS | Lecture / 🔄  | Peric |
| ST 2025 | 2312685 | <a href="#">Practice to Digital Circuit Design</a> | 1 SWS | Practice / 🔄 | Peric |

Legend: 📺 Online, 🔄 Blended (On-Site/Online), 📍 On-Site, ✕ Cancelled


T

**8.68 Course: Digital Control [T-MACH-105317]**

**Responsible:** Prof. Dr.-Ing. Michael Knoop  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107045 - Digital Control](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |                                 |       |   |             |
|----------|---------|---------------------------------|-------|---|-------------|
| WT 24/25 | 2137309 | <a href="#">Digital Control</a> | 2 SWS | Lecture /  | Knoop, Rack |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

written exam

60 min.

**Prerequisites**

none

**Workload**

120 hours




T

**8.69 Course: Digital Hardware Design Laboratory [T-ETIT-104571]**

**Responsible:** Prof. Dr.-Ing. Jürgen Becker  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-102266 - Digital Hardware Design Laboratory](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |  |        |
|---------|---------|--|-------|--|--------|
| ST 2025 | 2311645 | <a href="#">Digital Hardware Design Laboratory</a> | 4 SWS | Practical course /  | Becker |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Control of success is carried out in an oral examination as well as during the laboratory exercises in form of laboratory reports and/or oral interrogations.

**Prerequisites**

none

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The module [M-ETIT-102264 - Digital Hardware Design Laboratory](#) must not have been started.

**Recommendation**

Previous knowledge in design and design automation for electronic systems (e.g. from the lectures SAE, No. 23606, HSO, No. 23619 or HMS, No. 23608) is recommended.

**Annotation**

The module ETIT-102264 („Praktikum Entwurf digitaler Systeme“) must not have been started or completed.





T

**8.70 Course: Digital Hardware Design Laboratory [T-ETIT-104570]**

**Responsible:** Prof. Dr.-Ing. Jürgen Becker  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-102264 - Digital Hardware Design Laboratory](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |  |        |
|---------|---------|---|-------|--|--------|
| ST 2025 | 2311637 | <a href="#">Laboratory in Design Automation</a> | 4 SWS | Practical course /  | Becker |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

**Modeled Conditions**


The following conditions have to be fulfilled:


1. The module [M-ETIT-102266 - Digital Hardware Design Laboratory](#) must not have been started.

T

**8.71 Course: Digital Twin Engineering [T-ETIT-112224]****Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-106040 - Digital Twin Engineering](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |   |                |
|----------|---------|--|-------|---|----------------|
| WT 24/25 | 2301486 | <a href="#">Digital Twin Engineering</a> | 2 SWS | Lecture /  | Barth, Witucki |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

The examination takes place in form of other types of examination. It consists of a model library developed in the course of a semester-long project in the modeling language Modelica and a presentation of the library lasting 25 minutes. The quality of the model library is evaluated within the framework of the criteria: documentation, formal correctness, functionality, usability, HMI and modeling level of detail. The presentation is evaluated as an additional aspects. The overall impression is evaluated.

The assessment of the developed model library and the presentation of the library will be included in the module grade. More details will be given at the beginning of the course.

**Prerequisites**

none

T

**8.72 Course: Digitalization of Products, Services & Production [T-MACH-108491]****Responsible:** Dr.-Ing. Bernd Pätzold**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105476 - Digitalization of Products, Services & Production](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 4       | Grade to a third | Each term  | 2       |

**Competence Certificate**

Assessment of another type. Two presentations in team work and two written compositions. Grading: each composition 1/6 and each presentation 2/3.

**Prerequisites**

none

**Workload**

120 hours





T

**8.73 Course: Digitization in the Railway System [T-MACH-113016]**

**Responsible:** Prof. Dr.-Ing. Martin Cichon  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-106513 - Railway System Digitalisation](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1 terms   | 2       |

| Events   |         |   |       |   |              |
|----------|---------|---|-------|---|--------------|
| WT 24/25 | 2115920 | <a href="#">Railway System Digitalisation</a> | 2 SWS | Lecture /  | Jost, Cichon |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Oral examination

Duration: approx. 20 minutes

No tools or reference material may be used during the exam.

**Workload**



120 hours

T

**8.74 Course: Distributed Discrete Event Systems [T-ETIT-100960]**

**Responsible:** Prof. Dr.-Ing. Michael Heizmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100361 - Distributed Discrete Event Systems](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |  |          |
|---------|---------|--|-------|--|----------|
| ST 2025 | 2302106 | <a href="#">Distributed Discrete Event Systems</a>             | 2 SWS | Lecture /   | Heizmann |
| ST 2025 | 2302108 | <a href="#">Practice to Distributed Discrete Event Systems</a> | 1 SWS | Practice /  | Hoffmann |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

## 8.75 Course: Drive System Engineering B: Stationary Machinery [T-MACH-114000]

**Responsible:** Sascha Ott

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107190 - Drive System Engineering B: Stationary Machinery](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1 terms   | 2       |

### Competence Certificate

written examination: 90 min duration

### Prerequisites

Mutual exclusion with T-MACH-113981 (combined course/ exam) and T-MACH-105216 (German variant)

### Recommendation

None

### Annotation

None

### Workload

120 hours

## T

## 8.76 Course: Drive Train of Mobile Machines [T-MACH-105307]

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105800 - Drive Train of Mobile Machines](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |               |                        |
|----------|---------|--|-------|---------------|------------------------|
| WT 24/25 | 2113077 | <a href="#">Drive Train of Mobile Machines</a>         | 2 SWS | Lecture / 🗣️  | Geimer                 |
| WT 24/25 | 2113078 | <a href="#">Exercise Drivetrain of Mobile Machines</a> | 1 SWS | Practice / 🗣️ | Geimer, Bargaen-Herzog |

Legend: 🗣️ Online, 🔄 Blended (On-Site/Online), 🗣️ On-Site, ✕ Cancelled

### Competence Certificate

The final assessment will be an oral examination (20 min) taking place during the recess period. The examination will be offered in every semester and can be repeated at any regular examination date.

### Prerequisites

none

### Recommendation

- General principles of mechanicals engineering
- Basic knowledge of hydraulics
- Interest in mobile machinery

### Annotation

At the end of the lecture, participants can explain the structure and function of all discussed drive trains of mobile machines. They can analyze complex gearbox schematics and synthesize simple transmission functions using rough calculations.

### Content:

In this course the different drive trains of mobile machinery will be discussed. The focus of this course is:

- mechanical gears
- torque converter
- hydrostatic drives
- power split drives
- electrical drives
- hybrid drives
- axles
- terra mechanics

**Media:** projector presentation

**Literature:** Download of lecture slides from ILIAS. Further literature recommendations during lectures.

### Workload

120 hours



T

**8.77 Course: Dynamics of Electro-Mechanical Systems [T-MACH-111260]**

**Responsible:** Philipp Altoé  
Prof. Dr.-Ing. Alexander Fidlín

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105612 - Dynamics of Electro-Mechanical Systems](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 5       | Grade to a third | Each summer term | 1 terms   | 2       |

**Competence Certificate**

Written exam, 180 minutes

**Prerequisites**

None

**Workload**

150 hours

T

**8.78 Course: Dynamics of the Automotive Drive Train [T-MACH-105226]****Responsible:** Prof. Dr.-Ing. Alexander Fidlin**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-102700 - Dynamics of the Automotive Drive Train](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 3       |

**Competence Certificate**

Oral examination, 30 min.

**Prerequisites**

none

**Recommendation**

Powertrain Systems Technology A: Automotive Systems Machine Dynamics Vibration Theory

**Workload**

120 hours

T

## 8.79 Course: Educational Development for Student Teachers - Basic Level [T-ETIT-100797]

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

**Type**  
Completed coursework

**Credits**  
2

**Grading scale**  
pass/fail

**Recurrence**  
Each term

**Version**  
1

| Events   |         |   |  |              |     |
|----------|---------|---|--|--------------|-----|
| WT 24/25 | 2411802 | <a href="#">Tutorenschulung „Start in die Lehre“ (PEBA)</a> |  | Others (sons | Heß |

### Competence Certificate

Success monitoring consists of participation in attendance modules (attendance requirement of 80%) and submission of a written reflection portfolio.

Attendance is required both to perform the work as a team on-site and to provide practical techniques and skills that cannot be learned in pure self-study.

### Prerequisites


Part-time work as a tutor at KIT during program participation.

T

**8.80 Course: Electric Drives and Power Electronics Lab [T-ETIT-114162]**

**Responsible:** Prof. Dr. Martin Doppelbauer  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-107138 - Electric Drives and Power Electronics Lab](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |  |                   |
|---------|---------|--|-------|--|-------------------|
| ST 2025 | 2306331 | <a href="#">Lab Course Electrical Drives and Power Electronics</a> | 4 SWS | Practical course /  | Brodatzki, Hiller |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Success control takes place in the form of other types of examination. It consists of one oral examination per experiment. The overall impression is assessed.

The assessments of the oral examinations are included in the module grade. Further details will be provided at the beginning of the course.

**Prerequisites**



none

## T

**8.81 Course: Electric Drives for E-Mobility [T-ETIT-113936]**

**Responsible:** Prof. Dr. Martin Doppelbauer  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106971 - Electric Drives for E-Mobility](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |  |             |
|---------|---------|--|-------|--|-------------|
| ST 2025 | 2306500 | <a href="#">Electric Drives for E-Mobility</a>                     | 2 SWS | Lecture /   | Doppelbauer |
| ST 2025 | 2306501 | <a href="#">Practice to 2306500 Electric Drives for E-Mobility</a> | 1 SWS | Practice /  | Doppelbauer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The success control takes place in the form of an oral examination of approximately 30 minutes.

**Prerequisites**

none

**Recommendation**

Basic knowledge in the field of electric machines and drives is helpful, for example by attending the course "Elektrische Maschinen und Stromrichter (EMS)" in the KIT-Bachelor.

Basic knowledge in the field of hybrid and electric vehicles is helpful, for example by attending the course "Hybridelektrische Fahrzeuge HEF)" in the KIT-Bachelor.

T

**8.82 Course: Electric Power Transmission & Grid Control [T-ETIT-110883]****Responsible:** Prof. Dr.-Ing. Thomas Leibfried**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-105394 - Electric Power Transmission & Grid Control](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1 terms   | 2       |

| Events   |         |   |       |              |           |
|----------|---------|---|-------|--------------|-----------|
| WT 24/25 | 2307376 | <a href="#">Electric Power Transmission &amp; Grid Control</a>                      | 2 SWS | Lecture / ✕  | Leibfried |
| ST 2025  | 2307376 | <a href="#">Electric Power Transmission &amp; Grid Control</a>                      | 2 SWS | Lecture / 🎧  | Leibfried |
| ST 2025  | 2307377 | <a href="#">Tutorial for 2307376 Electric Power Transmission &amp; Grid Control</a> | 2 SWS | Practice / 🎧 | Weber     |

Legend: 📺 Online, 🎧 Blended (On-Site/Online), 🎧 On-Site, ✕ Cancelled

**Competence Certificate**

The examination takes place in form of a written examination lasting 120 minutes. The module grade is the grade of the written exam.

**Prerequisites**

none

T

**8.83 Course: Electrical Energy Systems Lab [T-ETIT-114160]**

**Responsible:** Dr.-Ing. Rainer Badent  
 Prof. Dr. Martin Doppelbauer  
 Prof. Dr.-Ing. Thomas Leibfried

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-107137 - Electrical Energy Systems Lab](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |                      |                         |
|----------|---------|---|-------|----------------------|-------------------------|
| WT 24/25 | 2307398 | <a href="#">Lab Course Electrical Power Engineering</a> | 4 SWS | Practical course / ● | Badent, Brodatzki, N.N. |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

Success control takes place in the form of other types of examinations consisting of written and oral questions on the content of the experiments. The overall impression is assessed.

The questions on the individual experiments are included in the module grade. Further details will be provided at the beginning of the course.

**Prerequisites**

none

**Recommendation**

Participation in the courses Elektrische Maschinen and Stromrichter and Elektroenergiesysteme (bachelor courses)

**Annotation**



Joint event of the IEH and the ETI.

T

**8.84 Course: Electrocatalysis [T-ETIT-111831]**

**Responsible:** Dr. Philipp Röse  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-105883 - Electrocatalysis](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |  |      |
|---------|---------|--|-------|--|------|
| ST 2025 | 2304300 | <a href="#">Electrocatalysis</a>                         | 3 SWS | Lecture /   | Röse |
| ST 2025 | 2304301 | <a href="#">Exercise to 2304300<br/>Electrocatalysis</a> | 1 SWS | Practice /  | Röse |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The examination takes place in form of a written examination lasting 120 minutes.



T

**8.85 Course: Elements and Systems of Technical Logistics [T-MACH-102159]**

**Responsible:** Georg Fischer  
Dr.-Ing. Martin Mittwollen

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102688 - Elements of Technical Logistics](#)  
[M-MACH-105015 - Elements of Technical Logistics incl. Project](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

**Competence Certificate**

The assessment consists of an oral exam (20min) taking place in the recess period according to § 4 paragraph 2 Nr. 2 of the examination regulation.

**Prerequisites**

none

**Recommendation**

Knowledge out of "Basics of Technical Logistics I" (T-MACH-109919) preconditioned.

**Workload**

120 hours

T

## 8.86 Course: Elements and Systems of Technical Logistics - Project [T-MACH-108946]

**Responsible:** Georg Fischer  
Dr.-Ing. Martin Mittwollen

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105015 - Elements of Technical Logistics incl. Project](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 2       | Grade to a third | Each winter term | 1       |

### Competence Certificate

Presentation of performed project and defense (30min) according to §4 (2), No. 3 of the examination regulation

### Prerequisites

T-MACH-102159 (Elements and Systems of Technical Logistics) must have been started

### Modeled Conditions

The following conditions have to be fulfilled:

1. The course [T-MACH-102159 - Elements and Systems of Technical Logistics](#) must have been started.

### Recommendation

Knowledge out of "Basics of Technical Logistics I" (T-MACH-109919) preconditioned.

### Workload



60 hours





## T

## 8.87 Course: Energy Storage and Network Integration [T-ETIT-104644]

**Responsible:** Prof. Dr.-Ing. Mathias Noe  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-101969 - Energy Storage and Network Integration](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 2       |

| Events   |         |   |       |  |                  |
|----------|---------|---|-------|--|------------------|
| WT 24/25 | 2312687 | <a href="#">Energy Storage and Network Integration</a>                      | 2 SWS | Lecture /   | Grilli, De Carne |
| WT 24/25 | 2312689 | <a href="#">Tutorial for 2312687 Energy Storage and Network Integration</a> | 1 SWS | Practice /  | De Carne, Grilli |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Success is assessed in an overall oral examination (30 minutes).

**Prerequisites**

The course "T-MACH-105952 – Energiespeicher und Netzintegration" must not have started.

**Recommendation**

Basic knowledge in the fields of Electrical Engineering and Thermodynamics is helpful.


**Annotation**





Exam and Lecture will be held in English.

T

**8.88 Course: Energy Systems I: Renewable Energy [T-MACH-105408]****Responsible:** apl. Prof. Dr. Ron Dagan**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107139 - Energy Systems I - Renewable Energy](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 2       |

| Events   |         |   |       |   |       |
|----------|---------|---|-------|---|-------|
| WT 24/25 | 2129901 | <a href="#">Energy Systems I - Renewable Energy</a> | 2 SWS | Lecture /  | Dagan |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam, approx. 1/2 hour

**Prerequisites**

none

**Workload**

120 hours


T

**8.89 Course: Energy Systems II: Reactor Physics [T-MACH-105550]**

**Responsible:** Dr. Aurelian Florin Badea  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107071 - Reactor Physics](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |       |
|---------|---------|--|-------|---|-------|
| ST 2025 | 2130929 | <a href="#">Energy systems II: Reactor Physics</a> | 2 SWS | Lecture /  | Badea |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral exam, 20 min

**Prerequisites**

none

**Workload**


120 hours





T

**8.90 Course: Energy Topology and Resilience [T-MACH-112755]**

**Responsible:** Dr. Sadeeb Simon Ottenburger  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-107061 - Energy Topology and Resilience](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |             |
|---------|---------|--|-------|---|-------------|
| ST 2025 | 2153446 | <a href="#">Energy Topology and Resilience</a> | 2 SWS | Lecture /  | Ottenburger |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral

Duration: approx. 30 minutes

No auxiliary meand

**Prerequisites**

none

**Workload**

140 hours

T

**8.91 Course: Engine Measurement Techniques [T-MACH-105169]**

**Responsible:** Dr.-Ing. Sören Bernhardt  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107160 - Engine Measurement Techniques](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |           |
|---------|---------|---|-------|---|-----------|
| ST 2025 | 2134137 | <a href="#">Engine measurement techniques</a> | 2 SWS | Lecture /  | Bernhardt |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral examination, Duration: 0,5 hours, no auxiliary means

**Prerequisites**

none

**Recommendation**

T-MACH-102194 Combustion Engines I


**Workload**





120 hours

T

**8.92 Course: Engineering Materials for the Energy Transition [T-MACH-112691]****Responsible:** Prof. Dr. Hans Jürgen Seifert**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107066 - Engineering Materials for the Energy Transition](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |                  |
|---------|---------|---|-------|---|------------------|
| ST 2025 | 2193008 | <a href="#">Engineering Materials for the Energy Transition</a> | 2 SWS | Lecture /  | Seifert, Ziebert |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam; about 30 minutes

**Prerequisites**

T-MACH-108688 - The energetics of engineering materials for the energy transition must not have been started.

**Recommendation**

Knowledge of Materials Science.

**Workload**

120 hours



T


**8.93 Course: Engineer's Field of Work [T-MACH-105721]**





**Responsible:** Prof. Dr. Martin Doppelbauer  
Prof. Dr.-Ing. Marcus Geimer

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                           | Credits | Grading scale | Recurrence       | Version |
|--------------------------------|---------|---------------|------------------|---------|
| Completed coursework (written) | 2       | pass/fail     | Each summer term | 2       |

| Events  |         |  |       |   |                     |
|---------|---------|--|-------|---|---------------------|
| ST 2025 | 2114917 | <a href="#">Engineer's Field of Work</a> | 2 SWS | Lecture /  | Doppelbauer, Geimer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

written test

Duration: 60 minutes

result: passed / not passed

No tools or reference materials may be used during the exam.

**Prerequisites**

none

**Workload**

60 hours

T

**8.94 Course: Entrepreneurship [T-WIWI-102864]**

**Responsible:** Prof. Dr. Orestis Terzidis  
**Organisation:** KIT Department of Economics and Management  
**Part of:** [M-ETIT-105073 - Student Innovation Lab](#)



**Type**  
Written examination





**Credits**  
3

**Grading scale**  
Grade to a third

**Recurrence**  
Each term

**Version**  
1

| Events   |         |                                  |       |   |                |
|----------|---------|----------------------------------|-------|---|----------------|
| WT 24/25 | 2545001 | <a href="#">Entrepreneurship</a> | 2 SWS | Lecture /  | Terzidis, Dang |
| ST 2025  | 2545001 | <a href="#">Entrepreneurship</a> | 2 SWS | Lecture /  | Terzidis, Dang |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment consists of a written exam (60 minutes) (following §4(2), 1 of the examination regulation).

Students are offered the opportunity to earn a grade bonus through separate assignments. If the grade of the written exam is between 4.0 and 1.3, the bonus improves the grade by a maximum of one grade level (0.3 or 0.4). The exact criteria for awarding a bonus will be announced at the beginning of the lecture.

**Prerequisites**

None

**Recommendation**


None





T

**8.95 Course: Ethics of Technology [T-MACH-113903]**

**Responsible:** Prof. Dr. Dr. Rafaela Hillerbrand  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                 | Credits | Grading scale | Recurrence       | Expansion | Version |
|----------------------|---------|---------------|------------------|-----------|---------|
| Completed coursework | 2       | pass/fail     | Each summer term | 1 terms   | 2       |

| Events  |         |                               |  |   |                        |
|---------|---------|-------------------------------|--|---|------------------------|
| ST 2025 | 9003014 | <a href="#">Energy Ethics</a> |  | Seminar /  | Frigo, Calidori, Gruba |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Academic achievements in the form of written assignments and/or oral performances.

**Prerequisites**

none

**Workload**

60 hours

T



## 8.96 Course: Fabrication Processes in Microsystem Technology [T-MACH-102166]





**Responsible:** Dr. Klaus Bade

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105478 - Fabrication Processes in Microsystem Technology](#)

| Type             | Credits | Grading scale    | Recurrence | Version |
|------------------|---------|------------------|------------|---------|
| Oral examination | 4       | Grade to a third | Each term  | 1       |

| Events   |         |   |       |   |      |
|----------|---------|---|-------|---|------|
| WT 24/25 | 2143882 | <a href="#">Fabrication Processes in Microsystem Technology</a> | 2 SWS | Lecture /  | Bade |
| ST 2025  | 2143882 | <a href="#">Fabrication Processes in Microsystem Technology</a> | 2 SWS | Lecture /  | Bade |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Oral examination, 20 minutes

### Prerequisites

none

### Workload



120 hours

T

**8.97 Course: Field Propagation and Coherence [T-ETIT-100976]**

**Responsible:** Prof. Dr. Wolfgang Freude  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100566 - Field Propagation and Coherence](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |  |              |
|----------|---------|--|-------|--|--------------|
| WT 24/25 | 2309466 | <a href="#">Field Propagation and Coherence</a>                      | 2 SWS | Lecture /   | Freude       |
| WT 24/25 | 2309467 | <a href="#">Tutorial for 2309466 Field Propagation and Coherence</a> | 1 SWS | Practice /  | Freude, N.N. |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled



**Prerequisites**





none

T

**8.98 Course: Flows and Heat Transfer in Energy Technology [T-MACH-105403]****Responsible:** Prof. Dr.-Ing. Xu Cheng**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107120 - Flows and Heat Transfer in Energy Technology](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |  |                    |
|----------|---------|--|-------|--|--------------------|
| WT 24/25 | 2189910 | <a href="#">Flows and Heat Transfer in Energy Technology</a>             | 2 SWS | Lecture /   | Cheng              |
| WT 24/25 | 2189911 | <a href="#">Tutorial 'Flows and Heat Transfer in Energy Technology '</a> | 1 SWS | Practice /  | Cheng, Mitarbeiter |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam, 20 min

**Prerequisites**

none

**Workload**

120 hours

T



## 8.99 Course: Fundamentals in the Development of Commercial Vehicles [T-MACH-111389]





**Responsible:** Christof Weber

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105824 - Fundamentals in the Development of Commercial Vehicles](#)

| Type             | Credits | Grading scale    | Recurrence      | Version |
|------------------|---------|------------------|-----------------|---------|
| Oral examination | 4       | Grade to a third | see Annotations | 2       |

| Events   |         |   |       |   |       |
|----------|---------|---|-------|---|-------|
| WT 24/25 | 2113812 | <a href="#">Fundamentals in the Development of Commercial Vehicles I</a>  | 1 SWS | Lecture /  | Weber |
| ST 2025  | 2114844 | <a href="#">Fundamentals in the Development of Commercial Vehicles II</a> | 1 SWS | Lecture /  | Weber |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Oral group examination

Duration: appr. 30 minutes

Auxiliary means: none

### Prerequisites

none

### Annotation

Fundamentals in the Development of Commercial Vehicles I, WT

Fundamentals in the Development of Commercial Vehicles II, ST



### Workload





120 hours

T

**8.100 Course: Fundamentals of Automobile Development I [T-MACH-105162]****Responsible:** Dr. Manfred Harrer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105289 - Principles of Whole Vehicle Engineering I](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 2       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |   |        |
|----------|---------|---|-------|---|--------|
| WT 24/25 | 2113810 | <a href="#">Fundamentals of Automobile Development I</a>  | 1 SWS | Lecture /  | Harrer |
| WT 24/25 | 2113851 | <a href="#">Principles of Whole Vehicle Engineering I</a> | 1 SWS | Lecture /  | Harrer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Written examination

Duration: 90 minutes

Auxiliary means: none

**Prerequisites**

none

**Workload**



60 hours







T

**8.101 Course: Fundamentals of Automobile Development II [T-MACH-105163]****Responsible:** Dr. Manfred Harrer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105290 - Principles of Whole Vehicle Engineering II](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 2       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |   |        |
|---------|---------|--|-------|---|--------|
| ST 2025 | 2114842 | <a href="#">Principles of Whole Vehicle Engineering II</a> | 1 SWS | Block /  | Harrer |
| ST 2025 | 2114860 | <a href="#">Principles of Whole Vehicle Engineering II</a> | 1 SWS | /         | Harrer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Written examination

Duration: 90 minutes

Auxiliary means: none

**Prerequisites**

none

**Workload**

60 hours





T


**8.102 Course: Fundamentals of Combustion I [T-MACH-105213]**

**Responsible:** Prof. Dr. Ulrich Maas  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102707 - Fundamentals of Combustion I](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 3       |

| Events   |         |   |       |  |                 |
|----------|---------|---|-------|--|-----------------|
| WT 24/25 | 2165515 | <a href="#">Fundamentals of Combustion I</a>            | 2 SWS | Lecture /   | Maas, Shrotriya |
| WT 24/25 | 2165517 | <a href="#">Fundamentals of Combustion I (Tutorial)</a> | 1 SWS | Practice /  | Bykov           |
| WT 24/25 | 3165016 | <a href="#">Fundamentals of Combustion I</a>            | 2 SWS | Lecture /   | Maas            |
| WT 24/25 | 3165017 | <a href="#">Fundamentals of Combustion I (Tutorial)</a> | 1 SWS | Practice /  | Bykov           |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written exam, approx. 3 hours

**Prerequisites**

T-MACH-114043 and T-MACH-113998 must not have started

**Workload**

120 hours

## T



## 8.103 Course: Fundamentals of Combustion II [T-MACH-114044]





**Responsible:** Dr. Viatcheslav Bykov  
Prof. Dr. Ulrich Maas

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107117 - Fundamentals of Combustion II](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |  |                        |
|---------|---------|--|-------|--|------------------------|
| ST 2025 | 3166550 | <a href="#">Fundamentals of Combustion II</a>            | 2 SWS | Lecture /   | Maas, Shrotriya, Bykov |
| ST 2025 | 3166551 | <a href="#">Fundamentals of Combustion II (Tutorial)</a> | 1 SWS | Practice /  | Maas, Bykov, Shrotriya |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

oral exam

### Prerequisites

T-MACH-105325 and T-MACH-113998 must not be started

### Workload

120 hours

T



**8.104 Course: Fundamentals of Energy Technology [T-MACH-105220]**





**Responsible:** Dr. Aurelian Florin Badea  
Prof. Dr.-Ing. Xu Cheng

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102690 - Fundamentals of Energy Technology](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 8       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |              |
|---------|---------|---|-------|---|--------------|
| ST 2025 | 2130927 | <a href="#">Fundamentals of Energy Technology</a> | 3 SWS | Lecture /  | Cheng, Badea |
| ST 2025 | 3190923 | <a href="#">Fundamentals of Energy Technology</a> | 3 SWS | Lecture /  | Badea        |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written examination, 90 min

**Prerequisites**

none

**Workload**

240 hours

T

**8.105 Course: Fundamentals of Reactor Safety for the Operation and Dismantling of Nuclear Power Plants [T-MACH-105530]****Responsible:** Dr. Victor Hugo Sanchez-Espinoza**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107150 - Fundamentals of Reactor Safety for the Operation and Dismantling of Nuclear Power Plants](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

**Competence Certificate**

oral exam about 30 minutes

**Prerequisites**

none

**Workload**

120 hours

T

**8.106 Course: Fusion Technology A [T-MACH-105411]**

**Responsible:** Dr. Sara Perez Martin  
Dr. Klaus-Peter Weiss

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107124 - Fusion Technology A](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 2       |

| Events   |         |  |       |                           |                     |
|----------|---------|--|-------|---------------------------|---------------------|
| WT 24/25 | 2169483 | <a href="#">Fusion Technology A</a>          | 2 SWS | Lecture / Practice ( / ●) | Weiss, Perez Martin |
| WT 24/25 | 2169484 | <a href="#">Exercise Fusion Technology A</a> | 2 SWS | Practice / ●              | Weiss, Perez Martin |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

oral exam of about 30 minutes

**Prerequisites**

T-MACH-113977 must not have been started.

**Recommendation**

appreciated is knowledge in heat and mass transfer as well as in electrical engineering, basic knowledge in fluid mechanics, material sciences and physics

**Workload**

120 hours

T

**8.107 Course: Fusion Technology B [T-MACH-105433]**

**Responsible:** Dr. Sara Perez Martin  
Dr. Michael Rieth

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107154 - Fusion Technology B](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |              |                     |
|---------|---------|--|-------|--------------|---------------------|
| ST 2025 | 2190492 | <a href="#">Fusion Technology B</a>          | 2 SWS | Lecture / 🗣️ | Perez Martin, Rieth |
| ST 2025 | 2190493 | <a href="#">Exercise Fusion Technology B</a> | 2 SWS | Practice / 📱 | Perez Martin, Rieth |

Legend: 📱 Online, 🔄 Blended (On-Site/Online), 🗣️ On-Site, ✕ Cancelled

**Competence Certificate**

oral exam of about 30 minutes

**Prerequisites**

none

**Recommendation**

attendance of fusion technology A lecture

reliable capability to use fundamental knowledge communicated in the bachelor study in physics, material sciences , electrical engineering and engineering design

**Annotation**

none


**Workload**





120 hours

T

**8.108 Course: Handling Characteristics of Motor Vehicles I [T-MACH-105152]****Responsible:** Dr.-Ing. Hans-Joachim Unrau**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105288 - Handling Characteristics of Motor Vehicles I](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |   |       |
|----------|---------|--|-------|---|-------|
| WT 24/25 | 2113807 | <a href="#">Handling Characteristics of Motor Vehicles I</a> | 2 SWS | Lecture /  | Unrau |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Verbally

Duration: 30 up to 40 minutes

Auxiliary means: none

**Prerequisites**

none

**Workload**


120 hours







T

**8.109 Course: Handling Characteristics of Motor Vehicles II [T-MACH-105153]****Responsible:** Dr.-Ing. Hans-Joachim Unrau**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107073 - Handling Characteristics of Motor Vehicles II](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |       |
|---------|---------|---|-------|---|-------|
| ST 2025 | 2114838 | <a href="#">Handling Characteristics of Motor Vehicles II</a> | 2 SWS | Lecture /  | Unrau |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Oral Examination

Duration: 30 up to 40 minutes

Auxiliary means: none

**Prerequisites**

none

**Workload**

120 hours

T



**8.110 Course: Hardware Modeling and Simulation [T-ETIT-100672]**





**Responsible:** Dr.-Ing. Jens Becker  
Prof. Dr.-Ing. Jürgen Becker

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-100449 - Hardware Modeling and Simulation](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 2       |

| Events   |         |   |       |  |                |
|----------|---------|---|-------|--|----------------|
| WT 24/25 | 2311608 | <a href="#">Hardware Modeling and Simulation</a>                      | 2 SWS | Lecture /   | Becker, Becker |
| WT 24/25 | 2311610 | <a href="#">Tutorial for 2311608 Hardware Modeling and Simulation</a> | 1 SWS | Practice /  | Unger          |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Achievement is examined in the form of a written examination lasting 120 minutes.

**Prerequisites**



none





T

**8.111 Course: Hardware Synthesis and Optimization [T-ETIT-113922]**

**Responsible:** Prof. Dr.-Ing. Jürgen Becker  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106963 - Hardware Synthesis and Optimization](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |  |         |
|---------|---------|--|-------|--|---------|
| ST 2025 | 2311619 | <a href="#">Hardware Synthesis and Optimization</a>                      | 3 SWS | Lecture /   | Becker  |
| ST 2025 | 2311621 | <a href="#">Tutorial for 2311619 Hardware Synthesis and Optimization</a> | 1 SWS | Practice /  | Schmidt |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The examination takes place within the framework of an oral overall examination (approx. 30 minutes).  
 The module grade is the grade of the oral exam.

**Prerequisites**



none

T

**8.112 Course: Hardware/Software Co-Design [T-ETIT-100671]**

**Responsible:** Dr.-Ing. Tanja Harbaum  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100453 - Hardware/Software Co-Design](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |  |                 |
|----------|---------|--|-------|--|-----------------|
| WT 24/25 | 2311620 | <a href="#">Hardware/Software Co-Design</a>                      | 2 SWS | Lecture /   | Harbaum, Becker |
| WT 24/25 | 2311623 | <a href="#">Tutorial for 2311620 Hardware/Software Co-Design</a> | 1 SWS | Practice /  | Gutermann       |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Achievement will be examined in an oral examination (approx. 20 minutes).

**Prerequisites**

none

## T




## 8.113 Course: Heat and Mass Transfer [T-MACH-105292]





**Responsible:** Prof. Dr. Ulrich Maas  
Dr.-Ing. Chunkan Yu

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102717 - Heat and Mass Transfer](#)

| Type                | Credits | Grading scale    | Recurrence | Version |
|---------------------|---------|------------------|------------|---------|
| Written examination | 4       | Grade to a third | Each term  | 1       |

| Events   |         |   |       |  |                 |
|----------|---------|---|-------|--|-----------------|
| WT 24/25 | 2165512 | <a href="#">Heat and mass transfer</a>            | 2 SWS | Lecture /   | Yu, Maas        |
| WT 24/25 | 2165513 | <a href="#">Heat and Mass Transfer (Tutorial)</a> | 2 SWS | Practice /  | Yu, Maas, Bykov |
| ST 2025  | 3122512 | <a href="#">Heat and Mass Transfer</a>            | 2 SWS | Lecture /   | Maas            |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Written exam, approx. 3 h

### Prerequisites

none

### Workload

120 hours

T



**8.114 Course: Heatpumps [T-MACH-105430]**





**Responsible:** Prof. Dr. Ulrich Maas  
Dr. Heiner Wirbser

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107075 - Heat Pumps](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events   |         |                           |       |   |         |
|----------|---------|---------------------------|-------|---|---------|
| WT 24/25 | 2166534 | <a href="#">Heatpumps</a> | 2 SWS | Lecture /  | Wirbser |
| ST 2025  | 2166534 | <a href="#">Heatpumps</a> | 2 SWS | Lecture /  | Wirbser |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Oral exam (20 min)

**Prerequisites**

none



**Workload**

120 hours

T

**8.115 Course: High-Voltage Technology [T-ETIT-110266]****Responsible:** Dr.-Ing. Rainer Badent**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-105060 - High-Voltage Technology](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 1 terms   | 1       |

| Events   |         |   |       |  |                  |
|----------|---------|---|-------|--|------------------|
| WT 24/25 | 2307360 | <a href="#">High-Voltage Technology</a>                     | 2 SWS | Lecture /   | Badent           |
| WT 24/25 | 2307362 | <a href="#">Tutorial for 2307362High-Voltage Technology</a> | 1 SWS | Practice /  | Badent, Zajadatz |



Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T

**8.116 Course: High-Voltage Test Technique [T-ETIT-101915]**

**Responsible:** Dr.-Ing. Rainer Badent  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100417 - High-Voltage Test Technique](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |  |         |
|----------|---------|--|-------|--|---------|
| WT 24/25 | 2307392 | <a href="#">High-Voltage Test Technique</a>                      | 2 SWS | Lecture /   | Badent  |
| WT 24/25 | 2307394 | <a href="#">Tutorial for 2307392 High-Voltage Test Technique</a> | 2 SWS | Practice /  | Gielnik |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none




**T 8.117 Course: Holistic Approach of Managing Power Plant Operation under Uncertainty and Volatility [T-MACH-112238]**

**Responsible:** Dr. Marcus Seidl  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107097 - Holistic Approach of Managing Power Plant Operation under Uncertainty and Volatility](#)

| Type             | Credits | Grading scale    | Recurrence | Version |
|------------------|---------|------------------|------------|---------|
| Oral examination | 4       | Grade to a third | Each term  | 1       |

| Events   |         |  |       |   |       |
|----------|---------|--|-------|---|-------|
| WT 24/25 | 2189405 | <a href="#">Holistic approach of managing power plant operation under uncertainty and volatility</a> | 2 SWS | Lecture /  | Seidl |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**  
 oral exam of about 30 minutes

**Prerequisites**  
 none

**Annotation**  
 none

**Workload**  
 120 hours

T

## 8.118 Course: Hot Research Topics in AI for Engineering Applications [T-MACH-113669]


**Responsible:** Prof. Dr.-Ing. Anne Meyer





**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-101283 - Virtual Engineering A](#)

[M-MACH-107089 - Hot Research Topics in AI for Engineering Applications](#)

| Type                        | Credits | Grading scale    | Recurrence       | Expansion | Version |
|-----------------------------|---------|------------------|------------------|-----------|---------|
| Examination of another type | 4       | Grade to a third | Each winter term | 1 terms   | 1       |

| Events   |         |  |       |  |             |
|----------|---------|--|-------|--|-------------|
| WT 24/25 | 2121341 | <a href="#">Hot Research Topics in AI for Engineering Applications</a> | 3 SWS | Project (P /  ) | Meyer, Dörr |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

The grade is determined by an examination of another type. This consists of an individual knowledge check after the lecture part, the continuous assessment of teamwork during the implementation task and a final presentation. The overall impression is assessed; in addition to the implementation task, the knowledge test and the final presentation are also taken into account.

### Prerequisites

none

### Recommendation

Basic knowledge of artificial intelligence and machine learning, Programming experience, preferably in Python, English proficiency

### Annotation

Limited number of participants.

### Workload

120 hours

T

**8.119 Course: Human Brain and Central Nervous System: Anatomy, Information Transfer, Signal Processing, Neurophysiology and Therapy [T-INFO-101262]**

**Responsible:** Prof. Dr.-Ing. Tamim Asfour  
Hon.-Prof. Dr. Uwe Spetzger

**Organisation:** KIT Department of Informatics

**Part of:** [M-INFO-100725 - Human Brain and Central Nervous System: Anatomy, Information Transfer, Signal Processing, Neurophysiology and Therapy](#)



**Type**  
Written examination

**Credits**  
3

**Grading scale**  
Grade to a third

**Recurrence**  
Each term

**Version**  
2

| Events   |         |   |       |   |          |
|----------|---------|---|-------|---|----------|
| WT 24/25 | 2424139 | <a href="#">Human Brain and Central Nervous System: Anatomy, Information Transfer, Signal Processing, Neurophysiology and Therapy</a> | 2 SWS | Lecture /  | Spetzger |
| ST 2025  | 24678   | <a href="#">Human Brain and Central Nervous System: Anatomy, Information Transfer, Signal Processing, Neurophysiology and Therapy</a> | 2 SWS | Lecture /  | Spetzger |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T


**8.120 Course: Human-Machine-Interaction in Anthropomatics: Basics [T-INFO-101361]**





**Responsible:** Prof. Dr.-Ing. Jürgen Beyerer  
Dr.-Ing. Florian van de Camp

**Organisation:** KIT Department of Informatics

**Part of:** [M-INFO-100824 - Human-Machine-Interaction in Anthropomatics: Basics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 3       | Grade to a third | Each winter term | 4       |

| Events   |         |   |       |   |             |
|----------|---------|---|-------|---|-------------|
| WT 24/25 | 2424100 | <a href="#">Human-Machine-Interaction in Anthropomatics: Basics</a> | 2 SWS | Lecture /  | van de Camp |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T

**8.121 Course: Humanoid Robots - Seminar [T-INFO-114170]**

**Responsible:** Prof. Dr.-Ing. Tamim Asfour  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-107152 - Humanoid Robots - Seminar](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 3       | Grade to a third | Each winter term | 1       |

**Competence Certificate**

The assessment is carried out as an examination of another type (§ 4 Abs. 2 No. 3 SPO). It includes a presentation at the end of the term and a term paper.

**Prerequisites**

None.

**Recommendation**

Attending the lectures Robotics I – Introduction to Robotics, Robotics II: Humanoid Robotics, Robotics III – Sensors and Perception in Robotics, Mechano-Informatics and Robotics and Wearable Robotic Technologies is recommended.

T


## 8.122 Course: Hydrogen and reFuels - Energy Conversion in Combustion Engines [T-MACH-111585]





**Responsible:** Dr.-Ing. Heiko Kubach

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107158 - Hydrogen and reFuels - Energy Conversion in Combustion Engines](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1 terms   | 2       |

| Events   |         |  |       |   |      |
|----------|---------|--|-------|---|------|
| WT 24/25 | 2134155 | <a href="#">Hydrogen and reFuels - Energy Conversion in Combustion Engines</a> | 2 SWS | Lecture /  | Koch |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

oral exam, appr. 25 minutes, no auxillary means

### Prerequisites

T-MACH-113979 must not have been started.

### Workload

120 hours





T

**8.123 Course: Industrial Business Administration [T-WIWI-100796]**

**Responsible:** Prof. Dr. Wolf Fichtner  
**Organisation:** KIT Department of Economics and Management  
**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                           | Credits | Grading scale | Recurrence       | Version |
|--------------------------------|---------|---------------|------------------|---------|
| Completed coursework (written) | 3       | pass/fail     | Each winter term | 1       |

| Events   |         |  |       |   |          |
|----------|---------|--|-------|---|----------|
| WT 24/25 | 2581040 | <a href="#">Industrial Business Administration</a> | 2 SWS | Lecture /  | Fichtner |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment of this course is a ungraded written examination (60 min).

**Prerequisites**


None


T

**8.124 Course: Industrial Circuitry [T-ETIT-100716]**

**Responsible:** Dr.-Ing. Andreas Liske  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100399 - Industrial Circuitry](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each winter term | 1       |

| Events   |         |                                      |       |   |       |
|----------|---------|--------------------------------------|-------|---|-------|
| WT 24/25 | 2306327 | <a href="#">Industrial Circuitry</a> | 2 SWS | Lecture /  | Liske |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none





T



**8.125 Course: Industrial Mobile Robotics Lab [T-MACH-113701]**

**Responsible:** Prof. Dr.-Ing. Kai Furmans  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106830 - Industrial Mobile Robotics Lab](#)

| Type                 | Credits | Grading scale | Recurrence | Version |
|----------------------|---------|---------------|------------|---------|
| Completed coursework | 4       | pass/fail     | Each term  | 2       |

| Events   |         |  |       |  |               |
|----------|---------|--|-------|--|---------------|
| WT 24/25 | 2117073 | <a href="#">Industrial Mobile Robotics Lab</a> | 2 SWS | Practical course /  | Enke, Furmans |
| ST 2025  | 2117073 | <a href="#">Industrial Mobile Robotics Lab</a> | 2 SWS | Practical course /  | Furmans, Enke |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Certificate through colloquium with presentation, documentation of the work results and fulfilment of the attendance requirement.

**Prerequisites**

T-MACH-105230 must not be started.

**Recommendation**

Basic knowledge of Python programming and basic knowledge of technical logistics of advantage.

**Annotation**

The number of participants is limited to 15 students.

The selection procedure is based on a letter of motivation in which the following questions should be answered:

- Why do you want to attend the course?  
What skills and previous knowledge do you have?

**Workload**

120 hours

T



**8.126 Course: Information Engineering [T-MACH-102209]**





**Responsible:** Prof. Dr.-Ing. Anne Meyer  
Prof. Dr.-Ing. Jivka Ovtcharova

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-101283 - Virtual Engineering A](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 3       | Grade to a third | Each term  | 2       |

| Events   |         |   |       |   |               |
|----------|---------|---|-------|---|---------------|
| WT 24/25 | 2121355 | <a href="#">Information Engineering</a> | 2 SWS | Seminar /  | Meyer, Rönnau |
| ST 2025  | 2122014 | <a href="#">Information Engineering</a> | 2 SWS | Seminar /  | Meyer, Rönnau |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Alternative exam assessment (written composition and speech)

**Prerequisites**

None

**Workload**



90 hours

T

**8.127 Course: Information Fusion [T-ETIT-106499]**

**Responsible:** Michael Heizmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-103264 - Information Fusion](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |  |                  |
|----------|---------|---|-------|--|------------------|
| WT 24/25 | 2302139 | <a href="#">Information Fusion</a>                      | 2 SWS | Lecture /   | Heizmann         |
| WT 24/25 | 2302141 | <a href="#">Exercize for 2302139 Information Fusion</a> | 1 SWS | Practice /  | Heizmann, Bihler |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

**8.128 Course: Information Processing in Sensor Networks [T-INFO-101466]**

**Responsible:** Prof. Dr.-Ing. Uwe Hanebeck  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-100895 - Information Processing in Sensor Networks](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each winter term | 1       |

T

## 8.129 Course: Information Systems and Supply Chain Management [T-MACH-102128]

**Responsible:** Dr.-Ing. Christoph Kilger

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105281 - Information Systems and Supply Chain Management](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 3       | Grade to a third | Each summer term | 3       |

### Competence Certificate

The success control takes place in form of a written examination (60 min) during the semester break (according to §4(2), 1 SPO). If the number of participants is low, an oral examination (according to §4 (2), 2 SPO) may also be offered.

### Prerequisites

none

### Workload





90 hours

T

**8.130 Course: Information Technology in Industrial Automation Systems [T-ETIT-100698]****Responsible:** Dr.-Ing. Peter-Axel Bort**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-100367 - Information Technology in Industrial Automation Systems](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |      |
|---------|---------|---|-------|---|------|
| ST 2025 | 2302144 | <a href="#">Information Technology in Industrial Automation Systems</a> | 2 SWS | Lecture /  | Bort |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Prerequisites**

none

T



## 8.131 Course: Innovation and Project Management in Rail Vehicle Engineering [T-MACH-113068]

**Responsible:** Prof. Dr.-Ing. Martin Cichon

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106514 - Innovation and Project Management in Rail Vehicle Engineering](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 4       | Grade to a third | Each term  | 5       |

| Events   |         |   |       |   |              |
|----------|---------|---|-------|---|--------------|
| WT 24/25 | 2115921 | <a href="#">Innovation and Project Management in Rail Vehicle Engineering</a> | 2 SWS | Lecture /  | Lang, Cichon |
| ST 2025  | 2115921 | <a href="#">Innovation and Project Management in Rail Vehicle Engineering</a> | 2 SWS | Lecture /  | Lang, Cichon |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Graded examination:

2/3 of the examination: 20-minute oral examination on the content of the lecture

1/3 of the examination performance of another type: unit accompanying the lecture as part of a 10-minute presentation and a practical application from innovation and project management

### Workload

120 hours

T



**8.132 Course: Innovation Lab [T-ETIT-110291]**





**Responsible:** Prof. Dr.-Ing. Sören Hohmann  
 Prof. Dr. Werner Nahm  
 Prof. Dr.-Ing. Eric Sax  
 Prof. Dr. Wilhelm Stork  
 Prof. Dr.-Ing. Thomas Zwick

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-105073 - Student Innovation Lab](#)

| Type                        | Credits | Grading scale    | Recurrence | Expansion | Version |
|-----------------------------|---------|------------------|------------|-----------|---------|
| Examination of another type | 9       | Grade to a third | Each term  | 2 terms   | 1       |

| Events   |         |                                |       |  |  |
|----------|---------|--------------------------------|-------|--|--|
| WT 24/25 | 2303192 | <a href="#">Innovation Lab</a> | 2 SWS | Project (P /  ) | Hohmann, Zwick, Sax, Stork, Nahm, Schmalen, Rost |
| ST 2025  | 2303192 | <a href="#">Innovation Lab</a> | 2 SWS | Project (P /  ) | Hohmann, Zwick, Sax, Stork, Terzidis             |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

see module description



T

## 8.133 Course: Innovation2Business – Innovation Strategy in the Industrial Corporate Practice [T-MACH-112882]





**Responsible:** Prof. Dr.-Ing. Albert Albers

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107188 - Innovation2Business – Innovation Strategy in the Industrial Corporate Practice](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1 terms   | 1       |

| Events   |         |  |       |   |        |
|----------|---------|--|-------|---|--------|
| WT 24/25 | 2145182 | <a href="#">Innovation2Business – Innovation Strategy in the Industrial Corporate Practice</a> | 2 SWS | Lecture /  | Albers |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Written exam based on the lecture handout and materials, duration 90 minutes

### Prerequisites

none

### Recommendation

None

### Workload


120 hours





T

**8.134 Course: Innovative Concepts for Programming Industrial Robots [T-INFO-101328]****Responsible:** Prof. Dr.-Ing. Björn Hein**Organisation:** KIT Department of Informatics**Part of:** [M-INFO-100791 - Innovative Concepts for Programming Industrial Robots](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 4       | Grade to a third | Each summer term | 2       |

**Events**

|         |       |   |       |   |      |
|---------|-------|---|-------|---|------|
| ST 2025 | 24179 | <a href="#">Innovative Concepts for Programming Industrial Robots</a> | 2 SWS | Lecture /  | Hein |
|---------|-------|---|-------|---|------|

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T


**8.135 Course: Innovative Nuclear Systems [T-MACH-105404]**

**Responsible:** Prof. Dr.-Ing. Xu Cheng  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107119 - Innovative Nuclear Systems](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |     |       |
|---------|---------|--|-------|-----|-------|
| ST 2025 | 2130973 | <a href="#">Innovative Nuclear Systems</a> | 2 SWS | / ● | Cheng |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral exam, 20 min

**Prerequisites**

none

**Workload**

120 hours





T

**8.136 Course: Integrated Intelligent Sensors [T-ETIT-100961]**

**Responsible:** Prof. Dr. Wilhelm Stork  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100457 - Integrated Intelligent Sensors](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |       |
|---------|---------|--|-------|---|-------|
| ST 2025 | 2311630 | <a href="#">Integrated Intelligent Sensors</a> | 2 SWS | Lecture /  | Stork |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Achievement will be examined in an oral examination (approx. 20 minutes).

**Prerequisites**

none

T




**8.137 Course: Integrated Product Development [T-MACH-105401]**





**Responsible:** Prof. Dr.-Ing. Albert Albers  
Prof. Dr.-Ing. Tobias Düser

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107141 - Integrated Product Development](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 18      | Grade to a third | Each winter term | 3       |

| Events   |         |   |       |  |        |
|----------|---------|---|-------|--|--------|
| WT 24/25 | 2145156 | <a href="#">Lecture: IP – Integrated Product Development</a>      | 4 SWS | Lecture /       | Albers |
| WT 24/25 | 2145157 | <a href="#">Workshop: IP – Integrated Product Development</a>     | 4 SWS | Practice /      | Albers |
| WT 24/25 | 2145300 | <a href="#">Project Work: IP - Integrated Product Development</a> | 2 SWS | Others (sons /  | Albers |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral examination (approx. 60 minutes)

**Prerequisites**

none

**Annotation**

Due to organizational reasons, the number of participants is limited. Thus a selection has to be made. For registration to the selection process a standard form has to be used, that can be downloaded from IPEK homepage from April to July. The selection itself is made by the course's responsible in personal interviews. The criterion for selection is the progress of studies. In the event of equal progress, the decision is made by lot.

**Workload**



480 hours





T

**8.138 Course: Integrated Systems and Circuits [T-ETIT-100972]**

**Responsible:** Prof. Dr. Sebastian Kempf  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100474 - Integrated Systems and Circuits](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |  |        |
|---------|---------|--|-------|--|--------|
| ST 2025 | 2312688 | <a href="#">Integrated Systems and Circuits</a>                      | 2 SWS | Lecture /   | Ilin   |
| ST 2025 | 2312690 | <a href="#">Tutorial for 2312688 Integrated Systems and Circuits</a> | 1 SWS | Practice /  | Wünsch |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

## 8.139 Course: Intellectual Property Rights and Strategies in Industrial Companies [T-MACH-105442]





**Responsible:** Dipl.-Ing. Frank Zacharias

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type             | Credits | Grading scale    | Recurrence | Version |
|------------------|---------|------------------|------------|---------|
| Oral examination | 4       | Grade to a third | Each term  | 1       |

| Events   |         |   |       |   |           |
|----------|---------|---|-------|---|-----------|
| WT 24/25 | 2147161 | <a href="#">Intellectual Property Rights and Strategies in Industrial Companies</a> | 2 SWS | Block /  | Zacharias |
| ST 2025  | 2147160 | <a href="#">Patents and Patentstrategies in innovative companies</a>                | 2 SWS | /         | Zacharias |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

oral exam (ca. 20 min)

### Prerequisites

none

### Recommendation

None

### Workload

120 hours


T





**8.140 Course: International Production Engineering A [T-MACH-110334]**

**Responsible:** Prof. Dr.-Ing. Jürgen Fleischer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105109 - International Production Engineering](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 4       | Grade to a third | Each summer term | 4       |

| Events  |         |  |       |   |           |
|---------|---------|--|-------|---|-----------|
| ST 2025 | 2150600 | <a href="#">International Production Engineering A</a> | 2 SWS | Lecture /  | Fleischer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Alternative test achievement (graded):

- Result of the project work and final presentation with weighting 65%
- Oral exam (ca. 15 min) with weighting 35%

**Prerequisites**

One of the following courses must be started:

- T-MACH-108844 - Automated Manufacturing Systems
- T-MACH-110962 - Machine Tools and High-Precision Manufacturing Systems

**Modeled Conditions**

You have to fulfill one of 2 conditions:

1. The course T-MACH-108844 - Automated Manufacturing Systems must have been started.
2. The course [T-MACH-110962 - Machine Tools and High-Precision Manufacturing Systems](#) must have been started.

**Recommendation**

This course should be attended in combination with International Production Engineering B in the next winter semester.

**Workload**

120 hours




T





**8.141 Course: International Production Engineering B [T-MACH-110335]**

**Responsible:** Prof. Dr.-Ing. Jürgen Fleischer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105109 - International Production Engineering](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 4       | Grade to a third | Each winter term | 4       |

| Events   |         |  |       |   |           |
|----------|---------|--|-------|---|-----------|
| WT 24/25 | 2149620 | <a href="#">International Production Engineering B</a> | 2 SWS | Lecture /  | Fleischer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Alternative test achievement (graded):  
 - Result of the project work and final presentation with weighting 65%  
 - Oral exam (ca. 15 min) with weighting 35%

**Prerequisites**

The following course must be started:

- T-MACH-110334 - International Production Engineering A

Furthermore successful completion of one of the following courses:

- T-MACH-108844 - Automated Manufacturing Systems
- T-MACH-110962 - Machine Tools and High-Precision Manufacturing Systems

**Modeled Conditions**

The following conditions have to be fulfilled:

1. You have to fulfill one of 2 conditions:
  1. The course T-MACH-108844 - Automated Manufacturing Systems must have been passed.
  2. The course [T-MACH-110962 - Machine Tools and High-Precision Manufacturing Systems](#) must have been passed.
2. The course [T-MACH-110334 - International Production Engineering A](#) must have been started.


**Workload**





120 hours

T

**8.142 Course: Introduction to Automotive and Industrial Lidar Technology [T-ETIT-111011]****Responsible:** Prof. Dr. Wilhelm Stork**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-105461 - Introduction to Automotive and Industrial Lidar Technology](#)

| Type                        | Credits | Grading scale    | Recurrence       | Expansion | Version |
|-----------------------------|---------|------------------|------------------|-----------|---------|
| Examination of another type | 3       | Grade to a third | Each winter term | 1 terms   | 2       |


| Events   |         |  |       |   |                |
|----------|---------|--|-------|---|----------------|
| WT 24/25 | 2311604 | <a href="#">Introduction to automotive and industrial Lidar technology</a> | 2 SWS | Lecture /  | Stork, Heußner |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T

**8.143 Course: Introduction to Bionics [T-MACH-111807]****Responsible:** apl. Prof. Dr. Hendrik Hölscher**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-106525 - Introduction to Bionics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 3       |

| Events  |         |   |       |   |                   |
|---------|---------|---|-------|---|-------------------|
| ST 2025 | 2142151 | <a href="#">Introduction to Biomimetics</a> | 2 SWS | Lecture /  | Hölscher, Greiner |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

written exam (duration: 60 minutes)

**Prerequisites**

none

**Annotation**



Brick T-MACH-102172 may not be started





T

**8.144 Course: Introduction to Energy Economics [T-WIWI-102746]**

**Responsible:** Prof. Dr. Wolf Fichtner  
**Organisation:** KIT Department of Economics and Management  
**Part of:** [M-WIWI-100498 - Introduction into Energy Economics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each summer term | 7       |

| Events  |         |  |       |  |                                  |
|---------|---------|--|-------|--|----------------------------------|
| ST 2025 | 2581010 | <a href="#">Introduction to Energy Economics</a>               | 2 SWS | Lecture /   | Fichtner                         |
| ST 2025 | 2581011 | <a href="#">Übungen zu Einführung in die Energiewirtschaft</a> | 2 SWS | Practice /  | Sandmeier, Fichtner, Scharnhorst |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment consists of a written exam (90 minutes) (following §4(2) of the examination regulation). The exam takes place in every semester. Re-examinations are offered at every ordinary examination date. Depending on the respective pandemic situation, the exam may be offered as an open book exam (alternative exam assessment, following §4(2), 3 of the examination regulation).

**Prerequisites**

None.

T


**8.145 Course: Introduction to Microsystem Technology I [T-MACH-114100]**





**Responsible:** Dr. Vlad Badilita  
Prof. Dr. Jan Gerrit Korvink

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102691 - Introduction to Microsystem Technology I](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |   |                   |
|----------|---------|--|-------|---|-------------------|
| WT 24/25 | 2141861 | <a href="#">Introduction to Microsystem Technology I</a> | 2 SWS | Lecture /  | Korvink, Badilita |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

written examination (60 min)

**Prerequisites**

T-MACH-114035 and T-MACH-105182 must not have started

**Workload**

120 hours

T


**8.146 Course: Introduction to Microsystem Technology II [T-MACH-105183]**





**Responsible:** Dr. Vlad Badilita  
Prof. Dr. Jan Gerrit Korvink

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102706 - Introduction to Microsystem Technology II](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 3       |

| Events  |         |   |       |   |                   |
|---------|---------|---|-------|---|-------------------|
| ST 2025 | 2142874 | <a href="#">Introduction to Microsystem Technology II</a> | 2 SWS | Lecture /  | Korvink, Badilita |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

written examination (60 min)

**Prerequisites**

T-MACH-114035 and T-MACH-114101 must not have started

**Workload**

120 hours

T

**8.147 Course: Introduction to Nanotechnology [T-MACH-111814]**

**Responsible:** apl. Prof. Dr. Hendrik Hölscher  
**Organisation:** KIT Department of Mechanical Engineering  
 KIT Department of Economics and Management  
**Part of:** [M-MACH-107207 - Introduction to Nanotechnology](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |   |          |
|---------|---------|--|-------|---|----------|
| ST 2025 | 2142152 | <a href="#">Introduction to Nanotechnology</a> | 2 SWS | Lecture /  | Hölscher |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

written exam 90 min

**Prerequisites**

none

**Annotation**

Brick T-MACH-111814 may not be started

**Workload**

120 hours

T

**8.148 Course: Introduction to Nuclear Energy [T-MACH-105525]****Responsible:** Prof. Dr.-Ing. Xu Cheng**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107122 - Introduction to Nuclear Energy](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |   |       |
|----------|---------|--|-------|---|-------|
| WT 24/25 | 2189903 | <a href="#">Introduction to Nuclear Energy</a> | 2 SWS | Lecture /  | Cheng |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam, 30 min

**Prerequisites**

none

**Workload**

120 hours








T

**8.149 Course: Introduction to Philosophy of Technology [T-MACH-113883]**

**Responsible:** Prof. Dr. Dr. Rafaela Hillerbrand  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                 | Credits | Grading scale | Recurrence       | Expansion | Version |
|----------------------|---------|---------------|------------------|-----------|---------|
| Completed coursework | 2       | pass/fail     | Each winter term | 1 terms   | 2       |

| Events   |         |   |       |   |                    |
|----------|---------|---|-------|---|--------------------|
| WT 24/25 | 5000046 | <a href="#">Philosophical Foundations of Technology Assessment: An Introduction to Philosophy of Technology</a> | 2 SWS | Seminar /  | Hillerbrand, Frigo |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Academic achievements in the form of written assignments and/or oral performances.

**Prerequisites**

none



**Workload**





60 hours

T

**8.150 Course: Introduction to the Scientific Method (Seminar, Englisch) [T-ETIT-111317]****Responsible:** Prof. Dr. Werner Nahm**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                 | Credits | Grading scale | Recurrence | Expansion | Version |
|----------------------|---------|---------------|------------|-----------|---------|
| Completed coursework | 1       | pass/fail     | Each term  | 1 terms   | 1       |

| Events   |         |   |       |   |      |
|----------|---------|---|-------|---|------|
| WT 24/25 | 2305746 | <a href="#">Introduction to the Scientific Method</a> | 1 SWS | Seminar /  | Nahm |
| ST 2025  | 2305745 | <a href="#">Introduction to the Scientific Method</a> | 1 SWS | Seminar /  | Nahm |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

The success control takes place in the form of a study achievement. The exam consists of the preparation and the presentation of a seminar paper.

**Prerequisites**

none

**Annotation**


Detailed information on contents, competence goals, and work load at:





[M-ETIT-105665 – Introduction to the Scientific Method \(Seminar\)](#)

T

**8.151 Course: Introduction to the Scientific Method (Seminar, German) [T-ETIT-111316]****Responsible:** Prof. Dr. Werner Nahm**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                 | Credits | Grading scale | Recurrence | Expansion | Version |
|----------------------|---------|---------------|------------|-----------|---------|
| Completed coursework | 1       | pass/fail     | Each term  | 1 terms   | 1       |

| Events   |         |   |       |   |      |
|----------|---------|---|-------|---|------|
| WT 24/25 | 2305504 | <a href="#">Einführung in die wissenschaftliche Methode</a> | 1 SWS | Seminar /  | Nahm |
| ST 2025  | 2305744 | <a href="#">Einführung in die wissenschaftliche Methode</a> | 1 SWS | Seminar /  | Nahm |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Prerequisites**

none

T

**8.152 Course: IoT Platform for Engineering [T-MACH-106743]****Responsible:** Prof. Dr.-Ing. Jivka Ovtcharova**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-101283 - Virtual Engineering A](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 4       | Grade to a third | Each term  | 2       |

| Events   |         |  |       |                 |                      |
|----------|---------|--|-------|-----------------|----------------------|
| WT 24/25 | 2123352 | <a href="#">IoT platform for engineering</a> | 3 SWS | Project (P / ●) | Meyer, Maier, Rönnau |
| ST 2025  | 2123352 | <a href="#">IoT platform for engineering</a> | 3 SWS | Project (P / ●) | Meyer, Maier         |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**


Assessment of another type (graded), Group teaching project on Industry 4.0 consisting of: Conception, implementation, accompanying documentation and final presentation.





T

**8.153 Course: IT/OT-Security Seminar [T-ETIT-113648]**

**Responsible:** Prof. Dr.-Ing. Mike Barth  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106789 - IT/OT-Security Seminar](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1 terms   | 1       |

| Events   |         |  |       |   |               |
|----------|---------|--|-------|---|---------------|
| WT 24/25 | 2303201 | <a href="#">IT/OT-Security Seminar</a> | 2 SWS | Seminar /  | Barth, Madsen |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The examination takes place in the form of an oral examination.

The module grade is the grade of the oral exam.

**Prerequisites**

none

T

**8.154 Course: IT-Fundamentals of Logistics [T-MACH-105187]****Responsible:** Prof. Dr.-Ing. Frank Thomas**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105282 - IT-Fundamentals of Logistics: Opportunities for Digital Transformation](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 4       |

**Competence Certificate**

The assessment consists of an oral exam (20 min.) taking place in the recess period according to § 4 paragraph 2 Nr. 2 of the examination regulation.

**Prerequisites**

none

**Workload**

120 hours

T


**8.155 Course: Lab Computer-Aided Methods for Measurement and Control [T-MACH-105341]**





**Responsible:** Jonas Merkert  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105291 - Lab Computer-Aided Methods for Measurement and Control](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 4       | pass/fail     | Each winter term | 1       |

| Events   |         |  |       |  |         |
|----------|---------|--|-------|--|---------|
| WT 24/25 | 2137306 | <a href="#">Lab Computer-aided methods for measurement and control</a> | 3 SWS | Practical course /  | Stiller |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Colloquia

**Prerequisites**

none

**Workload**



120 hours





T

**8.156 Course: Lab Course on Nanoelectronics [T-ETIT-100757]**

**Responsible:** Prof. Dr. Sebastian Kempf  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100468 - Lab Course on Nanoelectronics](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1       |

| Events   |         |  |       |  |                              |
|----------|---------|--|-------|--|------------------------------|
| WT 24/25 | 2312669 | <a href="#">Laboratory Nanoelectronics</a> | 4 SWS | Practical course /  | Kempf, weitere Mitarbeitende |
| ST 2025  | 2312669 | <a href="#">Laboratory Nanoelectronics</a> | 4 SWS | Practical course /  | Kempf, Mitarbeiter*innen     |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none



T

**8.157 Course: Laboratory Exercise in Energy Technology [T-MACH-105331]**



**Responsible:** Prof. Dr.-Ing. Hans-Jörg Bauer  
 Prof. Dr. Ulrich Maas  
 Dr.-Ing. Heinrich Wirbser


**Organisation:** KIT Department of Mechanical Engineering

Institute of Thermal Turbomachinery

**Part of:** [M-MACH-107206 - Laboratory Exercise in Energy Technology](#)

| Type                 | Credits | Grading scale | Recurrence | Version |
|----------------------|---------|---------------|------------|---------|
| Completed coursework | 4       | pass/fail     | Each term  | 1       |

| Events   |         |  |       |  |                             |
|----------|---------|--|-------|--|-----------------------------|
| WT 24/25 | 2171487 | <a href="#">Laboratory Exercise in Energy Technology</a> | 3 SWS | Practical course /  | Bauer, Maas, Bykov          |
| ST 2025  | 2171487 | <a href="#">Laboratory Exercise in Energy Technology</a> | 3 SWS | Practical course /  | Bauer, Maas, Bykov, Schießl |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

1 report, approx. 12 pages

Discussion of the documented results with the assistants

**Prerequisites**

none

**Workload**



120 hours





T

**8.158 Course: Laboratory FPGA Based Circuit Design [T-ETIT-100759]**

**Responsible:** Prof. Dr. Sebastian Kempf  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100470 - Laboratory FPGA Based Circuit Design](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1       |

| Events   |         |  |       |  |               |
|----------|---------|--|-------|--|---------------|
| WT 24/25 | 2312674 | <a href="#">Laboratory FPGA Based Circuit Design</a> | 4 SWS | Practical course /  | Wünsch, Kempf |
| ST 2025  | 2312674 | <a href="#">Laboratory FPGA Based Circuit Design</a> | 4 SWS | Practical course /  | Kempf, Wünsch |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**


none





T

**8.159 Course: Laboratory in Software Engineering [T-ETIT-100681]**

**Responsible:** Prof. Dr.-Ing. Eric Sax  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100460 - Laboratory in Software Engineering](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |  |     |
|---------|---------|--|-------|--|-----|
| ST 2025 | 2311640 | <a href="#">Laboratory in Software Engineering</a> | 4 SWS | Practical course /  | Sax |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

## 8.160 Course: Laboratory Information Systems in Power Engineering [T-ETIT-114183]

**Responsible:** Prof. Dr.-Ing. Thomas Leibfried  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-107159 - Laboratory Information Systems in Power Engineering](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |                      |                            |
|---------|---------|---|-------|----------------------|----------------------------|
| ST 2025 | 2307388 | <a href="#">Praktikum: Informationssysteme in der elektrischen Energietechnik</a> | 4 SWS | Practical course / ● | Leibfried, und Mitarbeiter |

Legend: 📺 Online, 🔄 Blended (On-Site/Online), ● On-Site, ✕ Cancelled

### Competence Certificate

Success control takes place in the form of other types of examination and is assessed in form of 3 experiments.

The module grade results of the assessment of the 3 experiments.

- 20 points are awarded for each experiment (max. 10 for preparation and max. 10 for performance).
- This results in a total of 60 points.
- At least 27 points must be achieved in order to pass the module.

### Prerequisites


none

T

**8.161 Course: Laboratory Mechatronic Measurement Systems [T-ETIT-106854]**

**Responsible:** Prof. Dr.-Ing. Michael Heizmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-103448 - Laboratory Mechatronic Measurement Systems](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |  |                    |
|----------|---------|--|-------|--|--------------------|
| WT 24/25 | 2302123 | <a href="#">Laboratory Mechatronic Measurement Systems</a> | 4 SWS | Practical course /  | Heizmann, Steffens |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The success control is carried out in the form of a written test of 120 minutes. If there are fewer than 20 candidates, an oral exam of around 20 minutes can alternatively take place. The module grade is the grade of the written or oral exam.

**Prerequisites**

none

**Recommendation**

Knowledge from the lectures "Metrology" or "Metrology in Mechatronics" and "Manufacturing Metrology" as well as basic knowledge of programming (e.g. in Matlab, C / C++) are helpful.

**Annotation**

Annotations

The submission of the protocols of all experiments is required for admission to the examination. The quality of the protocols is assessed; for the admission to the exam, the quality must be acceptable.

Attendance of all laboratory dates including the introductory event is required. Already in the event of a single unexcused absence, admission to the examination will not be granted.

T


**8.162 Course: Laboratory Mechatronics [T-MACH-105370]**



**Responsible:** Prof. Dr. Veit Hagenmeyer  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102699 - Laboratory Mechatronics](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 4       | pass/fail     | Each winter term | 4       |

| Events   |         |   |       |  |                                 |
|----------|---------|---|-------|--|---------------------------------|
| WT 24/25 | 2105014 | <a href="#">Laboratory mechatronics</a> | 3 SWS | Practical course /  | Hagenmeyer, Stiller, Chen, Orth |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The laboratory course is offered exclusively as ungraded course work. The assessment consists of a group colloquium at the beginning of the individual specialization phases (Part 1). In addition, a robot control system for a pick-and-place task must be successfully implemented in the group phase (Part 2).

**Prerequisites**

None

**Workload**

120 hours





T

**8.163 Course: Laboratory Nanotechnology [T-ETIT-100765]**

**Responsible:** Prof. Dr. Ulrich Lemmer  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100478 - Laboratory Nanotechnology](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1       |

| Events   |         |   |       |  |                  |
|----------|---------|---|-------|--|------------------|
| WT 24/25 | 2313714 | <a href="#">Laboratory Nanotechnology</a> | 4 SWS | Practical course /  | Lemmer, Trampert |
| ST 2025  | 2313714 | <a href="#">Laboratory Nanotechnology</a> | 4 SWS | Practical course /  | Trampert, Lemmer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**



none





T

**8.164 Course: Laboratory Optoelectronics [T-ETIT-100764]**

**Responsible:** Dr.-Ing. Klaus Trampert  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100477 - Laboratory Optoelectronics](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1       |

| Events   |         |  |       |  |                 |
|----------|---------|--|-------|--|-----------------|
| WT 24/25 | 2313712 | <a href="#">Laboratory Optoelectronics</a> | 4 SWS | Practical course /  | Kling, Trampert |
| ST 2025  | 2313712 | <a href="#">Laboratory Optoelectronics</a> | 4 SWS | Practical course /  | Trampert, Kling |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none









T

**8.165 Course: Laboratory Solar Energy [T-ETIT-104686]**

**Responsible:** Dr.-Ing. Klaus Trampert  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-102350 - Laboratory Solar Energy](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1       |

| Events   |         |   |       |  |                              |
|----------|---------|---|-------|--|------------------------------|
| WT 24/25 | 2313716 | <a href="#">Laboratory Solar Energy</a> | 4 SWS | Practical course /  | Richards, Trampert, Paetzold |
| ST 2025  | 2313708 | <a href="#">Laboratory Solar Energy</a> | 4 SWS | Practical course /  | Trampert, Paetzold, Richards |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none


T





**8.166 Course: Leadership in Interdisciplinary Teams [T-MACH-106460]**

**Responsible:** Prof. Dr.-Ing. Sven Matthiesen  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)  
[M-MACH-107142 - Leadership in Interdisciplinary Teams](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 4       | pass/fail     | Each winter term | 1       |

| Events   |         |   |       |  |            |
|----------|---------|---|-------|--|------------|
| WT 24/25 | 2145189 | <a href="#">Leadership in interdisciplinary teams</a> | 2 SWS | Others (sons /  ) | Matthiesen |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**  
oral colloquium, ungraded

**Prerequisites**  
none

**Annotation**  
NwT students attend only part of the lecture



**Workload**  
120 hours

T

**8.167 Course: Liberalised Power Markets [T-WIWI-107043]**

**Responsible:** Prof. Dr. Wolf Fichtner  
**Organisation:** KIT Department of Economics and Management  
**Part of:** [M-WIWI-105403 - Liberalised Power Markets](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 3       |

| Events   |         |  |       |  |                           |
|----------|---------|--|-------|--|---------------------------|
| WT 24/25 | 2581998 | <a href="#">Liberalised Power Markets</a>            | 2 SWS | Lecture /   | Fichtner                  |
| WT 24/25 | 2581999 | <a href="#">Übungen zu Liberalised Power Markets</a> | 2 SWS | Practice /  | Signer, Fichtner, Beranek |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment consists of a written exam (60 minutes) (following §4(2) of the examination regulation). The exam takes place in every semester. Re-examinations are offered at every ordinary examination date. Depending on the respective pandemic situation, the exam may be offered as an open book exam (alternative exam assessment, following §4(2), 3 of the examination regulation).

**Recommendation**

None

**Workload**


180 hours

T

**8.168 Course: Lighting Engineering [T-ETIT-100772]**

**Responsible:** Prof. Dr. Cornelius Neumann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100485 - Lighting Engineering](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |   |         |
|----------|---------|--|-------|---|---------|
| WT 24/25 | 2313739 | <a href="#">Lighting Engineering</a>                       | 2 SWS | Lecture /  | Neumann |
| WT 24/25 | 2313741 | <a href="#">Lighting Engineering (Tutorial to 2313739)</a> | 1 SWS | Practice  | Neumann |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

**8.169 Course: Lightweight Engineering Design [T-MACH-105221]**





**Responsible:** Prof. Dr.-Ing. Tobias Düser  
Sascha Ott

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102696 - Lightweight Engineering Design](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |   |     |
|---------|---------|--|-------|---|-----|
| ST 2025 | 2146190 | <a href="#">Lightweight Engineering Design</a> | 2 SWS | Lecture /  | Ott |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written examination (90 min)

**Prerequisites**

None

**Workload**

120 hours




T

**8.170 Course: Localization of Mobile Agents [T-INFO-101377]**

**Responsible:** Prof. Dr.-Ing. Uwe Hanebeck  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-100840 - Localization of Mobile Agents](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each summer term | 2       |

| Events  |       |   |       |   |                  |
|---------|-------|---|-------|---|------------------|
| ST 2025 | 24613 | <a href="#">Localization of Mobile Agents</a> | 3 SWS | Lecture /  | Hanebeck, Frisch |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment takes the form of an oral examination, usually lasting 15 minutes in accordance with Section 4 (2) No. 2 of the SPO.

It will be announced six weeks before the examination (§ 6 Para. 3 SPO) whether the performance assessment

- in the form of an oral examination in accordance with § 4 Para. 2 No. 2 SPO **or**
- in the form of a written examination in accordance with § 4 Para. 2 No. 1 SPO

will take place.

**Prerequisites**

None.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-INFO-114169 - Localization of Mobile Agents Pass](#) must have been started.

**Recommendation**

Basic knowledge of linear algebra and stochastics is helpful.

T

**8.171 Course: Localization of Mobile Agents Pass [T-INFO-114169]**

**Responsible:** Prof. Dr.-Ing. Uwe Hanebeck  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-100840 - Localization of Mobile Agents](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 0       | pass/fail     | Each summer term | 1       |

**Competence Certificate**

The assessment is carried out in form of course work (German Studienleistung, § 4 Abs. 3 SPO).

The assessment is carried out in digital form. There are ILIAS tests with individual, randomized tasks that can be solved by hand or with a small numerical program. User input is automatically assessed and there is instant feedback. There is no limit on retakes. All tests must be passed; learning progress is displayed in ILIAS.

**Prerequisites**

None.


**Recommendation**





Basic knowledge of linear algebra and stochastics is helpful.

T

**8.172 Course: Logistics and Supply Chain Management [T-MACH-110771]****Responsible:** Prof. Dr.-Ing. Kai Furmans**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105298 - Logistics and Supply Chain Management](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 9       | Grade to a third | Each summer term | 5       |

| Events  |         |   |       |   |                 |
|---------|---------|---|-------|---|-----------------|
| ST 2025 | 2118078 | <a href="#">Logistics and Supply Chain Management</a> | 4 SWS | Lecture /  | Furmans, Alicke |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

The success control takes place in the form of an examination performance of a different kind. This is composed as follows:

- 50% assessment of a written examination (60 min) during the semester break
- 50% assessment of an oral examination (20 min) during the semester break

To pass the examination, both examination performances must be passed.

**Prerequisites**

None

**Annotation**

The brick cannot be taken if one of the bricks "T-MACH-102089 – Logistics - Organisation, Design and Control of Logistic Systems" and "T-MACH-105181 – Supply Chain Management" has been taken.

**Workload**




270 hours



T

**8.173 Course: Machine Dynamics [T-MACH-105210]****Responsible:** Prof. Dr.-Ing. Carsten Proppe**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-102694 - Machine Dynamics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each summer term | 1       |

| Events   |         |   |       |  |                        |
|----------|---------|---|-------|--|------------------------|
| WT 24/25 | 2161224 | <a href="#">Machine Dynamics</a>            | 2 SWS | Lecture /   | Proppe                 |
| ST 2025  | 2161224 | <a href="#">Machine Dynamics</a>            | 2 SWS | Lecture /   | Proppe                 |
| ST 2025  | 2161225 | <a href="#">Machine Dynamics (Tutorial)</a> | 1 SWS | Practice /  | Proppe, Kaupp, Fischer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

written exam, 180 min.

**Prerequisites**

none

**Workload**

150 hours

T

**8.174 Course: Machine Learning - Basic Methods [T-INFO-110630]**

**Responsible:** Prof. Dr. Gerhard Neumann  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-105252 - Machine Learning - Basic Methods](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each winter term | 2       |

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-WIWI-106340 - Machine Learning 1 - Basic Methods](#) must not have been started.

T

**8.175 Course: Machine Learning - Foundations and Algorithms [T-INFO-111558]**

**Responsible:** Prof. Dr. Gerhard Neumann  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-107169 - Machine Learning - Foundations and Algorithms](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |                          |         |
|---------|---------|---|-------|--------------------------|---------|
| ST 2025 | 2400018 | <a href="#">Machine Learning – Foundations and Algorithms</a> | 4 SWS | Lecture / Practice ( / ) | Neumann |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

The success control takes place in the form of a written exam, usually 90 minutes in length, according to § 4 Abs. 2 Nr. 1 SPO.

*A bonus can be acquired through successful participation in the exercise as a success control of a different kind (§4(2), 3 SPO 2008) or study performance (§4(3) SPO 2015). The exact criteria for awarding a bonus will be announced at the beginning of the lecture. If the grade of the written examination is between 4.0 and 1.3, the bonus improves the grade by one grade level (0.3 or 0.4). The bonus is only valid for the main and post exams of the semester in which it was earned. After that, the grade bonus expires.*

**Prerequisites**

None.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-WIWI-106340 - Machine Learning 1 - Basic Methods](#) must not have been started.
2. The course [T-INFO-110630 - Machine Learning - Basic Methods](#) must not have been started.

**Recommendation**



- Attendance of the lecture "Foundations of Artificial Intelligence" ("Grundlagen der Künstlichen Intelligence")
- Knowledge in python
- Mathematics-heavy lecture. The basics will be reviewed, but mathematical proficiency is helpful





T

**8.176 Course: Machine Learning 1 - Basic Methods [T-WIWI-106340]**

**Responsible:** Prof. Dr.-Ing. Johann Marius Zöllner  
**Organisation:** KIT Department of Economics and Management  
**Part of:** [M-WIWI-105003 - Machine Learning 1](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each winter term | 4       |

| Events   |         |   |       |  |                                   |
|----------|---------|---|-------|--|-----------------------------------|
| WT 24/25 | 2511500 | <a href="#">Machine Learning 1 - Fundamental Methods</a>              | 2 SWS | Lecture /   | Zöllner                           |
| WT 24/25 | 2511501 | <a href="#">Exercises to Machine Learning 1 - Fundamental Methods</a> | 1 SWS | Practice /  | Zöllner, Polley, Fechner, Daaboul |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Depending on further pandemic developments, the exam will be offered either as an open-book exam, or as a written exam (60 min):

The exam takes place every semester and can be repeated at every regular examination date.

A grade bonus can be earned by successfully completing practice exercises. If the grade of the written exam is between 4.0 and 1.3, the bonus improves the grade by up to one grade level (0.3 or 0.4). Details will be announced in the lecture.

**Prerequisites**

None.

**Workload**



150 hours





T

**8.177 Course: Machine Learning 2 – Advanced Methods [T-WIWI-106341]**

**Responsible:** Prof. Dr.-Ing. Johann Marius Zöllner  
**Organisation:** KIT Department of Economics and Management  
**Part of:** [M-WIWI-105006 - Machine Learning 2](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each summer term | 4       |

| Events  |         |   |       |  |                                     |
|---------|---------|---|-------|--|-------------------------------------|
| ST 2025 | 2511502 | <a href="#">Machine Learning 2 - Advanced Methods</a>               | 2 SWS | Lecture /   | Zöllner, Fechner, Polley, Stegmaier |
| ST 2025 | 2511503 | <a href="#">Exercises for Machine Learning 2 - Advanced Methods</a> | 1 SWS | Practice /  | Zöllner, Fechner, Polley, Stegmaier |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Depending on further pandemic developments, the exam will be offered either as an open-book exam, or as a written exam (60 min).

The exam takes place every semester and can be repeated at every regular examination date.

**Prerequisites**

None.

**Workload**

150 hours

T

## 8.178 Course: Machine Learning and Optimization in Energy Systems [T-WIWI-113073]

**Responsible:** Prof. Dr. Wolf Fichtner

**Organisation:** KIT Department of Economics and Management

**Part of:** [M-WIWI-106604 - Machine Learning and Optimization in Energy Systems](#)

**Type**  
Written examination

**Credits**  
4





**Grading scale**  
Grade to a third

**Recurrence**  
Each winter term

**Version**  
4

### Events

|          |         |   |       |                          |                |
|----------|---------|---|-------|--------------------------|----------------|
| WT 24/25 | 2581050 | <a href="#">Machine Learning and Optimization in Energy Systems</a> | 3 SWS | Lecture / Practice ( / ) | Dengiz, Yilmaz |
|----------|---------|---|-------|--------------------------|----------------|

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

The assessment of this course is a written examination (60 min) or an oral exam (30 min) depending on the number of participants. A bonus can be acquired through successful participation in the computer exercise. If the grade of the written examination is between 4.0 and 1.3, the bonus improves the grade by one grade level (0.3 or 0.4). The exact criteria for awarding a bonus will be announced at the beginning of the exercises.

### Workload

120 hours

T

**8.179 Course: Machine Learning for Robotic Systems 1 [T-MACH-113064]**

**Responsible:** Jun.-Prof. Dr. Rania Rayyes  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
 KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106457 - Machine Learning for Robotic Systems 1](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |                          |        |
|----------|---------|--|-------|--------------------------|--------|
| WT 24/25 | 2117055 | <a href="#">Machine Learning for Robotic Systems 1</a> | 4 SWS | Lecture / Practice ( / ) | Rayyes |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

The assessment of this course is a written examination (90 min) according to §4(2), 1 of the examination regulation or an oral exam (20 min) following §4, Abs. 2, 2 of the examination regulation.

**Prerequisites**

None

**Recommendation**

- The course assumes basic knowledge in mathematics. e.g., particular (conditional) probabilities, the exponential function, basic linear algebra etc.
- programming skills in one programming language is recommended.
- Attendance of the lectures Robotics 1.
- Some knowledge in statistics is useful.

**Workload**

150 hours

T

**8.180 Course: Machine Learning for Robotic Systems 2 [T-MACH-113403]**

**Responsible:** Jun.-Prof. Dr. Rania Rayyes  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
 KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106652 - Machine Learning for Robotic Systems 2](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 5       | Grade to a third | Each summer term | 1 terms   | 1       |

| Events  |         |  |       |                          |        |
|---------|---------|--|-------|--------------------------|--------|
| ST 2025 | 2100015 | <a href="#">Machine Learning for Robotic Systems 2</a> | 4 SWS | Lecture / Practice ( / ) | Rayyes |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

The assessment of this course is a written examination (90 min) according to §4(2), 1 of the examination regulation or an oral exam (approx. 20 min) following §4, Abs. 2, 2 of the examination regulation.

**Prerequisites**

None

**Recommendation**

- The course assumes basic knowledge in mathematics. e.g., particular (conditional) probabilities, the exponential function, basic linear algebra etc.
- programming skills in one programming language is recommended.
- Attendance of the lecture Machine Learning for Robotic Systems 1
- Attendance of the lectures Robotics 1.
- Some knowledge in statistics is useful.

**Workload**

150 hours







T

**8.181 Course: Machine Tools and High-Precision Manufacturing Systems [T-MACH-110962]****Responsible:** Prof. Dr.-Ing. Jürgen Fleischer**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105107 - Machine Tools and Industrial Handling](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 8       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |                          |           |
|----------|---------|--|-------|--------------------------|-----------|
| WT 24/25 | 2149910 | <a href="#">Machine Tools and High-Precision Manufacturing Systems</a> | 6 SWS | Lecture / Practice ( / ) | Fleischer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Oral exam (40 minutes)

**Prerequisites**

T-MACH-102158 - Machine Tools and Industrial Handling must not be commenced.

T-MACH-109055 - Machine Tools and Industrial Handling must not be commenced.

T-MACH-110963 - Machine Tools and High-Precision Manufacturing Systems must not be commenced.

**Workload**

240 hours

T

**8.182 Course: Machine Vision [T-MACH-105223]**

**Responsible:** Dr. Martin Lauer  
Prof. Dr.-Ing. Christoph Stiller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-101923 - Machine Vision](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 8       | Grade to a third | Each winter term | 2       |

| Events   |         |                                |       |                          |                |
|----------|---------|--------------------------------|-------|--------------------------|----------------|
| WT 24/25 | 2137308 | <a href="#">Machine Vision</a> | 4 SWS | Lecture / Practice ( / ) | Lauer, Merkert |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

Type of Examination: written exam

Duration of Examination: 60 minutes

**Prerequisites**

None

**Workload**

240 hours

T


**8.183 Course: Magnet Technology of Fusion Reactors [T-MACH-105434]**





**Responsible:** Dr. Klaus-Peter Weiss  
Dr. Michael Wolf

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107223 - Magnet Technology of Fusion Reactors](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |             |
|---------|---------|--|-------|---|-------------|
| ST 2025 | 2190496 | <a href="#">Magnet Technology of Fusion Reactors</a> | 2 SWS | Lecture /  | Weiss, Wolf |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Oral examination of about 30 minutes

**Prerequisites**

none

**Annotation**

none

**Workload**

120 hours

T

**8.184 Course: Master's Thesis [T-ETIT-114214]**

**Responsible:** Prof. Dr. Martin Doppelbauer  
Prof. Dr.-Ing. Marcus Geimer

**Organisation:** KIT Department of Electrical Engineering and Information Technology  
KIT Department of Mechanical Engineering

**Part of:** [M-ETIT-107192 - Master's Thesis](#)

| Type         | Credits | Grading scale    | Recurrence | Version |
|--------------|---------|------------------|------------|---------|
| Final Thesis | 30      | Grade to a third | Each term  | 1       |

**Competence Certificate**

The Master's Thesis module has 30 credits. It consists of the Master's Thesis and a presentation. The presentation must be carried out within the processing time in accordance with SPO Section §14(4).

**Prerequisites**

According to SPO Section §14(1) the prerequisite for admission to the Master's Thesis module is that the student has successfully completed module examinations totaling 75 credits.

**Final Thesis**

This course represents a final thesis. The following periods have been supplied:

**Submission deadline** 6 months

**Maximum extension period** 3 months

**Correction period** 8 weeks

This thesis requires confirmation by the examination office.

T

**8.185 Course: Material Flow in Logistic Systems [T-MACH-102151]**

**Responsible:** Prof. Dr.-Ing. Kai Furmans  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-104984 - Material Flow in Logistic Systems](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 9       | Grade to a third | Each winter term | 3       |

**Competence Certificate**

The assessment (Prüfungsleistung anderer Art) consists of the following assignments:

- 40% assessment of the final case study as individual performance,
- 60% semester evaluation which includes working on 5 case studies and defending those (For both assessment types, the best 4 of 5 tries count for the final grade.):
  - 40% assessment of the result of the case studies as group work,
  - 20% assessment of the oral examination during the case study colloquiums as individual performance.

A detailed description of the learning control can be found under Annotations.

**Prerequisites**

none

**Recommendation**

Recommended elective subject: Probability Theory and Statistics

**Annotation**

Students are divided into groups for this course. Five case studies are carried out in these groups. The results of the group work during the lecture period are presented and evaluated in writing. In the oral examination during the case study colloquiums, the understanding of the result of the group work and the models dealt with in the course is tested. The participation in the oral defenses is compulsory and will be controlled. For the written submission the group receives a common grade, in the oral defense each group member is evaluated individually.

After the lecture period, there is the final case study. This case study contains the curriculum of the whole semester. The students work individually on this case study which takes place at a predefined place and time (duration: 4h).


**Workload**





270 hours

T

**8.186 Course: Materials of Lightweight Construction [T-MACH-105211]****Responsible:** Dr.-Ing. Wilfried Liebig**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-102727 - Materials for Lightweight Construction](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |   |        |
|---------|---------|---|-------|---|--------|
| ST 2025 | 2174574 | <a href="#">Materials of Lightweight Construction</a> | 2 SWS | Lecture /  | Liebig |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Oral exam, about 25 minutes

**Prerequisites**

T-MACH-114012 must not have been started.

**Recommendation**

Materials Science I/II


**Workload**





120 hours

T

**8.187 Course: Materials Recycling and Sustainability [T-MACH-110937]****Responsible:** Dr.-Ing. Wilfried Liebig**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107043 - Materials Recycling and Sustainability](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 3       |

| Events  |         |  |       |   |        |
|---------|---------|--|-------|---|--------|
| ST 2025 | 2173520 | <a href="#">Materials Recycling and Sustainability</a> | 2 SWS | Lecture /  | Liebig |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam (about 25 min.)

**Prerequisites**

T-MACH-114012 must not have been started.


**Workload**





120 hours

T

**8.188 Course: Mathematical Methods in Continuum Mechanics [T-MACH-110375]****Responsible:** Prof. Dr.-Ing. Thomas Böhlke**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-106210 - Mathematical Methods in Continuum Mechanics](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1 terms   | 1       |

| Events   |         |   |       |   |        |
|----------|---------|---|-------|---|--------|
| WT 24/25 | 2161254 | <a href="#">Mathematical Methods in Continuum Mechanics</a> | 2 SWS | Lecture /  | Böhlke |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

written exam (90 min). Additives as announced.

**Prerequisites**

Passing the Tutorial to Mathematical Methods of Continuum Mechanics (T-MACH-110376)

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-MACH-110376 - Tutorial Mathematical Methods in Continuum Mechanics](#) must have been passed.

**Workload**

120 hours



T

**8.189 Course: Mathematical Methods in Fluid Mechanics [T-MACH-113955]**

**Responsible:** Prof. Dr.-Ing. Bettina Frohnäpfel  
Dr.-Ing. Davide Gatti

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107032 - Mathematical Methods in Fluid Mechanics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1       |

**Competence Certificate**

written examination - 90 minutes

**Prerequisites**

none

**Recommendation**

Basic Knowledge about Fluid Mechanics

**Workload**

180 hours

T

**8.190 Course: Mathematical Methods in Fluid Mechanics [T-MACH-113956]**

**Responsible:** Prof. Dr.-Ing. Bettina Frohnapfel  
Dr.-Ing. Davide Gatti

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-101283 - Virtual Engineering A](#)  
[M-MACH-107032 - Mathematical Methods in Fluid Mechanics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |                          |                   |
|---------|---------|---|-------|--------------------------|-------------------|
| ST 2025 | 2154540 | <a href="#">Mathematical Methods in Fluid Mechanics</a> | 4 SWS | Lecture / Practice ( / ) | Gatti, Frohnapfel |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

written examination - 90 minutes

**Prerequisites**

T-MACH-105295 must not be started.

**Recommendation**

Basic Knowledge about Fluid Mechanics

**Workload**

180 hours

T

**8.191 Course: Mathematical Methods in Hydraulics [T-MACH-113912]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-107210 - Mathematical Methods in Hydraulics](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1 terms   | 1       |

**Competence Certificate**

Oral examination, duration approx. 30 minutes

**Prerequisites**

T-MACH-113913 must be passed.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-MACH-113913 - Tutorial Mathematical Methods in Hydraulics](#) must have been passed.

**Workload**

120 hours

T


**8.192 Course: Mechanical Properties of Nanomaterials and Microsystems [T-MACH-114018]**



**Responsible:** Dr. Patric Gruber  
 Prof. Dr. Christoph Kirchlechner  
 Dr. Daniel Weygand

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107185 - Mechanical Properties of Nanomaterials and Microsystems](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |                               |
|---------|---------|---|-------|---|-------------------------------|
| ST 2025 | 2178420 | <a href="#">Mechanical Properties of Nanomaterials and Microsystems</a> | 2 SWS | Lecture /  | Kirchlechner, Gruber, Weygand |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral exam ca. 30 minutes

**Prerequisites**

Mutual exclusion with T-MACH-114071

**Workload**

120 hours

T

## 8.193 Course: Medical Image Processing for Guidance and Navigation [T-ETIT-113425]

**Responsible:** Prof. Dr.-Ing. Maria Francesca Spadea

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-106672 - Medical Image Processing for Guidance and Navigation](#)

**Type**  
Oral examination

**Credits**  
9

**Grading scale**  
Grade to a third

**Recurrence**  
Each winter term

**Version**  
2

| Events   |         |  |       |                           |                                     |
|----------|---------|--|-------|---------------------------|-------------------------------------|
| WT 24/25 | 2305297 | <a href="#">Medical Image Processing for Guidance and Navigation</a> | 6 SWS | Lecture / Practice ( / ●) | Spadea, Raggio, Riggio, Arndt, Hopp |
| ST 2025  | 2305297 | <a href="#">Medical Image Processing for Guidance and Navigation</a> | 4 SWS | Lecture / Practice ( / X) | Spadea, Raggio, Riggio              |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

### Competence Certificate

The examination takes place within the framework of an oral overall examination of approx. 30 minutes about the lecture including a presentation and discussion of the project developed during the course. The overall impression is rated.

The module grade is the grade of the oral exam.

A bonus can be earned for submitting homework that will be provided during the lecture time.

The exact criteria for awarding a bonus will be announced at the beginning of the lecture period. If the grade in the oral exam is between 4.0 and 1.3, the bonus improves the grade by 0.3 or 0.4.

Bonus points do not expire and are retained for any examinations taken at a later date.

### Prerequisites

none

T


## 8.194 Course: Methods and Processes of PGE - Product Generation Engineering [T-MACH-109192]


**Responsible:** Prof. Dr.-Ing. Albert Albers  
Prof. Dr.-Ing. Norbert Burkardt  
Prof. Dr.-Ing. Sven Matthiesen

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102718 - Product Development – Methods of Product Engineering](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |               |
|---------|---------|---|-------|---|---------------|
| ST 2025 | 2146176 | <a href="#">Methods and Processes of PGE – Product Generation Engineering</a> | 4 SWS | Lecture /  | Albers, Düser |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Written exam (processing time: 120 min + 10 min reading time)

Auxiliaries:

- Calculator
- German dictionary (books only)

### Prerequisites

None

### Annotation

This lecture is the basis for the main subject Integrated Product Development, which is offered as a specialisation.


### Workload

180 hours

T

**8.195 Course: Microactuators [T-MACH-101910]****Responsible:** Prof. Dr. Manfred Kohl**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-100487 - Microactuators](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 3       |

| Events  |         |                                |       |   |      |
|---------|---------|--------------------------------|-------|---|------|
| ST 2025 | 2142881 | <a href="#">Microactuators</a> | 2 SWS | Lecture /  | Kohl |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

written exam, 60 min.

**Prerequisites**

T-MACH-114036 must not be started

**Workload**

120 hours

T


**8.196 Course: Microenergy Technologies [T-MACH-105557]**





**Responsible:** Prof. Dr. Manfred Kohl  
Dr. Jingyuan Xu

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102714 - Microenergy Technologies](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |    |
|---------|---------|--|-------|---|----|
| ST 2025 | 2142897 | <a href="#">Microenergy Technologies</a> | 2 SWS | Lecture /  | Xu |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Oral examination (30 Min.)

**Prerequisites**

none

**Workload**

120 hours



T



## 8.197 Course: Microsystem Product Design for Young Entrepreneurs [T-MACH-105814]





**Responsible:** Prof. Dr. Jan Gerrit Korvink  
Dr.-Ing. Dario Mager

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107195 - Microsystem Product Design for Young Entrepreneurs](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 4       | Grade to a third | Each term  | 2       |

| Events   |         |  |       |  |                |
|----------|---------|--|-------|--|----------------|
| WT 24/25 | 2141503 | <a href="#">Microsystem product design for young entrepreneurs</a> | 4 SWS | Practical course /  | Korvink, Mager |
| ST 2025  | 2141503 | <a href="#">Microsystem product design for young entrepreneurs</a> | 4 SWS | Practical course /  | Korvink, Mager |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

The class is a laboratory course that is taken in groups, hence the active and productive participation in the team effort is evaluated. To check the individual performance, there will be weekly discussions about the project. To evaluate each group's progress, there will be 2 presentation during the duration of the course. The final mark is determined from the marks obtained in the presentation and an oral group examination of 1 hour.

### Prerequisites

T-MACH-114218 must not have been started.

### Workload

120 hours

T

**8.198 Course: Microsystem Simulation [T-MACH-108383]**

**Responsible:** Prof. Dr. Jan Gerrit Korvink  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105486 - Micro System Simulation](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 2       |

**Competence Certificate**

written exam

**Prerequisites**

T-MACH-114072 must not be started.

**Workload**


120 hours





T

**8.199 Course: Microsystem Technology [T-ETIT-100752]**

**Responsible:** Prof. Dr. Wilhelm Stork  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100454 - Microsystem Technology](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |   |       |
|----------|---------|--|-------|---|-------|
| WT 24/25 | 2311625 | <a href="#">Microsystem Technology</a> | 2 SWS | Lecture /  | Stork |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Achievement will be examined in an oral examination (approx. 20 minutes).

**Prerequisites**





none





T

**8.200 Course: Microwave Engineering [T-ETIT-100802]**

**Responsible:** Prof. Dr.-Ing. Thomas Zwick  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100535 - Microwave Engineering](#)

| Type                | Credits | Grading scale    | Recurrence | Version |
|---------------------|---------|------------------|------------|---------|
| Written examination | 5       | Grade to a third | Each term  | 1       |

| Events   |         |  |       |  |         |
|----------|---------|--|-------|--|---------|
| WT 24/25 | 2308407 | <a href="#">Microwave Engineering</a>                      | 2 SWS | Lecture /   | Pauli   |
| WT 24/25 | 2308409 | <a href="#">Tutorial for 2308407 Microwave Engineering</a> | 1 SWS | Practice /  | Bhutani |
| ST 2025  | 2308407 | <a href="#">Microwave Engineering</a>                      | 2 SWS | Lecture /   | Pauli   |
| ST 2025  | 2308409 | <a href="#">Tutorial for 2308407 Microwave Engineering</a> | 1 SWS | Practice /  | Nuß     |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

**Annotation**

WS: german

SS: english



The exam is in each semester and for every student bilingual.





T

**8.201 Course: Microwave Engineering Lab [T-ETIT-113938]**

**Responsible:** Prof. Dr.-Ing. Thomas Zwick  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106973 - Microwave Engineering Lab](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1       |

| Events   |         |   |       |  |       |
|----------|---------|---|-------|--|-------|
| WT 24/25 | 2308415 | <a href="#">Microwave Engineering Lab</a> | 4 SWS | Practical course /  | Pauli |
| ST 2025  | 2308415 | <a href="#">Microwave Engineering Lab</a> | 4 SWS | Practical course /  | Pauli |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

In preparation for the laboratory experiments, each laboratory group must work together on a number of tasks as homework before the experiment and submit a single copy to the supervisor immediately before the start of the experiment. The tasks for the experiment itself are completed and recorded during the experiment. The protocol should be handed in to the supervisor immediately after the experiment. Before each experiment is carried out, there is a written or oral examination (approx. 20 minutes, no aids) on the content of the experiment.

The grade for the experiments is made up of the preparation, the protocol and the written or oral assessment of the learning objectives for each experiment. The final grade for the entire laboratory results from the overall impression of the performance. Students who appear unprepared for the respective experiment may not take part in the experiment. The experiment must be repeated at another time.

**Prerequisites**

none

**Recommendation**


Knowledge of microwave measurement technology and RF components and systems is helpful.





T

**8.202 Course: Microwaves Measurement Techniques [T-ETIT-100733]**

**Responsible:** Prof. Dr.-Ing. Thomas Zwick  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100424 - Microwaves Measurement Techniques](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 4       |

| Events  |         |   |       |  |       |
|---------|---------|---|-------|--|-------|
| ST 2025 | 2308420 | <a href="#">Microwaves Measurement Techniques</a>         | 2 SWS | Lecture /   | Pauli |
| ST 2025 | 2308422 | <a href="#">Übungen zu 2308420 Mikrowellenmesstechnik</a> | 1 SWS | Practice /  | Pauli |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**



none





T

**8.203 Course: Microwaves Measurement Techniques [T-ETIT-114046]**

**Responsible:** Prof. Dr.-Ing. Thomas Zwick  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-107007 - Microwaves Measurement Techniques](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |  |       |
|---------|---------|---|-------|--|-------|
| ST 2025 | 2308420 | <a href="#">Microwaves Measurement Techniques</a>         | 2 SWS | Lecture /   | Pauli |
| ST 2025 | 2308422 | <a href="#">Übungen zu 2308420 Mikrowellenmesstechnik</a> | 1 SWS | Practice /  | Pauli |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Success control takes place in the form of an oral examination (approx. 20 minutes).

The module grade is the grade of the oral exam.

**Prerequisites**

none

T

**8.204 Course: Miniaturized Heat Exchangers [T-MACH-108613]****Responsible:** Prof. Dr.-Ing. Jürgen Brandner**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107063 - Miniaturized Heat Transfer](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |          |
|---------|---------|--|-------|---|----------|
| ST 2025 | 2142880 | <a href="#">Miniaturized Heat Exchangers</a> | 2 SWS | Lecture /  | Brandner |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam, 20 min.

**Prerequisites**

none

**Workload**

120 hours









T

**8.205 Course: MMIC Design Laboratory [T-ETIT-111006]**

**Responsible:** Prof. Dr.-Ing. Ahmet Cagri Ulusoy  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-105464 - MMIC Design Laboratory](#)

| Type                        | Credits | Grading scale    | Recurrence | Expansion | Version |
|-----------------------------|---------|------------------|------------|-----------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1 terms   | 1       |

| Events   |         |  |       |  |                 |
|----------|---------|--|-------|--|-----------------|
| WT 24/25 | 2308438 | <a href="#">MMIC Design Laboratory</a> | 4 SWS | Practical course /  | Ulusoy          |
| ST 2025  | 2308423 | <a href="#">MMIC Design Laboratory</a> | 4 SWS | Practical course /  | Ulusoy, Balaban |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The written report and the oral presentation are used to mark the course. The overall impression is assessed.


T





**8.206 Course: Mobile Machines [T-MACH-105168]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107041 - Mobile Machines](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 8       | Grade to a third | Each summer term | 2       |

| Events  |         |                                 |       |   |                    |
|---------|---------|---------------------------------|-------|---|--------------------|
| ST 2025 | 2114073 | <a href="#">Mobile Machines</a> | 4 SWS | Lecture /  | Geimer, Kazenwadel |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment consists of an oral exam (45 min) taking place in the recess period. The exam takes place in every semester. Re-examinations are offered at every ordinary examination date.

**Prerequisites**

none

**Recommendation**

Knowledge in Fluid Power Systems is required. It is recommended to attend the course *Fluid Power Systems* [2114093] beforehand.

**Annotation****Learning objectives:**

After successful participation in the course:

- the student will be able to name the wide range of mobile machinery
- know the possible applications and operating sequences of the most important mobile machines
- be able to describe selected subsystems and components

Content:

- Presentation of the components used and the most important mobile machines
- Basics and structure of the machines
- Practical insights into the development of the machines

Media:

Downloadable set of slides for the lecture

Book "Grundlagen mobiler Arbeitsmaschinen", Karlsruhe series of publications on vehicle systems technology, Volume 22, KIT Scientific Publishing

**Workload**

240 hours

T



**8.207 Course: Modern Control Concepts I [T-MACH-105539]**





**Responsible:** apl. Prof. Dr. Lutz Groell  
apl. Prof. Dr. Jörg Matthes

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105308 - Modern Control Concepts I](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |  |                 |
|---------|---------|---|-------|--|-----------------|
| ST 2025 | 2105024 | <a href="#">Modern Control Concepts I</a>             | 2 SWS | Lecture /   | Matthes, Groell |
| ST 2025 | 2106020 | <a href="#">Tutorial on Modern Control Concepts I</a> | 2 SWS | Practice /  | Matthes         |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written exam (Duration: 1 h)

**Prerequisites**

none

**Workload**

120 hours

T

**8.208 Course: Modern Control Concepts II [T-MACH-106691]****Responsible:** apl. Prof. Dr. Lutz Groell**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105313 - Modern Control Concepts II](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |   |        |
|----------|---------|--|-------|---|--------|
| WT 24/25 | 2106032 | <a href="#">Modern Control Concepts II</a> | 2 SWS | Lecture /  | Groell |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam (Duration: 30min)

**Prerequisites**

none

**Workload**

120 hours

T

**8.209 Course: Modern Control Concepts III [T-MACH-106692]****Responsible:** apl. Prof. Dr. Lutz Groell**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105314 - Modern Control Concepts III](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |        |
|---------|---------|---|-------|---|--------|
| ST 2025 | 2106035 | <a href="#">Modern Control Concepts III</a> | 2 SWS | Lecture /  | Groell |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam (Duration: 30min)

**Prerequisites**

none

**Workload**

120 hours

T

**8.210 Course: Modern Radio Systems Engineering [T-ETIT-100735]**

**Responsible:** Prof. Dr.-Ing. Thomas Zwick  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100427 - Modern Radio Systems Engineering](#)



**Type**  
Oral examination





**Credits**  
6

**Grading scale**  
Grade to a third

**Recurrence**  
Each term

**Version**  
2

| Events  |         |  |       |  |         |
|---------|---------|--|-------|--|---------|
| ST 2025 | 2308430 | <a href="#">Modern Radio Systems Engineering</a>                     | 3 SWS | Lecture /   | Zwick   |
| ST 2025 | 2308431 | <a href="#">Tutorial to 2308430 Modern Radio Systems Engineering</a> | 1 SWS | Practice /  | Bhutani |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The success control takes place in the form of an oral examination of approx. 20 minutes. The module grade is the grade of the oral examination.

**Prerequisites**

none





T

**8.211 Course: Modern VLSI Technologies [T-ETIT-113864]**

**Responsible:** Prof. Dr. Jasmin Aghassi-Hagmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106921 - Modern VLSI Technologies](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |  |                 |
|---------|---------|---|-------|--|-----------------|
| ST 2025 | 2308441 | <a href="#">Modern VLSI Technologies</a>          | 2 SWS | Lecture /   | Aghassi-Hagmann |
| ST 2025 | 2308442 | <a href="#">Tutorial Modern VLSI Technologies</a> | 2 SWS | Practice /  | Cadilha Marques |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**


Success control takes place in form of an oral examination with a duration of approx. 20 minutes. Exercises have to be successfully completed before the exam is taken. Further details will be provided at the beginning of the course. The module grade is the grade of the oral exam.





T

**8.212 Course: Motion in Human and Machine - Seminar [T-INFO-105140]**

**Responsible:** Prof. Dr.-Ing. Tamim Asfour  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-102555 - Motion in Human and Machine - Seminar](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 3       | Grade to a third | Each summer term | 3       |

| Events  |         |   |       |   |        |
|---------|---------|---|-------|---|--------|
| ST 2025 | 2400063 | <a href="#">Motion in Human and Machine</a> | 3 SWS | Seminar /  | Asfour |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment is carried out as an examination of another type (§ 4 Abs. 2 No. 3 SPO). It includes a term paper and a final presentation.

**Prerequisites**

None.

**Recommendation**

Programming experience in C++, Python or Matlab is recommended.

Attending the lectures Robotics I – Introduction to Robotics, Robotics II: Humanoid Robotics, Robotics III - Sensors and Perception in Robotics, Mechano-Informatics and Robotics and Wearable Robotic Technologies is recommended.

**Annotation**

The block internship is an interdisciplinary event in co-operation with the University of Stuttgart and the University of Heidelberg.



T

**8.213 Course: Motor Vehicle Labor (graded) [T-ETIT-114320]**

**Responsible:** Dr.-Ing. Michael Frey  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
 KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102695 - Motor Vehicle Laboratory](#)

| Type                | Credits | Grading scale    | Recurrence | Version |
|---------------------|---------|------------------|------------|---------|
| Written examination | 4       | Grade to a third | Each term  | 1       |

**Competence Certificate**

Colloquium before each experiment

After completion of the experiments: written examination

Duration: 90 minutes

Auxiliary means: none

**Prerequisites**

none

**Workload**



120 hours

T

## 8.214 Course: Nano- and Quantum Electronics [T-ETIT-111232]

**Responsible:** Prof. Dr. Sebastian Kempf  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-105604 - Nano- and Quantum Electronics](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1 terms   | 1       |

| Events  |         |  |       |  |        |
|---------|---------|--|-------|--|--------|
| ST 2025 | 2312668 | <a href="#">Nano- and Quantum Electronics</a>                      | 3 SWS | Lecture /   | Kempf  |
| ST 2025 | 2312670 | <a href="#">Tutorial for 2312668 Nano- and Quantum Electronics</a> | 1 SWS | Practice /  | Wünsch |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment of success takes place in the form of a written examination lasting 120min. The grade corresponds to the result of the written examination.

**Prerequisites**

none


**Recommendation**





Successful completion of the modules "Superconductivity for Engineers" and „Einführung in die Quantentheorie für Elektrotechniker“ is recommended.

T

**8.215 Course: NMR Micro Probe Hardware Conception and Construction [T-MACH-108407]****Responsible:** Prof. Dr. Jan Gerrit Korvink**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107196 - NMR Micro Probe Hardware Conception and Construction](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 4       | pass/fail     | Each summer term | 1       |

| Events  |         |  |       |  |                |
|---------|---------|--|-------|--|----------------|
| ST 2025 | 2142551 | <a href="#">NMR Micro Probe Hardware Conception and Construction</a> | 2 SWS | Practical course /  | Korvink, Jouda |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Successful participation.

**Prerequisites**

none

**Workload**


120 hours





T

**8.216 Course: Nonlinear Control Systems [T-ETIT-100980]**

**Responsible:** Dr.-Ing. Mathias Kluwe  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100371 - Nonlinear Control Systems](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 3       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |       |
|---------|---------|---|-------|---|-------|
| ST 2025 | 2303173 | <a href="#">Nichtlineare Regelungssysteme</a> | 2 SWS | Lecture /  | Kluwe |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**



none





T

**8.217 Course: Nonlinear Optics [T-ETIT-101906]**

**Responsible:** Prof. Dr.-Ing. Christian Koos  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100430 - Nonlinear Optics](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |  |      |
|---------|---------|---|-------|--|------|
| ST 2025 | 2309468 | <a href="#">Nonlinear Optics</a>            | 2 SWS | Lecture /   | Koos |
| ST 2025 | 2309469 | <a href="#">Nonlinear Optics (Tutorial)</a> | 2 SWS | Practice /  | Koos |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

**8.218 Course: Novel Actuators and Sensors [T-MACH-102152]**





**Responsible:** Prof. Dr. Manfred Kohl  
Dr. Martin Sommer

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105292 - Novel Actuators and Sensors](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 4       |

| Events   |         |   |       |   |              |
|----------|---------|---|-------|---|--------------|
| WT 24/25 | 2141865 | <a href="#">Novel actuators and sensors</a> | 2 SWS | Lecture /  | Kohl, Sommer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

written exam, 60 minutes

**Prerequisites**

T-MACH-114036 must not be started


**Workload**





120 hours

T

**8.219 Course: Nuclear Power and Reactor Technology [T-MACH-110332]****Responsible:** Dr. Aurelian Florin Badea**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107042 - Nuclear Power and Reactor Technology](#)

| Type             | Credits | Grading scale    | Expansion | Version |
|------------------|---------|------------------|-----------|---------|
| Oral examination | 4       | Grade to a third | 1 terms   | 1       |

| Events   |         |  |       |   |       |
|----------|---------|--|-------|---|-------|
| WT 24/25 | 2189921 | <a href="#">Nuclear Power and Reactor Technology</a> | 3 SWS | Lecture /  | Badea |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam, approx. 20 min.

**Prerequisites**

None

**Workload**

120 hours

T


**8.220 Course: Nuclear Power Plant Technology [T-MACH-105402]**





**Responsible:** Dr. Aurelian Florin Badea  
Prof. Dr.-Ing. Xu Cheng

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107121 - Nuclear Power Plant Technology](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |                    |
|---------|---------|--|-------|---|--------------------|
| ST 2025 | 2170460 | <a href="#">Nuclear Power Plant Technology</a> | 2 SWS | Lecture /  | Cheng, Schulenberg |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral exam, Duration: approximately 30 minutes

no tools or reference materials may be used during the exam

**Prerequisites**

none

**Workload**

120 hours



T

**8.221 Course: Numerical Fluid Mechanics [T-MACH-105338]**





**Responsible:** Prof. Dr.-Ing. Bettina Frohnäpfel  
Dr.-Ing. Davide Gatti

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107036 - Numerical Fluid Mechanics](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 4       |

| Events   |         |   |       |   |       |
|----------|---------|---|-------|---|-------|
| WT 24/25 | 2153441 | <a href="#">Numerical Fluid Mechanics</a> | 4 SWS | Lecture / Practice ( /  | Gatti |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral exam - 30 minutes

**Prerequisites**

none

**Workload**

120 hours

T

**8.222 Course: Numerical Methods - Exam [T-MATH-111700]**

**Responsible:** apl. Prof. Dr. Peer Kunstmann  
 TT-Prof. Dr. Xian Liao  
 Prof. Dr. Wolfgang Reichel

**Organisation:** KIT Department of Mathematics

**Part of:** [M-MATH-105831 - Numerical Methods](#)  
[M-MATH-106972 - Numerical Methods with Programming Practice](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |          |           |
|---------|---------|---|-------|----------|-----------|
| ST 2025 | 0180300 | <a href="#">Numerical Methods (Electrical Engineering, Meteorology, Remote Sensing, Geoinformatics)</a> | 2 SWS | Lecture  | Tolksdorf |
| ST 2025 | 0180400 | <a href="#">Tutorial for 0180300</a>  | 1 SWS | Practice | Tolksdorf |

**Competence Certificate**

Success control takes the form of a written examination (120 minutes).

**Prerequisites**

none

T

**8.223 Course: Numerical Methods - Workshop [T-MATH-113937]**

**Responsible:** apl. Prof. Dr. Peer Kunstmann  
 TT-Prof. Dr. Xian Liao  
 Prof. Dr. Wolfgang Reichel

**Organisation:** KIT Department of Mathematics

**Part of:** [M-MATH-106972 - Numerical Methods with Programming Practice](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 1       | pass/fail     | Each summer term | 1       |

**Competence Certificate**

Successful participation in the workshop is confirmed by signing the attendance sheet provided at each practice session.

**Prerequisites**


None





T

**8.224 Course: Optical Design Lab [T-ETIT-100756]**

**Responsible:** Prof. Dr. Wilhelm Stork  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100464 - Optical Design Lab](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each summer term | 2       |

| Events  |         |                                    |       |  |       |
|---------|---------|------------------------------------|-------|--|-------|
| ST 2025 | 2311647 | <a href="#">Optical Design Lab</a> | 4 SWS | Practical course /  | Stork |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

**8.225 Course: Optical Engineering and Machine Vision [T-ETIT-113941]**

**Responsible:** Prof. Dr.-Ing. Michael Heizmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106974 - Optical Engineering and Machine Vision](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 1       |

**Competence Certificate**

The examination takes place in form of a written examination lasting 90 minutes.

The module grade is the grade of the written examination.

**Prerequisites**



none

T

**8.226 Course: Optical Transmitters and Receivers [T-ETIT-100639]**

**Responsible:** Prof. Dr. Wolfgang Freude  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100436 - Optical Transmitters and Receivers](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each winter term | 2       |

| Events   |         |   |       |  |              |
|----------|---------|---|-------|--|--------------|
| WT 24/25 | 2309460 | <a href="#">Optical Transmitters and Receivers</a>                      | 2 SWS | Lecture /   | Freude       |
| WT 24/25 | 2309461 | <a href="#">Tutorial for 2309460 Optical Transmitters and Receivers</a> | 2 SWS | Practice /  | Freude, N.N. |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**



none

T

**8.227 Course: Optical Waveguides and Fibers [T-ETIT-101945]**

**Responsible:** Prof. Dr.-Ing. Christian Koos  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100506 - Optical Waveguides and Fibers](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |  |                 |
|----------|---------|--|-------|--|-----------------|
| WT 24/25 | 2309464 | <a href="#">Optical Waveguides and Fibers</a>                      | 2 SWS | Lecture /   | Koos, N.N., Bao |
| WT 24/25 | 2309465 | <a href="#">Tutorial for 2309464 Optical Waveguides and Fibers</a> | 1 SWS | Practice /  | Koos, N.N.      |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none





T

**8.228 Course: Optimal Control and Estimation [T-ETIT-104594]**

**Responsible:** Prof. Dr.-Ing. Sören Hohmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-102310 - Optimal Control and Estimation](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |       |
|---------|---------|--|-------|---|-------|
| ST 2025 | 2303162 | <a href="#">Optimal Control and Estimation</a> | 2 SWS | Lecture /  | Kluwe |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none







T

**8.229 Course: Optimization of Dynamic Systems [T-ETIT-100685]**

**Responsible:** Prof. Dr.-Ing. Sören Hohmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100531 - Optimization of Dynamic Systems](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |  |         |
|----------|---------|---|-------|--|---------|
| WT 24/25 | 2303183 | <a href="#">Optimization of Dynamic Systems</a>   | 2 SWS | Lecture /     | Hohmann |
| WT 24/25 | 2303185 | <a href="#">Optimization of Dynamic Systems (Tutorial to 2303183)</a>                   | 1 SWS | Practice /    | Hess    |
| WT 24/25 | 2303851 | <a href="#">Accompanying group tutorial for 2303183 Optimization of Dynamic Systems</a> | 1 SWS | Tutorial ( /  | Hess    |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment consists of a written exam (120 min) taking place in the recess period.

**Prerequisites**

none

T

**8.230 Course: Optoelectronic Measurement Engineering [T-ETIT-100771]**

**Responsible:** Dr.-Ing. Klaus Trampert  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100484 - Optoelectronic Measurement Engineering](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |          |
|---------|---------|--|-------|---|----------|
| ST 2025 | 2313736 | <a href="#">Optoelectronic Measurement Engineering</a> | 2 SWS | Lecture /  | Trampert |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none


T


**8.231 Course: Organ Support Systems [T-MACH-105228]**

**Responsible:** apl. Prof. Dr. Christian Pylatiuk  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102702 - Organ Support Systems](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |                                       |       |   |          |
|---------|---------|---------------------------------------|-------|---|----------|
| ST 2025 | 2106008 | <a href="#">Organ support systems</a> | 2 SWS | Lecture /  | Pylatiuk |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written examination (Duration: 45min)

**Prerequisites**

none

**Workload**

120 hours

T

**8.232 Course: Pattern Recognition [T-INFO-101362]**





**Responsible:** Prof. Dr.-Ing. Jürgen Beyerer  
Tim Zander

**Organisation:** KIT Department of Informatics

**Part of:** [M-INFO-100825 - Pattern Recognition](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 2       |

| Events  |       |                                     |       |                          |         |
|---------|-------|-------------------------------------|-------|--------------------------|---------|
| ST 2025 | 24675 | <a href="#">Pattern Recognition</a> | 4 SWS | Lecture / Practice ( / ) | Beyerer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T

**8.233 Course: Photonics and Communications Lab [T-ETIT-109173]**





**Responsible:** Prof. Dr.-Ing. Christian Koos  
Prof. Dr.-Ing. Sebastian Randel

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-104485 - Photonics and Communications Lab](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |  |                              |
|---------|---------|--|-------|--|------------------------------|
| ST 2025 | 2309490 | <a href="#">Photonics and Communications Lab</a> | 4 SWS | Practical course /  | Koos, Freude, Randel, Kuzmin |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled



T

**8.234 Course: Photovoltaics [T-ETIT-101939]**

**Responsible:** Prof. Dr.-Ing. Michael Powalla  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100513 - Photovoltaics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |  |                 |
|---------|---------|---|-------|--|-----------------|
| ST 2025 | 2313737 | <a href="#">Photovoltaics</a>                 | 3 SWS | Lecture /   | Powalla, Lemmer |
| ST 2025 | 2313738 | <a href="#">Tutorial 2313737 Photovoltaik</a> | 1 SWS | Practice /  | Powalla, Lemmer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

"T-ETIT-100774 - Solar Energy" must not have started.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-ETIT-100774 - Solar Energy](#) must not have been started.

T

**8.235 Course: Physical Basics of Laser Technology [T-MACH-102102]**

**Responsible:** Dr.-Ing. Johannes Schneider  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107064 - Physical Basics of Laser Technology](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 5       | Grade to a third | Each winter term | 5       |

| Events   |         |   |       |                          |           |
|----------|---------|---|-------|--------------------------|-----------|
| WT 24/25 | 2181612 | <a href="#">Physical basics of laser technology</a> | 3 SWS | Lecture / Practice ( / ) | Schneider |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

oral examination (ca. 25-30 min)

no tools or reference materials

**Prerequisites**

It is not possible, to combine this brick with brick Laser Material Processing [T-MACH-112763], brick Laser Application in Automotive Engineering [T-MACH-105164] and brick Physical Basics of Laser Technology [T-MACH-109084].

**Recommendation**

Basic knowledge of physics, chemistry and material science

**Workload**

150 hours

T

**8.236 Course: Plasma Sources [T-ETIT-100768]**

**Responsible:** Prof. Dr. Wolfgang Heering  
Dr.-Ing. Rainer Kling

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-100481 - Plasma Sources](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |                                |       |             |       |
|----------|---------|--------------------------------|-------|-------------|-------|
| WT 24/25 | 2313729 | <a href="#">Plasma Sources</a> | 3 SWS | Lecture / X | Kling |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none



T

**8.237 Course: PLM for Product Development in Mechatronics [T-MACH-102181]**

**Responsible:** Prof. Dr.-Ing. Martin Eigner  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-101283 - Virtual Engineering A](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 2       |

**Competence Certificate**

Oral examination 20 min.

**Prerequisites**

none


**Workload**





120 hours

T

**8.238 Course: Polymers in MEMS A: Chemistry, Synthesis and Applications [T-MACH-102192]****Responsible:** Dr.-Ing. Matthias Worgull**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107183 - Polymers in MEMS A: Chemistry, Synthesis and Applications](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |  |         |
|----------|---------|---|-------|--|---------|
| WT 24/25 | 2141853 | <a href="#">Polymers in MEMS A: Chemistry, Synthesis and Applications</a> | 2 SWS | /  | Worgull |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Oral examination

**Prerequisites**

none

**Workload**

120 hours

T


## 8.239 Course: Polymers in MEMS B: Physics, Microstructuring and Applications [T-MACH-102191]





**Responsible:** Dr.-Ing. Matthias Worgull

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107035 - Polymers in MEMS B: Physics, Microstructuring and Applications](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |   |         |
|----------|---------|--|-------|---|---------|
| WT 24/25 | 2141854 | <a href="#">Polymers in MEMS B: Physics, Microstructuring and Applications</a> | 2 SWS | Lecture /  | Worgull |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Oral examination

### Prerequisites

none


### Workload





120 hours

T

**8.240 Course: Polymers in MEMS C: Biopolymers and Bioplastics [T-MACH-102200]****Responsible:** Dr.-Ing. Matthias Worgull**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107085 - Polymers in MEMS C: Biopolymers and Bioplastics](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |  |         |
|---------|---------|--|-------|--|---------|
| ST 2025 | 2142855 | <a href="#">Polymers in MEMS C - Biopolymers and Bioplastics</a> | 2 SWS | /  | Worgull |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Oral examination

**Prerequisites**

none

**Workload**

120 hours

T

**8.241 Course: Power Electronic Systems in Energy Technology [T-ETIT-112286]**

**Responsible:** Prof. Dr.-Ing. Marc Hiller  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106067 - Power Electronic Systems in Energy Technology](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |              |                 |
|----------|---------|---|-------|--------------|-----------------|
| WT 24/25 | 2306357 | <a href="#">Power Electronic Systems in Energy applications</a> | 3 SWS | Lecture / 🗎  | Hiller          |
| WT 24/25 | 2306358 | <a href="#">Power Electronic Systems in Energy Applications</a> | 1 SWS | Practice / 🔄 | Hiller, Knierim |

Legend: 🗎 Online, 🔄 Blended (On-Site/Online), 🗎 On-Site, ✕ Cancelled

**Prerequisites**

none

T




## 8.242 Course: Power Electronics [T-ETIT-109360]





**Responsible:** Prof. Dr.-Ing. Marc Hiller

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-104567 - Power Electronics](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1 terms   | 6       |

| Events  |         |  |       |  |                 |
|---------|---------|--|-------|--|-----------------|
| ST 2025 | 2300004 | <a href="#">Ausweich- und Praktikumstermin für ETI-Vorlesungen</a> | 2 SWS | Practical course /  | Hiller, Thönelt |
| ST 2025 | 2306323 | <a href="#">Power Electronics</a>                                  | 2 SWS | Lecture /           | Hiller          |
| ST 2025 | 2306324 | <a href="#">Tutorial for 2306385 Power Electronics</a>             | 2 SWS | Practice /          | Hiller, Thönelt |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

The examination takes place in form of a written examination lasting 120 minutes.

### Prerequisites

none

T

**8.243 Course: Power Electronics for Photovoltaics and Wind Energy [T-ETIT-104569]****Responsible:** Prof. Dr.-Ing. Marc Hiller**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-102261 - Power Electronics for Photovoltaics and Wind Energy](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |         |        |
|---------|---------|---|-------|---------|--------|
| ST 2025 | 2306347 | <a href="#">Power Electronics for Photovoltaics and Wind Energy</a> | 2 SWS | Lecture | Burger |

**Prerequisites**


none

T

**8.244 Course: Power System Protection and Automation [T-ETIT-113164]**

**Responsible:** Prof. Dr.-Ing. Thomas Leibfried  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106506 - Power System Protection and Automation](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 3       | Grade to a third | Each winter term | 1 terms   | 1       |

| Events   |         |  |       |   |       |
|----------|---------|--|-------|---|-------|
| WT 24/25 | 2307396 | <a href="#">Power System Protection and Automation</a> | 2 SWS | Lecture /  | Loitz |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none







T

**8.245 Course: Power Systems and Economy [T-ETIT-100725]**

**Responsible:** Dr.-Ing. Bernd Hoferer  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100413 - Power Systems and Economy](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |   |             |
|----------|---------|---|-------|---|-------------|
| WT 24/25 | 2307383 | <a href="#">Power Systems and Economy</a> | 2 SWS | Lecture /  | Weissmüller |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

**8.246 Course: Practical Aspects of Electrical Drives [T-ETIT-100711]**

**Responsible:** Prof. Dr. Martin Doppelbauer  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100394 - Practical Aspects of Electrical Drives](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 2       |

| Events   |         |   |       |              |                        |
|----------|---------|---|-------|--------------|------------------------|
| WT 24/25 | 2306311 | <a href="#">Practical Aspects of Electrical Drives</a>          | 2 SWS | Lecture / ✕  | Brodatzki, Doppelbauer |
| WT 24/25 | 2306313 | <a href="#">Übungen zu 2306311 Praxis elektrischer Antriebe</a> | 1 SWS | Practice / ✕ | Doppelbauer            |
| ST 2025  | 2306311 | <a href="#">Practical Aspects of Electrical Drives</a>          | 2 SWS | Lecture / ✕  | Doppelbauer            |
| ST 2025  | 2306313 | <a href="#">Übungen zu 2306311 Praxis elektrischer Antriebe</a> | 1 SWS | Practice / ✕ | Doppelbauer            |

Legend: Online, Blended (On-Site/Online), On-Site, ✕ Cancelled

**Prerequisites**

none


**Annotation**





Shift from SoSe to WiSe, does not take place in WiSe24/25 and SoSe25.

T

**8.247 Course: Practical Course Polymers in MEMS [T-MACH-105556]****Responsible:** Dr.-Ing. Matthias Worgull**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107034 - Practical Course Polymers in MEMS](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 2       | pass/fail     | Each summer term | 1       |

| Events  |         |   |       |   |         |
|---------|---------|---|-------|---|---------|
| ST 2025 | 2142856 | <a href="#">Practical Course Polymers in MEMS</a> | 2 SWS | Block /  | Worgull |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

The practical course will close with an oral examination. There will be only passed and failed results, no grades.

**Prerequisites**

none

T

**8.248 Course: Practical Course: Autonomous Driving [T-MACH-113713]**





**Responsible:** Dr.-Ing. Michael Frey  
Dr.-Ing. Martin Gießler

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107052 - Practical Course: Autonomous Driving](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 6       | pass/fail     | Each winter term | 1       |

| Events   |         |  |       |                      |      |
|----------|---------|--|-------|----------------------|------|
| WT 24/25 | 2113820 | <a href="#">Practical Course: Autonomous Driving</a> | 3 SWS | Practical course / ● | Frey |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

To pass the course it is necessary to successfully complete the colloquia, the homework and the final demonstration of the driving task.

**Prerequisites**

none

**Workload**

180 hours

T


**8.249 Course: Practical Course: Machine Learning and Intelligent Systems [T-INFO-112104]**





**Responsible:** Michael Fennel  
Prof. Dr.-Ing. Uwe Hanebeck

**Organisation:** KIT Department of Informatics

**Part of:** [M-INFO-105958 - Practical Course: Machine Learning and Intelligent Systems](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 8       | Grade to a third | Each term  | 1       |

| Events  |       |   |       |  |                   |
|---------|-------|---|-------|--|-------------------|
| ST 2025 | 24871 | <a href="#">Practical Course Machine Learning and Intelligent Systems</a> | 4 SWS | Practical course /  | Hanebeck, Prossel |


Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled





T

**8.250 Course: Practical Course: Robotics [T-INFO-114172]**

**Responsible:** Prof. Dr.-Ing. Tamim Asfour  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-107155 - Robotics - Practical Course](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each summer term | 1       |

| Events  |       |   |       |  |        |
|---------|-------|---|-------|--|--------|
| ST 2025 | 24870 | <a href="#">Robotics - Practical Course</a> | 4 SWS | Practical course /  | Asfour |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment is carried out as an examination of another type (§ 4 Abs. 2 No. 3 SPO). It is composed of several sub-tasks.

**Prerequisites**

Knowledge of the programming language C++ is required.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-INFO-105107 - Robotics - Practical Course](#) must not have been started.

**Recommendation**



Attending the lectures Robotics I – Introduction to Robotics, Robotics II: Humanoid Robotics, Robotics III - Sensors and Perception in Robotics and Mechano-Informatics and Robotics is recommended.





T

**8.251 Course: Practical Course: Smart Energy System [T-INFO-112030]**

**Responsible:** Dr.-Ing. Simon Waczowicz  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-105955 - Practical Course: Smart Energy System](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1       |

| Events   |         |   |       |  |   |
|----------|---------|---|-------|--|---|
| WT 24/25 | 2400159 | <a href="#">Lab Course: Smart Energy System Lab</a> | 4 SWS | Practical course /  | Hagenmeyer, Waczowicz, Jumar, Fernengel |
| ST 2025  | 2400170 | <a href="#">Laboratory: Smart Energy System Lab</a> | 4 SWS | Practical course /  | Hagenmeyer, Waczowicz, Jumar, Fernengel |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment is carried out as an examination of another type (§ 4 Abs. 2 No. 3 SPO). A written paper must be prepared and a presentation given.

**Prerequisites**

None.

**Recommendation**

- Knowledge of the fundamentals of energy informatics is a prerequisite.
- Knowledge of the fundamentals of electrical engineering and energy technology is required.
- Knowledge of the basics of mechatronics, data analysis and signal processing is helpful.
- Knowledge of power systems or power electronics is helpful.

T


## 8.252 Course: Practical Course: Software Development and Application of Mobile, Bio-Inspired Robots [T-MACH-113854]

**Responsible:** Prof. Dr.-Ing. Arne Rönnau

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106904 - Practical Course: Software Development and Application of Mobile, Bio-Inspired Robots](#)

| Type                        | Credits | Grading scale    | Recurrence       | Expansion | Version |
|-----------------------------|---------|------------------|------------------|-----------|---------|
| Examination of another type | 6       | Grade to a third | Each winter term | 1 terms   | 1       |

| Events   |         |   |       |  |        |
|----------|---------|---|-------|--|--------|
| WT 24/25 | 2121342 | <a href="#">Practical Course: Software Development and Application of Mobile, Bio-Inspired Robots</a> | 4 SWS | Practical course /  | Rönnau |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Success is assessed in the form of a different type of examination in accordance with Section 4 (2) No. 3 SPO.

Code must be generated, a written report prepared and a presentation given.

### Prerequisites

None

### Recommendation

Knowledge of the basics of robotics from Robotics 1 is helpful. Basic knowledge of C++ or Python and Linux is a prerequisite.

### Workload

180 hours



T

**8.253 Course: Practical Machine Learning [T-ETIT-113426]**

**Responsible:** Prof. Dr.-Ing. Michael Heizmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106673 - Practical Machine Learning](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |                        |       |
|---------|---------|--|-------|------------------------|-------|
| ST 2025 | 2302200 | <a href="#">Practical Machine Learning</a> | 4 SWS | Lecture / Practice ( / | Gardi |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Success is assessed by the submission of the scientific essay and the presentation of the team project lasting approx. 30 minutes.

The module grade results from the team project accompanying the semester and the presentation of the team project. The overall impression is assessed. Further details will be provided at the beginning of the course.

**Prerequisites**

none

T

**8.254 Course: Practical Project Robotics and Automation I (Software) [T-INFO-104545]**

**Responsible:** Prof. Dr.-Ing. Björn Hein  
Prof. Dr.-Ing. Thomas Längle

**Organisation:** KIT Department of Informatics

**Part of:** [M-INFO-102224 - Practical Project Robotics and Automation I \(Software\)](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1       |

T

**8.255 Course: Practical Project Robotics and Automation II (Hardware) [T-INFO-104552]**

**Responsible:** Prof. Dr.-Ing. Björn Hein  
Prof. Dr.-Ing. Thomas Längle

**Organisation:** KIT Department of Informatics

**Part of:** [M-INFO-102230 - Practical Project Robotics and Automation II \(Hardware\)](#)


| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 6       | Grade to a third | Each term  | 1       |

T

**8.256 Course: Practical Tools for Control Engineers [T-ETIT-113628]**

**Responsible:** Dr.-Ing. Balint Varga  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106780 - Practical Tools for Control Engineers](#)

| Type                        | Credits | Grading scale    | Recurrence       | Expansion | Version |
|-----------------------------|---------|------------------|------------------|-----------|---------|
| Examination of another type | 4       | Grade to a third | Each winter term | 1 terms   | 1       |

| Events   |         |   |       |   |       |
|----------|---------|---|-------|---|-------|
| WT 24/25 | 2303210 | <a href="#">Practical Tools for Control Engineers</a> | 2 SWS | Lecture /  | Varga |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The examination takes place in form of other types of examination. It consists of an oral overall examination in the amount of 25 minutes and a homework programming task. The examination includes questions from the lecture slides and the presentation of the homework assignment. The homework must be submitted two weeks before of the oral exam. The overall impression is evaluated.

**Prerequisites**

none

**Recommendation**

The contents of the modules "Optimization of Dynamic Systems (ODS)" and "Regelung linearer Mehrgrößensysteme (RLM)" are helpful for the lecture.

**Workload**

120 hours

T

## 8.257 Course: Practical Training in Basics of Microsystem Technology [T-MACH-102164]

**Responsible:** Dr. Arndt Last

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105479 - Practical Training in Basics of Microsystem Technology](#)




**Type**  
Written examination





**Credits**  
4

**Grading scale**  
Grade to a third

**Recurrence**  
Each term

**Version**  
2

| Events   |         |   |       |  |      |
|----------|---------|---|-------|--|------|
| WT 24/25 | 2143875 | <a href="#">Introduction to Microsystem Technology - Practical Course</a> | 2 SWS | Practical course /  | Last |
| WT 24/25 | 2143877 | <a href="#">Introduction to Microsystem Technology - Practical Course</a> | 2 SWS | Practical course /  | Last |
| ST 2025  | 2143875 | <a href="#">Introduction to Microsystem Technology - Practical Course</a> | 2 SWS | Practical course /  | Last |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Success is assessed in the form of a written examination lasting 60 minutes.


### Prerequisites





none

T

**8.258 Course: Probabilistic Measurement and Estimation [T-MACH-113873]****Responsible:** Prof. Dr.-Ing. Christoph Stiller**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107087 - Probabilistic Measurement and Estimation](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1 terms   | 2       |

| Events  |         |  |       |   |                  |
|---------|---------|--|-------|---|------------------|
| ST 2025 | 2138334 | <a href="#">Probabilistic Measurement and Estimation</a> | 2 SWS | Lecture /  | Stiller, Steiner |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

written exam

60 min.

2 DIN A4 Self-created formular sheets allowed

**Prerequisites**

none

**Workload**

120 hours

T


## 8.259 Course: Product- and Production-Concepts for Modern Automobiles [T-MACH-110318]





**Responsible:** Dr. Stefan Kienzle  
Dr. Dieter Steegmüller

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105346 - Product- and Production-Concepts for modern Automobiles](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |   |                      |
|----------|---------|---|-------|---|----------------------|
| WT 24/25 | 2149670 | <a href="#">Product- and Production-Concepts for modern Automobiles</a> | 2 SWS | Lecture /  | Steegmüller, Kienzle |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Oral Exam (20 min)

### Prerequisites

T-MACH-105166 - Materials and Processes for Body Lightweight Construction in the Automotive Industry must not have been started.

### Workload

120 hours

T


**8.260 Course: Production Techniques Laboratory [T-MACH-105346]**

**Responsible:** Prof. Dr.-Ing. Barbara Deml  
 Prof. Dr.-Ing. Jürgen Fleischer  
 Prof. Dr.-Ing. Kai Furmans  
 Prof. Dr.-Ing. Jivka Ovtcharova

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102711 - Production Techniques Laboratory](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 4       | pass/fail     | Each summer term | 4       |

| Events  |         |  |       |  |                                 |
|---------|---------|--|-------|--|---------------------------------|
| ST 2025 | 2110678 | <a href="#">Production Techniques Laboratory</a> | 4 SWS | Practical course /  | Deml, Fleischer, Furmans, Meyer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Active participation in lab course and successful completion of colloquia before each course. The colloquia are graded.

**Annotation**

The course is limited in capacity, therefore the allocation of places is based on § 5 (4) in the Study and Examination Regulations

This results in the following selection criteria:

The selection is based

- on the study progress (here the study progress in credit points and not the study progress in semesters is taken as a basis),
- on the waiting period in the case of equal progress in studies
- by lot if the waiting period is the same.

The procedure is explained in more detail on ILIAS.

Successful participation requires active and continuous participation in the course.

**Workload**

120 hours



T

## 8.261 Course: Project Management in the Development of Products for Safety-Critical Applications [T-ETIT-109148]

**Responsible:** Dr.-Ing. Manfred Nolle

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-104475 - Project Management in the Development of Products for Safety-Critical Applications](#)



**Type**  
Written examination





**Credits**  
4

**Grading scale**  
Grade to a third

**Recurrence**  
Each winter term

**Version**  
3

| Events   |         |   |       |  |       |
|----------|---------|---|-------|--|-------|
| WT 24/25 | 2311641 | <a href="#">Project Management in the Development of Products for Safety-Critical Applications</a>                      | 2 SWS | /            | Nolle |
| WT 24/25 | 2311643 | <a href="#">Tutorial for 2311641 Project Management in the Development of Products for Safety-Critical Applications</a> | 1 SWS | Practice /  | Nolle |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T



**8.262 Course: Project Workshop: Automotive Engineering [T-MACH-102156]**





**Responsible:** Dr.-Ing. Michael Frey  
Dr.-Ing. Martin Gießler

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107074 - Project Workshop: Automotive Engineering](#)

| Type             | Credits | Grading scale    | Recurrence | Version |
|------------------|---------|------------------|------------|---------|
| Oral examination | 6       | Grade to a third | Each term  | 1       |

| Events   |         |  |       |   |               |
|----------|---------|--|-------|---|---------------|
| WT 24/25 | 2115817 | <a href="#">Project Workshop: Automotive Engineering</a> | 3 SWS | Lecture /  | Gießler, Frey |
| ST 2025  | 2115817 | <a href="#">Project Workshop: Automotive Engineering</a> | 3 SWS | Lecture /  | Gießler, Frey |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Oral examination

Duration: 30 up to 40 minutes

Auxiliary means: none

**Prerequisites**

none

**Workload**

180 hours

T


## 8.263 Course: ProVIL - Product Development in a Virtual Idea Laboratory [T-MACH-106738]


**Responsible:** Prof. Dr.-Ing. Albert Albers  
Prof. Dr.-Ing. Tobias Düser

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)  
[M-MACH-105418 - ProVIL - Product Development in a Virtual Idea Laboratory](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 4       | pass/fail     | Each summer term | 1       |

| Events  |         |   |       |   |               |
|---------|---------|---|-------|---|---------------|
| ST 2025 | 2146210 | <a href="#">ProVIL - Product Development in a Virtual Idea Laboratory</a> | 4 SWS | Lecture /  | Albers, Düser |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

colloquia and presentations.

### Prerequisites

none

### Annotation

Offered for the last time in summer semester 2025.


### Workload

120 hours

T

**8.264 Course: Python Algorithms for Vehicle Technology [T-MACH-110796]****Responsible:** Stephan Rhode**Organisation:****Part of:** [M-MACH-107072 - Python Algorithms for Automotive Engineering](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |       |
|---------|---------|--|-------|---|-------|
| ST 2025 | 2114862 | <a href="#">Python Algorithms for Automotive Engineering</a> | 2 SWS | Lecture /  | Rhode |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Written Examination

Duration: 90 minutes

**Prerequisites**

none

**Workload**

120 hours


T

**8.265 Course: Quality Management [T-MACH-102107]**

**Responsible:** Prof. Dr.-Ing. Gisela Lanza  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105332 - Quality Management](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 3       |

| Events   |         |                                    |       |   |               |
|----------|---------|------------------------------------|-------|---|---------------|
| WT 24/25 | 2149667 | <a href="#">Quality Management</a> | 2 SWS | Lecture /  | Lanza, Stamer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written Exam (60 min)

**Prerequisites**

It is not possible to combine this brick with brick [Quality Management \[T-MACH-112586\]](#).

**Workload**



120 hours

T

**8.266 Course: Quantum Detectors and Sensors [T-ETIT-111234]**

**Responsible:** Prof. Dr. Sebastian Kempf  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-105606 - Quantum Detectors and Sensors](#)

|                                    |                     |  |                                       |                             |                     |
|------------------------------------|---------------------|--|---------------------------------------|-----------------------------|---------------------|
| <b>Type</b><br>Written examination | <b>Credits</b><br>6 | <b>Grading scale</b><br>Grade to a third | <b>Recurrence</b><br>Each winter term | <b>Expansion</b><br>1 terms | <b>Version</b><br>1 |
|------------------------------------|---------------------|--|---------------------------------------|-----------------------------|---------------------|

| Events   |         |  |       |  |       |
|----------|---------|--|-------|--|-------|
| WT 24/25 | 2312706 | <a href="#">Quantum Detectors and Sensors</a>                      | 3 SWS | Lecture /   | Kempf |
| WT 24/25 | 2312707 | <a href="#">Exercise for 2312706 Quantum Detectors and Sensors</a> | 1 SWS | Practice /  | Ilin  |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment of success takes place in the form of a written examination lasting 120min. The grade corresponds to the result of the written examination.

**Prerequisites**

None

**Recommendation**

Successful completion of the module "Superconductivity for Engineers" is recommended.

T

**8.267 Course: Quantum Machines I [T-MACH-113827]**

**Responsible:** Prof. Dr. Marcel Utz  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-107164 - Quantum Machines I](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1 terms   | 1       |

**Competence Certificate**

Written exam, duration: 90 minutes

**Prerequisites**

none

**Recommendation**

- A standard BSc degree in mechanical, materials or electrical engineering
- Solid knowledge of engineering mechanics, including statics, dynamics and mechanics of materials.
- Basic knowledge of engineering thermodynamics.
- Proficiency in complex numbers, including their algebraic and polar forms.
- Understanding of linear algebra, including vector spaces, matrices, eigenvalues and eigenvectors.
- Familiarity with ordinary differential equations (ODEs) and their solutions, especially as they relate to physical systems.

**Workload**

120 hours

T

**8.268 Course: Quantum Machines II [T-MACH-113826]**

**Responsible:** Prof. Dr. Marcel Utz  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-107165 - Quantum Machines II](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1 terms   | 1       |

**Competence Certificate**

Written exam, duration: 90 minutes

**Prerequisites**

none

**Recommendation**

- A standard BSc degree in mechanical, materials or electrical engineering
- Solid knowledge of engineering mechanics, including statics, dynamics and mechanics of materials.
- Basic knowledge of engineering thermodynamics.
- Foundations of quantum mechanics (Quantum Machines I is recommended).
- Proficiency in complex numbers, including their algebraic and polar forms.
- Understanding of linear algebra, including vector spaces, matrices, eigenvalues and eigenvectors.
- Familiarity with ordinary differential equations (ODEs) and their solutions, especially as they relate to physical systems.

**Workload**

120 hours





T

**8.269 Course: Radio-Frequency Electronics [T-ETIT-113910]**

**Responsible:** Prof. Dr.-Ing. Ahmet Cagri Ulusoy  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106955 - Radio-Frequency Electronics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |  |        |
|----------|---------|--|-------|--|--------|
| WT 24/25 | 2308503 | <a href="#">Radio-Frequency Electronics</a>                      | 2 SWS | Lecture /   | Ulusoy |
| WT 24/25 | 2308504 | <a href="#">Exercise for 2308503 Radio-Frequency Electronics</a> | 1 SWS | Practice /  | Kuo    |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The examination takes place in form of a written examination lasting 120 minutes.

The module grade is the grade of the written examination.

**Prerequisites**

none



T





**8.270 Course: Rail System Technology [T-MACH-106424]**

**Responsible:** Prof. Dr.-Ing. Martin Cichon  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-103232 - Rail System Technology](#)

| Type                | Credits | Grading scale    | Recurrence | Version |
|---------------------|---------|------------------|------------|---------|
| Written examination | 4       | Grade to a third | Each term  | 4       |

| Events   |         |  |       |   |        |
|----------|---------|--|-------|---|--------|
| WT 24/25 | 2115919 | <a href="#">Rail System Technology</a> | 2 SWS | Lecture /  | Cichon |
| ST 2025  | 2115919 | <a href="#">Rail System Technology</a> | 2 SWS | Lecture /  | Cichon |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

written examination in German language

Duration: 60 minutes

No tools or reference materials may be used during the exam except calculator and dictionary

**Prerequisites**

none

**Workload**

120 hours



T





**8.271 Course: Rail Vehicle Technology [T-MACH-105353]**

**Responsible:** Prof. Dr.-Ing. Martin Cichon  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102683 - Rail Vehicle Technology](#)

| Type                | Credits | Grading scale    | Recurrence | Version |
|---------------------|---------|------------------|------------|---------|
| Written examination | 4       | Grade to a third | Each term  | 4       |

| Events   |         |   |       |   |        |
|----------|---------|---|-------|---|--------|
| WT 24/25 | 2115996 | <a href="#">Rail Vehicle Technology</a> | 2 SWS | Lecture /  | Cichon |
| ST 2025  | 2115996 | <a href="#">Rail Vehicle Technology</a> | 2 SWS | Lecture /  | Cichon |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

written examination in German language

Duration: approx 60 minutes

No tools or reference materials may be used during the exam except calculator and dictionary

**Prerequisites**

none

**Workload**

120 hours

T





**8.272 Course: Railways in the Transportation Market [T-MACH-105540]**

**Responsible:** Prof. Dr.-Ing. Martin Cichon  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107044 - Railways in the Transportation Market](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |        |
|---------|---------|---|-------|---|--------|
| ST 2025 | 2114914 | <a href="#">Railways in the Transportation Market</a> | 2 SWS | Block /  | Cichon |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Oral examination

Duration: ca. 20 minutes

No tools or reference materials may be used during the exam.

**Prerequisites**

none

**Workload**

120 hours

T

## 8.273 Course: Re:Invent - Revolutionary Business Models as the Basis for Product Innovations [T-MACH-111888]





**Responsible:** Dr.-Ing. Thomas Schneider

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106662 - Re:Invent - Revolutionary Business Models as the Basis for Product Innovations](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1 terms   | 1       |

| Events  |         |  |       |   |           |
|---------|---------|--|-------|---|-----------|
| ST 2025 | 2147177 | <a href="#">Re:Invent - Revolutionary Business Models as the Basis for Product Innovations (Lecture)</a> | 2 SWS | Lecture /  | Schneider |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Oral exam, duration: approx. 20 minutes

### Prerequisites

None

### Workload

120 hours

T

**8.274 Course: Reactor Safety I: Fundamentals [T-MACH-105405]**

**Responsible:** Dr. Victor Hugo Sanchez-Espinoza  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107116 - Reactor Safety 1: Fundamentals](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |                  |
|---------|---------|--|-------|---|------------------|
| ST 2025 | 2189465 | <a href="#">Reactor Safety I: Fundamentals</a> | 2 SWS | Lecture /  | Sanchez-Espinoza |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral exam about 30 minutes

**Prerequisites**

none

**Workload**



120 hours





T

**8.275 Course: Real Time Control of Electrical Drives [T-ETIT-111898]**

**Responsible:** Dr.-Ing. Andreas Liske  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-105916 - Real Time Control of Electrical Drives](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |  |       |
|----------|---------|---|-------|--|-------|
| WT 24/25 | 2306353 | <a href="#">Real Time Control of Electrical Drives</a>                      | 3 SWS | Lecture /   | Liske |
| WT 24/25 | 2306354 | <a href="#">Tutorial for 2306353 Real Time Control of Electrical Drives</a> | 1 SWS | Practice /  | Liske |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T

**8.276 Course: Real-Time Systems [T-INFO-101340]**

**Responsible:** Prof. Dr.-Ing. Thomas Längle  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-100803 - Real-Time Systems](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1       |



T

**8.277 Course: Reinforcement Learning [T-INFO-111255]**

**Responsible:** TT-Prof. Dr. Rudolf Lioutikov  
Prof. Dr. Gerhard Neumann

**Organisation:** KIT Department of Informatics

**Part of:** [M-INFO-105623 - Reinforcement Learning](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 2       |

| Events   |         |  |  |   |
|----------|---------|--|--|---|
| WT 24/25 | 2400163 | <a href="#">Reinforcement Learning</a> |  | Lecture / Practice ( /<br>● Neumann, Lioutikov,<br>Zhou |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

The success control takes place in the form of a written exam, usually 90 minutes in length, according to § 4 Abs. 2 Nr. 1 SPO.

A bonus can be acquired through successful participation in the exercise as a success control of a different kind (§4(2), 3 SPO 2008) or study performance (§4(3) SPO 2015). The exact criteria for awarding a bonus will be announced at the beginning of the lecture. If the grade of the written examination is between 4.0 and 1.3, the bonus improves the grade by one grade level (0.3 or 0.4). The bonus is only valid for the main and post exams of the semester in which it was earned. After that, the grade bonus expires.

**Prerequisites**

None.

**Recommendation**

- Students should be familiar with the content of the "Foundations of Artificial Intelligence" lecture.
- Good Python knowledge is required.
- Good mathematical background knowledge is required.



## T





**8.278 Course: Reliability and Test Engineering [T-MACH-111840]**

**Responsible:** Dr.-Ing. Thomas Gwosch  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-106050 - Reliability and Test Engineering](#)

| Type                        | Credits | Grading scale    | Recurrence       | Expansion | Version |
|-----------------------------|---------|------------------|------------------|-----------|---------|
| Examination of another type | 5       | Grade to a third | Each winter term | 1 terms   | 2       |

| Events   |         |  |       |  |        |
|----------|---------|--|-------|--|--------|
| WT 24/25 | 2145350 | <a href="#">Reliability and Test Engineering (Lecture)</a> | 1 SWS | Lecture /           | Gwosch |
| WT 24/25 | 2145351 | <a href="#">Workshop Reliability and Test Engineering</a>  | 2 SWS | Practical course /  | Gwosch |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The grade is composed of the evaluation of a final report following the practical part. The assessment criteria are as follows:

- Structure of the report
- Comprehensibility and comprehensibility
- Preparation of the tests
- Use of test and reliability methods
- Formulation and answering of test hypotheses
- Test evaluation, comprehensible results

Attendance and active participation in the lab is mandatory.

**Prerequisites**

none

**Recommendation**

None





**Workload**

150 hours

T

**8.279 Course: Renewable Energy-Resources, Technologies and Economics [T-WIWI-100806]****Responsible:** Prof. Dr. Patrick Jochem**Organisation:** KIT Department of Economics and Management**Part of:** [M-WIWI-100500 - Renewable Energy-Resources, Technologies and Economics](#)**Type**  
Written examination**Credits**  
4**Grading scale**  
Grade to a third**Recurrence**  
Each winter term**Version**  
8**Events**

|          |         |  |       |   |        |
|----------|---------|--|-------|---|--------|
| WT 24/25 | 2581012 | <a href="#">Renewable Energy – Resources, Technologies and Economics</a> | 2 SWS | Lecture /  | Jochem |
|----------|---------|--|-------|---|--------|

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

The assessment consists of a written exam (60 minutes, in English, answers are possible in German or English) (following §4(2) of the examination regulation). The exam takes place in every semester. Re-examinations are offered at every ordinary examination date. Depending on the respective pandemic situation, the exam may be offered as an open book exam (alternative exam assessment, following §4(2), 3 of the examination regulation).

**Prerequisites**

None.

T

**8.280 Course: Robotics II - Humanoid Robotics [T-INFO-114152]**

**Responsible:** Prof. Dr.-Ing. Tamim Asfour  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-107123 - Robotics II - Humanoid Robotics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 3       | Grade to a third | Each summer term | 1       |

**Competence Certificate**

The assessment is carried out as a written examination (§ 4 Abs. 2 No. 1 SPO) lasting 60 minutes.

**Prerequisites**

- M-INFO-100816 - Robotics II - Learning and planning robots Module must not have been started.
- T-INFO-101391 - Anthropomatics: Humanoid Robotics Partial work must not have been started.

**Recommendation**

Having visited the lectures on Robotics I - Introduction to Robotics and Mechano-Informatics and Robotics is recommended.

T

**8.281 Course: Robotics III - Sensors and Perception in Robotics [T-INFO-114155]**

**Responsible:** Prof. Dr.-Ing. Tamim Asfour  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-107130 - Robotics III - Sensors and Perception in Robotics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 3       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |             |        |
|---------|---------|---|-------|-------------|--------|
| ST 2025 | 2400067 | <a href="#">Robotics III - Sensors and Perception in Robotics</a> | 2 SWS | Lecture / 🗎 | Asfour |

Legend: 🗎 Online, 🗎 Blended (On-Site/Online), 🗎 On-Site, ✕ Cancelled

**Competence Certificate**

The assessment is carried out as a written examination (§ 4 Abs. 2 No. 1 SPO) lasting 60 minutes.

**Prerequisites**

none.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-INFO-109931 - Robotics III - Sensors and Perception in Robotics](#) must not have been started.

**Recommendation**

Attending the lecture Robotics I – Introduction to Robotics is recommended.

T

**8.282 Course: Seamless Engineering [T-MACH-111401]**

**Responsible:** Prof. Dr.-Ing. Kai Furmans  
Prof. Dr.-Ing. Eric Sax

**Organisation:** KIT Department of Electrical Engineering and Information Technology  
KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105725 - Seamless Engineering](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 9       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |                          |              |
|----------|---------|--|-------|--------------------------|--------------|
| WT 24/25 | 2117072 | <a href="#">Seamless Engineering - Logistics Robotics Workshop</a> | 2 SWS | Lecture / Practice ( / ) | Furmans, Sax |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

Competence certificate in the form of an examination of another type.

The overall grade is composed as follows:

- 50% assessment of an examination as individual performance as the conclusion of the lecture block.
- 50% assessment of colloquia as individual performance on defined milestones during the project work

Failing the final examination or the colloquia does not result in failing the course.

**Prerequisites**

None

**Recommendation**

None

**Annotation**

The course consists of two components. Theoretical knowledge and basics about structured system design are taught in lecture and exercise. In parallel, a practical part takes place throughout the semester. In this, the students design and implement a mechatronic system in small groups using industry-related hardware and software to deal with a given task in the logistics environment.

**Workload**

270 hours

T

**8.283 Course: Self Assignment-HOC-SPZ-FORUM-graded [T-ETIT-111688]****Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                        | Credits | Grading scale    | Version |
|-----------------------------|---------|------------------|---------|
| Examination of another type | 2       | Grade to a third | 1       |

**Self service assignment of supplementary studies**

This course can be used for self service assignment of grade acquired from the following study providers:

- House of Competence
- Sprachenzentrum
- Studium Generale. Forum Wissenschaft und Gesellschaft (FORUM) (ehem. ZAK)

**Annotation**

Placeholder for self-booking of a graded interdisciplinary qualification, which was provided at the House of Competence, the "Sprachenzentrum" or the Center for Applied Cultural Studies and Studium Generale.

Title and credits of the achievement are adopted.

T

**8.284 Course: Self Assignment-HOC-SPZ-FORUM-graded [T-ETIT-111689]****Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                        | Credits | Grading scale    | Version |
|-----------------------------|---------|------------------|---------|
| Examination of another type | 2       | Grade to a third | 1       |

**Self service assignment of supplementary studies**

This course can be used for self service assignment of grade acquired from the following study providers:

- House of Competence
- Sprachenzentrum
- Studium Generale. Forum Wissenschaft und Gesellschaft (FORUM) (ehem. ZAK)

**Annotation**

Placeholder for self-booking of a graded interdisciplinary qualification, which was provided at the House of Competence, the "Sprachenzentrum" or the Center for Applied Cultural Studies and Studium Generale.

Title and credits of the achievement are adopted.



T

**8.285 Course: Self Assignment-HOC-SPZ-FORUM-ungraded [T-ETIT-112899]****Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                 | Credits | Grading scale | Version |
|----------------------|---------|---------------|---------|
| Completed coursework | 2       | pass/fail     | 1       |

**Annotation**

Placeholder for self-booking of a ungraded interdisciplinary qualification, which was provided at the House of Competence, the "Sprachenzentrum" or the Center for Applied Cultural Studies and Studium Generale.

Title and credits of the achievement are adopted.

T

**8.286 Course: Self Assignment-HOC-SPZ-FORUM-ungraded [T-ETIT-112898]****Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                 | Credits | Grading scale | Version |
|----------------------|---------|---------------|---------|
| Completed coursework | 2       | pass/fail     | 1       |

**Self service assignment of supplementary studies**

This course can be used for self service assignment of grade acquired from the following study providers:

- House of Competence
- Sprachenzentrum
- Studium Generale. Forum Wissenschaft und Gesellschaft (FORUM) (ehem. ZAK)

**Annotation**

Placeholder for self-booking of a ungraded interdisciplinary qualification, which was provided at the House of Competence, the "Sprachenzentrum" or the Center for Applied Cultural Studies and Studium Generale.

Title and credits of the achievement are adopted.

T

## 8.287 Course: Seminar Application of Artificial Intelligence in Production [T-MACH-112121]





**Responsible:** Prof. Dr.-Ing. Jürgen Fleischer

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105968 - Artificial Intelligence in Production](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 4       | Grade to a third | Each summer term | 5       |

| Events  |         |  |       |   |           |
|---------|---------|--|-------|---|-----------|
| ST 2025 | 2150910 | <a href="#">Seminar Application of Artificial Intelligence in Production</a> | 2 SWS | Seminar /  | Fleischer |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Alternative test achievement (graded):

- Presentation of the results (approx. 20 min) followed by a colloquium (approx. 15 min) with weighting 25%
- Written processing of the results with weighting 75%

### Prerequisites

none

### Recommendation

Previous participation in the lecture 2149921 "Artificial Intelligence in Production" or advanced knowledge of Python.

### Workload


120 hours

T

**8.288 Course: Seminar Creating a Patent Specification [T-ETIT-100754]**

**Responsible:** Prof. Dr. Wilhelm Stork  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 3       | pass/fail     | Each summer term | 1       |

| Events  |         |   |       |   |       |
|---------|---------|---|-------|---|-------|
| ST 2025 | 2311633 | <a href="#">Seminar Creating a Patent Specification</a> | 2 SWS | Seminar /  | Stork |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

**8.289 Course: Seminar Data-Mining in Production [T-MACH-108737]****Responsible:** Prof. Dr.-Ing. Gisela Lanza**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105477 - Seminar Data-Mining in Production](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 3       | Grade to a third | Each winter term | 2       |

| Events   |         |   |       |             |       |
|----------|---------|---|-------|-------------|-------|
| WT 24/25 | 2151643 | <a href="#">Seminar Data Mining in Production</a> | 2 SWS | Seminar / ● | Lanza |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

alternative test achievement (graded):

- written elaboration (workload of at least 80 h)
- oral presentation (approx. 30 min)

**Prerequisites**

none

**Annotation**The number of students is limited to twelve. Dates and deadlines for the seminar will be announced at <https://www.wbk.kit.edu/studium-und-lehre.php>.**Workload**

90 hours

T

## 8.290 Course: Seminar Development of Automated Production Systems [T-MACH-113999]

**Responsible:** Prof. Dr.-Ing. Jürgen Fleischer

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107020 - Development of Automated Production Systems](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 4       | Grade to a third | Each winter term | 1       |

### Competence Certificate

Alternative test achievement (graded):

- Presentation of the results (approx. 20 min) followed by a colloquium (approx. 15 min) with weighting 25%
- Written processing of the results with weighting 75%

### Prerequisites

T-MACH-108844 - Automated production systems must not be started

### Workload



120 hours





T

**8.291 Course: Seminar Electrocatalysis [T-ETIT-111256]**

**Responsible:** Prof. Dr.-Ing. Ulrike Krewer  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-105629 - Seminar Electrocatalysis](#)

| Type                        | Credits | Grading scale    | Recurrence | Expansion | Version |
|-----------------------------|---------|------------------|------------|-----------|---------|
| Examination of another type | 3       | Grade to a third | Each term  | 1 terms   | 1       |

| Events   |         |  |       |   |      |
|----------|---------|--|-------|---|------|
| WT 24/25 | 2304238 | <a href="#">Seminar Electrocatalysis</a> | 2 SWS | Seminar /  | Röse |
| ST 2025  | 2304302 | <a href="#">Seminar Elektrokatalyse</a>  | 2 SWS | Seminar /  | Röse |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

**8.292 Course: Seminar Embedded Systems [T-ETIT-100753]**

**Responsible:** Prof. Dr.-Ing. Jürgen Becker  
 Prof. Dr.-Ing. Eric Sax  
 Prof. Dr. Wilhelm Stork

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-100455 - Seminar Embedded Systems](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 4       | Grade to a third | Each term  | 3       |

| Events   |         |  |       |              |                    |
|----------|---------|--|-------|--------------|--------------------|
| WT 24/25 | 2311627 | <a href="#">Seminar Embedded Systems</a> | 2 SWS | Seminar / 🗓️ | Becker, Sax, Stork |
| ST 2025  | 2311627 | <a href="#">Seminar Embedded Systems</a> | 2 SWS | Seminar / 🔄  | Becker, Sax, Stork |

Legend: 📺 Online, 🔄 Blended (On-Site/Online), 🗓️ On-Site, ✖ Cancelled

**Prerequisites**



none







T

**8.293 Course: Seminar for Rail System Technology [T-MACH-108692]****Responsible:** Prof. Dr.-Ing. Martin Cichon**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-104197 - Seminar for Rail System Technology](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 3       | Grade to a third | Each term  | 2       |

| Events   |         |  |       |   |                |
|----------|---------|--|-------|---|----------------|
| WT 24/25 | 2115009 | <a href="#">Seminar for Rail System Technology</a> | 2 SWS | Seminar /  | Cichon, Ziesel |
| ST 2025  | 2115009 | <a href="#">Seminar for Rail System Technology</a> | 2 SWS | Seminar /  | Ziesel, Cichon |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Examination: Writing a Seminararbeit, final presentation

**Prerequisites**

none

**Workload**


90 hours

T

**8.294 Course: Seminar Industrial Process and Plant Engineering [T-ETIT-113932]**

**Responsible:** Prof. Dr.-Ing. Mike Barth  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106970 - Seminar Industrial Process and Plant Engineering](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |             |
|---------|---------|--|-------|---|-------------|
| ST 2025 | 2303650 | <a href="#">Seminar Industrial Process and Plant Engineering</a> | 3 SWS | Seminar /  | Barth, Jilg |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The examination will be the seminar presentation at the end of the semester. The criteria are:

- Live presentation of the created CAD and simulation models
- Poster design and usage within the presentation
- Answering the questions from the examiners
- Structure of the talk

**Prerequisites**

none

T

**8.295 Course: Seminar Intelligent Industrial Robots [T-INFO-104526]**



**Responsible:** Prof. Dr.-Ing. Björn Hein  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-102212 - Seminar Intelligent Industrial Robots](#)





|  |                     |  |                                |                     |
|--|---------------------|--|--------------------------------|---------------------|
| <b>Type</b><br>Examination of another type | <b>Credits</b><br>3 | <b>Grading scale</b><br>Grade to a third | <b>Recurrence</b><br>Each term | <b>Version</b><br>1 |
|--|---------------------|--|--------------------------------|---------------------|

T

**8.296 Course: Seminar New Components and Systems of Power Electronics [T-ETIT-100713]****Responsible:** Prof. Dr.-Ing. Marc Hiller**Organisation:** KIT Department of Electrical Engineering and Information Technology**Part of:** [M-ETIT-100396 - Seminar New Components and Systems of Power Electronics](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 4       | Grade to a third | Each term  | 2       |

| Events   |         |   |       |   |        |
|----------|---------|---|-------|---|--------|
| WT 24/25 | 2306317 | <a href="#">New Components and Systems of Power Electronics</a> | 3 SWS | Seminar /  | Hiller |
| ST 2025  | 2306317 | <a href="#">New Components and Systems of Power Electronics</a> | 3 SWS | Seminar /  | Hiller |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Prerequisites**

none

T


## 8.297 Course: Seminar Novel Concepts for Solar Energy Harvesting [T-ETIT-108344]





**Responsible:** Prof. Dr. Bryce Sydney Richards

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-103447 - Seminar Novel Concepts for Solar Energy Harvesting](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 3       | Grade to a third | Each summer term | 2       |

| Events  |         |  |       |   |          |
|---------|---------|--|-------|---|----------|
| ST 2025 | 2313761 | <a href="#">Seminar Novel Concepts for Solar Energy Harvesting</a> | 2 SWS | Seminar /  | Paetzold |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

The examination consists of a written journal article and an oral presentation of the student's work, both given in English. The overall impression is rated.

### Prerequisites

none

T

**8.298 Course: Seminar Project Management for Engineers [T-ETIT-100814]**

**Responsible:** Prof. Dr.-Ing. Mathias Noe  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 3       | pass/fail     | Each summer term | 1       |

**Competence Certificate**

Type of Examination: Oral exam

Duration of Examination: approx. 30 minutes

**Prerequisites**

none

**Annotation****Not applicable in summer term 2022**

Exam and Seminar are held in English.

Detailed information on contents, competence goals, and work load at:

[M-ETIT-100551 – Seminar Project Management for Engineers](#)

T


**8.299 Course: Seminar Project Management for Engineers [T-ETIT-108820]**

**Responsible:** Dr. Christian Day  
Prof. Dr.-Ing. Mathias Noe

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                        | Credits | Grading scale | Recurrence       | Version |
|-----------------------------|---------|---------------|------------------|---------|
| Completed coursework (oral) | 3       | pass/fail     | Each summer term | 2       |

| Events  |         |  |       |   |     |
|---------|---------|--|-------|---|-----|
| ST 2025 | 2312684 | <a href="#">Project Management for Engineers</a> | 2 SWS | Seminar /  | Noe |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**



none





T

**8.300 Course: Seminar: Bionic Algorithms and Robot Technologies [T-MACH-113842]**

**Responsible:** Prof. Dr.-Ing. Arne Rönnau  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-106902 - Seminar: Bionic Algorithms and Robot Technologies](#)

| Type                        | Credits | Grading scale    | Recurrence | Expansion | Version |
|-----------------------------|---------|------------------|------------|-----------|---------|
| Examination of another type | 3       | Grade to a third | Each term  | 1 terms   | 1       |

| Events   |         |   |       |   |        |
|----------|---------|---|-------|---|--------|
| WT 24/25 | 2121343 | <a href="#">Seminar: Bionic Algorithms and Robot Technologies</a> | 2 SWS | Seminar /  | Rönnau |
| ST 2025  | 2121343 | <a href="#">Seminar: Bionic Algorithms and Robot Technologies</a> | 2 SWS | Seminar /  | Rönnau |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Success is assessed through the preparation of a written seminar paper and its presentation as an examination of a different kind.

**Prerequisites**

None

**Recommendation**

Attending the lecture "Biologically Inspired Robots" is helpful.

**Workload**

90 hours








T

**8.301 Course: Sensors [T-ETIT-101911]**

**Responsible:** Dr. Wolfgang Menesklou  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100378 - Sensors](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 3       | Grade to a third | Each summer term | 2       |

| Events  |         |                         |       |   |           |
|---------|---------|-------------------------|-------|---|-----------|
| ST 2025 | 2304231 | <a href="#">Sensors</a> | 2 SWS | Lecture /  | Menesklou |


Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled





T

**8.302 Course: Signal Processing Lab [T-ETIT-113369]**

**Responsible:** Prof. Dr.-Ing. Sander Wahls  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106633 - Signal Processing Lab](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |                                       |       |  |                 |
|---------|---------|---------------------------------------|-------|--|-----------------|
| ST 2025 | 2302134 | <a href="#">Signal Processing Lab</a> | 4 SWS | Practical course /  | Wahls, van Wijk |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Success is assessed in the form of a written examination lasting 120 minutes.

**Prerequisites**

none

**Recommendation**

Knowledge of the contents of the modules "Signals and Systems", "Measurement Technology" and "Methods of Signal Processing" is strongly recommended.

**Annotation**

A prerequisite for admission to the examination is the submission of protocols of all experiments. The quality of the protocols will be assessed; they must be acceptable for admission to the examination.

Attendance is compulsory during all practical sessions, including the introductory session. Admission to the examination will not be granted for even one unexcused absence.

T

**8.303 Course: Signal Processing Methods [T-ETIT-113837]**

**Responsible:** Prof. Dr.-Ing. Sander Wahls  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106899 - Signal Processing Methods](#)



**Type**  
Written examination

**Credits**  
6

**Grading scale**  
Grade to a third

**Recurrence**  
Each winter term

**Version**  
1

| Events   |         |   |       |  |                   |
|----------|---------|---|-------|--|-------------------|
| WT 24/25 | 2302113 | <a href="#">Signal Processing Methods</a>                     | 2 SWS | Lecture /   | Wahls             |
| WT 24/25 | 2302115 | <a href="#">Tutorial to 2302113 Signal Processing Methods</a> | 2 SWS | Practice /  | Wahls, Al-Hammadi |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Written exam, approx. 120 minutes.  
 The module grade is the grade of the written exam.

**Prerequisites**

none

**Recommendation**

Familiarity with signals and systems (in particular, Fourier transforms) and probability theory at the Bachelor level is assumed.

T



## 8.304 Course: Signal Processing with Nonlinear Fourier Transforms and Koopman Operators [T-ETIT-113428]





**Responsible:** Prof. Dr.-Ing. Sander Wahls

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-106675 - Signal Processing with Nonlinear Fourier Transforms and Koopman Operators](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |  |              |
|---------|---------|---|-------|--|--------------|
| ST 2025 | 2302135 | <a href="#">Signal Processing with Nonlinear Fourier Transforms and Koopman Operators</a>                     | 2 SWS | Lecture /   | Wahls        |
| ST 2025 | 2302136 | <a href="#">Practice to 2302135 Signal Processing with Nonlinear Fourier Transforms and Koopman Operators</a> | 2 SWS | Practice /  | Wahls, Liang |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

The examination in this module consists of programming assessments and a graded written examination of 120 minutes.

The programming assignments are either pass or fail. They must be passed during the lecture period for admission to the written examination.

The module grade is the grade of the written exam.

### Prerequisites

none

T

**8.305 Course: SIL Entrepreneurship Project [T-WIWI-110166]**

**Responsible:** Prof. Dr. Orestis Terzidis  
**Organisation:** KIT Department of Economics and Management  
**Part of:** [M-ETIT-105073 - Student Innovation Lab](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 3       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |         |          |
|----------|---------|--|-------|---------|----------|
| WT 24/25 | 2545082 | <a href="#">SIL Entrepreneurship Project</a> | 4 SWS | Seminar | Terzidis |

**Competence Certificate**

Alternative exam assessment (§4(2), 3 SPO). The final grade is a result from both, the grade of the term paper and its presentation, as well as active participation during the seminar. In addition, smaller, ungraded tasks are provided in the course to monitor progress.

**Prerequisites**

None

**Recommendation**

None

**Workload**





90 hours

T

**8.306 Course: Simulation and Optimization in Robotics and Biomechanics [T-INFO-113123]****Responsible:** Prof. Dr. Katja Mombaur**Organisation:** KIT Department of Informatics**Part of:** [M-INFO-106504 - Simulation and Optimization in Robotics and Biomechanics](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each winter term | 4       |

| Events   |         |  |       |                          |         |
|----------|---------|--|-------|--------------------------|---------|
| WT 24/25 | 2400160 | <a href="#">Simulation and Optimization in Robotics and Biomechanics</a> | 4 SWS | Lecture / Practice ( / ) | Mombaur |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

The assessment is carried out as an oral examination (§ 4 Abs. 2 No. 1 SPO) lasting up to 30 minutes. It can be repeated once. As a prerequisite for the participation in the oral exam, students must regularly and successfully participate in the exercises. Students must regularly submit exercise sheets. The number of exercise sheets and the scale for passing will be announced at the beginning of the course.

**Prerequisites**

none

**Recommendation**

General principles of robotics are strongly recommended (e.g. from "Robotics I - Introduction to Robotics": T-INFO-101465, T-INFO-108014 or T-INFO-114190).

**Annotation**


Limitation to 30 participants





T

**8.307 Course: Simulation with Lumped Parameters [T-MACH-113862]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-107053 - Simulation with Lumped Parameters](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 1 terms   | 2       |

| Events  |         |   |       |   |                  |
|---------|---------|---|-------|---|------------------|
| ST 2025 | 2114071 | <a href="#">Simulation with Lumped Parameters</a> | 2 SWS | Lecture /  | Geimer, Michiels |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Oral examination, duration approx. 20 minutes

**Prerequisites**

none

**Recommendation**

Knowledge of mechanics and hydraulics

**Workload**

90 hours

T


## 8.308 Course: Simulator Exercises Combined Cycle Power Plants [T-MACH-105445]





**Responsible:** Prof. Dr.-Ing. Daniel Banuti  
Hon.-Prof. Dr. Thomas Schulenberg

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107062 - Combined Cycle Power Plants](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 2       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |  |                     |
|---------|---------|---|-------|--|---------------------|
| ST 2025 | 2170491 | <a href="#">Simulator Exercises Combined Cycle Power Plants</a> | 2 SWS | Practical course /  | Banuti, Schulenberg |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

oral exam (ca. 15 min)

### Prerequisites

none

### Recommendation

Participation at LV-No. 2170490 "Combined Cycle Power Plants" (T-MACH-105444) is recommended.

### Workload

60 hours








T

**8.309 Course: Software Engineering [T-ETIT-108347]**

**Responsible:** Dr. Clemens Reichmann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100450 - Software Engineering](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 4       |

| Events  |         |                                      |       |   |           |
|---------|---------|--------------------------------------|-------|---|-----------|
| ST 2025 | 2311611 | <a href="#">Software Engineering</a> | 2 SWS | Lecture /  | Reichmann |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Success control takes place in the form of an oral examination lasting approx. 25 minutes.

The module grade is the grade of the oral examination.

**Prerequisites**



none





T

**8.310 Course: Solar Energy [T-ETIT-100774]**

**Responsible:** Prof. Dr. Bryce Sydney Richards  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100524 - Solar Energy](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |  |                    |
|----------|---------|---|-------|--|--------------------|
| WT 24/25 | 2313745 | <a href="#">Solar Energy</a>                  | 3 SWS | Lecture /   | Richards, Paetzold |
| WT 24/25 | 2313750 | <a href="#">Tutorial 2313745 Solar Energy</a> | 1 SWS | Practice /  | Richards, Paetzold |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

Students are not allowed to take „T-ETIT-101939 - Photovoltaik" in addition to this one.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-ETIT-101939 - Photovoltaics](#) must not have been started.

T

**8.311 Course: Solar Thermal Energy Systems [T-MACH-106493]****Responsible:** apl. Prof. Dr. Ron Dagan**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-101924 - Solar Thermal Energy Systems](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 4       |

| Events   |         |  |       |   |       |
|----------|---------|--|-------|---|-------|
| WT 24/25 | 2189400 | <a href="#">Solar Thermal Energy Systems</a> | 2 SWS | Lecture /  | Dagan |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam of about 30 minutes

**Prerequisites**

none

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-MACH-105225 - Thermal Solar Energy](#) must not have been started.

**Recommendation**

Literature

1. "Solar Engineering of Thermal Processes", 4th Edition, J. Duffie & W. Beckman. Published by Wiley & Sons
2. "Heat Transfer", 10th Edition, J. P. Holman. Mc. Graw Hill publisher
3. "Fundamentals of classical Thermodynamics", G. Van Wylen & R. E. Sonntag. Published by Wiley & Sons

**Workload**

120 hours

T



**8.312 Course: Spaceborne Radar Remote Sensing - Exam [T-ETIT-112857]**





**Responsible:** Prof. Dr.-Ing. Alberto Moreira  
Dr. Pau Prats

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-103042 - Spaceborne Radar Remote Sensing](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |  |                |
|---------|---------|--|-------|--|----------------|
| ST 2025 | 2308428 | <a href="#">Spaceborne Radar Remote Sensing</a>          | 2 SWS | Lecture /     | Prats, Moreira |
| ST 2025 | 2308429 | <a href="#">Tutorial Spaceborne Radar Remote Sensing</a> | 1 SWS | Tutorial ( /  | Younis         |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment takes place in the form of a written examination lasting 120 min.

**Prerequisites**

"T-ETIT-106056 - Spaceborne Radar Remote Sensing" is not allowed to be started or to be completed.

**Recommendation**

Signal processing and radar fundamentals.

**Annotation**

Further information can be found at the internet page of the IHE (<https://s.kit.edu/ihe-srrs>).

T

**8.313 Course: Spaceborne Radar Remote Sensing - Workshop [T-ETIT-112858]**

**Responsible:** Prof. Dr.-Ing. Marwan Younis  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-103042 - Spaceborne Radar Remote Sensing](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 2       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |     |               |
|---------|---------|---|-------|-----|---------------|
| ST 2025 | 2308427 | <a href="#">Spaceborne Radar Remote Sensing</a> | 1 SWS | / ● | Younis, Prats |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

The assessment takes place in the form of reports (other types of examination). Those reports have to be submitted as part of the SAR computer workshop (approx. a total of five workshops). Details will be given during the lecture.

**Prerequisites**

"T-ETIT-106056 - Spaceborne Radar Remote Sensing" is not allowed to be started or to be completed.

**Recommendation**

Signal processing and radar fundamentals.

**Annotation**


Further information can be found at the internet page of the IHE (<https://s.kit.edu/ihe-srrs>).





T

**8.314 Course: Stochastic Information Processing [T-INFO-101366]**

**Responsible:** Prof. Dr.-Ing. Uwe Hanebeck  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-100829 - Stochastic Information Processing](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |   |                  |
|----------|---------|---|-------|---|------------------|
| WT 24/25 | 2424113 | <a href="#">Stochastic Information Processing</a> | 3 SWS | Lecture /  | Hanebeck, Frisch |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

T

## 8.315 Course: Strategic Product Development - Identification of Potentials of Innovative Products [T-MACH-105696]





**Responsible:** Prof. Dr.-Ing. Andreas Siebe

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107140 - Strategic Product Development - Identification of Potentials of Innovative Products](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 3       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |   |       |
|---------|---------|---|-------|---|-------|
| ST 2025 | 2146198 | <a href="#">Strategic product development - identification of potentials of innovative products</a> | 2 SWS | Lecture /  | Siebe |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Oral exam in small groups (30 minutes)

### Prerequisites

The precondition of this partial work is the successful processing of a case study(T-MACH-110396): Documentation and presentation of the overall results (15 minutes)

### Modeled Conditions

The following conditions have to be fulfilled:

1. The course [T-MACH-110396 - Strategic Product Development - Identification of Potentials of Innovative Products - Case Study](#) must have been passed.

### Workload

90 hours

T

**8.316 Course: Strategic Product Development - Identification of Potentials of Innovative Products - Case Study [T-MACH-110396]**





**Responsible:** Prof. Dr.-Ing. Albert Albers  
 Prof. Dr.-Ing. Sven Matthiesen  
 Prof. Dr.-Ing. Andreas Siebe

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107140 - Strategic Product Development - Identification of Potentials of Innovative Products](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 1       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |   |       |
|---------|---------|---|-------|---|-------|
| ST 2025 | 2146198 | <a href="#">Strategic product development - identification of potentials of innovative products</a> | 2 SWS | Lecture /  | Siebe |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Successful processing of a case study(T-MACH-110396): documentation and presentation of the overall results (15 minutes)

**Workload**

30 hours








T

**8.317 Course: Strategy Derivation for Engineers [T-ETIT-111369]**

**Responsible:** Prof. Dr. Tabea Arndt  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                        | Credits | Grading scale | Recurrence       | Version |
|-----------------------------|---------|---------------|------------------|---------|
| Completed coursework (oral) | 3       | pass/fail     | Each winter term | 2       |

| Events   |         |  |       |   |       |
|----------|---------|--|-------|---|-------|
| WT 24/25 | 2314010 | <a href="#">Strategy Derivation for Engineer</a> | 2 SWS | Seminar /  | Arndt |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T





**8.318 Course: Structural Materials [T-MACH-100293]**

**Responsible:** Dr.-Ing. Stefan Guth  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-100291 - Structural Materials](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 6       | Grade to a third | Each winter term | 3       |

| Events   |         |                                      |       |                          |      |
|----------|---------|--------------------------------------|-------|--------------------------|------|
| WT 24/25 | 2174580 | <a href="#">Structural Materials</a> | 4 SWS | Lecture / Practice ( / ) | Guth |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Oral exam, about 25 minutes

**Prerequisites**

none

**Workload**


180 hours

T

**8.319 Course: Superconducting Magnet Technology [T-ETIT-113440]**

**Responsible:** Prof. Dr. Tabea Arndt  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106684 - Superconducting Magnet Technology](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 2       |

| Events  |         |   |       |   |       |
|---------|---------|---|-------|---|-------|
| ST 2025 | 2312698 | <a href="#">Superconducting Magnet Technology</a> | 3 SWS | Lecture / Practice ( /  ) | Arndt |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The examination takes place in form of an oral exam (abt. 30 minutes).

Two timeslots (weeks) for examination dates will be announced (usually near end of lecture period & end of semester).

The module grade is the grade of the oral exam.

**Prerequisites**

none

T

**8.320 Course: Superconducting Power Systems [T-ETIT-113439]**

**Responsible:** Prof. Dr.-Ing. Mathias Noe  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-106683 - Superconducting Power Systems](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 2       |

| Events   |         |   |       |                          |     |
|----------|---------|---|-------|--------------------------|-----|
| WT 24/25 | 2314011 | <a href="#">Superconducting Power Systems</a> | 3 SWS | Lecture / Practice ( / ) | Noe |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The examination takes place in form of an oral exam (abt. 45 minutes).

The module grade is the grade of the oral exam.


**Prerequisites**





none

T

**8.321 Course: Sustainable Product Engineering [T-MACH-114033]****Responsible:** Dr.-Ing. Karl-Friedrich Ziegahn**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107189 - Sustainable Product Engineering: Sustainable Product Design - Long-term Business Success with Sustainably Developed Products](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |         |
|---------|---------|---|-------|---|---------|
| ST 2025 | 2146193 | <a href="#">Sustainable Product Engineering</a> | 2 SWS | Lecture /  | Ziegahn |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

written exam (90 min)

**Prerequisites**

none

**Recommendation**

None

**Workload**

120 hours

T

## 8.322 Course: System Integration and Communication Structures in Industry 4.0 and IoT [T-ETIT-112212]





**Responsible:** Prof. Dr.-Ing. Jürgen Becker

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-106026 - System Integration and Communication Structures in Industry 4.0 and IoT](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 3       | Grade to a third | Each winter term | 1 terms   | 1       |

| Events   |         |   |       |   |       |
|----------|---------|---|-------|---|-------|
| WT 24/25 | 2311614 | <a href="#">System Integration and Communication Structures in Industry 4.0 and IoT</a> | 2 SWS | Lecture /  | Babel |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled


### Prerequisites





none

T

**8.323 Course: System Integration in Micro- and Nanotechnology [T-MACH-105555]****Responsible:** apl. Prof. Dr. Ulrich Gengenbach**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105315 - System Integration in Micro- and Nanotechnology](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |            |
|---------|---------|---|-------|---|------------|
| ST 2025 | 2106033 | <a href="#">System Integration in Micro- and Nanotechnology I</a> | 2 SWS | Lecture /  | Gengenbach |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

oral exam (Duration: 30 min)

**Prerequisites**

none


**Workload**





120 hours

T

**8.324 Course: System Integration in Micro- and Nanotechnology 2 [T-MACH-110272]****Responsible:** apl. Prof. Dr. Ulrich Gengenbach**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-105316 - System Integration in Micro- and Nanotechnology 2](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |   |            |
|----------|---------|---|-------|---|------------|
| WT 24/25 | 2105040 | <a href="#">System Integration in Micro- and Nanotechnology 2</a> | 2 SWS | Lecture /  | Gengenbach |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Oral exam, approx. 15 min.

**Prerequisites**

None

**Workload**

120 hours



T

**8.325 Course: System-on-Chip Laboratory [T-ETIT-100798]**

**Responsible:** Prof. Dr.-Ing. Jürgen Becker  
Prof. Dr. Ivan Peric

**Organisation:** KIT Department of Electrical Engineering and Information Technology

**Part of:** [M-ETIT-100451 - System-on-Chip Laboratory](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 6       | Grade to a third | Each winter term | 1       |

| Events   |         |   |       |                      |               |
|----------|---------|---|-------|----------------------|---------------|
| WT 24/25 | 2311612 | <a href="#">Laboratory System-on-Chip</a> | 4 SWS | Practical course / ● | Becker, Peric |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Prerequisites**

none

T

**8.326 Course: Systems and Software Engineering [T-ETIT-100675]**

**Responsible:** Prof. Dr.-Ing. Eric Sax  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100537 - Systems and Software Engineering](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each winter term | 2       |

| Events   |         |   |       |              |        |
|----------|---------|---|-------|--------------|--------|
| WT 24/25 | 2311605 | <a href="#">Systems and Software Engineering</a>                      | 2 SWS | Lecture / 🔄  | Sax    |
| WT 24/25 | 2311607 | <a href="#">Tutorial for 2311605 Systems and Software Engineering</a> | 1 SWS | Practice / 🔄 | Nägele |

Legend: 📺 Online, 🔄 Blended (On-Site/Online), 📍 On-Site, ✕ Cancelled

**Competence Certificate**

Written exam, approximately 90 minutes.

Students are given the opportunity to earn a grade bonus through separate task assignments. If the grade of the written exam is between 4.0 and 1.3, the bonus improves the grade by a maximum of one grade level (0.3 or 0.4). The exact criteria for awarding a bonus will be announced at the beginning of the lecture. Bonus points do not expire and remain valid for exams taken at a later date:

The grade is determined by the written exam and the bonus points.

**Prerequisites**

none

T

**8.327 Course: Technical Design in Product Development [T-MACH-105361]**

**Responsible:** Prof. Dr.-Ing. Albert Albers  
Prof. Dr.-Ing. Sven Matthiesen  
Dr.-Ing. Markus Schmid

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105318 - Technical Design in Product Development](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1       |

**Competence Certificate**

Written exam (60 min)

Only dictionary is allowed

**Workload**



120 hours

T

**8.328 Course: Technical Optics [T-ETIT-100804]**

**Responsible:** Prof. Dr. Cornelius Neumann  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-100538 - Technical Optics](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 5       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |  |         |
|----------|---------|--|-------|--|---------|
| WT 24/25 | 2313720 | <a href="#">Technical Optics</a>                       | 2 SWS | Lecture /   | Neumann |
| WT 24/25 | 2313722 | <a href="#">Technical Optics (Tutorial to 2313720)</a> | 1 SWS | Practice /  | Neumann |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Prerequisites**

none

T

**8.329 Course: Technology Assessment and its Normative Basis [T-MACH-113884]**

**Responsible:** Prof. Dr. Dr. Rafaela Hillerbrand  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-ETIT-107193 - Interdisciplinary Qualifications](#)

| Type                 | Credits | Grading scale | Recurrence       | Expansion | Version |
|----------------------|---------|---------------|------------------|-----------|---------|
| Completed coursework | 2       | pass/fail     | Each winter term | 1 terms   | 2       |

| Events   |         |  |       |                    |             |
|----------|---------|--|-------|--------------------|-------------|
| WT 24/25 | 5000057 | <a href="#">Aufbaumodul:<br/>Technikfolgenabschätzung und<br/>Normativität</a> | 2 SWS | Advanced seminar ( | Hillerbrand |

**Competence Certificate**

Coursework in the form of written assignments and/or oral performances.

**Prerequisites**

none

**Workload**

60 hours

T

**8.330 Course: Thermal Solar Energy [T-MACH-105225]**

**Responsible:** apl. Prof. Dr. Ron Dagan  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-102388 - Thermal Solar Energy](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 2       |

| Events   |         |  |       |   |       |
|----------|---------|--|-------|---|-------|
| WT 24/25 | 2189400 | <a href="#">Solar Thermal Energy Systems</a> | 2 SWS | Lecture /  | Dagan |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Oral examination of about 30 minutes

**Prerequisites**

none

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-MACH-106493 - Solar Thermal Energy Systems](#) must not have been started.

**Workload**

120 hours

T

**8.331 Course: Thermal Turbomachines I [T-MACH-114052]**

**Responsible:** Prof. Dr.-Ing. Hans-Jörg Bauer  
**Organisation:** KIT Department of Mechanical Engineering  
Institute of Thermal Turbomachinery  
**Part of:** [M-MACH-107219 - Thermal Turbomachines I](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 8       | Grade to a third | Each winter term | 1       |

**Competence Certificate**

oral exam, duration approx. 30 min.

**Prerequisites**

none

**Workload**

240 hours


T

**8.332 Course: Thermal-Fluid-Dynamics [T-MACH-106372]**

**Responsible:** Dr. Sebastian Ruck  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107112 - Thermal-Fluid-Dynamics](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |  |       |   |      |
|----------|---------|--|-------|---|------|
| WT 24/25 | 2189423 | <a href="#">Thermal-Fluid-Dynamics</a> | 2 SWS | Lecture /  | Ruck |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

oral exam of about 30 minutes

**Prerequisites**

none

**Workload**

120 hours



T


## 8.333 Course: Tires and Wheel Development for Passenger Cars [T-MACH-102207]





**Responsible:** Prof. Dr.-Ing. Günter Leister

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107070 - Tires and Wheel Development for Passenger Cars](#)

| Type             | Credits | Grading scale    | Recurrence       | Version |
|------------------|---------|------------------|------------------|---------|
| Oral examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |   |         |
|---------|---------|--|-------|---|---------|
| ST 2025 | 2114845 | <a href="#">Tires and Wheel Development for Passenger Cars</a> | 2 SWS | Lecture /  | Leister |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Oral Examination

Duration: 30 up to 40 minutes

Auxiliary means: none

### Prerequisites

none

### Workload

120 hours

**8.334 Course: Tractors [T-MACH-105423]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
Hon.-Prof. Dr. Martin Kremmer

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-107058 - Tractors](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 1       |

| Events   |         |                          |       |   |         |
|----------|---------|--------------------------|-------|---|---------|
| WT 24/25 | 2113080 | <a href="#">Tractors</a> | 2 SWS | / | Kremmer |

Legend: Online, Blended (On-Site/Online), On-Site, Cancelled

**Competence Certificate**

The assessment consists of an written exam taking place in the recess period (90 min).

**Prerequisites**

none

**Recommendation**

Basic knowledge in mechanical engineering.

**Annotation****Learning Outcomes**

After completion of the course the Students know:

- important problems in agritechnological developments
- Customer requirements and their implementation in tractors
- Tractor technology in width and depth

**Content**

Tractors are one of the most underestimated vehicles in regard to performance und technics. Almost none vehicle is as multifunctional and fulfilled with high-tech as a tractor. Automatic guidance, special chassis suspension or special concepts of power trains are one of the topics where tractors are in leading position in technologies. During the lecture an overview about the design and construction and application area is given. A close look will be taken on the historical background, legal requirements, ways of development, agricultural organizations and the process of development itself.

In detail the following topics will be dealt with:

- agricultural organization / legal requirements
- history of tractors
- tractor engineering
- tractor mechanics
- chassis suspension
- combustion engine
- transmission
- interfaces
- hydraulics
- wheels and tyres
- cabin
- electrics and electronics

**Literature**

- K.T. Renius: Traktoren - Technik und ihre Anwendung; DLG Verlag (Frankfurt), 1985
- E. Schilling: Landmaschinen - Lehr- und Handbuch für den Landmaschinenbau; Schilling-Verlag (Köln), 1960

**Workload**

120 hours

T


## 8.335 Course: Tutorial Continuum Mechanics of Solids and Fluids [T-MACH-110333]


**Responsible:** Prof. Dr.-Ing. Thomas Böhlke  
Prof. Dr.-Ing. Bettina Frohnappel

**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-105180 - Continuum Mechanics](#)

| Type                 | Credits | Grading scale | Recurrence       | Version |
|----------------------|---------|---------------|------------------|---------|
| Completed coursework | 1       | pass/fail     | Each winter term | 1       |

| Events   |         |   |       |  |                           |
|----------|---------|---|-------|--|---------------------------|
| WT 24/25 | 2161253 | <a href="#">Tutorial Continuum mechanics of solids and fluids</a> | 2 SWS | Practice /  | Gisy, Speichinger, Böhlke |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Successfully passing the Tutorial is a prerequisite for taking part in the exam "Continuum Mechanics of Solids and Fluids" (T-MACH-110377).

For students of Mechanical Engineering (BSc) that have chosen the Major Field "Continuum Mechanics" and for students of Material Science and Material Technology (BSc) the prerequisites consist of successfully solving the written homework sheets as well as the computational homework sheets during the associated computer tutorials.

For students of Mechanical Engineering that have chosen a different Major Field of students from different fields of study the prerequisites consist of successfully solving only the written homework sheets.

### Prerequisites

None

### Annotation

Due to capacity reasons it is possible that not all students of this course can be admitted to the computer tutorials. Students of the bachelor's degree program in mechanical engineering who have chosen the Major Field Continuum Mechanics (SP-Nr 13) and students of the bachelor's degree program in material science and material technology will be admitted to the computer tutorials in any case.

If additional places are available in the computer tutorials for this course, these will be allocated according to the BSc average grade.

### Workload

30 hours

T

## 8.336 Course: Tutorial Mathematical Methods in Continuum Mechanics [T-MACH-110376]

**Responsible:** Prof. Dr.-Ing. Thomas Böhlke  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-106210 - Mathematical Methods in Continuum Mechanics](#)

| Type                 | Credits | Grading scale | Recurrence       | Expansion | Version |
|----------------------|---------|---------------|------------------|-----------|---------|
| Completed coursework | 2       | pass/fail     | Each winter term | 1 terms   | 2       |

| Events   |         |  |       |              |                      |
|----------|---------|--|-------|--------------|----------------------|
| WT 24/25 | 2161255 | <a href="#">Tutorial Mathematical Methods in Continuum Mechanics</a> | 2 SWS | Practice / ● | Lauff, Klein, Böhlke |

Legend: 📺 Online, 🔄 Blended (On-Site/Online), ● On-Site, ✕ Cancelled

### Competence Certificate

successfully solving the homework sheets. Details are announced in the first lecture.

### Prerequisites

None

### Workload

60 hours

T

**8.337 Course: Tutorial Mathematical Methods in Hydraulics [T-MACH-113913]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-107210 - Mathematical Methods in Hydraulics](#)

| Type                 | Credits | Grading scale | Recurrence       | Expansion | Version |
|----------------------|---------|---------------|------------------|-----------|---------|
| Completed coursework | 2       | pass/fail     | Each winter term | 1 terms   | 1       |

**Competence Certificate**

Successful completion of Ilias tests. Details will be announced in the first lecture.

**Prerequisites**

none

**Annotation**

See "Mathematical methods of hydraulics".

**Workload**


60 hours

T

**8.338 Course: Tutorial Simulation with Lumped Parameters [T-MACH-113863]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-107053 - Simulation with Lumped Parameters](#)

| Type                 | Credits | Grading scale | Recurrence       | Expansion | Version |
|----------------------|---------|---------------|------------------|-----------|---------|
| Completed coursework | 1       | pass/fail     | Each summer term | 1 terms   | 1       |

| Events  |         |  |       |  |                  |
|---------|---------|--|-------|--|------------------|
| ST 2025 | 2114072 | <a href="#">Simulation with Lumped Parameters (Tutorial)</a> | 2 SWS | Practice /  | Geimer, Michiels |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Submission of a report at the end of the lecture period.

**Prerequisites**

none

**Recommendation**

Knowledge of mechanics and hydraulics

**Annotation**

This tutorial is a prerequisite for the partial performance T-MACH-113862 - Simulation with concentrated parameters (examination) in the MSc Mechanical Engineering program (SPO 2025).

**Workload**

30 hours

T

**8.339 Course: Ubiquitous Computing [T-INFO-114188]**

**Responsible:** Prof. Dr.-Ing. Michael Beigl  
**Organisation:** KIT Department of Informatics  
**Part of:** [M-INFO-107161 - Ubiquitous Computing](#)

**Type**  
Oral examination





**Credits**  
5

**Grading scale**  
Grade to a third

**Recurrence**  
Each winter term

**Version**  
1

| Events  |       |   |       |   |                         |
|---------|-------|---|-------|---|-------------------------|
| ST 2025 | 24844 | <a href="#">Seminar: Ubiquitous Systems</a> | 2 SWS | Seminar /  | Riedel, Beigl, Röddiger |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment is carried out as an oral examination (§ 4 Abs. 2 Nr. 2 SPO) lasting 20 minutes.

**Prerequisites**

None.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-INFO-101326 - Ubiquitous Computing](#) must not have been started.



T

**8.340 Course: Validation of Technical Systems [T-MACH-113982]****Responsible:** Prof. Dr.-Ing. Tobias Düser**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-107143 - Validation of Technical Systems](#)

| Type                | Credits | Grading scale    | Recurrence       | Expansion | Version |
|---------------------|---------|------------------|------------------|-----------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1 terms   | 3       |

| Events  |         |   |       |   |       |
|---------|---------|---|-------|---|-------|
| ST 2025 | 2146230 | <a href="#">Validation of technical Systems</a> | 2 SWS | Lecture /  | Düser |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Written exam with a duration of 60 minutes.

**Prerequisites**

None

**Recommendation**

None

**Annotation**

None

**Workload**

120 hours

T

**8.341 Course: Vehicle Drive Technology [T-MACH-113997]**

**Responsible:** Prof. Dr.-Ing. Marcus Geimer  
**Organisation:** KIT Department of Mechanical Engineering  
**Part of:** [M-MACH-107056 - Vehicle Drive Technology](#)

| Type             | Credits | Grading scale    | Recurrence       | Expansion | Version |
|------------------|---------|------------------|------------------|-----------|---------|
| Oral examination | 4       | Grade to a third | Each winter term | 1 terms   | 1       |

**Competence Certificate**

Oral examination, duration approx. 20 minutes

**Prerequisites**

none

**Workload**

120 hours

T


## 8.342 Course: Vehicle Lightweight Design - Strategies, Concepts, Materials [T-MACH-105237]





**Responsible:** Prof. Dr.-Ing. Frank Henning  
**Organisation:** KIT Department of Mechanical Engineering

Lightweight Design

**Part of:** [M-MACH-102703 - Vehicle Lightweight Design - Strategies, Concepts, Materials](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 3       |

| Events   |         |  |       |   |         |
|----------|---------|--|-------|---|---------|
| WT 24/25 | 2113102 | <a href="#">Vehicle Lightweight design – Strategies, Concepts, Materials</a> | 2 SWS | Lecture /  | Henning |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

### Competence Certificate

Written exam; Duration approx. 90 min

### Prerequisites

[T-MACH-114001](#) must not have been started.

### Recommendation

none

### Workload





120 hours

T

**8.343 Course: Vehicle Systems for Urban Mobility [T-MACH-113069]****Responsible:** Prof. Dr.-Ing. Martin Cichon**Organisation:** KIT Department of Mechanical Engineering**Part of:** [M-MACH-106515 - Vehicle Systems for Urban Mobility](#)

| Type             | Credits | Grading scale    | Version |
|------------------|---------|------------------|---------|
| Oral examination | 4       | Grade to a third | 3       |

| Events   |         |  |       |   |                |
|----------|---------|--|-------|---|----------------|
| WT 24/25 | 2115922 | <a href="#">Vehicle Systems for Urban Mobility</a> | 2 SWS | Lecture /  | Cichon, Ziesel |
| ST 2025  | 2115922 | <a href="#">Vehicle Systems for Urban Mobility</a> | 2 SWS | Lecture /  | Ziesel, Cichon |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled**Competence Certificate**

Oral examination

Duration: approx. 20 minutes

No tools or reference material may be used during the exam.

**Workload**

120 hours

T

**8.344 Course: Virtual Engineering I [T-MACH-102123]**

**Responsible:** Prof. Dr.-Ing. Jivka Ovtcharova  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-101283 - Virtual Engineering A](#)  
[M-MACH-105293 - Virtual Engineering 1](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 3       |

| Events   |         |   |       |               |  |
|----------|---------|---|-------|---------------|--|
| WT 24/25 | 2121352 | <a href="#">Virtual Engineering I</a>           | 2 SWS | Lecture / 🗣️  | Ovtcharova, weitere Mitarbeitende          |
| WT 24/25 | 2121353 | <a href="#">Exercises Virtual Engineering I</a> | 2 SWS | Practice / 🗣️ | Ovtcharova, Mitarbeiter, Mitarbeiter/innen |

Legend: 📺 Online, 🔄 Blended (On-Site/Online), 🗣️ On-Site, ✖ Cancelled

**Competence Certificate**  
 Written examination 90 min.

**Prerequisites**  
 None

**Workload**  
 120 hours



T





**8.345 Course: Virtual Engineering Lab [T-MACH-106740]**

**Responsible:** Prof. Dr.-Ing. Jivka Ovtcharova  
**Organisation:** KIT Department of Mechanical Engineering

**Part of:** [M-MACH-101283 - Virtual Engineering A](#)  
[M-MACH-105475 - Virtual Engineering Lab](#)

| Type                        | Credits | Grading scale    | Recurrence | Version |
|-----------------------------|---------|------------------|------------|---------|
| Examination of another type | 4       | Grade to a third | Each term  | 1       |

| Events   |         |   |       |  |                    |
|----------|---------|---|-------|--|--------------------|
| WT 24/25 | 2123350 | <a href="#">Virtual Engineering Lab</a> | 3 SWS | Project (P /  ) | Ovtcharova, Häfner |
| ST 2025  | 2123350 | <a href="#">Virtual Engineering Lab</a> | 3 SWS | Project (P /  ) | Häfner, Ovtcharova |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

Assessment of another type (graded), Group project to create a VR application (project task, implementation and presentation of the project work)

T

**8.346 Course: Wearable Robotic Technologies [T-INFO-114145]**

**Responsible:** Prof. Dr.-Ing. Tamim Asfour  
Prof. Dr.-Ing. Michael Beigl

**Organisation:** KIT Department of Informatics

**Part of:** [M-INFO-107113 - Wearable Robotic Technologies](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each summer term | 1       |

| Events  |         |   |       |   |               |
|---------|---------|---|-------|---|---------------|
| ST 2025 | 2400062 | <a href="#">Wearable Robotic Technologies</a> | 2 SWS | Lecture /  | Asfour, Beigl |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

The assessment is carried out as a written examination (§ 4 Abs. 2 No. 1 SPO) lasting 60 minutes.

**Prerequisites**

Attending the lecture Mechano-Informatics and Robotics is recommended.

**Modeled Conditions**

The following conditions have to be fulfilled:

1. The course [T-INFO-106557 - Wearable Robotic Technologies](#) must not have been started.

**Recommendation**


Attending the lecture Mechano-Informatics and Robotics is recommended.





T

**8.347 Course: Windpower [T-MACH-105234]**

**Responsible:** Norbert Lewald  
**Organisation:** KIT Department of Mechanical Engineering  
 Institute of Thermal Turbomachinery  
**Part of:** [M-MACH-105732 - Windpower](#)

| Type                | Credits | Grading scale    | Recurrence       | Version |
|---------------------|---------|------------------|------------------|---------|
| Written examination | 4       | Grade to a third | Each winter term | 2       |

| Events   |         |                           |       |   |        |
|----------|---------|---------------------------|-------|---|--------|
| WT 24/25 | 2157381 | <a href="#">Windpower</a> | 2 SWS | Lecture /  | Lewald |

Legend:  Online,  Blended (On-Site/Online),  On-Site,  Cancelled

**Competence Certificate**

written exam, 120 minutes

**Prerequisites**

none

**Workload**

120 hours



T

## 8.348 Course: Workshop Finite Element Method in Electromagnetics [T-ETIT-114166]

**Responsible:** Prof. Dr. Martin Doppelbauer  
**Organisation:** KIT Department of Electrical Engineering and Information Technology  
**Part of:** [M-ETIT-107147 - Workshop Finite Element Method in Electromagnetics](#)

| Type                        | Credits | Grading scale    | Recurrence       | Version |
|-----------------------------|---------|------------------|------------------|---------|
| Examination of another type | 3       | Grade to a third | Each summer term | 1       |

| Events  |         |  |       |             |                   |
|---------|---------|--|-------|-------------|-------------------|
| ST 2025 | 2306333 | <a href="#">Workshop Finite Element Method in Electromagnetics</a> | 2 SWS | Seminar / 📱 | Brodatzki, Gjeset |

Legend: 📱 Online, 🔄 Blended (On-Site/Online), ● On-Site, ✕ Cancelled

### Competence Certificate

Success control takes place in the form of different types of examination consisting of a written assignment in the form of an written report.

The module grade is the grade of the written paper.

### Prerequisites

none

## 9 Appendix

### 9.1 Definition - About this MHB

MHB, PDF-Version: <https://s.kit.edu/mhb-mit-msc25>